

Nehari's Theorem for Convex Domain Hankel and Toeplitz Operators in Several Variables

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We prove Nehari's theorem for integral Hankel and Toeplitz operators on simple convex polytopes in several variables. A special case of the theorem, generalizing the boundedness criterion of the Hankel and Toeplitz operators on the Paley–Wiener space, reads as follows. Let $\Xi = (0, 1)^d$ be a d -dimensional cube, and for a distribution f on 2Ξ , consider the Hankel operator

$$\Gamma_f(g)(x) = \int_{\Xi} f(x+y)g(y) dy, \quad x \in \Xi.$$

Then Γ_f extends to a bounded operator on $L^2(\Xi)$ if and only if there is a bounded function b on \mathbb{R}^d whose Fourier transform coincides with f on 2Ξ . This special case has an immediate application in matrix extension theory: every finite multilevel block Toeplitz matrix can be boundedly extended to an infinite multilevel block Toeplitz matrix. In particular, block Toeplitz operators with blocks that are themselves Toeplitz can be extended to bounded infinite block Toeplitz operators with Toeplitz blocks.

1 Introduction

For an open connected set $\Xi \subset \mathbb{R}^d$, $d \geq 1$, let

$$\Omega = \Xi + \Xi = \{x+y : x \in \Xi, y \in \Xi\},$$

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and consider a distribution f defined on Ω . The associated general domain Hankel operator $\Gamma_f = \Gamma_{f, \Xi}$ is the (densely defined) operator $\Gamma_f: L^2(\Xi) \rightarrow L^2(\Xi)$, given by

$$\Gamma_f(g)(x) = \int_{\Xi} f(x+y)g(y) dy, \quad x \in \Xi,$$

where dy is the Lebesgue measure on \mathbb{R}^d .

The case $\Xi = \mathbb{R}_+ = (0, \infty)$ for $d = 1$ corresponds to the class of usual Hankel operators; when represented in the appropriate basis of $L^2(\mathbb{R}_+)$, the operator Γ_{f, \mathbb{R}_+} is realized as an infinite Hankel matrix $\{a_{n+m}\}_{n,m=0}^{\infty}$ [31, Ch. 1.8]. *Nehari's theorem* [25] characterizes the bounded Hankel matrices of this type, but it has an equivalent version for operators of the type $\Gamma_f: L^2(\mathbb{R}_+) \rightarrow L^2(\mathbb{R}_+)$, which reads as follows (we again refer to [31, Ch. 1.8], Theorem 8.1). For a function g on \mathbb{R}^d , we let $\hat{g} = \mathcal{F}g$ denote its Fourier transform,

$$\hat{g}(\xi) = \mathcal{F}g(\xi) = \int_{\mathbb{R}^d} g(x)e^{-2\pi i x \cdot \xi} dx, \quad \xi \in \mathbb{R}^d.$$

Theorem. Suppose that f is a distribution in \mathbb{R}_+ , $f \in \mathcal{D}'(\mathbb{R}_+)$. Then $\Gamma_f: L^2(\mathbb{R}_+) \rightarrow L^2(\mathbb{R}_+)$ is bounded if and only if there exists a function $b \in L^\infty(\mathbb{R})$ such that $\hat{b}|_{\mathbb{R}_+} = f$. Moreover, it is possible to choose b so that

$$\|\Gamma_f\| = \|b\|_{L^\infty}. \quad (1.1)$$

Nehari's theorem is canonical in operator theory. The two most common proofs proceed either by factorization in the single variable Hardy space or by making use of the commutant lifting theorem.

For $d > 1$, the operators $\Gamma_{f, \mathbb{R}_+^d}$, $\Xi = \mathbb{R}_+^d$, correspond to (small) Hankel operators on the product domain multi-variable Hardy space H_d^2 . In this case, the analogue of Nehari's theorem remains true, apart from (1.1), but it is significantly more difficult to prove. It was established by Ferguson and Lacey ($d = 2$) and Lacey and Terwilleger ($d > 2$) [18, 23]. A precise statement is given in Theorem 2.1.

The main purpose of this article is to prove Nehari's theorem when $\Xi \subset \mathbb{R}^d$ is a simple convex polytope. When Ξ is convex note that $\Xi + \Xi = 2\Xi$.

Theorem 1.1. Let Ξ be a simple convex polytope, and let $f \in \mathcal{D}'(\Omega)$ where $\Omega = 2\Xi$. Then $\Gamma_f: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded if and only if there is a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_{\Omega} = f$. There exists a constant $c > 0$, depending on Ξ , such that b can be chosen

to satisfy

$$c\|b\|_{L^\infty} \leq \|\Gamma_f\| \leq \|b\|_{L^\infty}.$$

When $d = 1$, the only open connected sets $\Xi \subset \mathbb{R}$ are the intervals $\Xi = I$. In this case, Theorem 1.1 is due to Rochberg [35], who called the corresponding operators $\Gamma_{f,I}$ Hankel/Toeplitz operators on the Paley–Wiener space. They have also been called Wiener–Hopf operators on a finite interval [30]. These operators have inspired a wealth of theory in the single variable setting—see Section 2.5, where we shall interpret Theorem 1.1 in the context of Paley–Wiener spaces.

Even for $d = 1$, our proof of Theorem 1.1 appears to be new. However, in several variables our proof relies on the Nehari theorem of Ferguson–Lacey–Terwilleger and can therefore not be used to give a new proof of their results.

We shall also consider general domain Toeplitz operators $\Theta_f = \Theta_{f,\Xi}: L^2(\Xi) \rightarrow L^2(\Xi)$. In this context, f is a distribution defined on $\Omega = \Xi - \Xi$, and Θ_f is densely defined via

$$\Theta_f(g)(x) = \int_{\Xi} f(x - \gamma)g(\gamma) \, d\gamma, \quad x \in \Xi.$$

If Ξ after a translation is invariant under the reflection $x \mapsto -x$, then the classes of Hankel operators $\Gamma_{f,\Xi}$ and Toeplitz operators $\Theta_{\tilde{f},\Xi}$ are essentially the same, and Theorem 1.1 immediately yields a boundedness result. This reasoning is applicable to the cube $\Xi = (0, 1)^d$, for example.

Corollary 1.2. Let Ξ be a simple convex polytope such that for some $z \in \mathbb{R}^d$ it holds that $\Xi + z = -\Xi - z$. Let $f \in \mathcal{D}'(\Omega)$, $\Omega = \Xi - \Xi = 2\Xi + 2z$. Then Θ_f is bounded if and only if there exists a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_{\Omega} = f$. There exists a constant $c > 0$, depending on Ξ , such that b can be chosen to satisfy

$$c\|b\|_{L^\infty} \leq \|\Theta_f\| \leq \|b\|_{L^\infty}.$$

On the other hand, when Ξ is a proper convex unbounded set, containing an open cone say, it is clear that the boundedness characterizations of $\Theta_{f,\Xi}$ and $\Gamma_{f,\Xi}$ may be completely different; plainly explained by the fact that $\Omega = \Xi - \Xi = \mathbb{R}^d$ in the Toeplitz case, while $\Omega = \Xi + \Xi = 2\Xi \subsetneq \mathbb{R}^d$ for Hankel operators. In this setting, identifying the boundedness of Θ_f carries none of the subtleties of Nehari-type theorems. In Theorem 6.1 we obtain the expected boundedness result for a class

of “cone-like” domains Ξ . Rather than giving a precise statement here, let us record the following corollary of Theorem 6.1.

Corollary 6.2. Let $\Xi \subset \mathbb{R}^d$ be any open connected domain such that

$$(1, \infty)^d \subset \Xi \subset (0, \infty)^d,$$

and let $f \in \mathcal{D}'(\mathbb{R}^d)$. Then $\Theta_f: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded if and only if f is a tempered distribution and $\|\hat{f}\|_{L^\infty(\mathbb{R}^d)} < \infty$, and in this case

$$\|\Theta_f\| = \|\hat{f}\|_{L^\infty}.$$

In the final part of the paper we shall give an application of Theorem 1.1 to matrix completion theory, essentially obtained by discretizing Corollary 1.2 when Ξ is a cube. To avoid introducing further notation, we shall only state the result in words for now. Recall that a Toeplitz matrix is one whose diagonals are constant. An $N \times N$ d -multilevel block Toeplitz matrix is an $N \times N$ Toeplitz matrix whose entries are $N \times N$ $(d - 1)$ -multilevel block Toeplitz matrices. Here N could be finite or infinite. A 1-multilevel block Toeplitz matrix is simply an ordinary Toeplitz matrix. A 2-multilevel block Toeplitz matrix is what is usually considered a block Toeplitz matrix where each block itself is Toeplitz.

Theorem 7.1. Every finite $N \times N$ d -multilevel block Toeplitz matrix can be extended to an infinite d -multilevel block Toeplitz matrix bounded on ℓ^2 , with a constant that only depends on the dimension d .

For scalar Toeplitz matrices ($d = 1$) this result is well known [5, 26, 36, 38], although not as firmly cemented in the literature as the Nehari theorem itself; see [28, Ch. V.2, V.8] for a proof based on Parrot’s lemma and a discussion of the result’s history. For $d = 1$, the converse deduction of Theorem 1.1 starting from Theorem 7.1 can be found in [13].

The paper is laid out as follows. In Section 2 we will give a more formal background and introduce necessary notation. We will also discuss the relationship between $\Gamma_{f, \Xi}$, Paley–Wiener spaces, and co-invariant subspaces of the Hardy spaces. In Section 3 we will prove approximation results for distribution symbols with respect to Hankel and Toeplitz operators, allowing us to reduce to smooth symbols. Section 4 briefly outlines what we need to know about convex sets and polytopes. In Section 5

we prove Theorem 1.1, our Nehari theorem for Hankel operators. We also indicate how the proof extends to certain unbounded polyhedral domains. In Section 6 our main result on Toeplitz operators is shown, Theorem 6.1. Finally, Section 7 gives the proof of Theorem 7.1.

2 Further background and related results

2.1 Hankel operators on multi-variable Hardy spaces

Let us begin by placing Hankel operators Γ_f into the context of classical Hankel operators on Hardy spaces. As before, for $g \in L^2(\mathbb{R}^d)$, let $\hat{g} = \mathcal{F}g$ denote its Fourier transform,

$$\hat{g}(\xi) = \mathcal{F}g(\xi) = \int_{\mathbb{R}^d} g(x)e^{-2\pi i x \cdot \xi} dx, \quad \xi \in \mathbb{R}^d.$$

For the inverse transform we write $\mathcal{F}^{-1}(g) = \check{g}$. The product domain Hardy space H_d^2 is the proper subspace of $L^2(\mathbb{R}^d)$ of functions whose Fourier transforms are supported in the cone $\mathbb{R}_+^d, \mathbb{R}_+ = (0, \infty)$,

$$H_d^2 = \left\{ G \in L^2(\mathbb{R}^d) : \text{supp } \hat{G} \subset \overline{\mathbb{R}_+^d} \right\}.$$

We let $P_d: L^2(\mathbb{R}^d) \rightarrow H_d^2$ denote the orthogonal projection and let $J: L^2(\mathbb{R}^d) \rightarrow L^2(\mathbb{R}^d)$ be the involution defined by $JG(x) = G(-x), x \in \mathbb{R}$.

Consider $\Gamma_f = \Gamma_{f, \Xi}$ for $\Xi = \mathbb{R}_+^d$ with $f \in L^2(\mathbb{R}_+^d)$. For a dense set of $g, h \in L^2(\mathbb{R}_+^d)$ we have that

$$\langle \Gamma_f g, h \rangle_{L^2(\mathbb{R}_+^d)} = \langle \check{f} J \check{g}, \check{h} \rangle_{H_d^2}. \tag{2.1}$$

It follows that the (possibly unbounded) operator $\Gamma_f: L^2(\mathbb{R}_+^d) \rightarrow L^2(\mathbb{R}_+^d)$ is unitarily equivalent to the small Hankel operator $Z_{\check{f}}: H_d^2 \rightarrow H_d^2$,

$$Z_{\check{f}}G = P_d(\check{f} \cdot JG).$$

Note that any b such that $\hat{b}|_{\mathbb{R}_+^d} = f$ generates the same Hankel operator as $\check{f}, Z_b = Z_{\check{f}}$.

To justify the above computation easily we assumed that $f \in L^2(\mathbb{R}_+^d)$. An approximation argument is needed to consider general symbols f , which may only be distributions in \mathbb{R}_+^d . We provide this later in Proposition 3.2. We can then read off the boundedness of Γ_f from the boundedness of the corresponding Hankel operator on H_d^2 . When $d = 1$ and $\Xi = \Omega = \mathbb{R}_+$, the analogue of Theorem 1.1 is exactly the classical

Nehari theorem. In higher dimensions the corresponding theorem is due to Ferguson–Lacey–Terwillegger [18, 23]. In our notation, their results read as follows.

Theorem 2.1. Suppose $\Xi = \Omega = \mathbb{R}_+^d$ and that f is a distribution in \mathbb{R}_+^d , $f \in \mathcal{D}'(\mathbb{R}_+^d)$. Then $\Gamma_f: L^2(\mathbb{R}_+^d) \rightarrow L^2(\mathbb{R}_+^d)$ is bounded if and only if there exists a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_{\mathbb{R}_+^d} = f$. Moreover, there exists a constant $c > 0$, depending on d , such that b can be chosen to satisfy

$$c\|b\|_{L^\infty} \leq \|\Gamma_f\| \leq \|b\|_{L^\infty}. \quad (2.2)$$

For $d > 1$ it is not possible to take $c = 1$ in (2.2), see for example [29]. This result, as stated in [18, 23], requires that $f \in L^2(\mathbb{R}_+^d)$. The extension to the more general situation considered here is a technicality, but for completeness the details are provided in Section 3.

2.2 Hankel operators on bounded domains

We now discuss bounded domains Ξ , the setting of our main result. The only convex bounded domains in \mathbb{R} are the intervals $I \subset \mathbb{R}$. Translations, dilations, and reflections carry the operator $\Theta_{f,I}$ onto $\Gamma_{\tilde{f},J}$, where $J \subset \mathbb{R}$ is any other interval and \tilde{f} arises from transforming f appropriately. In one variable it thus suffices to consider operators $\Gamma_{f,(0,1)}$ where $\Xi = (0,1)$. Rochberg [35] called these operators Hankel operators on the Paley–Wiener space and proved Theorem 1.1 in the one-dimensional case.

In the same article [35], it is posed as an open problem to characterize the bounded Hankel operators $\Gamma_{f,\Xi}$ when Ξ is a disc in \mathbb{R}^2 . We are not able to settle this question, but Theorem 1.1 does provide the answer when $\Xi = (0,1)^d$ is a cube in \mathbb{R}^d . As we will see, the Hankel operators $\Gamma_{f,(0,1)^d}$ constitute a natural generalization of the Hankel operators on the Paley–Wiener space. On a technical level, the reason that we are able to prove Theorem 1.1 when Ξ is a simple convex polytope, but not when Ξ is a ball, is that we rely on Theorem 2.1. In applying Theorem 2.1 to our situation, the corners of the boundary of Ξ are actually of help rather than hindrance. We consider the case of a ball to be an interesting open problem for which we do not dare to make a firm conjecture. In view of Fefferman’s disproof of the disc conjecture [17], Nehari theorems might turn out to be quite different for balls and polytopes.

2.3 Toeplitz operators

When $d = 1$ and $\Xi = \mathbb{R}_+$, $\Omega = \mathbb{R}$, the operators Θ_f are known as Wiener–Hopf operators [11, Ch. 9]. Analogously with Hankel operators, these can be shown to be

unitarily equivalent to Toeplitz matrix operators on $\ell^2(\mathbb{N})$. In this case the boundedness characterization is easy to both state and prove

$$\|\Theta_f\| = \|\hat{f}\|_{L^\infty}. \quad (2.3)$$

In Theorem 6.1 we extend (2.3) to Toeplitz operators $\Theta_{f,\Xi}$ for a class of “cone-like” domains $\Xi \subset \mathbb{R}^d$, for which $\Omega = \Xi - \Xi = \mathbb{R}^d$.

2.4 Truncated correlation operators

For open connected sets $\Xi, \Upsilon \subset \mathbb{R}^d$ it is also convenient to introduce the more general “truncated correlation operators” $\Psi_{f,\Upsilon,\Xi}: L^2(\Upsilon) \rightarrow L^2(\Xi)$, defined by

$$\Psi_f(g)(x) = \int_{\Upsilon} f(x+y)g(y) \, dy, \quad x \in \Xi,$$

where f lives on $\Omega = \Xi + \Upsilon$. This class of operators includes both general domain Hankel and Toeplitz operators, by letting $\Upsilon = \Xi$ and $\Upsilon = -\Xi$, respectively.

For our purposes, general truncated correlation operators will only appear in intermediate steps toward proving the main results, but they also carry independent interest. They were introduced in [1], where their finite rank structure was investigated. In [2] it was shown that they have a fundamental connection with frequency estimation on general domains, motivating the practical need for understanding such operators, not only on domains of simple geometrical structure. In [3] it is explained how one may infer certain results for the integral operators Ψ_f from their discretized matrix counterparts. We warn the reader that in naming the operators Γ_f , Θ_f , and Ψ_f we have slightly departed from previous work, reserving the term (general domain) Hankel operator for truncated correlation operators of the form $\Psi_{f,\Xi,\Xi}$.

2.5 Hankel operators on multi-variable Paley–Wiener spaces

Another viewpoint is offered through co-invariant subspaces of the Hardy spaces H_d^2 . For a domain $\Xi \subset \mathbb{R}^d$, let PW_Ξ denote the subspace of $L^2(\mathbb{R}^d)$ of functions with Fourier transforms supported in Ξ ,

$$\text{PW}_\Xi = \{G \in L^2(\mathbb{R}^d) : \text{supp } \hat{G} \subset \Xi\}.$$

In the classical case $\Xi = (0, 1) \subset \mathbb{R}$, note that

$$\text{PW}_{(0,1)} = H_1^2 \ominus \{G \in H_1^2 : \text{supp } \hat{G} \subset [1, \infty)\} = H_1^2 \ominus \theta H_1^2,$$

where

$$\theta(x) = e^{i2\pi x}, \quad x \in \mathbb{R}.$$

Hence $\text{PW}_{(0,1)}$ is the ortho-complement (in H_1^2) of θH_1^2 , the shift-invariant subspace of H_1^2 with inner factor θ . This space is usually denoted K_θ ,

$$\text{PW}_{(0,1)} = K_\theta := (\theta H_1^2)^\perp.$$

By a calculation similar to (2.1) we see that $\Gamma_{f,(0,1)}$ is unitarily equivalent to the compression of the Hankel operator $Z_{\hat{f}}$ to $\text{PW}_{(0,1)}$,

$$\Gamma_{f,(0,1)} \simeq P_{\text{PW}_{(0,1)}} Z_{\hat{f}}|_{\text{PW}_{(0,1)}},$$

where $P_{\text{PW}_{(0,1)}} : H_1^2 \rightarrow \text{PW}_{(0,1)}$ denotes the orthogonal projection onto $\text{PW}_{(0,1)}$. Such *truncated Toeplitz and Hankel operators* are now very well studied on general K_θ -spaces [6, 7, 9, 10, 14, 20, 27, 30, 36].

In the case of the cube $\Xi = (0, 1)^d \subset \mathbb{R}^d$, $d > 1$, the Hankel operator $\Gamma_{f,\Xi}$ may, just as for $d = 1$, be understood as the compression of a Hankel operator to a co-invariant subspace of H_d^2 . Namely,

$$\text{PW}_{(0,1)^d} = \{G \in H_d^2 : \text{supp } \hat{G} \subset [0, 1]^d\} = \{G \in H_d^2 : \text{supp } \hat{G} \subset \overline{\mathbb{R}_+^d} \setminus (0, 1)^d\}^\perp.$$

If $G \in H_d^2 \cap L^\infty(\mathbb{R}^d)$, it is clear that $G\text{PW}_{(0,1)^d}^\perp \subset \text{PW}_{(0,1)^d}^\perp$, since

$$\mathcal{F}(GH)(\xi) = \int_{\mathbb{R}_+^d} \hat{G}(y)\hat{H}(\xi - y) dy = 0, \quad H \in \text{PW}_{(0,1)^d}^\perp, \quad \xi \in [0, 1]^d.$$

Hence $\text{PW}_{(0,1)^d}^\perp \subset H_d^2$ is an invariant subspace (under multiplication by bounded holomorphic functions), and as before we have that

$$\Gamma_{f,(0,1)^d} \simeq P_{\text{PW}_{(0,1)^d}} Z_{\hat{f}}|_{\text{PW}_{(0,1)^d}},$$

where $P_{\text{PW}_{(0,1)^d}} : H_d^2 \rightarrow \text{PW}_{(0,1)^d}$ denotes the orthogonal projection onto $\text{PW}_{(0,1)^d}$.

Finally, let us briefly discuss the viewpoint of weak factorization. The Hardy space H_d^1 is defined as the closure of $\mathcal{F}^{-1}(C_c^\infty(\mathbb{R}_+^d))$ in $L^1(\mathbb{R}^d)$. Similarly, we define PW_Ξ^1 as the closure of $\mathcal{F}^{-1}(C_c^\infty(\Xi))$ in $L^1(\mathbb{R}^d)$. As is well known, see for example [24, Theorem 6.4], Theorem 2.1 is equivalent to the fact that H_d^1 is the projective tensor product of two

copies of H_d^2 ,

$$H_d^1 = H_d^2 \odot H_d^2, \tag{2.4}$$

with equivalence of norms. Here the projective tensor product norm on $X \odot X$, X a Banach space of functions, is given by

$$\|G\|_{X \odot X} = \inf \left\{ \sum_j \|G_j\|_X \|H_j\|_X : G = \sum_j G_j H_j, G_j, H_j \in X \right\},$$

$X \odot X$ being defined as the completion of finite sums $\sum_j G_j H_j$ in this norm.

The reason that Theorem 2.1 is equivalent to (2.4) is the following: by (2.1), $\Gamma_{f, \mathbb{R}_+^d}$ is bounded if and only if

$$|\langle \check{f}, GH \rangle_{H_d^2}| \leq C \|G\|_{H_d^2} \|H\|_{H_d^2},$$

which means precisely that \check{f} induces a bounded functional on $H_d^2 \odot H_d^2$, $\check{f} \in (H_d^2 \odot H_d^2)^*$. On the other hand, the existence of $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_{\mathbb{R}_+^d} = f|_{\mathbb{R}_+^d}$, so that $\langle \check{f}, GH \rangle_{H_d^2} = \langle b, GH \rangle_{H_d^2}$, $G, H \in H_d^2$, means, by the Hahn–Banach theorem, precisely that $\check{f} \in (H_d^1)^*$.

Theorem 1.1 yields a similar weak factorization theorem for Paley–Wiener spaces. We postpone the proof to Section 5, but mention now that corresponding weak factorization for K_θ spaces plays an important role in [6] and [9]. Corollary 5.3 might also be compared to the results in [37], where weak factorization for multivariate analytic polynomials is deduced as a consequence of Theorem 2.1.

Corollary 5.3. Let Ξ be a simple convex polytope, and let $\Omega = 2\Xi$. Then

$$PW_\Omega^1 = PW_\Xi \odot PW_\Xi.$$

The norms of these Banach spaces are equivalent.

2.6 Brief historical overview

Z. Nehari published his famous theorem in 1957 [25], inspiring the search for analogous statements in other contexts; positive results are themselves often referred to as Nehari theorems. The most natural inquiries are perhaps those related to Hankel operators on Hardy spaces of several variables. Nehari's theorem for the Hardy space of the unit ball was proven by Coifman, Rochberg, and Weiss in 1976 [15, Thm. VII], but this setting is rather different from the one considered in this paper.

For the product domain Hardy space H_d^2 , Hankel operators can be defined by either projecting on H_d^2 or on the larger space $L^2(\mathbb{R}^d) \ominus H_d^2$. The 1st option leads to the “small” Hankel operators considered in Section 2.1, while the 2nd type of operator is commonly referred to as a “big” Hankel operator. In the notation of Section 2.4, a small Hankel operator is an operator $\Psi_{f, \mathbb{R}_+^d, \mathbb{R}_+^d} = \Gamma_{f, \mathbb{R}_+^d}$, whereas big Hankel operators are of the form $\Psi_{f, \mathbb{R}_+^d, \mathbb{R}^d \setminus \overline{\mathbb{R}_+^d}}$. When transferred to operators on the Hardy space of the polydisc, small Hankel operators correspond, in the standard basis, to infinite matrices with a certain block Hankel structure (cf. Section 7).

The big Hankel operators were extensively studied by Cotlar and Sadosky. In particular, boundedness of the big Hankel operators was characterized in terms of certain BMO type estimates in [16]. Small Hankel operators were investigated by Janson and Peetre [22] in 1988. They introduced “generalized Hankel and Toeplitz operators” as particular cases of a more general class of pseudo-differential operators called paracommutators. In their terminology, an operator of the form $\Psi_{f, \Xi, \Upsilon}$ is a generalized Hankel operator if Ξ and Υ are open cones and $\overline{\Xi} \cap (-\overline{\Upsilon}) = \{0\}$, whereas it is called Toeplitz if $\Xi \cap (-\Upsilon) \neq \emptyset$. Hence the general domain Hankel operators $\Gamma_{f, \Xi}$ are generalized Hankel operators a lá Janson–Peetre whenever Ξ is a cone with mild restrictions, while $\Theta_{f, \Xi}$ is a generalized Toeplitz operator a lá Janson–Peetre for every open cone Ξ . In the Toeplitz case, a full boundedness characterization is given in [22, p. 482]. In the Hankel case, only sufficient conditions for boundedness and Schatten class membership are provided, in terms of BMO and Besov spaces, respectively.

As previously mentioned, R. Rochberg considered Hankel operators for bounded domains in 1987 [35], studying the case of a finite interval in one dimension. Furthermore, he posed as an open problem to understand the case when $\Xi \subset \mathbb{R}^2$ is a disc. In this latter setting, L. Peng [32] characterized when $\Gamma_{f, \Xi}$ belongs to the Schatten class S_p , for $1 \leq p \leq 2$, in terms of certain Besov spaces adapted to the disc. L. Peng also carried out a similar study [33] for the case of the multidimensional cube, $\Xi = (-1, 1)^d$, describing membership in S_p for all p , $0 < p < \infty$, as well as giving a sufficient condition for boundedness.

Since then it seems that the field did not see progress until the results of Ferguson–Lacey–Terwilliger [18, 23] settled the issue of boundedness of small Hankel operators.

3 Distribution symbols

Let $\Xi, \Upsilon \subset \mathbb{R}^d$ be any open connected sets and let $f \in \mathcal{D}'(\Omega)$ be a distribution on Ω , $\Omega = \Xi + \Upsilon$. We follow the notation of [21] in our use of distributions. We then define

the truncated correlation operator Ψ_f as an operator $\Psi_{f,\Upsilon,\Xi} : C_c^\infty(\Upsilon) \rightarrow C^\infty(\Xi)$ by the formula

$$\Psi_f(\varphi)(x) = (f, T_x\varphi), \quad x \in \Xi,$$

where (f, φ) denotes the action of f on φ and

$$T_x\varphi(\cdot) = \varphi(\cdot - x).$$

We reserve the notation $\langle f, \varphi \rangle$ for scalar products that are anti-linear in the 2nd entry.

Since $T_x\varphi$ is compactly supported in Ω for $x \in \Xi$, it follows that $\Psi_f(\varphi)$ this is well defined and smooth in Ξ (see, e.g., [21, Theorem 4.1.1]). Since $C_c^\infty(\Upsilon)$ is dense in $L^2(\Upsilon)$, Ψ_f gives rise to a densely defined operator on the latter space, which extends to a bounded operator $\Psi_f: L^2(\Upsilon) \rightarrow L^2(\Xi)$ if and only if

$$\|\Psi_f\| = \sup \left\{ \frac{\|\Psi_f(\varphi)\|_{L^2(\Xi)}}{\|\varphi\|_{L^2(\Upsilon)}} : \varphi \in C_c^\infty(\Upsilon), \varphi \neq 0 \right\} < \infty.$$

It is clear that $\Psi_f(\varphi)(x) = \int f(x + y)\varphi(y) dy$ whenever $f \in L^1_{loc}(\Omega)$. By slight abuse of notation, we write the action of Ψ_f in this way even when f is not locally integrable.

The central question in this paper is the following: *for which domains Υ and Ξ is the boundedness of Ψ_f equivalent to the existence of a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_\Omega = f$?* Some care must be taken in interpreting this question. For example, the prototypical example of a bounded Hankel operator is the Carleman operator

$$\Gamma_{1/x, \mathbb{R}_+} = \Psi_{1/x, \mathbb{R}_+, \mathbb{R}_+}.$$

The symbol $f(x) = \frac{1}{x}\chi_{\mathbb{R}_+}(x)$ is in this case not a tempered distribution on \mathbb{R} (so the meaning of \check{f} is unclear)—it is, however, the restriction of the tempered distribution p. v. $\frac{1}{x}$ to \mathbb{R}_+ . An example with a delta function makes it clear that it is not necessary for f to be locally integrable in Ω either.

We first record the answer to our question in the trivial direction.

Proposition 3.1. Consider any connected open domains $\Xi, \Upsilon \subset \mathbb{R}^d$, with associated domain $\Omega = \Upsilon + \Xi$. Let $b \in L^\infty(\mathbb{R}^d)$ be given and suppose $f = \hat{b}|_\Omega$. Then $\Psi_f: L^2(\Upsilon) \rightarrow L^2(\Xi)$ is bounded and

$$\|\Psi_f\| \leq \|b\|_{L^\infty}. \tag{3.1}$$

Proof. For $\varphi \in C_c^\infty(\Upsilon)$ we have that

$$\Psi_f(\varphi) = \mathcal{F}M_b J \mathcal{F}^{-1} \varphi|_{\Xi},$$

where M_b is the operator of multiplication by b . The statement is obvious from here. ■

Next we establish two technical results on the approximation of distribution symbols by smooth compactly supported functions, Propositions 3.2 and 3.3. They will help us to overcome the technical issues mentioned earlier, in particular allowing us to deduce Theorem 2.1 from the corresponding statements in [18, 23].

Given open connected domains $\Xi, \Upsilon \subset \mathbb{R}^d$, let $(\Upsilon_n)_{n=1}^\infty$ be an increasing sequence of connected open subdomains $\Upsilon_n \subset \Upsilon$ such that

$$\text{dist}(\Upsilon_n, \partial\Upsilon) > 1/n, \quad \bigcup_{n=1}^\infty \Upsilon_n = \Upsilon.$$

Note that $\Omega_n = \Upsilon_n + \Xi$ is also increasing and satisfies

$$\text{dist}(\Omega_n, \partial\Omega) > 1/n, \quad \bigcup_{n=1}^\infty \Omega_n = \Omega.$$

Let $\psi \in C_c^\infty(\mathbb{R}^d)$ be a fixed non-negative function with compact support in the ball $B(0, 1/2)$ such that $\int_{\mathbb{R}^d} \psi(x) dx = 1$. For $n \geq 1$ let

$$\psi_n(x) = n^d \psi(nx),$$

so that $(\psi_n)_{n=1}^\infty$ is an approximation of the identity. Since $f \in \mathcal{D}'(\Omega)$ and $\text{supp } \psi_n \subset B(0, 1/2n)$, the convolution $f * \psi_n$ is well defined as a function in $C^\infty(\Omega_{2n})$. Let ρ_n be a smooth cut-off function that is 1 in a neighborhood of $\overline{\Omega_n}$ but zero in a neighborhood of Ω_{2n}^c , and note that $\rho_n(f * \psi_n)$ then naturally defines a function in $C^\infty(\mathbb{R}^n)$. Finally, for a non-negative function $\eta \in C_c^\infty(\mathbb{R}^d)$ with $\|\eta\|_{L^2} = 1$, let $\omega = \eta * \tilde{\eta}$, where $\tilde{\eta}(x) = \eta(-x)$. Then $\omega \in C_c^\infty(\mathbb{R}^d)$ and

$$\omega(0) = \|\hat{\omega}\|_{L^1} = 1.$$

Let $\omega_n(x) = \omega(x/n)$. We introduce

$$f_n = \omega_n \rho_n(f * \psi_n)$$

as an approximant of f , where the role of ω_n is to enforce compact support in case Ω is unbounded. By construction, $f_n \in C_c^\infty(\Omega)$ and it is straightforward to check that $f_n \rightarrow f$ in $\mathcal{D}'(\Omega)$. As for $\Psi_{f_n, \Upsilon_n, \Xi}$, we have the following result.

Proposition 3.2. Let Ξ, Υ be connected open domains, $\Omega = \Upsilon + \Xi$, and suppose $f \in \mathcal{D}'(\Omega)$. For $n \geq 1$, let $\Omega_n = \Upsilon_n + \Xi$ and f_n be constructed as above. Then

$$\|\Psi_{f_n, \Upsilon_n, \Xi}\| \leq \|\Psi_{f, \Upsilon, \Xi}\|.$$

Proof. We can assume that $\|\Psi_{f, \Upsilon, \Xi}\| < \infty$, since otherwise there is nothing to prove. First note that

$$\omega_n(x) = \int_{\mathbb{R}^d} n^d \hat{\omega}(n\xi) e^{2\pi i x \cdot \xi} \, d\xi,$$

the integrand on the right having L^1 -norm equal to $\|\hat{\omega}\|_{L^1(\mathbb{R}^d)}$. Letting $g_n = \rho_n(f * \psi_n)$, we have for $\varphi \in C_c^\infty(\Upsilon_n)$ and $x \in \Xi$ that

$$\Psi_{f_n}(\varphi)(x) = \int_{\Upsilon_n} \int_{\mathbb{R}^d} n^d \hat{\omega}(n\xi) e^{2\pi i(x+Y) \cdot \xi} \, d\xi g_n(x+Y) \varphi(Y) \, dY = \int_{\mathbb{R}^d} n^d \hat{\omega}(n\xi) e^{2\pi i\xi \cdot x} \Psi_{g_n}(\varphi_\xi)(x) \, d\xi,$$

where $\varphi_\xi(Y) = e^{2\pi i Y \cdot \xi} \varphi(Y)$. Since $\|\varphi_\xi\|_{L^2} = \|\varphi\|_{L^2}$ it follows by the triangle inequality (for L^2 -valued Bochner integrals) that

$$\|\Psi_{f_n, \Upsilon_n, \Xi}\| \leq \|\hat{\omega}\|_{L^1} \|\Psi_{g_n, \Upsilon_n, \Xi}\| = \|\Psi_{g_n, \Upsilon_n, \Xi}\|.$$

This reduces our task to proving that the operators

$$\Psi_{g_n, \Upsilon_n, \Xi} = \Psi_{\rho_n(f * \psi_n), \Upsilon_n, \Xi} = \Psi_{f * \psi_n, \Upsilon_n, \Xi}$$

are uniformly bounded in n . We have for $\varphi \in C_c^\infty(\Upsilon_n)$ and $x \in \Xi$ that

$$\begin{aligned} \Psi_{f * \psi_n}(\varphi)(x) &= \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} f((x+Y)-z) \psi_n(z) \, dz \varphi(Y) \, dY \\ &= \int_{\mathbb{R}^d} f(x+z) \int_{\mathbb{R}^d} \psi_n(Y-z) \varphi(Y) \, dY \, dz = \Psi_f(\tilde{\psi}_n * \varphi)(x), \end{aligned}$$

where $\tilde{\psi}_n(x) = \psi_n(-x)$. Since

$$\|\tilde{\psi}_n * \varphi\|_{L^2(\Upsilon)} \leq \|\psi_n\|_{L^1} \|\varphi\|_{L^2(\Upsilon_n)} = \|\psi\|_{L^1} \|\varphi\|_{L^2(\Upsilon_n)} = \|\varphi\|_{L^2(\Upsilon_n)},$$

this completes the proof. ■

Proof of Theorem 2.1. Suppose that $\Gamma_{f, \mathbb{R}_+^d} = \Psi_{f, \Xi, \Upsilon}$ is bounded, where $\Xi = \Upsilon = \mathbb{R}_+^d$. In this case, we let $\Upsilon_n = (2/n, \infty)^d$. By Proposition 3.2 we then have that

$$\|\Gamma_{f_n, \Upsilon_n}\| \leq \|\Psi_{f_n, \Upsilon_n, \Xi}\| \leq \|\Gamma_{f, \mathbb{R}_+^d}\|, \quad n \geq 1.$$

Since $\Upsilon_n = z_n + \mathbb{R}_+^d$, $z_n = (2/n, \dots, 2/n)$, we have that

$$\Gamma_{f_n, \Upsilon_n}(g)(x) = \Gamma_{\tilde{f}_n, \mathbb{R}_+^d}(\tilde{g})(x - z_n),$$

where $\tilde{f}_n(x) = f_n(x + 2z_n)$ and $\tilde{g}_n(x) = g(x + z_n)$. Since $\tilde{f}_n \in L^2(\mathbb{R}_+^d)$, the computation that led to (2.1) is justified, and we conclude from [18, 23] that there is $b_n \in L^\infty(\mathbb{R}^d)$ such that

$$\hat{b}_n|_{2\Upsilon_n} = f_n|_{2\Upsilon_n}, \quad \|b_n\|_{L^\infty} \leq C\|\Gamma_{f, \mathbb{R}_+^d}\|.$$

By Alaoglu's theorem it follows that there is a weak-star convergent subsequence $(b_{n_k})_{k=1}^\infty$ with limit $b \in L^\infty$ having norm less than $C\|\Gamma_{f, \mathbb{R}_+^d}\|$. It remains to prove that $f = \hat{b}|_{\mathbb{R}_+^d}$, that is, $(f, \varphi) = (b, \hat{\varphi})$ holds for all $\varphi \in C_c^\infty(\mathbb{R}_+^d)$. However, this is clear from the construction; since $\hat{\varphi} \in L^1$ we have that

$$(b, \hat{\varphi}) = \lim_{k \rightarrow \infty} (b_{n_k}, \hat{\varphi}) = \lim_{k \rightarrow \infty} (f_{n_k}, \varphi) = (f, \varphi). \quad \blacksquare$$

In Section 6 we will consider Toeplitz operators $\Theta_{f, \Xi}$ for which $\Omega = \Upsilon - \Xi = \mathbb{R}^d$. In this case $f * \psi_n$ is a smooth function defined in all of \mathbb{R}^d , and there is no need to multiply with ρ_n or to introduce the subdomains Υ_n . In this case we simply let

$$f_n = \omega_n(f * \psi_n).$$

Clearly, $f_n \rightarrow f$ in $\mathcal{D}'(\mathbb{R}^d)$ and we have, with the exact same proof as for Proposition 3.2, the following approximation result.

Proposition 3.3. Let Ξ, Υ be connected open domains for which $\Omega = \Upsilon + \Xi = \mathbb{R}^d$, and suppose $f \in \mathcal{D}'(\mathbb{R}^d)$. For $n \geq 1$, let f_n be constructed as above. Then

$$\|\Psi_{f_n, \Upsilon, \Xi}\| \leq \|\Psi_{f, \Upsilon, \Xi}\|.$$

4 On convex sets and polytopes

We recall some basic properties of convex sets. Given an unbounded convex set $\Omega \subset \mathbb{R}^d$ which is either open or closed, its characteristic cone, also known as its recession cone, is the closed set

$$\text{cc}_\Omega = \{x \in \mathbb{R}^d : \Omega + x\mathbb{R}_+ \subset \Omega\}.$$

The support function $h_\Omega : \mathbb{R}^d \rightarrow (-\infty, \infty]$ is defined by

$$h_\Omega(\theta) = \sup_{x \in \Omega} x \cdot \theta.$$

We refer to [21, Sec. 7.4] for the basic properties of h_Ω . The barrier cone of Ω is the set

$$\text{bc}_\Omega = \{\theta \in \mathbb{R}^d : h_\Omega(\theta) < \infty\}. \quad (4.1)$$

The characteristic cone cc_Ω coincides with the polar cone of the barrier cone bc_Ω , that is,

$$\text{cc}_\Omega = \{x \in \mathbb{R}^d : x \cdot y \leq 0, \forall y \in \text{bc}_\Omega\}.$$

To give a complete reference for this claim, first note that for closed convex sets Ω , cc_Ω coincides with the asymptotic cone of Ω , giving (4.1) by [4, Theorem 2.2.1]. When Ω instead is open and convex we have that Ω is equal to its *relative interior* $\text{ri}(\Omega)$, and since $\text{cc}_{\text{ri}(\Omega)} = \text{cc}_{\overline{\Omega}}$ [8, Proposition 1.4.2], it follows that $\text{cc}_\Omega = \text{cc}_{\overline{\Omega}}$ in this case.

We next recall some standard terminology and facts of polytopes, referring to for example [12, Ch. 7–9]. By an open half-space in \mathbb{R}^d we mean a set

$$H_\nu^r = \{x \in \mathbb{R}^d : x \cdot \nu > r\},$$

where $\nu \in \mathbb{R}^d$ is a non-zero vector and $r \in \mathbb{R}$. A closed half-space is the closure of such a set. A finite intersection of half-spaces is called a polyhedral set.

A convex polytope is a bounded polyhedral set. A closed convex polytope is the convex hull of a finite set of points. The minimal set of such points coincides with the extreme points of the polytope, that is, its vertices. If the minimal number of defining hyperspaces of a convex polytope is $d + 1$ (equivalently, if it has precisely $d + 1$ vertices), the polytope is called a simplex. For a non-closed polytope we define its vertices (and its edges and facets) as those of its closure.

The boundary of a polytope set is made up of a finite amount of facets (i.e. $d - 1$ dimensional faces), see Corollary 7.4 and Theorem 8.1 of [12]. For a polytope Π with vertex x_j , we denote by $\partial_{\text{far}, x_j} \Pi$ the part of its boundary made up of all facets not containing x_j .

A vertex of a polytope will be called simple if it is contained in precisely d of its edges. We say that a polytope is simple if all of its vertices are simple, which coincides with the standard terminology. Equivalently, this means that each vertex is contained in precisely d of its facets (cf. [12, Theorem 12.11]).

By an affine linear transformation we mean a map of the form $A(x) = x_0 + L(x)$ where L is a linear map, and we call x_0 the origin of such a map. The following simple lemma gives a 3rd characterization of simple vertices.

Lemma 4.1. Let $\{x_j\}_{j=1}^J$ be the vertices of a closed polytope Π . Then the vertex x_j is simple if and only if it is the origin of an invertible affine transformation A_j such that Π locally coincides with $A_j(\overline{\mathbb{R}_+^d})$ around x_j , in the sense that $A_j^{-1}(\Pi) \subset \overline{\mathbb{R}_+^d}$ and the facets of $A_j^{-1}(\Pi)$ containing 0 are precisely those of the form

$$A^{-1}(\Pi) \cap \{x \in \mathbb{R}^d : x \cdot e_k = 0\}, \quad 1 \leq k \leq d,$$

where $\{e_k\}_{k=1}^d$ denotes the standard basis of \mathbb{R}^d .

Proof. We may assume that $x_1 = 0$ is simple and that x_2, x_3, \dots, x_{d+1} are the other endpoints of the edges containing 0. Let $A: \mathbb{R}^d \rightarrow \mathbb{R}^d$ be the linear map such that $A(e_k) = x_{k+1}$, $1 \leq k \leq d$. A is invertible [12, Corollary 11.7], so that $A^{-1}(\Pi)$ is a closed convex polytope contained in $\overline{\mathbb{R}_+^d}$. Since 0 is a vertex of $A^{-1}(\Pi)$ with adjacent vertices e_1, \dots, e_d , the d facets containing 0 must be precisely those of the form $A^{-1}(\Pi) \cap \{x \in \mathbb{R}^d : x \cdot e_k = 0\}$.

For the converse, simply note that the property of being a simple vertex is preserved under affine isomorphisms. ■

By compactness it is easy to construct a partition of unity adapted to the vertices of Π .

Lemma 4.2. Given a polytope Π with vertices $\{x_j\}_{j=1}^J$ there exist functions $\{\mu_j\}_{j=1}^J$ such that $\mu_j \in C_c^\infty(\mathbb{R}^d)$, $\sum_{j=1}^J \mu_j(x) = 1$ for $x \in \overline{\Pi}$, and $\text{supp} \mu_j \cap \partial_{\text{far}, x_j} \Pi = \emptyset$.

Proof. For $\varepsilon > 0$ and $1 \leq j \leq J$, let

$$V_j^\varepsilon = \{x \in \mathbb{R}^d \mid \text{dist}(x, \partial_{\text{far}, x_j} \Pi) > \varepsilon \text{ and } \text{dist}(x, \overline{\Pi}) < 1\}.$$

Since every $x \in \overline{\Pi}$ is contained in some set V_j^ε , there is by compactness a fixed $\varepsilon_0 > 0$ such that $\overline{\Pi} \subset \bigcup_{j=1}^J V_j^{\varepsilon_0}$. Let $V_{J+1} = \mathbb{R}^d \setminus \overline{\Pi}$ and choose a smooth partition of unity $\{\mu_j\}_{j=1}^{J+1}$ of \mathbb{R}^d subordinate to $V_1^{\varepsilon_0}, \dots, V_J^{\varepsilon_0}, V_{J+1}$. Then $\{\mu_j\}_{j=1}^J$ is the required partition of unity. ■

5 General domain Hankel operators

We now consider general domain Hankel operators $\Gamma_{f,\Xi}$ for convex domains Ξ . Observe that in this case $\Omega = \Xi + \Xi = 2\Xi$. We begin with a proposition that links the bounded Hankel operators with weak factorization.

Proposition 5.1. Let Ξ be an open convex domain. Then

$$X = \left\{ \Gamma_{f,\Xi} : \|\Gamma_{f,\Xi}\| < \infty \right\}$$

is a closed subspace of the space of bounded linear operators on $L^2(\Xi)$. As a Banach space, it is isometrically isomorphic to the dual space $(PW_\Xi \odot PW_\Xi)^*$. More precisely, bounded functionals μ on the projective tensor product correspond to distributions f on $\Omega = 2\Xi$,

$$(f, g) = \mu(\mathcal{F}^{-1}g), \quad g \in C_c^\infty(\Omega),$$

for which $\|\Gamma_{f,\Xi}\| = \|\mu\|$.

Proof. The main fact to be proved is that

$$\mathcal{F}^{-1}(C_c^\infty(\Omega)) \subset PW_\Xi \odot PW_\Xi.$$

Since $C_c^\infty(\Xi)$ is dense in $L^2(\Xi)$, it then follows that $\mathcal{F}^{-1}(C_c^\infty(\Omega))$ is dense in the product $PW_\Xi \odot PW_\Xi$.

We will actually show a little more than the claim. Namely, every $g \in C_c^\infty(\Omega)$ can be written

$$g = \sum_k s_k * t_k, \quad s_k, t_k \in L^2(\Xi),$$

in such a way that the corresponding map $g \mapsto \sum_k \|s_k\|_{L^2(\Xi)} \|t_k\|_{L^2(\Xi)}$ is continuous from $C_c^\infty(\Omega)$, equipped with the usual test function topology, to \mathbb{R} . By employing a partition of unity in which each member is compactly supported in a cube, it is sufficient to prove the claim when $\Xi = (0, 1/2)^d$. For this we employ Fourier series. Let $\lambda(t) = 1/2 - |t - 1/2|$, $t \in [0, 1]$, and let

$$\Lambda(x) = \prod_{i=1}^d \lambda(x_i), \quad x \in (0, 1)^d.$$

Note that λ is in the Wiener algebra $A([0, 1])$, the space of functions on $[0, 1]$ with absolutely convergent Fourier series, equipped with pointwise multiplication. Therefore

Λ is in the Wiener algebra $A([0, 1]^d)$, since Λ is a tensor power of λ . Since $g \in C_c^\infty((0, 1)^d)$ and Λ is non-zero on compact subsets of $(0, 1)^d$ it follows by Wiener's lemma [19, Ch. 5] that $g/\Lambda \in A([0, 1]^d)$. Expanding g/Λ in a Fourier series,

$$(g/\Lambda)(x) = \sum_{k \in \mathbb{Z}^d} a_k e^{i2\pi k \cdot x}, \quad \sum_{k \in \mathbb{Z}^d} |a_k| < \infty, \quad x \in [0, 1]^d,$$

let $t_k(x) = e^{i2\pi k \cdot x} \chi_{(0, 1/2)^d}(x)$, $s_k = a_k t_k$. Then a computation shows that

$$(s_k * t_k)(x) = a_k e^{i2\pi k \cdot x} \Lambda(x), \quad x \in (0, 1)^d,$$

so that

$$g = \sum_{k \in \mathbb{Z}^d} s_k * t_k, \quad \sum_{k \in \mathbb{Z}^d} \|s_k\|_{L^2((0, 1/2)^d)} \|t_k\|_{L^2((0, 1/2)^d)} < \infty.$$

An inspection of the argument shows that the operation $g \mapsto g/\Lambda$ is continuous from $C_c^\infty((0, 1)^d)$ to $A([0, 1]^d)$, and therefore $g \mapsto \sum_k \|s_k\|_{L^2((0, 1/2)^d)} \|t_k\|_{L^2((0, 1/2)^d)}$ is continuous on $C_c^\infty((0, 1)^d)$ as promised.

Suppose now that $\mu \in (\text{PW}_\Xi \odot \text{PW}_\Xi)^*$. We have just demonstrated that $(f, g) = \mu(\mathcal{F}^{-1}g)$, $g \in C_c^\infty(\Omega)$, defines a distribution on Ω . Hence we may consider the Hankel operator $\Gamma_{f, \Xi}$. For $g, h \in C_c^\infty(\Xi)$ we have that

$$\langle \Gamma_{f, \Xi} g, h \rangle_{L^2(\Xi)} = (f, g * \bar{h}) = \mu(\mathcal{F}^{-1}g \cdot \mathcal{F}^{-1}\bar{h}). \quad (5.1)$$

Since μ is a bounded functional on $\text{PW}_\Xi \odot \text{PW}_\Xi$ we conclude that

$$|\langle \Gamma_{f, \Xi} g, h \rangle_{L^2(\Xi)}| \leq \|\mu\| \|\mathcal{F}^{-1}g\|_{\text{PW}_\Xi} \|\mathcal{F}^{-1}\bar{h}\|_{\text{PW}_\Xi} = \|\mu\| \|g\|_{L^2(\Xi)} \|h\|_{L^2(\Xi)},$$

that is, $\Gamma_{f, \Xi}$ is bounded, and in fact $\|\Gamma_{f, \Xi}\| = \|\mu\|$. Conversely, if f is a distribution on Ω such that $\Gamma_{f, \Xi}$ is bounded, it is clear that f induces a bounded functional μ on $\text{PW}_\Xi \odot \text{PW}_\Xi$ by (5.1). This proves that X is isometrically isomorphic to the Banach space $(\text{PW}_\Xi \odot \text{PW}_\Xi)^*$, which also entails that X is closed, completing the proof. ■

In the remainder of this section we assume that Ξ is a convex polytope. Next we prove Theorem 1.1 under the additional assumption that f is supported around one simple vertex of Ω .

Proposition 5.2. Let $\Xi \subset \mathbb{R}^d$ be an open convex polytope, x a simple vertex of $\Omega = 2\Xi$, and let $f \in \mathcal{D}'(\Omega)$ be such that $\text{supp } f \cap \partial_{\text{far},x}\Omega = \emptyset$. If Γ_f is bounded as an operator on $L^2(\Xi)$, then there exists a $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_\Omega = f$.

Proof. As in Lemma 4.1, let A be an affine transformation with origin x such that $A(\mathbb{R}_+^d)$ locally coincides with Ξ around x . It is straightforward to verify that it suffices to prove the proposition for $\Gamma_{f \circ A, A^{-1}(\Xi)}$. Since $A^{-1}(\Xi)$ is also a convex polytope, we may hence assume that $x = 0$ and that Ω locally coincides with \mathbb{R}_+^d around 0. In particular, $\Omega \subset \mathbb{R}_+^d$. Since $\text{supp } f \subset \overline{\Omega}$ and $\text{supp } f \cap \partial_{\text{far},0}\Omega = \emptyset$, we can extend f to a distribution on all of \mathbb{R}_+^d by letting it be zero outside Ω . Our strategy is to show that the operator $\Gamma_{f, \mathbb{R}_+^d}$ is bounded and to then apply Theorem 2.1.

For $n \in \mathbb{N}^d$ let C_n denote the cube $(n_1, n_1 + 1) \times \dots \times (n_d, n_d + 1)$. For a set $X \subset \mathbb{R}_+^d$, let $P_X : L^2(\mathbb{R}_+^d) \rightarrow L^2(\mathbb{R}_+^d)$ denote the orthogonal projection of $L^2(\mathbb{R}_+^d)$ onto $L^2(X)$, and let $r > 0$ be such that

$$2\sqrt{dr} < \text{dist}(\text{supp } f, \partial_{\text{far},0}\Omega).$$

By considering test functions $g \in C_c^\infty(\mathbb{R}_+^d)$ such that $\text{supp } g \cap \overline{rC_m} \subset rC_m$ for every m , we give meaning to the equality

$$\Gamma_{f, \mathbb{R}_+^d} = \left(\sum_{n \in \mathbb{N}^d} P_{rC_n} \right) \Gamma_{f, \mathbb{R}_+^d} \left(\sum_{m \in \mathbb{N}^d} P_{rC_m} \right) = \sum_{m, n \in \mathbb{N}^d} P_{rC_n} \Gamma_{f, \mathbb{R}_+^d} P_{rC_m},$$

a term $P_{rC_n} \Gamma_{f, \mathbb{R}_+^d} P_{rC_m}$ being non-zero only if

$$(rC_m + rC_n) \cap \text{supp } f \neq \emptyset. \tag{5.2}$$

Hence there are only finitely many non-zero terms in the decomposition. Since

$$\|P_{rC_n} \Gamma_{f, \mathbb{R}_+^d} P_{rC_m}\| = \|\Psi_{f, rC_m, rC_n}\|,$$

recalling the definition of Ψ_f from Section 2, it therefore suffices to prove that $\|\Psi_{f, rC_m, rC_n}\|$ is bounded whenever (5.2) holds. If $rC_m, rC_n \subset \Xi$ there is nothing to prove since $\Gamma_{f, \Xi}$ is bounded by hypothesis. For the other terms, note that (5.2) and the choice of r implies that

$$rC_m + rC_n \subset \Omega, \tag{5.3}$$

since $2\sqrt{d}r$ is the diameter of $rC_m + rC_n$. For any $z \in \mathbb{R}^d$, $x \in rC_n$, and $g \in C_c^\infty(rC_m)$ we have that

$$\Psi_{f,rC_m,rC_n}(g)(x) = \int_{rC_m} f(x+y)g(y) \, dy = \int_{rC_m+z} f(x+(y-z))g(y-z) \, dy,$$

and hence

$$\|\Psi_{f,rC_m,rC_n}\| = \|\Psi_{f,rC_m+z,rC_n-z}\|.$$

In particular, for $z = r(n-m)/2$ we obtain that

$$\|\Psi_{f,rC_m,rC_n}\| = \|\Psi_{f,rC_{\frac{m+n}{2}},rC_{\frac{m+n}{2}}}\|.$$

However, $2rC_{\frac{m+n}{2}} = rC_m + rC_n$ so by (5.3) we conclude that $rC_{\frac{m+n}{2}} \subset \Xi$. The desired boundedness now follows as it did in the first case considered.

We have just demonstrated that $\|\Gamma_{f,\mathbb{R}_+^d}\| < \infty$. By Theorem 2.1 there exists a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_{\mathbb{R}_+^d} = f$. This in particular implies that $\hat{b}|_\Omega = f$ when we return to the initial interpretation of f as a distribution on Ω . ■

We are now ready to provide the proof of Theorem 1.1.

Theorem 1.1. Let Ξ be a simple convex polytope, and let $f \in \mathcal{D}'(\Omega)$, $\Omega = 2\Xi$. Then $\Gamma_f: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded if and only if there is a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_\Omega = f$. There exists a constant $c > 0$, depending on Ξ , such that b can be chosen to satisfy

$$c\|b\|_{L^\infty} \leq \|\Gamma_f\| \leq \|b\|_{L^\infty}.$$

Proof. Assume that Γ_f is bounded. Let $\{x_j\}_{j=1}^J$ be the vertices of Ω , and let $\{\mu_j\}_{j=1}^J$ be partition of unity as in Lemma 4.2. For $\varphi \in C_c^\infty(\Xi)$ and $x \in \Xi$ we have that

$$\Gamma_{\mu_j f}(\varphi)(x) = \int_{\Xi} \int_{\mathbb{R}^d} \hat{\mu}_j(\xi) e^{2\pi i(x+y)\cdot\xi} \, d\xi f(x+y)\varphi(y) \, dy = \int_{\mathbb{R}^d} \hat{\mu}_j(\xi) e^{2\pi i\xi\cdot x} \Gamma_f(\varphi_\xi)(x) \, d\xi,$$

where $\varphi_\xi(y) = e^{2\pi iy\cdot\xi}\varphi(y)$. Hence, $\Gamma_{\mu_j f}: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded,

$$\|\Gamma_{\mu_j f}\| \leq \|\hat{\mu}_j\|_{L^1} \|\Gamma_f\|.$$

Therefore, by Proposition 5.2 there are functions $b_j \in L^\infty$ such that $\mu_j f = \hat{b}_j|_\Omega$. Thus $f = \hat{b}|_\Omega$, where $b = \sum_{j=1}^J b_j \in L^\infty$. Conversely, if $f = \hat{b}|_\Omega$, where $b \in L^\infty$, then Γ_f is bounded by Proposition 3.1.

The constant c now arises from abstract reasoning. Consider the Banach space

$$X = \left\{ \Gamma_{f, \Xi} : \|\Gamma_{f, \Xi}\| < \infty \right\}$$

of Proposition 5.1. We have just shown that $b \mapsto \Gamma_{\hat{b}|_\Omega, \Xi}$ is a map of L^∞ onto X . The open mapping theorem hence guarantees the existence of c . ■

We immediately obtain the corresponding result for Toeplitz operators, when Ξ is a simple convex polytope, which, possibly after a translation, is symmetric under $x \mapsto -x$.

Corollary 1.2. Let Ξ be a simple convex polytope such that for some $z \in \mathbb{R}^d$ it holds that $\Xi + z = -\Xi - z$. Let $f \in \mathcal{D}'(\Omega)$, $\Omega = \Xi - \Xi = 2\Xi + 2z$. Then Θ_f is bounded if and only if there exists a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_\Omega = f$. There exists a constant $c > 0$, depending on Ξ , such that b can be chosen to satisfy

$$c\|b\|_{L^\infty} \leq \|\Theta_f\| \leq \|b\|_{L^\infty}.$$

Proof. In this case $\Theta_f g = \Gamma_{\tilde{f}} \tilde{g}$, where $\tilde{f}(x) = f(x + 2z)$, $x \in 2\Xi$, and $\tilde{g}(x) = g(-x - 2z)$, $x \in \Xi$. Hence the result follows from Theorem 1.1. ■

We also deduce the weak factorization result for PW_Ω^1 , see Section 2.5.

Corollary 5.3. Let Ξ be a simple convex polytope, and let $\Omega = 2\Xi$. Then

$$PW_\Omega^1 = PW_\Xi \odot PW_\Xi.$$

The norms of these Banach spaces are equivalent.

Proof. By Cauchy–Schwarz, the inclusion $I: PW_\Xi \odot PW_\Xi \rightarrow PW_\Omega^1$ is bounded. Since I has dense range by Proposition 5.1, the adjoint $I^*: (PW_\Omega^1)^* \rightarrow (PW_\Xi \odot PW_\Xi)^*$ has empty kernel. Suppose $\mu \in (PW_\Xi \odot PW_\Xi)^*$. Note that $CG(x) = \overline{G(-x)}$ defines an anti-linear isometric involution $C: PW_\Xi \odot PW_\Xi \rightarrow PW_\Xi \odot PW_\Xi$. This induces an anti-linear isometric

involution $D: (\text{PW}_\Xi \odot \text{PW}_\Xi)^* \rightarrow (\text{PW}_\Xi \odot \text{PW}_\Xi)^*$,

$$D\mu(G) = \overline{\mu(CG)}, \quad G \in \text{PW}_\Xi \odot \text{PW}_\Xi.$$

According to Proposition 5.1, $(f, g) = \mu(\mathcal{F}^{-1}g)$, $g \in C_c^\infty(\Omega)$, defines a distribution on Ω such that $\|\Gamma_{f, \Xi}\| = \|\mu\|$. By Theorem 1.1, there is a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_\Omega = f$. Since $\text{PW}_\Omega^1 \subset L^1(\mathbb{R}^d)$, we can interpret b as an element of $(\text{PW}_\Omega^1)^*$, $b(G) = \langle G, b \rangle_{L^2(\mathbb{R}^d)}$. Then, recalling that $JG(x) = G(-x)$, we have that

$$DI^*b(G) = (b, JG) = (f, \mathcal{F}^{-1}JG) = (f, \mathcal{F}G) = \mu(G), \quad G \in \mathcal{F}^{-1}(C_c^\infty(\Omega)),$$

that is, $DI^*b = \mu$, or $I^*b = D\mu$. Since D is an involution, it follows that I^* is onto.

In other words, $I^*: (\text{PW}_\Omega^1)^* \rightarrow (\text{PW}_\Xi \odot \text{PW}_\Xi)^*$ is a Banach space isomorphism, and therefore the inclusion $I: \text{PW}_\Xi \odot \text{PW}_\Xi \rightarrow \text{PW}_\Omega^1$ is as well. Hence,

$$\text{PW}_\Xi \odot \text{PW}_\Xi = \text{PW}_\Omega^1,$$

and the norms of these two Banach spaces are equivalent, by the open mapping theorem. ■

The method used to prove Theorem 1.1 extends to many unbounded polyhedral sets. Instead of pursuing a general statement, let us consider the example of a strip in \mathbb{R}^2 ,

$$\Xi = \mathbb{R}_+ \times (0, 1). \tag{5.4}$$

This is an interesting addition to Theorem 1.1, since Ξ does not have a simple vertex at infinity. In fact, $\partial\Xi$ may be considered to have a cusp point there.

Proposition 5.4. Let Ξ be the strip defined in (5.4), and let $f \in \mathcal{D}'(\Omega)$, $\Omega = 2\Xi$. Then $\Gamma_f: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded if and only if there is a function $b \in L^\infty(\mathbb{R}^d)$ such that $\hat{b}|_\Omega = f$.

Proof sketch. Let $v_1, v_2 \in C_c^\infty(\mathbb{R})$ be functions such that $v_1(t) + v_2(t) = 1$ for $t \in [0, 2]$, v_1 vanishes in a neighborhood of 2, and v_2 vanishes in a neighborhood of 0. Let

$$\mu_j(x) = v_j(x_2), \quad j = 1, 2, \quad x = (x_1, x_2) \in \Omega.$$

Then for $\varphi \in C_c^\infty(\Xi)$ and $x = (x_1, x_2) \in \Xi$ we have that

$$\Gamma_{\mu_j f}(\varphi)(x) = \int_{\Xi} \int_{\mathbb{R}} \hat{v}_j(\xi) e^{2\pi i(x_2 + Y_2)\xi} d\xi f(x + Y)\varphi(Y) dY = \int_{\mathbb{R}} \hat{v}_j(\xi) e^{2\pi i x_2 \xi} \Gamma_f(\varphi_\xi)(x) d\xi,$$

where $\varphi_\xi(y) = e^{2\pi i Y_2 \xi} \varphi(y)$, $y = (y_1, y_2) \in \Xi$. Hence, as before we see that

$$\|\Gamma_{\mu_j f, \Xi}\| \leq \|\hat{v}_j\|_{L^1} \|\Gamma_f, \Xi\|, \quad j = 1, 2. \tag{5.5}$$

As in Proposition 5.2 and Theorem 1.1 it is sufficient to see that $\Gamma_{\mu_1 f}: L^2(\mathbb{R}_+^2) \rightarrow L^2(\mathbb{R}_+^2)$ and $\Gamma_{\mu_2 f}: L^2(\mathbb{R}_+ \times (-\infty, 1)) \rightarrow L^2(\mathbb{R}_+ \times (-\infty, 1))$ define bounded operators, and by symmetry it is sufficient to consider the first of the two.

For $n \in \mathbb{N}$, let S_n denote the strip $\mathbb{R}_+ \times (n, n + 1)$, and let $r > 0$ be such that

$$2r < \text{dist}([0, 2] \cap \text{supp } v_1, 2).$$

We decompose $\Gamma_{\mu_1 f}: L^2(\mathbb{R}_+^2) \rightarrow L^2(\mathbb{R}_+^2)$ according to strips instead of cubes,

$$\Gamma_{\mu_1 f, \mathbb{R}_+^2} = \sum_{m, n \in \mathbb{N}} P_{rS_n} \Gamma_{\mu_1 f, \mathbb{R}_+^2} P_{rS_m}.$$

There are only a finite number of non-zero terms in this decomposition, and for any such term we have by our choice of r that

$$rS_m + rS_n \subset \Omega. \tag{5.6}$$

For n, m corresponding to a non-zero term, we have that

$$\|P_{rS_n} \Gamma_{\mu_1 f, \mathbb{R}_+^2} P_{rS_m}\| = \|\Psi_{\mu_1 f, rS_m, rS_n}\| = \|\Psi_{\mu_1 f, rS_m + z, rS_n - z}\| = \|\Psi_{\mu_1 f, rS_{\frac{m+n}{2}}, rS_{\frac{m+n}{2}}}\|,$$

where $z = (0, r(n - m)/2)$. Since $rS_{\frac{m+n}{2}} \subset \Xi$ by (5.6) and $\Gamma_{\mu_1 f}: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded by (5.5), we conclude that each non-zero term $P_{rS_n} \Gamma_{\mu_1 f, \mathbb{R}_+^2} P_{rS_m}$ is bounded. Hence $\Gamma_{\mu_1 f}: L^2(\mathbb{R}_+^2) \rightarrow L^2(\mathbb{R}_+^2)$ is bounded, finishing the proof. ■

6 General domain Toeplitz operators

In this section we consider general domain Toeplitz operators on open convex domains $\tilde{\Xi} \subset \mathbb{R}^d$ such that both $\text{cc}_{\tilde{\Xi}}$ and $\text{bc}_{\tilde{\Xi}}$ have non-empty interior (as in the classical case $\tilde{\Xi} = \mathbb{R}_+$). This forces $\tilde{\Xi}$ to be unbounded and, as we shall soon see, it also entails that

$\tilde{\Omega} = \tilde{\Xi} - \tilde{\Xi} = \mathbb{R}^d$. We shall also consider more general open connected sets Ξ such that there are points x_0 and x_1 for which

$$x_1 + \tilde{\Xi} \subset \Xi \subset x_0 + \tilde{\Xi}, \quad (6.1)$$

and prove that $\|\Theta_{f,\Xi}\| = \|\hat{f}\|_{L^\infty}$ under this hypothesis. This allows for domains Ξ with very irregular boundaries, in sharp contrast to Theorem 1.1. The corresponding class of operators $\Theta_{f,\Xi}$ partially extends the class of generalized Toeplitz operators considered in [22], see Section 2.6. The next theorem can also be recovered by verifying the hypotheses of and keeping track of the constants in the proof of [22, Theorem 5.4]. However, for completeness we prefer to give our own concrete proof.

Theorem 6.1. Let Ξ be a set as above. Then $\Xi - \Xi = \mathbb{R}^d$ and, for $f \in \mathcal{D}'(\mathbb{R}^d)$, we have that $\Theta_f: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded if and only if $f \in \mathcal{F}^{-1}(L^\infty)$. Moreover, $\|\Theta_f\| = \|\hat{f}\|_{L^\infty}$.

Proof. Fix $z \in \mathbb{R}^d$ and set $|z| = R$. Pick a vector $e \in \text{int}(\text{cc}_{\tilde{\Xi}})$ with distance greater than R to the complement of $\text{cc}_{\tilde{\Xi}}$, which is possible since $\text{cc}_{\tilde{\Xi}}$ is a cone with non-empty interior. Then $e + z \in \text{cc}_{\tilde{\Xi}}$, so for any $x \in \tilde{\Xi}$ we have that $x_1 + x + e + z \in x_1 + \tilde{\Xi} \subset \Xi$. Similarly, $x_1 + x + e \in \Xi$. Since z is the difference of these two vectors, the 1st claim follows.

Suppose that we have proven the theorem for all $f \in C_c^\infty(\mathbb{R}^d)$. If f is a general symbol for which Θ_f is bounded, consider the sequence of functions $f_n \in C_c^\infty(\mathbb{R}^d)$ from Proposition 3.3. Then \hat{f}_n has, by Alaoglu's theorem, a subsequence \hat{f}_{n_k} that converges weak star in L^∞ to some element g . Since f_n converges to f in distribution, it must be that $g = \hat{f}$. Hence $f \in \mathcal{F}^{-1}(L^\infty)$ and, by Propositions 3.1 and 3.3, we have that

$$\|\hat{f}\|_{L^\infty} \leq \overline{\lim}_{k \rightarrow \infty} \|\hat{f}_{n_k}\|_{L^\infty} = \overline{\lim}_{k \rightarrow \infty} \|\Theta_{f_{n_k}}\| \leq \|\Theta_f\| \leq \|\hat{f}\|_{L^\infty}.$$

This proves the theorem for general symbols.

Hence we assume that $f \in C_c^\infty(\mathbb{R}^d)$. Fix $\xi \in \mathbb{R}^d$, pick any vector ν in $\text{int}(\text{bc}_{\tilde{\Xi}})$, and consider for $\varepsilon > 0$ the function

$$E_\varepsilon(x) = e^{\varepsilon x \cdot \nu + 2\pi i x \cdot \xi} \chi_\Xi(x), \quad x \in \Xi.$$

By [1, Lemma 9.5] this function is in $L^2(x_0 + \tilde{\Xi})$ (The set $bc_{\tilde{\Xi}}$ was denoted Θ in [1].) and hence $E_\varepsilon \in L^2(\Xi)$. We use E_ε as a test function:

$$\begin{aligned} \|\Theta_f\| &\geq \left| \frac{\langle \Theta_f E_\varepsilon, E_\varepsilon \rangle}{\|E_\varepsilon\|^2} \right| = \left| \frac{1}{\|E_\varepsilon\|^2} \int \int f(x - y) e^{\varepsilon(x+y)\cdot v} e^{2\pi i(y-x)\cdot \xi} \chi_\Xi(y) \chi_\Xi(x) \, dy \, dx \right| \\ &= \left| \frac{1}{\|E_\varepsilon\|^2} \int f(z) e^{-2\pi i z \cdot \xi} \int e^{\varepsilon(z+2y)\cdot v} \chi_\Xi(z + y) \chi_\Xi(y) \, dy \, dz \right|. \end{aligned}$$

Hence it follows that $\|\Theta_f\| \geq |\hat{f}(\xi)|$ upon showing that

$$\lim_{\varepsilon \rightarrow 0^+} \frac{e^{\varepsilon z \cdot v}}{\|E_\varepsilon\|^2} \int e^{2\varepsilon y \cdot v} \chi_\Xi(z + y) \chi_\Xi(y) \, dy = 1 \tag{6.2}$$

uniformly on compacts in z . Since ξ is arbitrary this establishes that $\|\Theta_f\| \geq \|\hat{f}\|_{L^\infty}$ and by Proposition 3.1 we then conclude that $\|\Theta_f\| = \|\hat{f}\|_{L^\infty}$.

Fix $R > 0$ and suppose that $z \in \mathbb{R}^d$ with $|z| < R$. Again, pick a vector $e \in \text{int}(cc_{\tilde{\Xi}})$ with distance greater than R to the complement of $cc_{\tilde{\Xi}}$. Then $e + z \in cc_{\tilde{\Xi}}$, and therefore

$$-z + \Xi \supset -z + (x_1 + \tilde{\Xi}) \supset -z + x_1 + (e + z) + \tilde{\Xi} \supset x_1 + e - x_0 + x_0 + \tilde{\Xi} \supset x_1 + e - x_0 + \Xi.$$

With $x_2 = x_1 + e - x_0$ we have just shown that $x_2 + \Xi \subset -z + \Xi$. It also holds that $x_2 + \Xi \subset \Xi$, by the last inclusion in the above chain and the fact that $x_1 + e + \tilde{\Xi} \subset x_1 + \tilde{\Xi} \subset \Xi$. This gives us that

$$\chi_\Xi(y - x_2) = \chi_\Xi(y) \chi_\Xi(y - x_2) \leq \chi_\Xi(y) \chi_\Xi(y + z) \leq \chi_\Xi(y),$$

and hence that

$$e^{\varepsilon 2x_2 \cdot v} \|E_\varepsilon\|^2 = \int e^{2\varepsilon y \cdot v} \chi_\Xi(y - x_2) \, dy \leq \int e^{2\varepsilon y \cdot v} \chi_\Xi(y + z) \chi_\Xi(y) \, dy \leq \int e^{2\varepsilon y \cdot v} \chi_\Xi(y) \, dy = \|E_\varepsilon\|^2.$$

The desired equality (6.2) is now immediate, completing the proof. ■

Corollary 6.2. Let $\Xi \subset \mathbb{R}^d$ be any open connected domain such that

$$(1, \infty)^d \subset \Xi \subset (0, \infty)^d,$$

and let $f \in \mathcal{D}'(\mathbb{R}^d)$. Then $\Theta_f: L^2(\Xi) \rightarrow L^2(\Xi)$ is bounded if and only if f is a tempered distribution and $\|\hat{f}\|_{L^\infty(\mathbb{R}^d)} < \infty$, and in this case

$$\|\Theta_f\| = \|\hat{f}\|_{L^\infty}.$$

7 Bounded extension of multilevel block Toeplitz/Hankel-matrices

In this section we interpret Corollary 1.2, when Ξ is a d -dimensional cube, as a result on the possibility of extending finite multilevel block Toeplitz matrices to infinite multilevel block Toeplitz matrices which are *bounded* as operators on ℓ^2 . In view of the equivalence between Toeplitz and Hankel operators on the cube (cf. the proof of Corollary 1.2), and a similar equivalence for finite Hankel and Toeplitz matrices, we could equally well make the analogous statement for multilevel block Hankel matrices. We present only the Toeplitz case. Such matrices appear in various applications, for example in multi-dimensional frequency estimation. Note in particular that Pisarenko's famous method for one-dimensional frequency estimation [34], which relies on the classical Carathéodory–Fejér theorem, was recently extended to the multi-variable case [39] (see also [3]).

When $d = 1$ our statement reduces to a well-known theorem on extending finite (ordinary) Toeplitz matrices, appearing previously for example in [5] and [26]. To describe it, recall that a finite $N \times N$ Toeplitz matrix is characterized by its constant diagonals, whose values we denote by $a = (a_{-N+1}, \dots, a_{N-1})$. As an operator T_a on $\ell^2(\{0, \dots, N-1\})$, its action is given by

$$T_a(v)(m) = \sum_{n=0}^{N-1} a_{m-n} v_n, \quad v \in \ell^2(\{0, \dots, N-1\}), \quad m \in \{0, \dots, N-1\}.$$

We can also consider the case when $N = \infty$, the definitions extending in the obvious way. The completion result then states that it is always possible to extend a to a *bi-infinite* sequence \tilde{a} such that the corresponding Toeplitz operator $T_{\tilde{a}}: \ell^2(\mathbb{N}) \rightarrow \ell^2(\mathbb{N})$ satisfies

$$\|T_{\tilde{a}}\| \leq 3\|T_a\|.$$

It is an open problem whether the constant 3 is the best possible in this inequality. A discussion offering different approaches to the optimal constant can be found in [9]. See also [36].

When $d > 1$, each multi-sequence $a = (a_n)_{n \in \{-N+1, \dots, N-1\}^d}$, generates a multilevel block Toeplitz matrix T_a . As an operator on $\ell^2(\{0, \dots, N-1\}^d)$ it is given by the formula

$$T_a(v)(m) = \sum_{n \in \{0, \dots, N-1\}^d} a_{m-n} v_n, \quad v \in \ell^2(\{0, \dots, N-1\}^d), \quad m \in \{0, \dots, N-1\}^d.$$

To understand this matrix, consider the d -level block Toeplitz matrix T_a as an ordinary $N \times N$ -Toeplitz matrix with entries which are $(d - 1)$ -level block Toeplitz matrices,

$$T_a = \{A_{i-j}\}_{i,j \in \{0, \dots, N-1\}}, \quad A_i = \{a_{(i,m-n)}\}_{m,n \in \{0, \dots, N-1\}^{d-1}}.$$

For instance, a multilevel block Toeplitz matrix for $d = 2$ is an $N \times N$ Toeplitz matrix whose entries are $N \times N$ Toeplitz matrices. Again, we allow for the possibility that $N = \infty$. We now provide the multilevel block Toeplitz matrix analogue of the Toeplitz matrix completion theorem.

Theorem 7.1. There exists a constant $C_d > 0$ such that any finite multi-sequence a can be extended to an infinite multi-sequence \tilde{a} on \mathbb{Z}^d for which $T_{\tilde{a}}: \ell^2(\mathbb{N}^d) \rightarrow \ell^2(\mathbb{N}^d)$ is bounded with norm

$$\|T_{\tilde{a}}\| \leq C_d \|T_a\|.$$

Proof. Let

$$f = \sum_{n \in \{-N+1, \dots, N-1\}^d} a_n \delta_n,$$

where δ_n is the Dirac delta function at n ,

$$\delta_n(\varphi) = \varphi(n), \quad \varphi \in C_c^\infty(\mathbb{R}^d).$$

Set $\Xi = (0, N)^d$ and consider $\Theta_f = \Theta_{f, \Xi}$. Given $g \in C_c^\infty(\Xi)$, a short calculation shows that

$$\Theta_f(g)(x) = \sum_{n \in \mathbb{Z}^d \cap (x - \Xi)} a_n g(x - n), \quad x \in (0, N)^d.$$

With $x = m + r$, where $m \in \{0, \dots, N-1\}^d$ and $r \in [0, 1)^d$, this can be rewritten

$$\Theta_f(g)(m + r) = \sum_{k \in \{0, \dots, N-1\}^d} a_{m-k} g(r + k).$$

In other words, with $g_r = \{g(r+n)\}_{n \in \{0, \dots, N-1\}^d}$, we have that

$$\Theta_f(g)(m+r) = T_a(g_r)(m).$$

Hence

$$\sum_{m \in \{0, \dots, N-1\}^d} |\Theta_f(g)(m+r)|^2 = \|T_a(g_r)\|^2 \leq \|T_a\|^2 \|g_r\|^2 = \|T_a\|^2 \sum_{m \in \{0, \dots, N-1\}^d} |g(m+r)|^2.$$

Integrating both sides over $r \in (0, 1)^d$ gives us that $\|\Theta_f(g)\|^2 \leq \|T_a\|^2 \|g\|^2$. In other words, $\Theta_f: L^2(\mathbb{E}) \rightarrow L^2(\mathbb{E})$ is bounded and

$$\|\Theta_f\| \leq \|T_a\|.$$

Noting that the constant c in Corollary 1.2 is invariant under homotheties, we find that there exists a distribution $\tilde{f} = \hat{b} \in \mathcal{D}'(\mathbb{R}^d)$, coinciding with f on $(-N, N)^d$, such that

$$\|\Theta_{\tilde{f}, \mathbb{R}^d}\| \leq C_d \|T_a\|,$$

where C_d only depends on the dimension d . Of course, $\Theta_{\tilde{f}, \mathbb{R}^d}: L^2(\mathbb{R}^d) \rightarrow L^2(\mathbb{R}^d)$ is nothing but the operator of convolution with \tilde{f} .

Now pick any function $\varphi \in C_c^\infty((-1/2, 1/2)^d)$ with $\int |\varphi|^2 dx = 1$ and consider the isometry $I: \ell^2(\mathbb{N}^d) \rightarrow L^2(\mathbb{R}^d)$ given by

$$Iv(x) = \sum_{n \in \mathbb{N}^d} v_n \varphi(x-n), \quad v \in \ell^2(\mathbb{N}^d), \quad x \in \mathbb{R}^d.$$

Then

$$I^*g(n) = \int_{\mathbb{R}^d} g(x) \overline{\varphi(x-n)} dx, \quad g \in L^2(\mathbb{R}^d), \quad n \in \mathbb{N}^d.$$

It follows that

$$I^* \Theta_{\tilde{f}} I v(m) = \sum_{n \in \mathbb{N}^d} \tilde{a}_{m-n} v_n, \quad v \in \ell^2(\mathbb{N}^d), \quad m \in \mathbb{N}^d,$$

where

$$\tilde{a}_n = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} f(x-y+n) \varphi(y) \overline{\varphi(x)} dy dx, \quad n \in \mathbb{Z}^d.$$

That is, $I^* \ominus_{\tilde{J}} I = T_{\tilde{a}}$. It is clear by construction that \tilde{a} is an extension of a ,

$$\tilde{a}_n = a_n \int_{\mathbb{R}^d} |\varphi(y)|^2 dy = a_n, \quad n \in \{-N+1, \dots, N-1\}^d.$$

This finishes the proof. ■

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