

Anders Torheim

Design of a gas carrier for transportation of NH₃ and CO₂

Bachelor's thesis in Ship Design

Supervisor: Håvard Vollset Lien

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Norwegian University of Science and Technology
Faculty of Engineering
Department of Ocean Operations and Civil Engineering

Preface

The following report is my bachelor's thesis for the bachelor's degree programme in ship design at the Department of Ocean Operations and Civil Engineering at the Norwegian University of Science and Technology (NTNU).

I would like to thank Horisont Energi, with a special notice to my contacts Ida Furrus and Ola Ravndal, for providing me with this thesis. Their helpful guidance and supplement of information is appreciated.

A special thanks goes to Håvard Vollset Lien, my advisor at NTNU, for providing me with knowledge, and for excellent mentorship and guidance throughout the design process.

Abstract

This Bachelor's Thesis is to design a carbon-emission free vessel for transportation of a given amount of liquid ammonia and liquid carbon dioxide per year. The mission requirements are given by Horisont Energi AS. From this specification, a transport logistics analysis is carried out. This analysis resulted in requirements to number of ships needed, speed and cargo capacity. The workflow in this project is based on the design spiral. The final ship design is capable of fulfilling the mission requirements. The work resulted in a general arrangement, lines plan, tank plan, stability calculations, and a specification. Also, an evaluation of the ships energy source and propulsion system is carried out.

Sammendrag

Denne bacheloroppgaven er å prosjektere et nullutslippskip av karbondioksid for transport av flytende ammoniakk og flytende karbondioksid. Kravspesifikasjonen til oppgaven er gitt av Horisont Energi AS. Fra denne spesifikasjonen er det gjort en analyse av transportlogistikken. Denne analysen resulterte i nødvendig antall skip, hastighet og lastekapasitet. Med designspiralen som utgangspunkt har arbeidet i denne oppgaven resultert i et skipsdesign som kan oppfylle kravspesifikasjonen. Generalarrangement, linjetegning, tankplan, stabilitetsberegninger og en kort spesifikasjon er blitt laget. En evaluering av forskjellige energibærere og løsninger for fremdriftssystem er også gjort.

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1 Introduction

1.1 Climate change motivation

The Paris Agreement entered into force on 4 November 2016. It is an agreement to reduce world-wide greenhouse gas, GHG, emissions. The main goal is to limit global warming to below 2 degrees Celsius, but preferably to below 1,5 degrees Celsius, compared to pre-industrial levels (UnitedNations 2021).

To achieve this goal, all types of industries around the world have to reduce their GHG emissions. This also includes the energy sector and the transportation sector. There has to come a transition in the world's energy supply to GHG emission free energy sources, and ultimately renewable energy sources. Also, the marine transportation sector has to switch from using fossil fuels such as heavy fuel oil, HFO, diesel, and LNG, over to other emissions free fuels. The International Maritime Organization, IMO, adopted in April 2018 the Initial Strategy on the reduction of GHG emissions from shipping. This states that GHG emissions from shipping shall be reduced to under half their level in 2008. The strategy also aims to phase out GHG emissions completely as soon as possible (IMO 2021).

1.2 Study Objective

Horisont Energi, HE, a Norwegian clean energy company, is planning on producing blue ammonia from natural gas. Through a production process of ammonia which includes carbon capture and storage, CCS, they will be able to deliver ammonia as a carbon neutral fuel. HE is also planning on offering carbon storage facilities to other businesses.

Horisont Energi is in the need for a vessel able to transport both carbon dioxide and ammonia. Because of their goal for a carbon neutral future the ships energy source is to be ammonia.

This Bachelor's Thesis is to design a carbon-emission free vessel for transportation of a given amount of CO₂ and NH₃ per year, based on the specifications given by HE. The project will result in a general arrangement, lines plan, tank arrangement, stability calculations and technical particulars. The vessels propulsion system is to be ammonia based.

1.3 Project specification

1.3.1 Project description

The work in this Bachelor's Thesis is to design one or several ships that transports ammonia from Hammerfest to Rotterdam, and carbon dioxide from Stockholm to Hammerfest. The ship design will therefore be a multi-cargo design, that being liquid ammonia and liquid carbon dioxide. The ship(s) is also to be zero-emissions of CO₂ vessels and comply with international regulations regarding NO_x and SO_x.

1.3.2 Specifications and constraints

The specifications given by Horisont Energi is listed in the following sub-chapters. It is sorted by the three port locations on the route. Here the required amount of cargo transported is listed. Other specifications that may be constraining are also shown.

1.3.2.1 Hammerfest

- Annual transportation of ammonia from Hammerfest is to be regular transportation of 400 000 tons per annum. If distributed evenly for each months follows 33 333 tons per month.
- Ice class is demanded if necessary.

1.3.2.2 Stockholm

- The CO₂ production in Stockholm is not constant and varies with three different seasons through the year. The CO₂ production is displayed in Table 1.1 below.

Table 1.1 CO₂ production

CO ₂ production			
High season		Low season	
140	t/h	84	t/h
6,5	months	2,5	months
4 680	h	1 800	h
655 200	T	151 200	T
100 800	T/months	60 480	T/months

High season is the months October-march. Low season is April, May and September. During the summer in June, July and August there is no CO₂ production.

- CO₂ intermediate storage in Stockholm is maximum 25 000 tons.
- Max draft is 11 meters.
- Max length overall is 162 meters.

1.3.2.3 Rotterdam

- No known constraints.
- Port fee is 10 000 € per arrival.

1.3.3 Additional information

- Horisont Energi has the ability to use a “rapid purge technology” which is under qualification. This will allow purging in 24 hours. The technology may be used if relevant.
- Loading and unloading rate set to is 1 200 m³ per hour.
- The ship is to be a carbon emission free vessel.

1.3.4 Route

The route goes as follows. From Hammerfest to Rotterdam with ammonia as cargo. From Rotterdam to Stockholm with no cargo, but the purging process is running during transit. And from Stockholm back to Hammerfest with CO₂ as cargo. The route is displayed in Figure 1.1. In Table 1.2 information about cargo and distance for each leg is listed.

Table 1.2 Route information

Leg	Cargo	Distance
Hammerfest – Rotterdam	Ammonia (NH ₃)	1400 nm
Rotterdam – Stockholm	Purging	1050 nm
Stockholm - Hammerfest	Carbon dioxide (CO ₂)	2100 nm

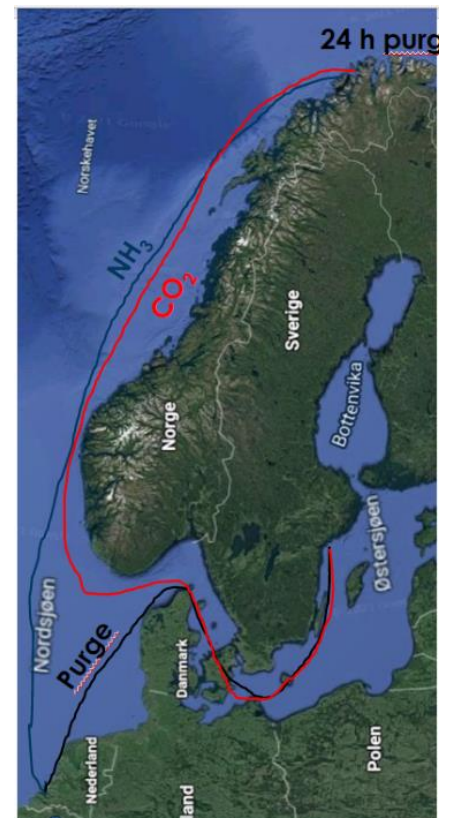


Figure 1.1 Route

1.3.5 Thermodynamic state of cargo

The thermodynamic state, including pressure, temperature, density and phase, of the two cargoes is listed in Table 1.3 below.

Table 1.3 Thermodynamic properties of cargo

Cargo	Pressure	Temperature	Density	Phase
NH ₃	5 bar	-33 °C	0,682 ton/m ³	Fluid
CO ₂	7 bar	-50 °C	1,155 ton/m ³	Fluid

2 Design Theory

2.1 Gas tankers

Transportation of gasses in their gaseous state is not physically practical onboard ships. When they are liquefied, the space they occupy is much less. Therefore, the gasses are brought to their liquid state either by being cooled down, pressurized or a combination of these. Gas carriers can be divided into the following categories.

1. Fully pressurized gas carriers
2. Fully refrigerated gas carriers
3. Semi-refrigerated gas carriers

Fully pressurized ships carry their cargo at ambient temperature, and at pressures normally up to 18 bar. No thermal insulation of the tanks, or a re-liquefaction plant is needed (Wärtsilä n.d b). Due to the high pressure, the tanks used are very small (Jørgen Amdahl 2017). The high design pressure also makes the tanks extremely heavy.

Fully refrigerated ships carry their cargo at atmospheric pressure, and at very low temperature. For LPG and LNG ships respectively, the cargo is kept at a temperature of -42 °C and -162 °C (Dokkum 2020). Large-scale cooling systems, and thermal insulation is needed because of the low temperature. Also, steel capable of withstanding the low temperatures is used in the tanks and the hull (Jørgen Amdahl 2017).

Semi-refrigerated ships carry their cargo at a combination of low temperature and high pressure. The pressure vessel tanks are designed for a vapour pressure of 4-8 bar. Low temperature steel is used to allow carriage of cargoes with temperature of -48 °C. In some cases, special alloy steel allows temperatures down to -104 °C. Semi-refrigerated ships is the most common for gas carriers in the size range of 1 500 to 30 000 m³ (Wärtsilä n.d b).

The cargo tanks in gas carriers are divided into three types of independent freestanding tanks, and one type of dependent tank. The dependent tanks are built into the hull of the ship. These tanks are commonly referred to as membrane tanks (Dokkum 2020).

The independent tanks are freely supported on foundations in the hull of the vessel. These tanks are not a part of the ship hull and does not contribute to strength of the hull girder. They are divided into the following three categories (Dokkum 2020):

- **Type A:** Fully cooled at atmospheric pressure with flat tank walls. Suitable for temperatures down to -42 °C.
- **Type B:** Fully cooled at atmospheric pressure. The tanks may be different-shaped, for example spherical steel tanks. Temperatures below -48 °C may be acceptable.
- **Type C:** Pressure vessel tanks. These are often designed as cylindrical horizontal tanks due to the high design pressure. The tanks may be insulated to prevent the pressure from rising. Pressures up to 18 bar is tolerated.

2.2 About the design process

2.2.1 Requirements to ships

Ship design is an iterative process. The goal is to come up with a final design that fulfils the specifications requirements given by the customer. In addition to these, there are three fundamental requirements for all types of ships (Jørgen Amdahl 2017):

- “The ship shall float with the correct side up and be stable”.

According to Archimedes’ law, for a ship to stay afloat it needs to be able to displace a water-volume with the same weight as the mass of the ship. The ship also needs to comply with stability criteria.

- “The ship shall be sea-worthy”

The ships need to be able to deliver cargo in good condition and on time. It follows that sufficient propulsion, steering, stability, freeboard, and ability to withstand forces from the surroundings needs to be in place.

- “Safety for passengers and cargo shall be maintained”

Other than seaworthiness, sufficient safety equipment and crew training needs to be in place.

2.2.2 The design spiral

The iterative process of ship design is carried out through several stages. These stages form what often is referred to as the design spiral. To come up with the final ship design that fulfils all requirements, several rounds in the design spiral is needs to be done. The stages are listed successively in order as they should be completed. However, the most convenient workflow is not given explicitly, and depends on available information, specifications and constraints to the final design (Jørgen Amdahl 2017). Often the workflow follows a more web

like path, rather than following the spiral successively. An illustration of the design spiral is shown in Figure 2.1 below.

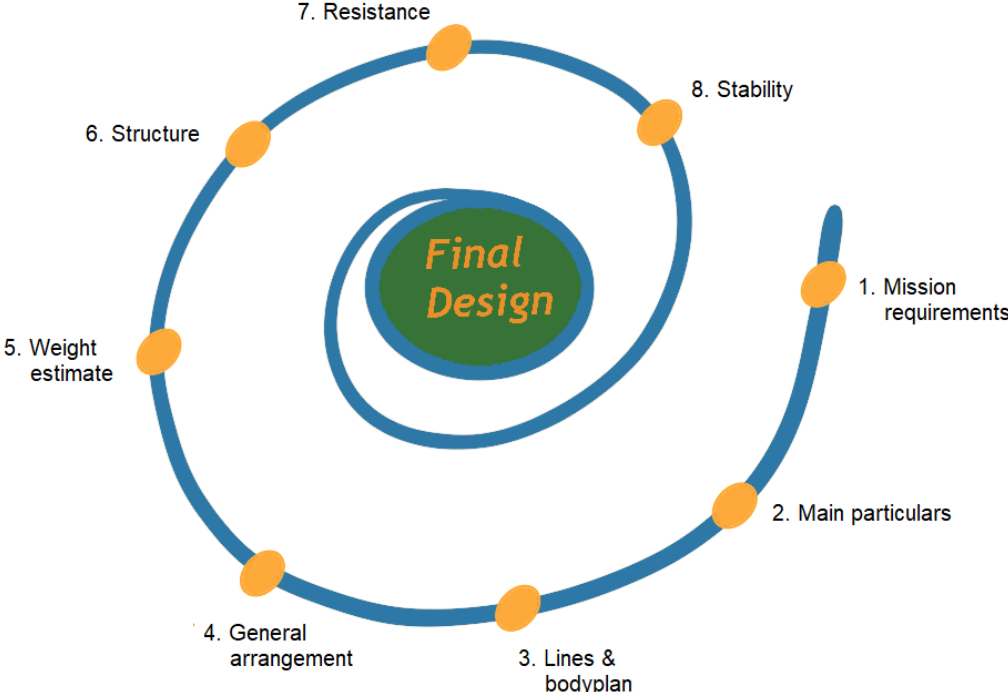


Figure 2.1 The design spiral

In the following, a description of each stage in the design spiral is given:

1. Mission requirements

Specifications and customer requirements to the final ship design makes up the basis and starting point for the design process. Requirements like cargo capacity, speed, range, route, draft, and costings is specified.

2. Main particulars

Needed displacement from deadweight (DWT) and lightship-weight (LWT) us found. Also dimensions for length (L), breath (B), depth (D), draft (T), and block coefficient (C_B) is set. These are related to each other as given in equation 2-1.

$$C_B = \frac{DWT + LWT}{L * B * T} \tag{2-1}$$

Starting values may be found from statistics.

3. Lines and bodyplan

A hull shape is modelled based on the main particulars from stage 2. The displacement from the 2nd stage is obtained when the hull is shaped to the desired block coefficient. Also, the location of the longitudinal centre of buoyancy (LCB) is preferably located at the longitudinal centre of gravity (LCG), to minimize trim.

4. General arrangement

The general arrangement is a key element in the design process. Here the design and layout of the ship is presented. It also contains all components of the hull and equipment on the ship. The general arrangement is continuously updated throughout the design process as changes and updates are made. It is therefore a valuable tool to keep track of the design process. It is also used as the foundation for the weight calculation in the next step in the design spiral.

5. Weight estimate

The weight, LCG, and VCG of the hull and each component on board the ship is listed systematically. The total LWT is calculated together with its lateral- and vertical moment from the aft perpendicular and the baseline. Design margins are added.

6. Structure

The hull is exposed to forces from the surroundings and weights from cargo and the ship itself. These forces result in stresses in hull girder. The hull needs to be strong enough do withstand these stresses. The structural design procedure (SDP) as described in the next section is carried out to dimension the hull plating, stiffeners, and girders. It should also be checked for buckling.

7. Resistance

The required engine break power and fuel capacity is calculated using data from a resistance analysis. The resistance depends on the hull shape and wetted area.

8. Stability

The final stage in the design spiral is a stability analysis. The ship must fulfil stability criteria given by IMO in all loading conditions.

When each round in the design spiral is completed, the resulting design is checked against the mission requirements. Eventual deviations are localised, and a new round in the design spiral is started. Finally, after several rounds, a final ship design that fulfils all specifications and requirements is obtained.

2.3 Structural design procedure

The structural strength of the hull girder is to be evaluated at stage 6 in the design spiral. Here the structural design procedure is used to calculate required plating and stiffener dimensions based on both global and local loads. The global loads come from still water bending moments and wave bending moments. The allowable local stress level from local loads is found in the DNV Rules for classification of ships.

The SDP is an iterative process and consists of eight stages. The stages are listed chronologically in the order as they should be completed. The procedure is described in the following. The iterative workflow is illustrated in figure Figure 2.2 below.

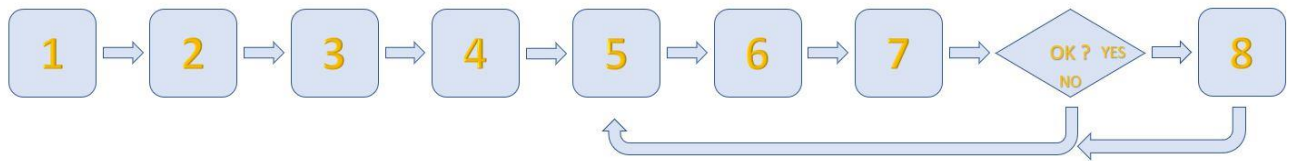


Figure 2.2 SDP workflow

Step 1 Input:

Gather input from the general arrangement to use in the further step.

Step 2 Stiffener topology:

Decide stiffener direction, distance s between stiffeners, and distance l between girders.

Step 3 Design bending moments:

The contributions to the total design bending moments come from still water bending moments, and wave bending moments. These are further divided into hogging and sagging moments. The critical still water moment is taken as the greatest of the moment calculated from the DNV Rules for classification of ships, or the moment from the actual loading condition. The wave bending moment is calculated from the DNV Rules for classification of ships.

Step 4 Critical cross section:

Identify the critical transverse cross section of the hull girder within 40 % of the midship section with regards to minimum section modulus.

Step 5 Plating and stiffener dimensions:

Calculate required dimensions of elements, i.e. plating and stiffeners, contributing to longitudinal strength based on local loads. Alternatively make an assumption of the values.

Step 6 Cross section properties:

From the critical cross section and established dimension, the values for neutral axis, moment of inertia, and section modulus for deck and bottom is calculated.

Step 7 Global longitudinal strength:

In this step, the global longitudinal strength is evaluated. The longitudinal stress level, σ_l , in the hull girder is calculated from maximum design bending moment and minimum section modulus for both deck and bottom. The stress level is calculated with the following formula.

$$\sigma_l = \frac{M_{SW} + M_W}{Z_{min}} \leq 175 * f_1 \quad (2-2)$$

Here M_{SW} and M_W are the still water- and wave bending moment respectively. Z_{min} is the minimum section modulus. The value of the material factor f_1 is set to 1 for normal steel. For steel with higher strength, f_1 may be higher.

If the calculated value stress level is higher than the allowed stress level $175*f_1$, new values for the plating and stiffener dimensions need to be set in step 5. Consequently step 6 and 7 must be re-evaluated. When the global longitudinal stress level is below the allowed stress level, the process may be continued to step 8.

Step 8 Recalculate required plating and stiffener dimensions

In this step the local strength is evaluated. Based on acceptable global longitudinal strength a stress factor, f_2 , is calculated for both deck and bottom using the following formula.

$$f_2 = \frac{5,7 * (M_{SW} + M_W)}{Z} \quad (2-3)$$

Required dimensions for plating and stiffeners based on global strength is found from the rules in the DNV Rules for classification of ships. New dimensions are re-established. The updated values are applied in step 5 and the process is continued. This iterative workflow is continued until convergence is reached and both local and global strength requirements are fulfilled.

3 The design process

3.1 Design phase 1 Logistics and main particulars

3.1.1 Transport logistics

The final ship design, especially the main particulars, depends on the transport logistics. There are several combinations of payload capacity and transit speeds that fulfils the requirements to amount of cargo transported per month. Therefore, the transport logistics determines the needed payload capacity.

3.1.1.1 Logistics constraints

According to the project constraints, maximum CO₂ storage at the intermediate storage in Stockholm is 25 000 tons. As listed in Table 1.1, the CO₂ production is 140 tons/hour in High season, and 84 tons/hour in Low season. Because of this there are specific requirements to how often a ship must dock in Stockholm for CO₂ loading before the storage gets full. Table 1.1 is therefore updated to contain the maximum arrival period in Stockholm for both High season and Low season, as shown below in the orange row in Table 3.1.

Table 3.1 CO₂ production with maximum arrival period

CO ₂ production					
High season			Low season		
140	t/h		84	t/h	
6,5	months		2,5	months	
4 680	h		1 800	h	
655 200	T		151 200	T	
100 800	T/months		60 480	T/months	
Arrival period Stockholm	7,4	Days	Arrival period Stockholm	12,4	days

Another deciding factor for the logistics is the monthly required amount of transported CO₂. This is shown in the green row in Table 3.1 above. Also, the requirement of even transport of 400 000 tons of NH₃ per annum affect the logistics. Approximately 33 333 tons of NH₃ has to be transported every month.

3.1.1.2 Logistics calculation

The logistics has been modelled in Excel. Screenshots from the spreadsheet is shown below in Table 3.2 and Table 3.3. Input parameters is marked with red, and important output data is marked with yellow.

Table 3.2 Example logistics model 1

High Season - 3 ships										
Leg	Cargo	Loading rate [m ³ /h]	Loading time [h]	Volume cargo [m ³]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]
Loading Hammerfest	NH ₃	1200	8	9600	6547,2				8,0	0,3
Hammerfest - Rotterdam	NH ₃				6547,2	1400	13	107,7	115,7	4,8
Unloading Rotterdam	NH ₃	1200	8	-9600	-6547,2				123,7	5,2
Rotterdam - Stockholm	Purging				0	1050	13	81	204,5	8,5
Loading Stockholm	CO ₂	1200	14,1	16920	19542,6				218,6	9,1
Stockholm - Hammerfest	CO ₂				19542,6	2100	13	161,5	380,1	15,8
Unloading Hammerfest	CO ₂	1200	14,1	-16920	-19542,6				394,2	16,4
Purging Hammerfest	Purging		24		0				418,2	17,4

In this case, since it is modelled with three ships, the arrival period and cargo transported per month is as shown in Table 3.3.

Table 3.3 Example logistics model 2

Arrival period [days]	CO ₂ in storage [ton]	Transported cargo	per month [ton]	per season [ton]
5,81	19516	NH ₃	33816	219806
Roundtrips per ship	Roundtrips for 3 ships	CO ₂	100937	656093
11,2	33,6			

The input parameters, speed and loading time, has been varied and optimized so that the following output values are fulfilled:

- Frequent enough arrival period in Stockholm
- Requirement to amount of CO₂ transported per month
- Requirement to amount of NH₃ transported per month

Table 3.2 and Table 3.3 above shows the model for High season. An equivalent procedure has been carried out for Low season. For the period when there is no CO₂ production, in Off season, another model has been made. In Off season, only ammonia is transported from Hammerfest to Rotterdam. The logistics spreadsheet is shown in Appendix A.

The logistics calculation has also been done for a varied number of vessels. There are several combinations of number of vessels, speed and payload capacity that fulfils the logistics constraints. The goal for the logistics calculation is to find the best and most cost-effective combination for each of the three seasons.

3.1.2 Early cost estimation

The logistics plan which is decided upon at this early stage will influence the economy for the whole project. It is therefore important to decide on the logistics based on what is assumed to result in the lowest total cost, and the lowest cost per ton CO₂ and NH₃ transported.

Horisont Energi has provided a cost estimation model based on a reference ship. The model has a set of input values and applies these on the reference ship. Then different costing values is calculated and cost per unit cargo transported is given as output. Also, the total project cost is calculated. Reference ship data is listed in Table 3.4. The input parameters, calculations and output parameters are listed below in Table 3.5.

Table 3.4 Cost model reference ship

Reference ship	
Reference	8000 cbm
Ref. cost	32 MUSD
at speed	4082 kW
SFC	0,195 kg/kWh
Consumption	796 kg/hr
Consumption	0,8 ton/hr
Consumption	19,1 ton/day
at rating	1,07 ton/hr

Table 3.5 Cost estimation model input, calculations, and output

Input	Distance [nm]	Size [m ³]	Contract speed [kts]	Logistics speed [kts]	Interest rate [%]	Loan period [yrs]
Calculations	Ship price [\$]	Annual capex [\$]	Fuel cost [\$/yrs]	Crew & opex cost [\$/yrs]	Annual cost [\$/yrs]	
Output	Cost per unit NH ₃ transported [\$/ton]		Cost per unit CO ₂ transported [\$/ton]		Total project cost [\$]	

3.1.3 Transport logistics results

The logistics results and cost estimation has been carried out for two, three, and four vessels and with different combinations of speed and payload capacity.

3.1.3.1 Two ships

With two ships, to load CO₂ in Stockholm frequent enough the minimum logistics speed is 17 knots. Then 25 000 tons of CO₂ is loaded at each arrival. The logistics speed is an average speed for the voyage between two ports. This speed is meant to account for lost time because of bad weather, manoeuvring time etc. Therefore approximately 2 knots is added to get the design speed. Hence the design speed for two vessels is 19 knots. A design speed of 19 knots is unrealistically high. The logistics model based on only two ships is then excluded.

It is worth mentioning in this report that it is the maximum CO₂ storage capacity in Stockholm that results in the excluding of the ability to use two ships. If the storage capacity was higher,

the required speed would be lower. Then the ship size could be increased up to the maximum length and draft constraints. This might have been a cheaper solution, but is not further considered.

3.1.3.2 Three ships

The method described above in chapter 3.1.1.2 is used. A logistics plan has been made for the logistics speeds 10 – 19 knots. The maximum monthly cargo transported is CO₂ from Stockholm to Hammerfest during High season. Because of this, the payload capacity needed for this voyage is the deciding factor for the final payload capacity for the ships. For every speed the corresponding cargo transported per voyage is found. Since the loading and offloading rate is set to 1 200 m³/hour the needed time for loading is calculated.

When setting up the logistics for Low season, the amount of CO₂ carried is set to the maximum payload capacity from High season. Then the speed is set to a minimum in order to fulfil the requirement to monthly cargo transported. The amount of ammonia transported per voyage is based on the speed and the requirement for monthly cargo transported. It is found to be viable with only two ships during Low season. Therefore two ships are used, and this is assumed to be cheaper than using three ships.

In Off season only ammonia is transported from Hammerfest to Rotterdam. The amount of ammonia transported per voyage is set to the maximum payload capacity. The speed is set thereafter. It is found to be viable with only one ship during Off season. Therefore one ship is used and is assumed to be cheaper than using two or three ships.

In Table 3.6 logistics speed, estimated cost per transported ton ammonia and CO₂, and estimated total project cost over 15 years for three ships is listed.

Table 3.6 Cost estimation three ships

Logistics speed [kts]	Cost per ton NH₃ transported [\$/ton]	Cost per ton CO₂ transported [\$/ton]	Total project cost 15 years [€]
10	\$ 46,43	\$ 46,08	\$ 714 751 632
11	\$ 45,00	\$ 44,91	\$ 694 698 761
12	\$ 44,50	\$ 44,08	\$ 679 313 549
13	\$ 43,43	\$ 43,30	\$ 664 241 268
14	\$ 42,82	\$ 42,67	\$ 649 527 155
15	\$ 41,99	\$ 41,79	\$ 638 803 576
16	\$ 41,59	\$ 41,34	\$ 626 562 875
17	\$ 40,86	\$ 40,72	\$ 616 923 669
18	\$ 40,37	\$ 40,04	\$ 607 956 907
19	\$ 39,88	\$ 39,56	\$ 598 988 859

The data in Table 3.6 is graphed in Figure 3.1 and Figure 3.2 below.

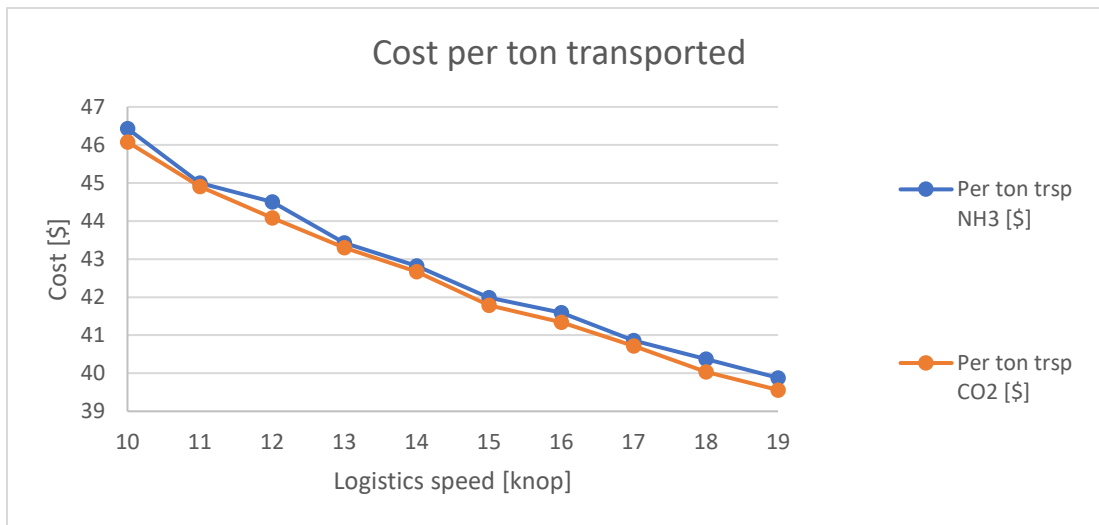


Figure 3.1 Cost per ton transported 3 ships

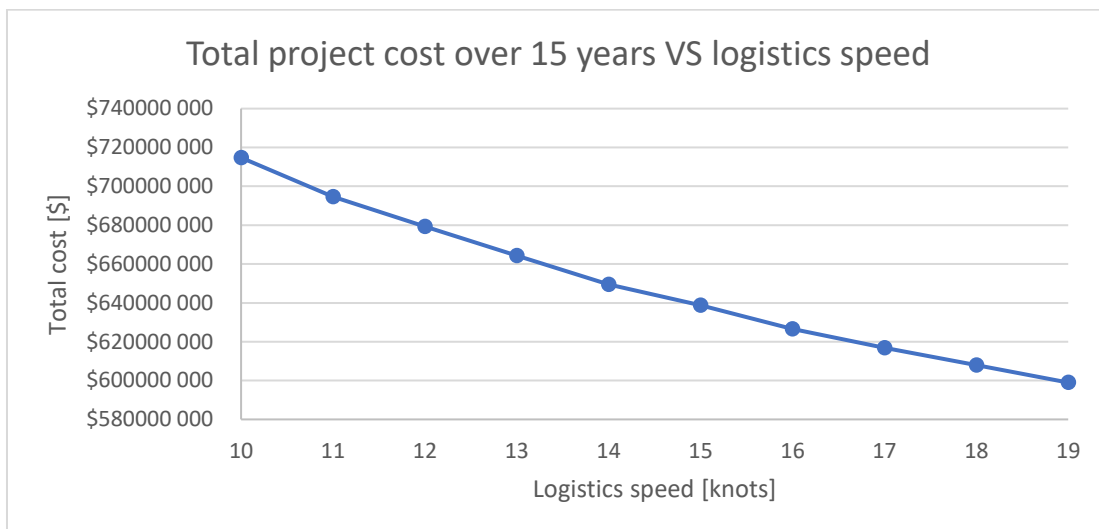


Figure 3.2 Total project cost 3 ships

It is clear from both Figure 3.1 and Figure 3.2 above that lowest cost is achieved with the highest speed. An explanation to that the cost model estimates lower cost with increasing speed may be that because of that when the speed increases the size of the vessel decreases. The building cost and loan cost decreases with smaller ships. The eventual increased fuel cost because of higher speeds does not weigh out the decreased build and loan cost due to smaller ships.

3.1.3.3 Four ships

The same procedure as described for in section 3.1.3.2 for three ships is used for the case of four ships. During High season four ships is used.

It has been tested for using two ships during Low season with the payload capacity found in High season for four ships, however the logistics model in Excel shows that this is not feasible because the payload capacity is too low. It is therefore necessary to use three ships during Low season.

The same goes for Off season; it is not possible to use only one ship during Off season when the logistics in High season is optimized for four ships. The payload capacity is too low. It is therefore necessary to use two ships during Off season

In Table 3.7 logistics speed, estimated cost per transported ton ammonia and CO₂, and estimated total project cost over 15 years for four ships is listed.

Table 3.7 Cost estimation four ships

Logistics speed [kts]	Cost per ton NH ₃ transported [\$/ton]	Cost per ton CO ₂ transported [\$/ton]	Total project cost 15 years [€]
10	\$ 54,35	\$ 53,95	\$ 835 704 293
12	\$ 52,45	\$ 51,90	\$ 795 861 655
14	\$ 50,50	\$ 50,30	\$ 763 669 180
16	\$ 48,99	\$ 48,87	\$ 737 900 010
18	\$ 47,65	\$ 47,82	\$ 715 632 922

The data in Table 3.7 is graphed in Figure 3.3 and Figure 3.4 below.

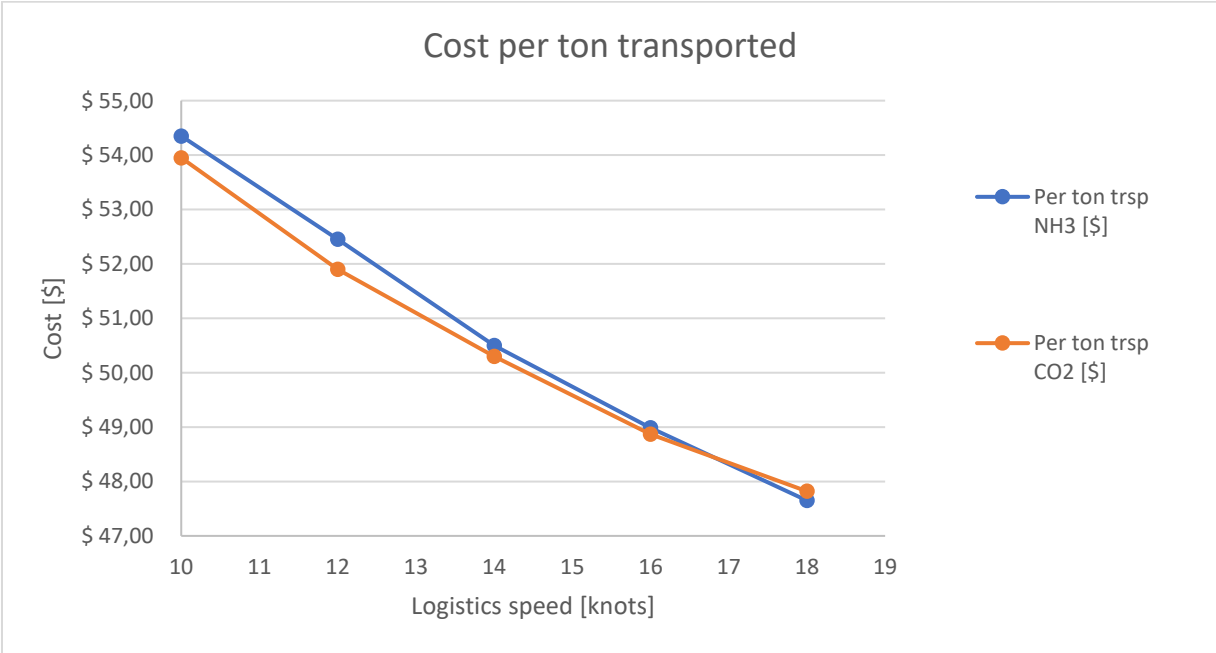


Figure 3.3 Cost per ton transported 4 ships

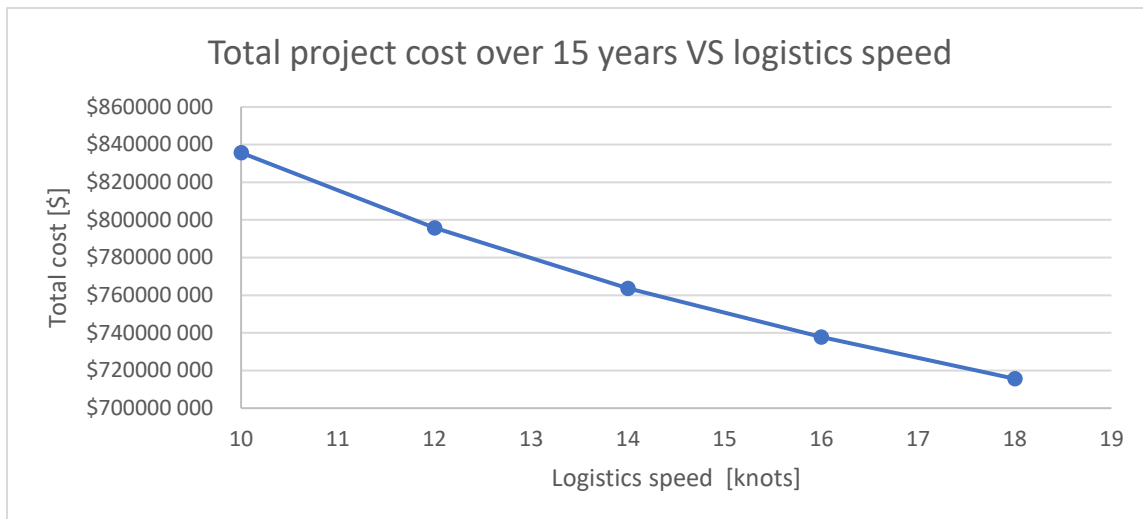


Figure 3.4 Total project cost 3 ships

When comparing the cost per transported ton of cargo, and the total project cost for three and four ships, it is clear that it is cheapest to use three ships. It is therefore decided to use three ships in the logistics, and the ships is designed thereafter.

3.1.3.4 Final decided logistics

The costing model shows that the cost decreases with increased speed. Hence it is beneficial to set the speed as high as possible. As mentioned earlier in chapter 3.1.3.1 a design speed of 19 knots is unrealistically high. Also design speeds up to 16-17 knots is considered not to be feasible. Figure 3.5 based on tanker statistics shows that 16 knots lie in the upper bound. Therefore, a design speed of 15 knots, and a logistics speed of 13 knots are decided upon.

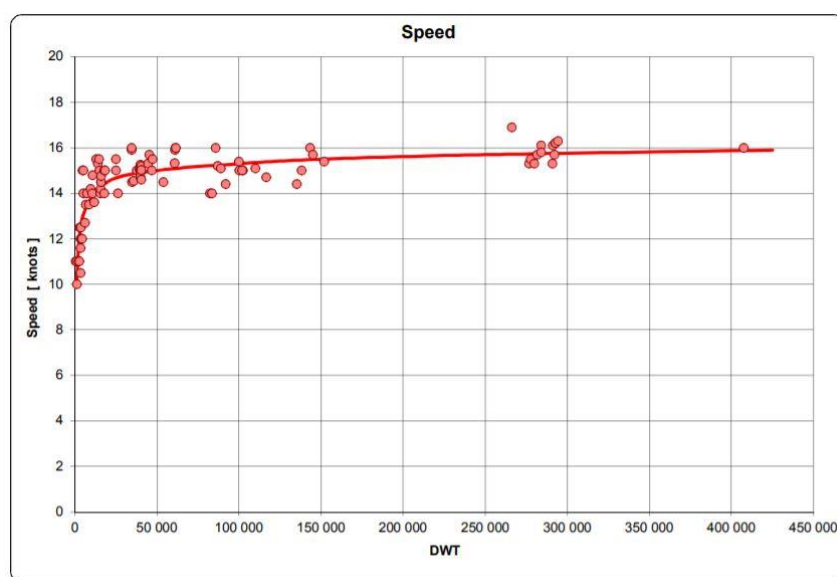


Figure 3.5 Tanker speed statistics, (Levander 2012)

Table 3.8 below shows the decided logistics and monthly and annually cargo transported. Also, the costings based on the cost estimation model is shown.

Table 3.8 Logistics, costings and total cargo transported for 3 ships

High Season - 3 ships										
Leg	Cargo	Loading rate [m3/h]	Loading time [h]	Volume cargo [m3]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]
Loading Hammerfest	NH3	1200	8	9600	6547,2				8,0	0,3
Hammerfest - Rotterdam	NH3				6547,2	1400		13	107,7	4,8
Unloading Rotterdam	NH3	1200	8	-9600	-6547,2				115,7	5,2
Rotterdam - Stockholm	Purging				0	1050		13	204,5	8,5
Loading Stockholm	CO2	1200	14,1	16920	19542,6				81	9,1
Stockholm - Hammerfest	CO2				19542,6	2100		13	218,6	15,8
Unloading Hammerfest	CO2	1200	14,1	-16920	-19542,6				161,5	16,4
Purging Hammerfest	Purging		24		0				394,2	17,4
									418,2	
				Arrival period [days]	CO2 in storage [ton]	Roundtrips per ship	Roundtrips 3 ships	Transported cargo per month [ton]	per season [ton]	
				5,81	19516	11,2	33,6 NH3	33816	219806	
							CO2	100937	656093	
Low Season - 2 ships										
Leg	Cargo	Loading rate [m3/h]	Loading time [h]	Volume cargo [m3]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]
Loading Hammerfest	NH3	1200	13	15600	10639,2				13,0	0,5
Hammerfest - Rotterdam	NH3				10639,2	1400		11,8	118,6	5,5
Unloading Rotterdam	NH3	1200	13	-15600	-10639,2				144,6	6,0
Rotterdam - Stockholm	Purging				0	1050		11,8	233,6	9,7
Loading Stockholm	CO2	1200	14,1	16920	19542,6				89,0	10,3
Stockholm - Hammerfest	CO2				19542,6	2100		11,8	247,7	17,7
Unloading Hammerfest	CO2	1200	14,1	-16920	-19542,6				178,0	18,3
Purging Hammerfest	Purging		24						439,8	19,3
									463,8	
				Arrival period [days]	CO2 in storage [ton]	Roundtrips per ship	Roundtrips 2 ships	Transported cargo per month [ton]	per season [ton]	
				9,66	19479	3,9	7,8 NH3	33033	82582	
							CO2	60676	151691	
Off Season - 1 ship										
Leg	Cargo	Loading rate [m3/h]	Loading time [h]	Volume cargo [m3]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]
Loading Hammerfest	NH3	1200	14,1	16920	11539,44				14,1	0,6
Hammerfest - Rotterdam	NH3				11539,44	1400		12,7	110,2	5,2
Unloading Rotterdam	NH3	1200	14,1	-16920	-11539,44				138,4	5,8
Rotterdam - Hammerfest	No cargo				0	1400		12,7	248,7	10,4
				Arrival period [days]	CO2 in storage [ton]	Roundtrips per ship	Roundtrips 1 ship	Transported cargo per month [ton]	per season [ton]	
				10,4	0	8,7	8,7 NH3	33411	100233	
							CO2	0	0	
Costings								Total cargo transported per year		
Cargo	Cost per ton trsp [\$ /ton]	Total project cost 15 years [\$]				Transported cargo per year [ton]				
NH3	\$ 43,43	\$ 664 241 268				NH3		402621		
CO2	\$ 43,30					CO2		807784		

The following bullet points are key points from the decided logistics in Table 3.8:

- Number of ships: 3 ships
- Design speed: 15 knots
- Cargo capacity, volume: Approx. 16 900 m³
- Cargo capacity, mass: Approx. 19 600 ton

3.1.4 Main particulars

To find starting values for the main particulars, ship statistics provided by Kai Levander in “System Based Ship Design” (Levander 2012) is used. Based on the deadweight, values for lightweight, length overall, length between perpendiculars, breadth, draft, and depth is found.

The deadweight, DWT, is approximated to equal the cargo capacity. I.e., the DWT is set to 19 600 tons. The statistical dimensions based on this is listed below in Table 3.9.

Table 3.9 Main particulars from statistics

DWT [ton]	19 600 ton
LWT [ton]	5 400 ton
Displacement (DWT + LWT)	25 000 ton
Loa [m]	150 m
Lpp [m]	147 m
B [m]	24 m
T [m]	9 m
D [m]	13 m
C_B [-]	0,74

These particulars based on statistics is checked by using empirical formulas. Froude number is calculated from the speed and the length:

$$Fn = \frac{V}{\sqrt{g * L}} \quad (3-1)$$

Here V is the speed in m/s, g is the gravitational acceleration, and L is L_{pp} in meters.

Based on Froude number, the following formulas from Schneekluth is used to estimate C_B

$$C_B = 1,06 - 1,68 * Fn \quad (3-2)$$

$$C_B = \frac{0,145}{Fn} \quad (3-3)$$

The following formulae from Posdunine is used to estimate the length:

$$L = C \left(\frac{V}{V + 2} \right)^2 \Delta^{\frac{1}{3}} \quad (3-4)$$

Here L is the length in meters, V is the speed in knots, and Δ is the displacement in tons. C is a constant set to 7,30. Recommended values for C is...

Also the following formula, Shneekluths formula, which is based on statistics, gives an estimation for the most economical length:

$$L_{pp} = \Delta^{0,3} * V^{0,3} * 3,2 * \frac{C_B + 0,5}{\left(\frac{0,145}{Fn} \right) + 0,5} \quad (3-5)$$

Here Δ is the displacement in tons and V is the speed in knots.

The results from these formulas are presented in Table 3.10 below.

Table 3.10 Main particulars based on empirical formulas

Formulae	Result	Comment
Froude number (3-6)	$F_n = 0,20$	
Schneekluth nr. 2 (3-7)	$C_B = 0,72$	Indicates lower C_B
Schneekluth nr. 2 (3-8)	$C_B = 0,71$	Indicates lower C_B
Posdunine (3-9)	$L_{pp} = 166 \text{ m}$	Indicates increased length
Schneekluth (3-10)	$L_{pp} = 151 \text{ m}$	Indicates increased length

From the results in Table 3.10 it is decided to increase L_{pp} to 151 meters and decrease C_B to 0,71.

To set a value for L_{oa} , three meters is added to L_{pp} .

With length, breadth, C_B , and displacement fixed, the required draft is 9,5 meters.

The resulting main particulars are presented in Table 3.11 below. Main particular ratios are listed in Table 3.12 below.

Table 3.11 Main particulars

DWT [ton]	19 600 ton
LWT [ton]	5 400 ton
Displacement [ton]	25 000 ton
L_{pp} [m]	151 m
L_{oa} [m]	154 m
B [m]	24 m
T [m]	9,5 m
D [m]	12 m
C_B [-]	0,71

Table 3.12 Main particulars ratios

L/B [-]	6,29
B/T [-]	2,53
[B/D] [-]	2,00
[L/D] [-]	12,58

3.2 Design phase 2 The design spiral round 1

3.2.1 Lines plan

From the main particulars established above, the hull shape is to be modelled. The computer programme *Maxsurf Modeler* is used for this task. This is done by forming a half cylinder with the desired dimensions. Length, breadth, depth, and design draft is fed as input to the programme. Thereafter, by moving control points, the half cylinder with these dimensions is shaped to comply with the following criteria.

The first criterion is to obtain the block coefficient of 0,71. This is to ensure that the ship floats on the decided waterline, provided that the weight assumption is correct.

A second criterion is to shape the foreship and the bow to the desired shape. The bow is shaped to have a typical shape for this type of vessel. A simple bulbous bow is also modelled. The ship will mainly be operated under the two loading conditions transit with CO₂ as cargo, and transit with ammonia as cargo. A bulbous bow designed for these loading conditions would be beneficial, however, a more detailed bow design is not carried out.

A third criterion is to shape the aftship to the desired shape. The aftship is designed so that there is enough space for the propeller, and enough clearance between the propeller and the hull above. An early estimation of the propeller diameter is done based on the load on the propeller, which is not to be above 300 kW per m². This is to minimize cavitation and to enable the propeller to work efficiently. The propeller diameter is estimated from the following formulae.

$$L = \frac{P_B}{\pi * r^2} \quad (3-6)$$

Here L is the allowed propeller load, P_B is the break power delivered from the engine, and r is the propeller radius. Based on installed engine power in a reference ship the break power is assumed to be 6500 kW. It then follows that the required propeller diameter is 5,3 m.

To achieve optimal water flow conditions around the propeller, and thereby maximizing the propeller efficiency, the propeller clearance is set to 25% of the propeller diameter. It then follows that the required vertical distance from baseline to the hull, at the longitudinal position where the propeller is located, is 6,6 m.

When designing the aftship it is also important to consider the need for buoyancy and also hull resistance due to submerged transom area. Since a weight calculation and an analysis of how the hull floats is not yet carried out this early in the design process, the aftship is not

designed with the need for buoyancy in mind. However, to minimize hull resistance, the aftship is designed so that the transom plate extends down not further than to the design waterline.

The aftship is also meant to contain a skeg, but this is not modelled because it is not relevant this early in the design process, other than that it contributes to small amount of buoyancy. The resulting hull shape from the first round in the design spiral is shown below in Figure 3.6.

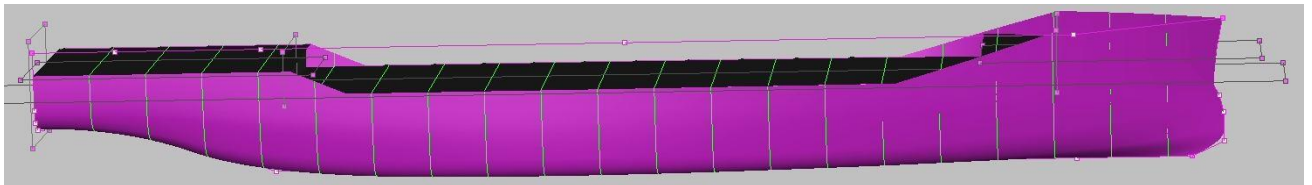


Figure 3.6 Hull shape from first round in the design spiral

3.2.2 General Arrangement

In the first round in the design spiral a detailed general arrangement is not necessary. The main goal at this stage is to include the hull shape and main equipment so that the most important weights are included. The lines forming the hull shape is exported from *Maxsurf Modeler* and imported to *Autocad*, where the general arrangement is drawn. The general arrangement for the first round in the design spiral is shown below in Figure 3.7.

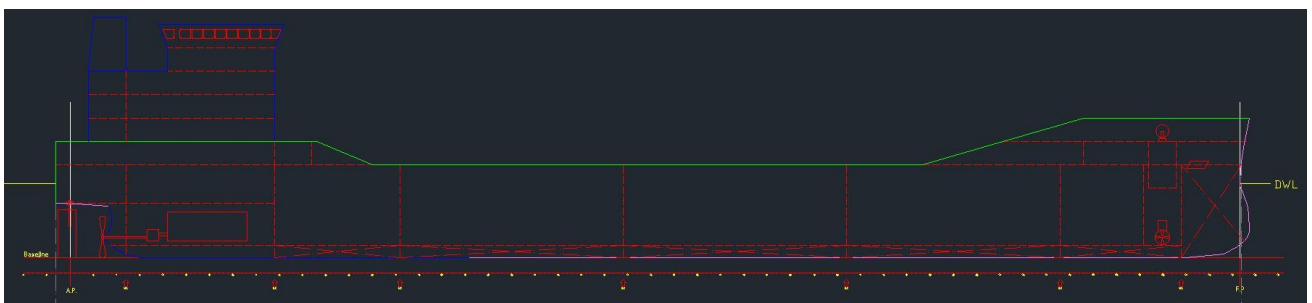


Figure 3.7 General arrangement from first round in the design spiral

3.2.2.1 General arrangement from ship classification rules.

An important dimension often referred to in IMO-rules and ship classification rules is the rule length, as defined by the International Convention of Load Lines. The rule length is either 96% of the length of the waterline at 85% of the least moulded depth, or as the length from the fore side of the stem to the axis of the rudderstock, if that be greater (DNV 2016).

From the first and the second part of this definition it follows that the rule length is 151 m or 146,7 m respectively. The rule length, L_F , then becomes 151 m.

The number of transverse watertight bulkheads required is derived from the rule length. Rule A302 in DNV Rules for classification of ships Pt. 3 Ch.1 Sec. 3 states that 7 watertight bulkheads is required for this length (DNV 2016).

The required placement of the collision bulkhead is found from rule 4.1.1 in DNV Rules for classification of Ships Pt. 3 Ch. 2 Sec. 2 (DNV 2021a). It is found that the collision bulkhead is to be in a position of 7,32 m to 11,85 m abaft the fore perpendicular, FP. A location of 7,6 m abaft FP is chosen.

An aft peak bulkhead shall also be provided according to DNV Rules for classification of Ships Pt. 3 Ch. 2 Sec. 2 rule 5.1.1. Its exact location is not further specified other than it shall enclose the stern tube and rudder trunk in a watertight compartment (DNV 2021a).

A double bottom is fitted in the first round in the design spiral. DNV Rules for classification of Ships rule 2.3 states the requirements to the height of the double bottom. The height h_{DB} , in mm, measured from the keel line needs to be $h_{DB} = 1000 \cdot B/20$, where B is the breadth measured in mm. In this case, it follows that $h_{DB} = 1200$ mm. However, the minimum height allowed is 760 mm, and it does not need to be higher than 2000 mm (DNV 2021a). To account for accessibility and production, the height of the double bottom is set to 1600 mm.

3.2.2.2 Other general arrangement design features

The extent of the cargo area and the placement of the engine room bulkhead are based on general arrangements from similar ships found in various publications of *Significant Ships* published by The Royal Institution of Naval Architects, RINA. The vertical distance between the double bottom and the main deck is divided by a tween deck at height of 7 m. A superstructure is also drawn, where the height of the bridge deck and the conning station is chosen based on the requirements to visibility from the bridge specified in SOLAS chapter V Regulation 22. The view of the ship surface from the conning station is not to be obscured by more than two ship lengths or 500 m, whichever is less.

3.2.2.3 Cargo tanks

Gas carriers are in the IGC code divided into three types according to the products they are intended to carry and the hazards the products represent. The types are type 1G ship, type 2G/2PG ship and type 3G ship. A type 1G ship is a gas carrier intended to carry products considered to present the greatest overall hazard and types 2G/2PG and type 3G for

products of progressively lower hazards. Therefore, the rules regulating a type 1G ship will be the strictest regarding damage survivability and cargo tank location (DNV 2021b).

Section 19 rule 1.1 in DNV Rules for classification of Ships Pt. 5 Ch. 7 specifies the ship type that is required for the product it is intended to carry. For ammonia, type 2G is required. For carbon dioxide, type 3G is required. It then follows that the vessel is to be a type 2G ship because these rules are the strictest (DNV 2021b).

The location of the cargo tanks is regulated by the IGC code. When the rules in DNV Rules for classification of Ships Pt. 5 Ch. 7 is fulfilled, the rules in the IGC code are also fulfilled.

Section 2 rule 4.1.1.2 regulates the placement of cargo tanks for type 2G ships regarding minimum distances inboard. In this case the minimum distance from the keel is 1,6 m, and the minimum distance from the ship side is 1,03 m. The placement of the cargo tanks fulfills these requirements.

An evaluation of the cargo tanks is carried out. Since the liquid CO₂ is to be carried at -50 °C at a pressure of 7 bar, cylindrical horizontal type C tanks that can withstand this pressure is chosen as cargo tanks.

The cargo hold area is 105,6 m in length. When using three separate cargo tanks with horizontal distance of 1,8 m between them and a clearance of 1,8 m between the tanks and the fore and aft bulkhead forming the cargo hold area, the available length for the cargo tanks is 32,8 m per tank. The tanks are placed on top of the double bottom, and a radius of 7,5 m is set for the inner tank volume. The outer radius of the tanks is estimated to be 8 m.

3.2.3 Weight estimation

3.2.3.1 Weight calculation method

The weight estimation is done systematically in an Excel spreadsheet where each weight component is listed with its LCG, VCG and horizontal extent. The weights are grouped in the following different weight groups; steel hull, propulsion- and manoeuvring system, other main equipment, steel outfitting, systems, accommodation, miscellaneous and finally margins are added. The final weight estimation spreadsheet is shown in Appendix B.

In the first round of the design spiral the steel hull weights is calculated using areas measured from the general arrangement in *Autocad*, an estimated plate thickness and a structure factor to take care of stiffener dimensions. For equipment in the other weight categories, the weights are either assumed or found exact from data given by the

manufacturer. Examples are engine dimensions and weight from an engine manufacturer, or cargo tank dimensions and weight from a tank manufacturer.

3.2.3.2 Fuel weight

An early estimation on required fuel capacity based on engine power from similar ships, and the range of the ship is carried out. The engine power is estimated to 7200 kW. The range is set to be the distance of one full round trip, which is 4550 nm. The total energy consumption is calculated. The ships fuel is to be ammonia. However, since the specific ammonia consumption for a suitable ammonia fuelled engine is not yet known, the fuel estimation is done for HFO, and a SFOC of 180 g/kWh. A safety margin of 10% is added. Then the ratio between the energy density, in MJ/L, for HFO and liquid ammonia at -33°C is used to convert the required volume for HFO to the required volume for liquid ammonia. This ratio is $\frac{35}{12,7} = 2,756$ (MAN 2019). The required volume of ammonia fuel is estimated to be 1417 m³, which corresponds to 966 tons.

3.2.3.3 Cargo tank weight

The weight of the three cargo tanks needs to be estimated. From a list of MAN Cryo tank sizes the average weight per surface area is calculated to be 0,34 ton/m² (MAN 2016). This is used as a scaling factor to estimate the weight of the cargo tanks installed in the ship. The surface area per cargo tank is 824,4 m². It then follows that the weight of each cargo tank is estimated to 280 tons. This weight is used in the first round in the design spiral.

3.2.4 Hull structure

The hulls structural strength is evaluated at this stage in the design spiral. Based on both global design bending moments due to stillwater and wave bending moments, and local loads, the plating and stiffener dimensions in the hull is calculated. The structural design procedure described previously is used.

3.2.4.1 Stiffener topology

The ship is decided to be longitudinally stiffened. This is because it gives the hull a higher capacity against buckling due to longitudinal stresses. Further, the distance between stiffeners is set to $s = 600 \text{ mm}$ and the distance between girders is set to $l = 2400 \text{ mm}$, so that $\frac{s}{l} = 0,25$.

3.2.4.2 Design bending moments

The design bending moments consist of both stillwater moments and wave bending moments. The stillwater bending moments are taken as the bending moments calculated from the DNV rules, or as the bending moment taken from a critical loading condition, if that be greater. The stillwater bending moments calculated from the DNV Rules are the bending moments from the DNV Rules for classification of Ships Pt. 3 Ch.1 Sec. 5 rule B106 (DNV 2016). The bending moment from a critical loading condition is found from *Maxsurf Stability* where the ship is loaded so that the stillwater bending moment is maximized.

The wave bending moments are calculated from the DNV Rules for classification of Ships Pt. 3 Ch.1 Sec. 5 rule B201 (DNV 2016). Sagging and hogging moments are found for both stillwater bending moments and wave bending moments. The total design bending moments are summarised for both sagging and hogging moments separately below in Table 3.13.

Table 3.13 Design bending moments

	Sagging moments [kNm]	Hogging moments [kNm]
Stillwater from DNV rules	486 973 kNm	599 351 kNm
Stillwater from load case	938 817 kNm	998 619 kNm
Wave bending	824 108 kNm	711 729 kNm
Design bending moments	1 762 925 kNm	1 710 348 kNm

3.2.4.3 Critical cross section

The critical cross section is taken as the cross section amidships in the longitudinal direction. A simplification of this cross section used in the first round in the design spiral is illustrated in Figure 3.1.

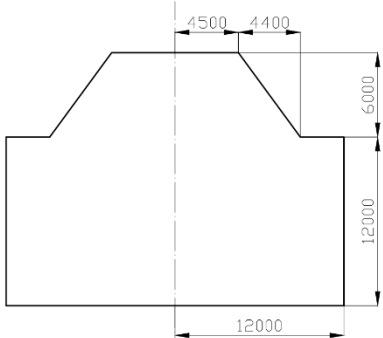


Figure 3.8 Critical cross section 1

3.2.4.4 Results

When the plating and stiffener dimension and cross section properties are calculated in an iterative process, the global longitudinal strength is evaluated. The requirement for the global longitudinal strength is satisfied when the maximum occurring stress level in the hull is below $175 \cdot f_1$, where f_1 is the material factor. The normal steel quality NV-NS with material factor $f_1=1,00$ is used. The plating and stiffener dimension also need to fulfil the local requirements

in DNV Rules for classification of Ships Pt. 3 Ch. 1 of 2016. The resulting plating and stiffener dimensions in the first round in the design spiral is shown in

Table 3.14 Resulting structure dimensions 1st round.

Category	Component	Dimensions [mm]	Type
Bottom structure	Plating	12	Plate
	Stiffeners	340 x 12	Holland profile
	Side girder	1000 x 12, 400 x 12	Web, Flange
	Centre girder	1000 x 12, 400 x 12	Web, Flange
Side structure	Plating	12	Plate
	Stiffeners	320 x 14	Holland profile
Deck structure	Plating	10	Plate
	Stiffeners	160 x 8	Holland profile
Tank casing sides	Plating	14	Plate
	Stiffeners	370 x 18	Holland profile
Tank casing top	Plating	20	Plate
	Stiffeners	370 x 18	Holland profile

Table 3.14 Resulting structure dimensions 1st round

3.2.5 Status

The first round in the design spiral is now completed. However, a stability analysis is not carried out. This is because an analysis of the cargo capacity shows that the total volume in the cargo tanks is not sufficient.

3.2.5.1 Cargo capacity analysis

When using three identical cargo tanks the required volume in each tank is $\frac{17000 \text{ m}^3}{3} = 5667 \text{ m}^3$. The tanks with the dimensions considered in section 3.2.2.3 are cylindrical without rounded ends. These tanks have a maximum capacity of 5680 m³, considering a permeability of 98 %. However, cylindrical type C tanks designed to withstand a pressure of 7 bar, needs to have rounded ends. Therefore, the volume capacity per tank is significantly lower than required.

Based on drawings of other cylindrical type C tanks, a cylindrical 32,8 meters long tank with rounded ends is modelled in *Maxsurf Modeler*. When this design is imported to *Maxsurf*

Stability, the volume capacity of this updated tank is calculated to be 5041 m³, which is 626 m³ less than required per tank.

Since the cargo capacity of the tanks is not sufficient, measures need to be taken. The cargo tanks need to be elongated. The extra length with a radius of 7,5 m needed for each tank is calculated by to be $\frac{5667 \text{ m}^3 - 5041 \text{ m}^3}{\pi * (7,5 \text{ m})^2 * 0,98} = 3,6 \text{ m}$ per tank. For three tanks a total extra length of 10,8 m is needed. The resulting inner tank dimensions is showed in Figure 3.9.

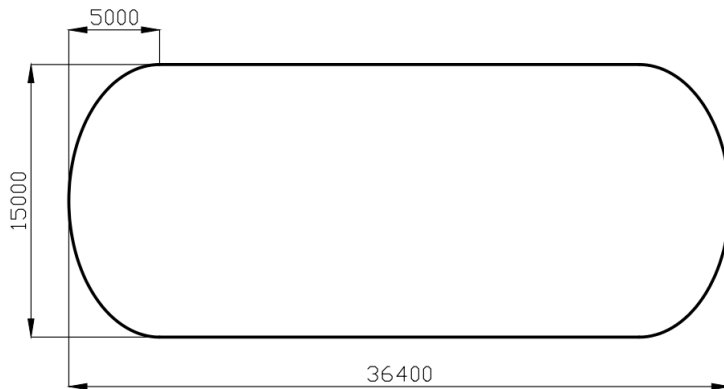


Figure 3.9 Inner cargo tank dimensions in millimetres

It is found from the general arrangement that there is not enough space in the cargo hold area for this increase in the cargo tank length. Consequently, the length of the ship is increased by 12 meters to an over all length of $L_{OA} = 162$ meters in order to fit three tanks with the new dimensions in the cargo hold area. The maximum length given in the project specifications in section 1.3.2.2 is 162 meters.

3.3 Design phase 3 The design spiral round 2 & 3

The workflow during the 2nd and 3rd round in the design spiral has not followed the design spiral chronologically step by step, but rather a more chaotic process has been used. As changes at one stage is made, the corresponding changes in the other stages in the design spiral is updated. An illustration of the process is shown in Figure 3.10.

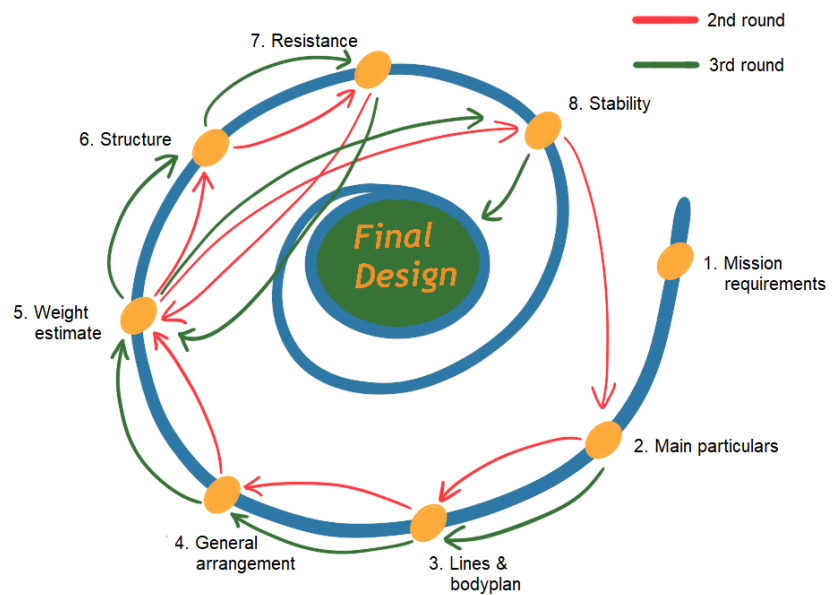


Figure 3.10 Design process phase 3

During this design phase, the major design changes are:

- A length increase to $L_{OA} = 162$ meters in order to fit the required cargo tanks.
- A freeboard increase to $D = 15$ meters in order to comply with stability criteria.

3.3.1 Main particulars

The main particulars used in the 2nd and 3rd round in the design spiral are listed in Table 3.15 below.

The change in the main particulars in the 2nd round is an increase in length to $L_{OA} = 162$ m, as discussed above. The length between the perpendiculars is increased accordingly to $L_{PP} = 157,4$ m. The breath, design waterline and depth are kept unchanged.

The stability analysis carried out in the 2nd round shows that some of the stability criteria is not fulfilled. Also, the ship floats on a deeper waterline than expected due to heavier lightship weight than expected. Therefore, the freeboard is increased to obtain better stability. The depth is increased to $D = 15$ m. The weight and stability in are discussed further in the following sections.

Table 3.15 Main particulars design phase 3

Dimension	2nd round	3rd round
Loa [m]	162,0 m	162,0 m
Lpp [m]	157,4 m	157,4 m
B [m]	24 m	24 m
T [m]	9,5 m	10,5 m
D [m]	12 m	15 m
C_B [-]	0,68	0,70

3.3.2 Lines plan

The hull modelled in *Maxsurf Modeler* is updated to the new length and block coefficient in the 2nd round in the design spiral. No further changes are made to the hull.

In the 3rd round in the design spiral, the depth of the modelled hull is increased to 15 meters. As discussed in the following sections, the ship floats on a deeper waterline than the design waterline in the 1st and 2nd round. Therefore, the design waterline in the 3rd round is set to $T = 10,5$ meters. Also, the aft ship section is updated due to an unacceptable high hull resistance. This is discussed later in section 3.3.6. The resulting block coefficient is 0,70.

3.3.3 General arrangement

Due to the length and depth increase, the general arrangement is updated accordingly. Other minor changes are also done. The rule length is now $L_F = 157,4$ meters. However, an increase in the amount of transverse watertight bulkheads is not needed, according to the DNV rules.

3.3.3.1 Double bottom

General arrangements from similar ships found in various publications of *Significant Ships* shows that these vessels are not fitted with a double bottom. A double bottom arrangement is normally required according to the SOLAS convention. However, “a double bottom need not to be fitted in way of watertight compartments used exclusively for the carriage of liquids, provided the safety of the ship in the event of a bottom damage is not thereby impaired” (DNV 2021a). Therefore, if it can be proven that the ship is capable of withstanding bottom damage, a double bottom need not to be fitted.

An analysis of the survivability of the ship when bottom damages is present is not carried out. However, it is assumed that in the case of bottom damages, the mounted cargo tanks will provide enough buoyancy so that the safety of the ship is not impaired. The double bottom is thereby removed from the general arrangement, which is updated accordingly. As a consequence, there is more available space for the cargo tanks.

3.3.3.2 Fuel tanks and the IGF Code

The fuel is earlier said to be liquid ammonia which is produced by Horisont Energi in Hammerfest. Information from Horisont Energi is that the ships can be fuelled at the ammonia loading port in Hammerfest. It is considered sufficient for the fuel capacity to be enough for one roundtrip with a 10 % margin added.

Since the ships fuel is ammonia, the regulations in the International Code of Safety for Ships Using Gases or Other Low-Flashpoint fuels i.e., the IGF-code, is applied. Part A-1 Regulation 5.3.3 in the IGF-Code states that the fuel tanks shall be protected from external damage caused by collision or grounding, and how the protective measures shall be taken (IMO-Vega n.d a). The minimum distance from the ship side, measured to the tank shell, is $B/5$ or 11,5 meters, whichever is less. Here B is the breadth of the ship. The minimum distance from the ship side is therefore $B/5 = 24/5 = 4,8$ meters. Due to lack of available space for the fuel tanks inside the ship hull, the fuel tanks are placed on the weather deck, as shown in the general arrangement provided in the appendices.

3.3.4 Weight estimate

The weight estimate is updated continuously as the general arrangement is changed. The weight of the hull is updated to contain the weight of the plating and stiffeners with the dimensions derived from the structural analysis in the previous round in the design spiral. Also, the areas from the updated general arrangement are used.

3.3.4.1 Cargo tank weight

The estimation of the cargo tank weight in the 1st round in the design spiral is considered to be a bit low. In an e-mail from MAN-Cryo it is communicated that the weight of a cylindrical type C tank with the dimensions as shown in Figure 3.9 might be approximately 500 tons. However, this estimated weight is not certain. This is the weight of each cargo tank used in the final weight estimation. A major contribution to why the ship is significantly heavier than estimated from the statistic comes from the heavy cargo tanks.

3.3.4.2 Fuel weight

The weight estimation is updated after the resistance analysis is done in both the 2nd and 3rd round in the design spiral. This is because from the resistance analysis the required break power and thereby the required fuel capacity is calculated. The lowered hull resistance due to the updated hull lines in the aft ship results in a lowered fuel consumption, and a lesser fuel capacity is required. The results from the resistance analysis are presented in Table 3.19 in section 3.3.6 below.

With data from the resistance analysis, the required fuel capacity is calculated in the following way. The total energy consumption for one roundtrip is calculated from the hull resistance, speed, and distance. The specific ammonia consumption for the engine installed is also needed. In an email from MAN Energy Solutions, it is communicated that the specific ammonia consumption for MAN B&W 2-stroke engines is approximately 370-380 g/kWh. A mean value of 375 g/kWh is used in the calculation. Then a 10 % safety margin is added. The resulting ammonia fuel capacity is listed in Table 3.16 below.

Table 3.16 Fuel capacity 2nd & 3rd round

Round in the design spiral	Break power [kW]	Fuel capacity [tons]
2nd	10 253,97 kW	1 295,99 tons
3rd	6 520,46 kW	824,11 tons

3.3.4.3 Fuel tank weight

The fuel is contained in six identical tanks located on the weather deck. From the list of MAN Cryo tank sizes a suitable tank is chosen. The volume per tank needed is 201 m³. One of the tanks in the list from MAN Cryo has a volume of 201 m³. These tanks are chosen to be the fuel tanks. They weigh 80 tons per tank (MAN 2016).

3.3.5 Hull Structure

The hull strength analysis is updated in both the 2nd and the 3rd round in the design spiral. The moulded depth increase to 15 meters in the 3rd round lead to a change in the cross section used in the calculations. Also, the inner ship sides forming the ballast tanks in the ship side is modelled in the cross section. This cross section is showed in Figure 3.11.

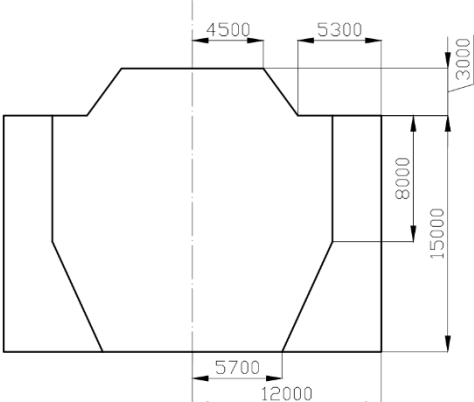


Figure 3.11 Critical cross section design spiral round 2 & 3

The design bending moments are kept unchanged. That is because the length used when calculating the bending moments from the DNV rules is the length between the perpendiculars after the length increase. Also, the bending moments from the critical loading conditions are kept unchanged because the bending moments are considered to be high enough.

Based on this new cross section, new dimensions in plate thickness and stiffeners are calculated. These are listed in Table 4.3 section 4.5.

3.3.6 Resistance analysis

The resistance analysis is carried out in *Maxsurf Resistance*. Here the modelled hull and the design waterline is imported. The input data to the calculation method for the 2nd and the 3rd round in the design spiral is listed in Table 3.17 and Table 3.18. The main difference here is the transom area and the transom waterline beam. The Holtrop resistance calculation method is used. The resulting resistance curves for power vs speed for the 2nd and 3rd round is shown in Figure 3.12 and Figure 3.13.

Table 3.17 Input data for resistance calculation 2nd round

	Item	Value	Units
1	LWL	160,899	m
2	Beam	23,723	m
3	Draft	10,5	m
4	Displaced volume	28086,314	m ³
5	Wetted area	5557,652	m ²
6	Prismatic coeff. (Cp)	0,805	
7	Waterpl. area coeff. (Cwp)	0,908	
8	1/2 angle of entrance	23,7	deg.
9	LCG from midships(+ve for	-2,652	m
10	Transom area	71,866	m ²
11	Transom wl beam	23,674	m
12	Transom draft	3,5	m
13	Max sectional area	216,906	m ²
14	Bulb transverse area	1,88	m ²
15	Bulb height from keel	9,5	m
16	Draft at FP	10,5	m
17	Deadrise at 50% LWL	7,6	deg.
18	Hard chine or Round bilge	Round bilge	
19			
20	Frontal Area	390	m ²
21	Headwind	0	kts
22	Drag Coefficient	1	
23	Air density	0,001	tonne/m
24	Appendage Area	288,56	m ²
25	Nominal App. length	32,55	m
26	Appendage Factor	2	
27			
28	Correlation allow.	0,0004	
29	Kinematic viscosity	0,000001188	m ² /s
30	Water Density	1,026	tonne/m

Table 3.18 Input data for resistance calculation 3rd round

	Item	Value	Units
1	LWL	160,899	m
2	Beam	23,671	m
3	Draft	10,5	m
4	Displaced volume	27978,638	m ³
5	Wetted area	5453,228	m ²
6	Prismatic coeff. (Cp)	0,803	
7	Waterpl. area coeff. (Cwp)	0,902	
8	1/2 angle of entrance	23,7	deg.
9	LCG from midships(+ve for	-2,181	m
10	Transom area	2,769	m ²
11	Transom wl beam	14,747	m
12	Transom draft	0,288	m
13	Max sectional area	216,654	m ²
14	Bulb transverse area	1,88	m ²
15	Bulb height from keel	9,5	m
16	Draft at FP	10,5	m
17	Deadrise at 50% LWL	7,5	deg.
18	Hard chine or Round bilge	Round bilge	
19			
20	Frontal Area	390	m ²
21	Headwind	0	kts
22	Drag Coefficient	1	
23	Air density	0,001	tonne/m
24	Appendage Area	288,56	m ²
25	Nominal App. length	32,55	m
26	Appendage Factor	2	
27			
28	Correlation allow.	0,0004	
29	Kinematic viscosity	0,000001188	m ² /s
30	Water Density	1,026	tonne/m

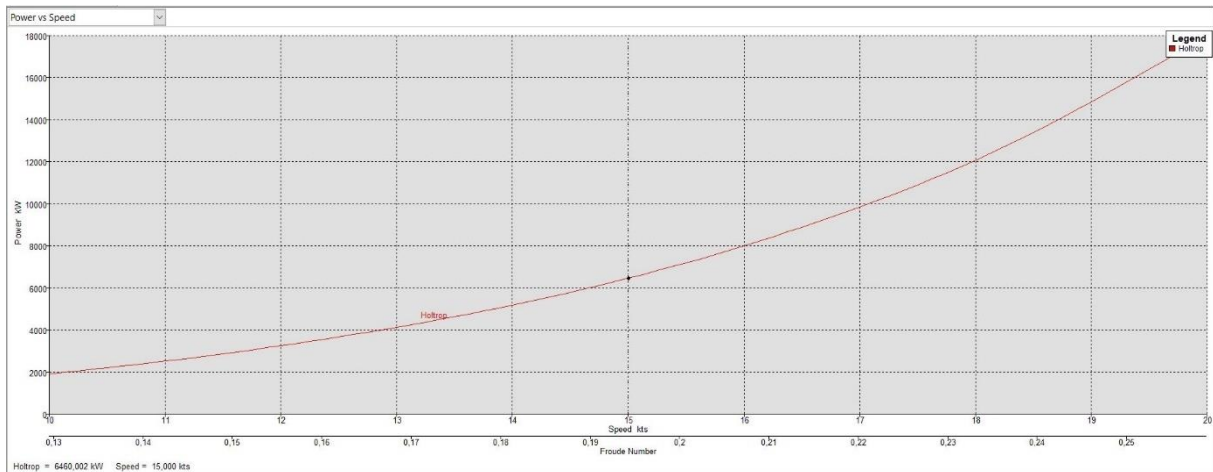


Figure 3.12 Resistance curve 2nd round

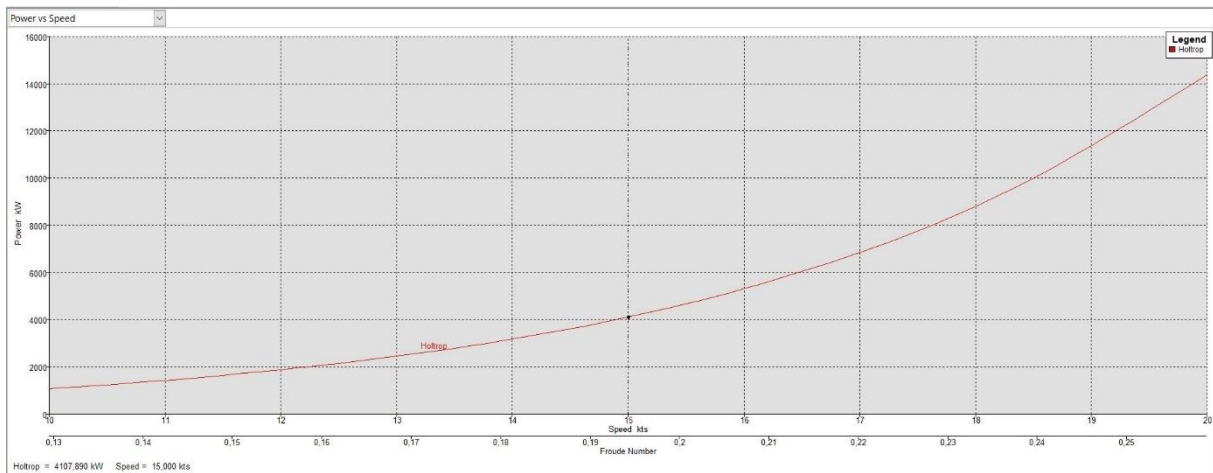


Figure 3.13 Resistance curve 3rd round

The reduced transom area as shown in Table 3.17 and Table 3.18 resulted in a significantly lowered resistance and consequently installed power, as shown in Figure 3.12 and Figure 3.13.

For the design speed at 15 knots, the results from the resistance analysis are shown in Table 3.19 below. The updated hull in the aft ship resulted in a reduction in the hull resistance by 36,4 %. To calculate the required break power delivered from the engine, the propulsion efficiency, η_D , of the propeller and mechanical efficiency, η_M , of the shaft and gearbox needs to be considered. The propeller efficiency is set to 66 %, and the mechanical efficiency is set to 96 %. A more detailed analysis of the efficiencies used in the resistance analysis is not carried out. The total efficiency, η_T , then becomes $\eta_T = \eta_D * \eta_M = 0,66 * 0,96 = 0,63$. With a total efficiency of $\eta_T = 0,63$, to propel the ship forwards at 15 knots, the required installed break power is 6520,46 kW, as shown in Table 3.19 below.

Table 3.19 Resistance analysis results

Round in the design spiral	Holtrop resistance [kN]	Power [kW], 100 % efficiency	Power [kW], 63 % efficiency
2nd	837,10 kN	6 460,00 kW	10 253,97 kW
3rd	532,30 kN	4 107,89 kW	6 520,46 kW

3.3.7 Stability

The final stage in the design spiral is a stability analysis. In *Maxsurf Stability*, stability for each loading condition is checked. The trim and draft are also checked. The loading conditions with description is listed in Table 3.20 below.

3.3.7.1 Loading conditions

The loading conditions are made from the lightship weight the deadweight. The deadweight is calculated by setting the fill percent in each of the modelled cargo and ballast water tanks. The fuel weights are added manually as individual weights. As a consequence of the fuel tanks being located on top of the weather deck, they could not be modelled as tanks in the hull in *Maxsurf Stability*.

Table 3.20 Loading conditions

Loading condition	Cargo	Fuel	Ballast
Lightship	No	No	No
Departure port CO ₂	CO ₂ , 100%	100%	1 530 tons
Departure port NH ₃	NH ₃ , 100%	100%	No
Arrival port CO ₂	CO ₂ , 100%	10%	1 682 tons
Arrival port NH ₃	NH ₃ , 100%	10%	No
Departure port ballast	No	100%	5 415 tons
Arrival port ballast	No	10%	6 515 tons

3.3.7.2 Draft

The analysis in the 2nd round in the design spiral showed that the vessel floats on a deeper waterline than expected from the statistics in the 1st round. The final weight of the ship in the departure port with CO₂ loading condition is 30 392 tons, an increase of 5 400 tons compared to the statistics. Therefore, the draft of the design waterline is increased, by 1 meter, to T_{DWL} = 10,5 meters.

3.3.7.3 Stability

The ships stability is checked to fulfil the requirements found in the IMO MSC.267(85) Code on Intact Stability Ch2 - General Criteria. This contains requirements to the area under the GZ curve. The stability criteria is listed in Table 3.21 below.

Table 3.21 IMO stability criteria

Criteria number	Criteria	Minimum value
2.2.1.a	Area 0 to 30 deg	3,1513 m.deg
2.2.1.b	Area 0 to 40 deg	5,1566 m.deg
2.2.1.c	Area 30 to 30 deg	1,7189 m.deg
2.2.2	Max GZ at 30 deg or greater	0,200 m
2.2.3	Angle of maximum GZ	25,0 deg
2.2.4	Initial GM _t	0,150 m
2.3	Severe wind and rolling	
	Angle of steady heel	Max 16,0 deg
	Angle of steady heel / deck immersion angle	Max 80 %
	Area1 / Area2	Min 100 %

The stability analysis in the 2nd round in the design spiral showed that the stability criteria was not fulfilled for the departure port with CO₂ loading condition. The criteria number 2.2.3.c, 2.2.2, and 2.2.3 failed by -29,80%, -5,00%, and -12,73% respectively. The resulting GZ curve for the loading condition after the 2nd round in the design spiral is shown in Figure 3.14 below.

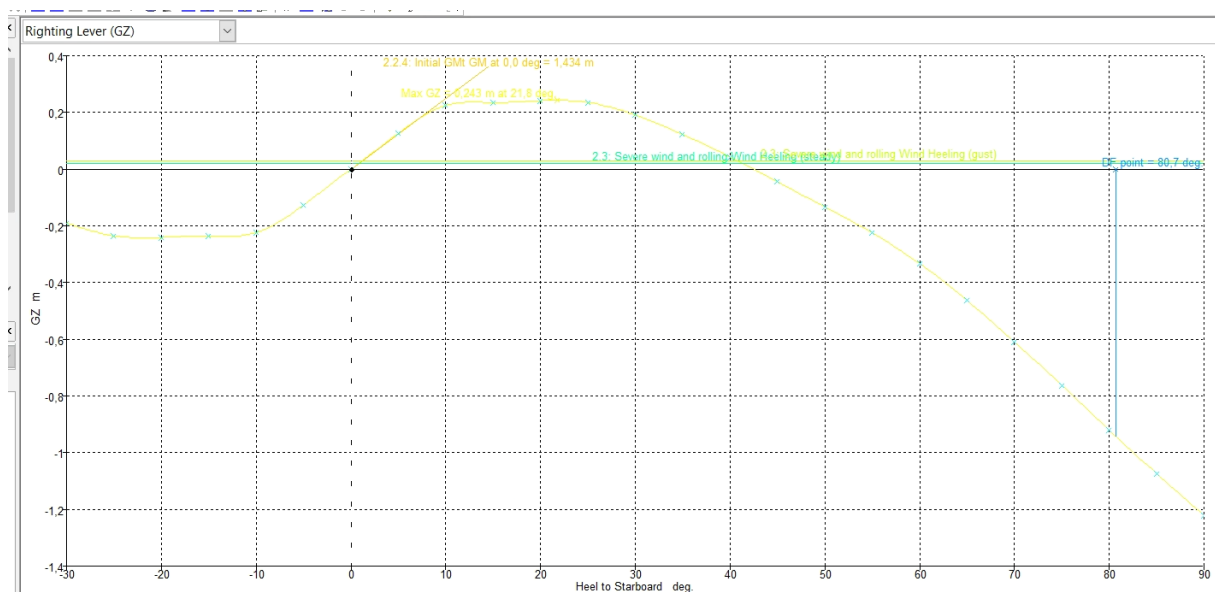


Figure 3.14 GZ curve for departure port CO₂ 2nd round

Since the stability criteria was not fulfilled, it was decided to increase the freeboard. The moulded depth was increased by 3 meters to $D = 15$ meters. This led to the stability criteria being fulfilled for all the loading conditions in the 3rd round in the design spiral.

3.3.7.4 Required freeboard

The required freeboard from the International Convention on Load Lines is calculated from regulation 28, 30, and 31 in Chapter 3 (IMO-Vega n.d b). The tabular freeboard for a type A ship with a length of 157 m is found to be 2 080 mm from regulation 28. A type A ship is a vessel designed to carry only liquid cargoes in bulk. A correction factor for the block coefficient is found using regulation 30. For a block coefficient of 0,7, the correction factor is 1,0147. Also, a correction for depth is found from regulation 31. With the rule length and depth of the ship as input, the correction becomes 1 127 mm. The resulting required freeboard then becomes

$$2\,080\text{ mm} * 1,0147 + 1\,127\text{ mm} = 3\,238\text{ mm}.$$

The freeboard when the ship is floating on the design waterline is

$$15\,000\text{ mm} - 10\,500\text{ mm} = 4\,500\text{ mm}.$$

The loading condition with the deepest waterline is the departure port with CO₂ loading condition, with a waterline at 11 000 mm. At this loading condition, the resulting freeboard is $15\,000\text{ mm} - 11\,000\text{ mm} = 4\,000\text{ mm}$. The ship therefore fulfils the tabular freeboard requirements in the International Convention on Load Lines.

3.4 Design phase 4 Energy source and propulsion system

According to the specifications given by Horisont Energi, the ship is to be a carbon emission free vessel. Therefore, traditional fuels like HFO, MDO, MGO, and LNG cannot be used. A discussion of alternative fuels and the propulsion systems is presented below.

3.4.1 Energy source

The maritime industry is currently facing a fuel transition from fossil fuels to non-fossil fuels. In order to tackle climate change, it is certain that this transition is coming. However, it is not certain which fuel we are transitioning to (DNV 2021c). It is not only sufficient to introduce fuels that have a zero or next to none GHG emissions when burned. The total CO₂ and GHG emissions during the fuel's lifecycle needs to be taken into account. In the DNV Maritime Forecast to 2050 report, this is referred to as tank-to-propeller emissions and well-to-tank emissions (DNV 2021c).

The well-to-tank perspective for the fuel is important. That is because the fuel's potential to reduce GHG emissions depends on the energy source, the fuel processing, and the supply chain (DNV 2021c). If a non-fossil fuel requires much energy in the production process, and is produced using energy from fossil-fuels, the reduction in lifecycle-GHG emissions is likely to be none or even negative. If a long and energy consuming supply chain is present, the reduction in GHG emissions might be considerably lower than expected. This shows that the total lifecycle-GHG emissions needs to be considered.

The DNV Maritime Forecast to 2050 states that the fuels need to be produced by either renewable energy sources or zero carbon energy sources. These primary energy sources can be categorized as (DNV 2021c):

- **Biofuels** from sustainable bioenergy sources
- **Electrofuels** from renewable electricity
- **Blue fuels** from reformed natural gas using CCS

The non-fossil fuels for future use discussed in the DNV Maritime Forecast to 2050 are ammonia, hydrogen, and methanol. These fuels are discussed as potential fuels to use for the vessel in this project. In Table 3.22 below, the fuels are listed with energy content, energy density, technology readiness level (TRL) for internal combustion engines (ICEs), and challenges. MGO is also included. The data is found in the MAN B&W two-stroke engine operating on ammonia (MAN 2020), and the DNV Maritime Forecast to 2050 (DNV 2021c). A description of the TRL levels is provided in Appendix C.

Table 3.22 Non-fossil fuel candidates

Fuel	Energy content, LHV [MJ/kg]	Energy density [MJ/L]	TRL	Challenges
Ammonia (NH ₃) (liquid, -33°C)	18,6	12,7	5-6	Toxicity, Combustion properties, N ₂ O emissions, Potential ammonia slip
Hydrogen (H ₂) (liquid, -253°C)	120	8,5	6-7	No class rules developed, Potential explosion risk, Very low boiling temperature
Methanol (CH ₃ OH) (65°C)	19,9	14,9	9	Not a fully carbon free fuel
MGO	42,7	35,7	9	A fossil-fuel

3.4.1.1 Methanol

Methanol is a promising future fuel for the maritime industry and can be produced from renewable feedstocks like bioenergy. Of the three non-fossil fuel candidates, methanol has the highest energy density. Also, the TRL for methanol is 9. The technology is ready for commercial application. Two-stroke methanol engines are commercially available (DNV 2021c). Despite these positive sides, methanol is not chosen as the fuel to be used. Methanol contains carbon, and CO₂ is produced in the combustion process.

3.4.1.2 Hydrogen

Hydrogen can be an electrofuel produced from electrolysis of water. When the electricity used comes from renewable sources, it becomes a carbon-neutral fuel.

Liquid hydrogen has a high energy content of 120 MJ/kg, however, the volumetric energy density of 8,5 MJ/L is very low. Therefore, for deep sea transport, the use of hydrogen is challenging due to the amount of storage space required. The fuel tank size needed for liquid hydrogen relative to MGO is 4,2 times the size, when considering energy density.

Because of the low ignition energy and the wide flammability range of hydrogen, there exists a potential risk of explosion. Hydrogen is also challenging to store in its liquid form due to its very low boiling temperature (DNV 2021c). Hydrogen is stored in its liquid form either at a high pressure of 250-700 bar or at very low temperatures of -253 °C. This is expensive and

volume intensive (DNV 2020), and makes it difficult to handle hydrogen both ashore and onboard. The TLR of hydrogen is 6-7.

The liquification process for hydrogen requires a lot of energy, because hydrogen is liquefied at -253 °C. The energy needed to liquefy hydrogen varies with the capacity of the liquefaction plant. For the largest liquefaction plants, with a capacity of 1000 kg/h, at least 30 % of the higher heating value (HHV) of hydrogen is needed. The energy needed increases with lowered liquefaction plant capacity. For small plants the energy used in the liquefaction process may even exceed the HHV of hydrogen (Ulf Bossel n.d). Hydrogen is not the chosen fuel for the ship in this project.

3.4.1.3 Ammonia

Safety and regulatory challenges, and challenges regarding storing large quantities of hydrogen onboard ships, have led to the exploration of alternative hydrogen based energy carriers such as ammonia (DNV 2021c).

There are some advantages to using ammonia compared to hydrogen. Ammonia has a volumetric energy density of 12,7 MJ/L, which is considerably higher than for hydrogen. When comparing the volumetric energy density of ammonia and MGO, it is found that a tank volume 2,8 times larger is needed to carry the same amount of energy in ammonia compared to MGO. The lower heating value of 18,6 MJ/kg is comparable to methanol (MAN 2020).

Ammonia can be stored at much higher temperatures than hydrogen. See Table 3.22. Therefore, it is less expensive and less complex to transport and store than hydrogen and other fuels in need of cryogenic temperatures (MAN 2020).

The lower explosion limit of ammonia at 15 % is higher than for hydrogen. The minimum ignition energy of ammonia is 8 mJ compared to 0,017 mJ for hydrogen (DNV 2020). Therefore, the lower risk of fire and explosion in ambient atmosphere for ammonia makes it safer to store in large quantities in terms of fire safety (MAN 2020).

Challenges related to ammonia as fuel include toxicity, combustion properties, nitrous oxide (N₂O) emissions, and potential ammonia slip (DNV 2021c). To manage the toxicity of ammonia, safety precautions need to be in place. It is vital to detect any leakages and direct these to a safe location. Double-walled design of fuel systems and piping is needed. Also, an ammonia capture system must be in place to prevent the release of ammonia to the surroundings (MAN 2020).

Ammonia has a low flame speed and narrow flammability range of 15-28 % (DNV 2020). Therefore, a low engine speed is needed to make time for the combustion to finish. Large dimensions lead to large volume-to-surface ratios, which are beneficial for a complete combustion (MAN 2020). Therefore, a large slow speed two-stroke combustion engine is suitable for burning ammonia.

The combustion of ammonia does not produce CO₂ because it does not contain carbon. However, there are other potential emissions to air gases. The NO_x levels produced in a two-stroke ammonia engine is expected to be in the range of a low-speed diesel engine. To reduce these emissions selective catalytic reduction (SCR) technology can be used. Ammonia, which is already carried as fuel, can be used as the catalytic agent (MAN 2020).

Other emissions to air that need to be minimized are ammonia slip and N₂O emissions. This is due to the toxicity of ammonia, and the high global warming potential of 265 (DNV 2020) for N₂O. These emissions can be minimized by ensuring a complete combustion of the ammonia fuel (MAN 2020). It is important that the introduction of a new non-fossil fuel to be used in the maritime sector does not arise new problematic emission problems for the shipping industry.

The TRL level for ammonia is estimated by DNV to be 5-6, which is a bit lower than for hydrogen and methanol. However, DNV has published the first-ever class rules for ammonia as fuel, in July 2021 (DNV 2021c).

The underlying reason for why this project is started, is because Horisont Energi is planning on producing ammonia from natural gas, using CCS, in Hammerfest. This makes the ammonia fuel a blue carbon-free fuel. It is also convenient to choose ammonia due to its availability at the production plant. As a consequence, the supply chain is super short and does not lead to any GHG-emissions, because transportation is not needed. This, combined with the facts discussed earlier in this chapter results in that ammonia, produced by Horisont Energi as a blue carbon-free fuel, is chosen as the fuel to be used in this project.

3.4.2 Propulsion system

The propulsion system on the ship in this project is considered to contain the systems from the main engine to the propeller and rudder. Sufficient propulsion and manoeuvrability, maximized efficiency, and power generation for electricity consumers and auxiliary systems are deciding factors when choosing the propulsion system. Efficiency is especially emphasised to keep the volume needed for the ammonia fuel to a minimum.

3.4.2.1 Main energy converter

The main energy converter is converting the chemical energy in the fuel to either rotational energy in the case of an ICE, or to electricity in the case of a fuel cell. DNV estimates the TRL for these ammonia energy converters to be 6-7. However, the fuel cell technology is generally less mature than ICEs. Fuel cells have yet to be commercially applied in shipping (DNV 2021c).

Two-stroke internal combustion engines are considered as the best energy converter due to large combustion chambers and long time scales with low RPM. This enables ammonia, with a slow burn rate to fully combust. Other advantages with ICEs compared to fuel cells is cost, power density, load response and robustness (DNV 2020).

MAN Energy Solutions is currently in a process of developing a two-stroke ammonia engine. In the *MAN B&W two-stroke engine operating on ammonia*, they write that “We will finalise the development process of the ammonia engine in 2021 and the commercial design verification is scheduled for 2023” (MAN 2020). Based on this a two-stroke ammonia engine is chosen as the main energy converter for the ship.

3.4.2.2 Power transmission

The power transmission from the engine to the propeller can either be mechanical through a shaft, or electrical. The highest transmission efficiency is obtained with a mechanical drive. Also, the arrangement of the engine room and propeller makes a mechanical transmission suitable, and an electrical transmission is not necessary. Therefore, a mechanical transmission through a shaft is chosen. Also, using a two-stroke slow speed ICE as a generator is not convenient due to the large dimensions and low RPM.

3.4.2.3 Propeller

The ship in this project has a relatively simple operational profile which mainly consists of time in transit, with a constant propulsion power demand, and time in harbour. A fixed pitch propeller is therefore favourable, due to a higher efficiency compared to a variable pitch propeller. Also, the number of propellers is evaluated. The highest efficiency is obtained with only one propeller. Therefore, one fixed pitch propeller is chosen to propel the ship. The aftship is designed so that one large propeller can be fitted. A bow thruster is fitted in the bow to obtain sufficient manoeuvrability.

3.4.2.4 Electricity production

Electricity is needed to power auxiliary systems like cargo handling systems, fuel supply systems, steering gear, bow thruster, and accommodation loads. Since the ship is to be a carbon emission free vessel, auxiliary diesel generators cannot be used.

As earlier mentioned, using slow speed two-stroke ICEs as auxiliary engines is not convenient. Four-stroke ICEs with smaller dimensions and higher RPM is more suitable. Wärtsilä have started developing a four-stroke ICE able to run on ammonia. Together with shipowners and energy companies, Wärtsilä plans to begin its first full scale, four-stroke engine tests in 2021 (Wärtsilä 2020). The product platform W31 provide modularity for the potential future conversion for ammonia use (DNV 2020). The Wärtsilä 31 product platform can be used as an auxiliary engine (Wärtsilä 2021), which is an electric power generator.

Another option for power generation is to use a shaft generator. The onboard electricity consumers have to be supplied with electric power with constant voltage and frequency by the shaft generator whilst RPM of the main engine changes (Wärtsilä n.d a). Therefore, a frequency converter is needed in the arrangement. Then the shaft generator and frequency converter combined can supply three-phase current with constant voltage and frequency. This is a PTO (power take out) system. Electric power generation from a shaft generator is a preferred solution because the main engine powering the generator and the propeller can be run at optimal RPM and loads. In this way the fuel consumption is minimized.

In the case where an ammonia fuelled four-stroke generator is commercially available, it could be beneficial to include both a shaft generator and an auxiliary ammonia generator. The auxiliary generator could be used to power cargo handling systems and accommodation when in harbour. Also, a PTI/PTH (power take in / power take home) system could be included in the machinery arrangement. Then the propeller could also be powered by the auxiliary generator. With this configuration redundancy is obtained, and the propeller could be powered by PTI/PTH in the case of main engine failure. This arrangement gives freedom in the power generation and distribution (Wärtsilä n.d a).

The discussion of the machinery arrangement above leads to the following choices. A two-stroke ammonia ICE will be the main energy converter to power the fixed pitch propeller through a mechanical shaft. A shaft generator is installed on the shaft between the main engine and the propeller. For power generation in harbour, and for redundancy, one or multiple auxiliary ammonia powered generators is included in the arrangement. A main switchboard is also needed for power distribution. Between the shaft generator and the main switchboard, a frequency converter is installed so that electric power with constant voltage

and frequency can be supplied to the main switchboard. The frequency converter is also used to power the PTI/PTO system in the shaft generator. Finally, the bow thruster is powered by electric current with the desired frequency from the frequency converter. The resulting machinery arrangement is illustrated below in Figure 3.15.

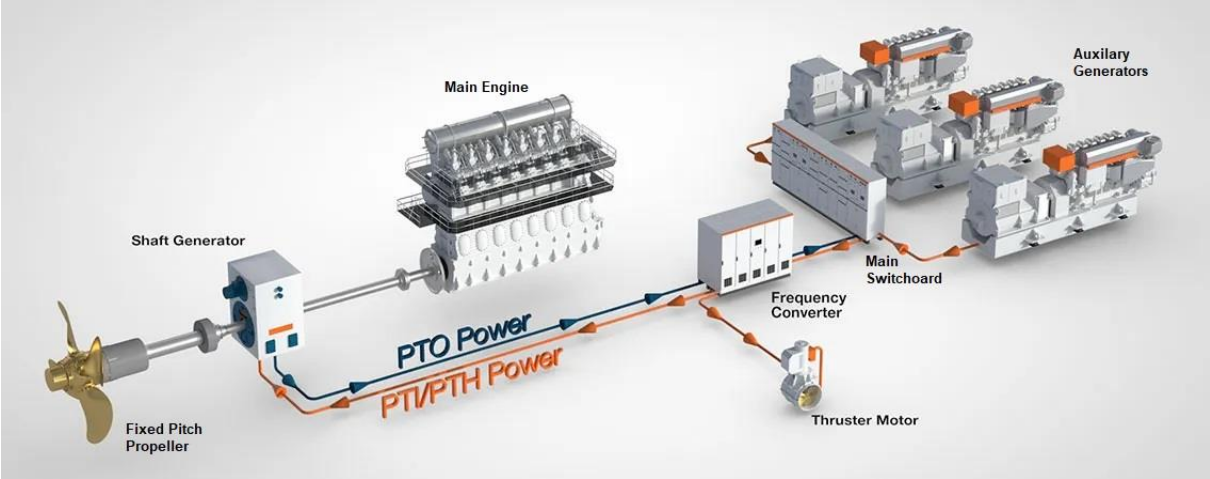


Figure 3.15 Machinery arrangement, (Wärtsilä n.d a)

The calculation of the required fuel capacity is done based on the power required to propel the ship at the design speed of 15 knots, and safety margin of 10% is added. The calculation does not consider the fuel consumption related to electric power generation. Therefore, the fuel capacity of the ship might not be sufficient. This problem could be solved by using boil of gas in the ammonia cargo tanks as fuel. Another option is to include ammonia bunkering in Rotterdam in the logistics. However, this problem is not further considered in this project.

4 Results

The final design in this Bachelor's thesis is a result from the mission requirements given by Horisont Energi after the completion of three rounds in the design spiral. The result is presented in the following sections.

4.1 Main Particulars

The final main particulars are listed below in Table 4.1. They are within the constraints given in the project specification.

Table 4.1 Final main particulars

DWT [ton]	20 018 ton
LWT [ton]	8 442 ton
Displacement [ton]	28 460 ton
L_{pp} [m]	157,4 m
L_{oa} [m]	162 m
B [m]	24 m
T [m]	10,5 m
D [m]	15 m
C_B [-]	0,70
L/B [-]	6,56
B/T [-]	2,29
B/D [-]	1,60
L/D [-]	10,49

4.2 Hull lines

A screenshot of the resulting hull shape is shown below in Figure 4.1. The final lines plan is also supplied in the appendices.

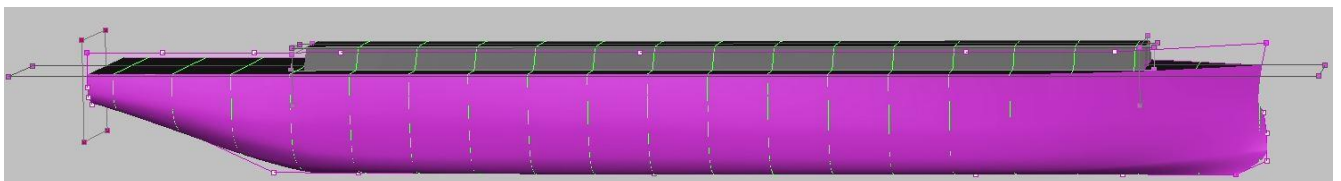


Figure 4.1 Final hull shape

A detailed modelling of a bulbous bow and a skeg is not done in this project due to lack of time and the fact that they are not considered to be of importance at this stage in the design

process. However, if there was time to complete a fourth round in the design spiral, it would be natural include a more detailed design of these elements.

4.3 General arrangement

The resulting general arrangement is supplied in the appendices. A screenshot of the profile view is shown in Figure 4.2 below. Also, a tank plan can be found in the appendices

Horizontal cylindrical type C tanks is chosen due to the design pressure of 7 bar. Also, a cylindrical shape is preferred due to the rapid purge technology that is to be used. The thickness of the tanks is estimated to be 500 mm, without a further tank structure analysis. There is a clearance of 1 000 mm from the outer tank walls to the surroundings.

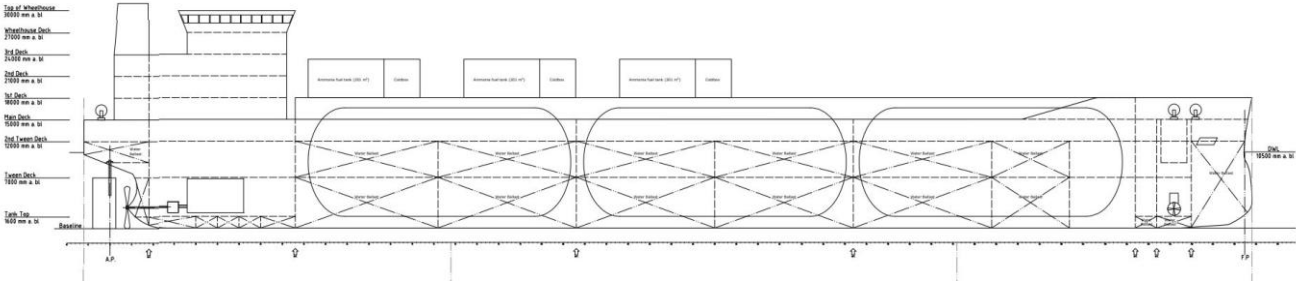


Figure 4.2 Profile view arrangement

4.4 Weight estimation

The final estimated LWT is 8 442 tons, which is 3 042 tons more than estimated from the statistics. As discussed earlier, a major contribution to this comes from the heavy cargo tanks. In Table 4.2 the weight of each weight group in the LWT is listed. Figure 4.3 shows the LWT distribution. The total weight of the cargo tanks is 1 500 tons. This is 75 % of the steel outfitting weight, and 18 % of the total LWT. The calculation spreadsheet in excel is supplied in the Appendix B.

Table 4.2 LWT weight groups

Weight group	Total weight
Steel hull	3 642,5 tons
Propulsion and manoeuvring system	236,5 tons
Other main equipment	126,0 tons
Steel outfitting	1 994,4 tons
Systems	747,0 tons
Accommodation	258,8 tons
Miscellaneous	30,0 tons
Margins	1 407,0 tons
Total LWT	8 442,3 tons

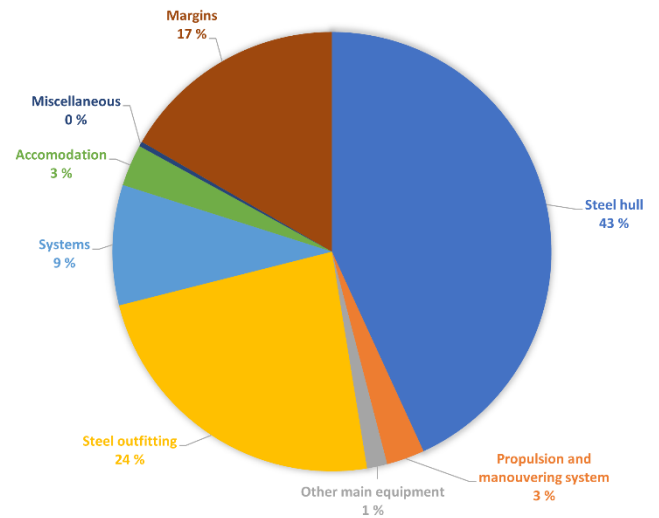


Figure 4.3 LWT distribution

4.5 Hull structure

The final hull structure is a result from the SDP method in round three in the design spiral, with input from the simplified critical cross section in Figure 3.11 and the design bending moments in Table 3.13. A screenshot of the cross-section frame with stiffeners is shown in Figure 4.4. The final structure dimensions are listed in Table 4.3.

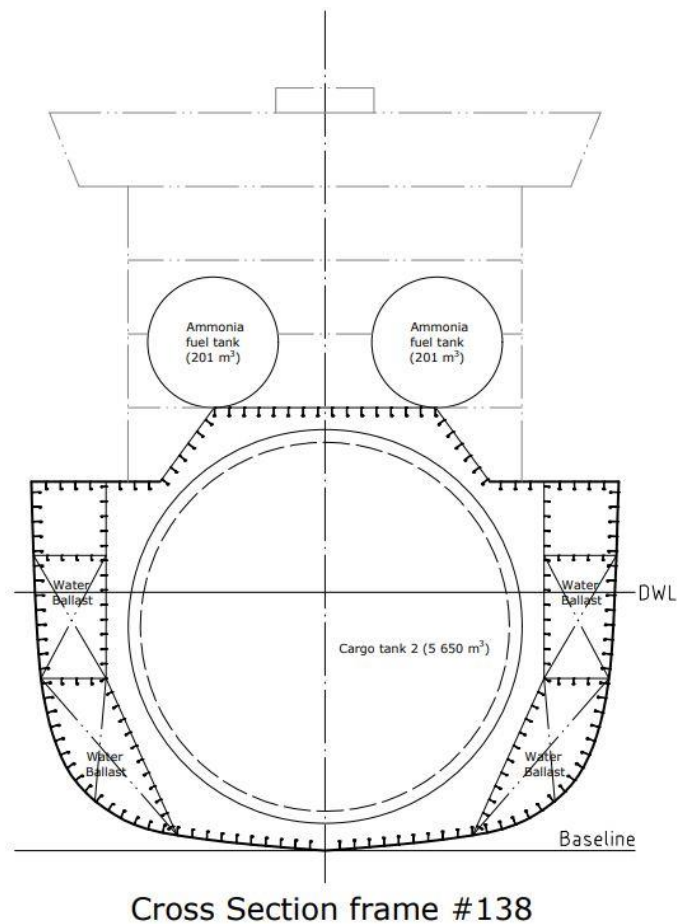


Figure 4.4 Resulting critical cross section

Table 4.3 Final structure dimensions

Category	Component	Dimensions [mm]	Type
Bottom structure	Plating	12	Plate
	Stiffeners	340 x 13	Holland profile
	Side girder	1000 x 12, 400 x 12	Web, Flange
	Centre girder	1000 x 12, 400 x 12	Web, Flange
Outer side structure	Plating	12	Plate
	Stiffeners	340 x 13	Holland profile
Inner side structure, lower	Plating	7	Plate
	Stiffeners	240 x 11	Holland profile
Inner side structure, upper	Plating	6	Plate
	Stiffeners	200 x 11	Holland profile
Deck structure	Plating	12	Plate
	Stiffeners	320 x 14	Holland profile
Tank casing sides	Plating	13	Plate
	Stiffeners	320 x 16	Holland profile
Tank casing top	Plating	17	Plate
	Stiffeners	340 x 16	Holland profile

4.6 Loading conditions

The seven loading conditions defined in *Maxsurf Stability* are presented in the following sections with displacement, draft, trim, still water moment, and a stability analysis. All the stability criteria in the IMO MSC.267(85) Code on Intact Stability Ch2 - General Criteria, listed in Table 3.21, are fulfilled for all the defined loading conditions. The defined weights, the resulting still water bending moments, stability report, and the GZ-curve for all loading conditions can be found in Appendix F. The amount of cargo, fuel and ballast are specified in Table 3.20.

4.6.1 LC Lightship

The main results from the hydrostatics, longitudinal strength and stability for the lightship loading condition are presented in Table 4.4 below.

Table 4.4 LC Lightship hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
8 442 tons	6,1 m	4,1 m	2,1 m	+3,9 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
413 517 kNm		Hogging moment		
Stability				
Initial GMt		Max GZ	Angle of max GZ	
3,30 m		1,05 m	28,2 deg	

The resulting waterline for the lightship loading condition is shown in Figure 4.5 below.

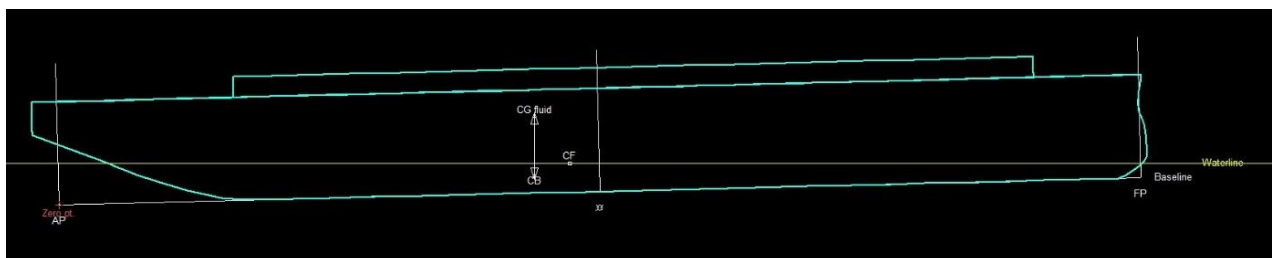


Figure 4.5 LC Lightship waterline

4.6.2 LC Departure Port CO₂

The main results from the hydrostatics, longitudinal strength and stability for the departure port with CO₂ loading condition are presented in Table 4.5 below.

Table 4.5 LC Departure Port CO₂ hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
30 392 tons	11,0 m	11,0 m	11,0 m	+0,0 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
166 360 kNm		Sagging moment		
Stability				
Initial GMt		Max GZ	Angle of max GZ	
1,38 m		0,62 m	25,9 deg	

The resulting waterline for the departure port with CO₂ loading condition is shown in Figure 4.6 below.

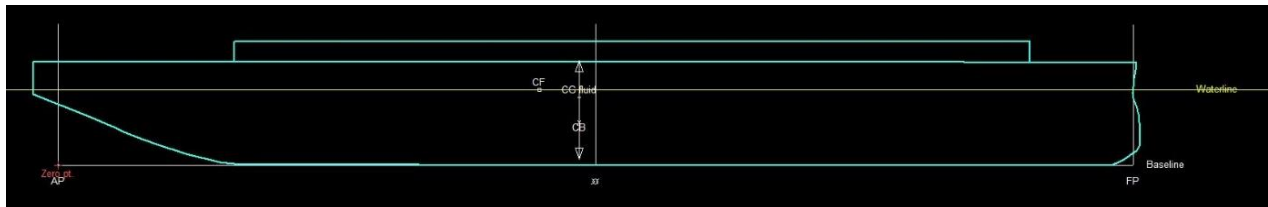


Figure 4.6 LC Departure Port CO₂ waterline

4.6.3 LC Departure Port NH₃

The main results from the hydrostatics, longitudinal strength and stability for the departure port with NH₃ loading condition are presented in Table 4.6 below.

Table 4.6 LC Departure Port NH₃ hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
20 845 tons	8,5 m	8,2 m	7,9 m	+0,6 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
92 379 kNm		Hogging moment		
Stability				
Initial GMt	Max GZ		Angle of max GZ	
0,89 m	0,87 m		38,2 deg	

The resulting waterline for the departure port with NH₃ loading condition is shown in Figure 4.7 below.

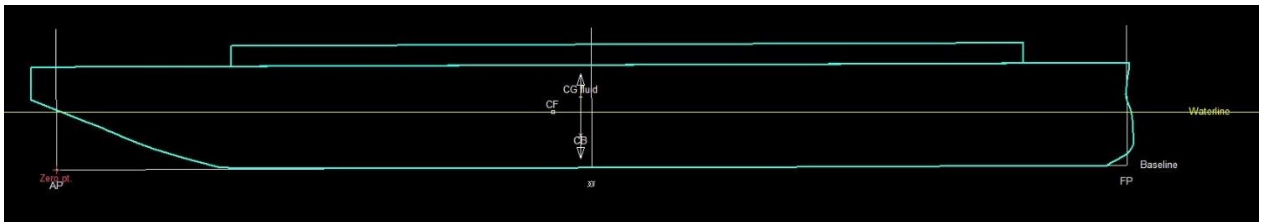


Figure 4.7 LC Departure Port NH₃ waterline

4.6.4 LC Arrival Port CO₂

The main results from the hydrostatics, longitudinal strength and stability for the arrival port with CO₂ loading condition are presented in Table 4.7 below.

Table 4.7 LC Arrival Port CO₂ hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
29 785 tons	10,7 m	10,8 m	10,9 m	-0,2 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
115 591 kNm		Sagging moment		
Stability				
Initial GMt		Max GZ	Angle of max GZ	
1,66 m		0,78 m	28,6 deg	

The resulting waterline for the arrival port with CO₂ loading condition is shown in Figure 4.8 below.

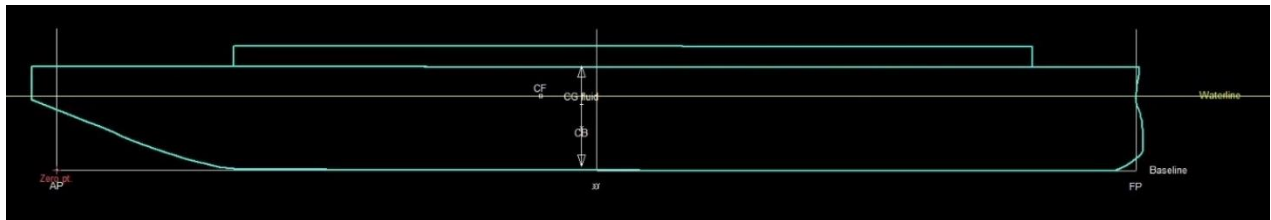


Figure 4.8 LC Arrival Port CO₂ waterline

4.6.5 LC Arrival Port NH₃

The main results from the hydrostatics, longitudinal strength and stability for the arrival port with NH₃ loading condition are presented in Table 4.8 below.

Table 4.8 LC Arrival Port NH₃ hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
20 086 tons	8,1 m	8,0 m	7,8 m	+0,3 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
123 564 kNm		Hogging moment		
Stability				
Initial GMt	Max GZ		Angle of max GZ	
1,29 m	1,15 m		40,0 deg	

The resulting waterline for the arrival port with NH₃ loading condition is shown in Figure 4.9 below.

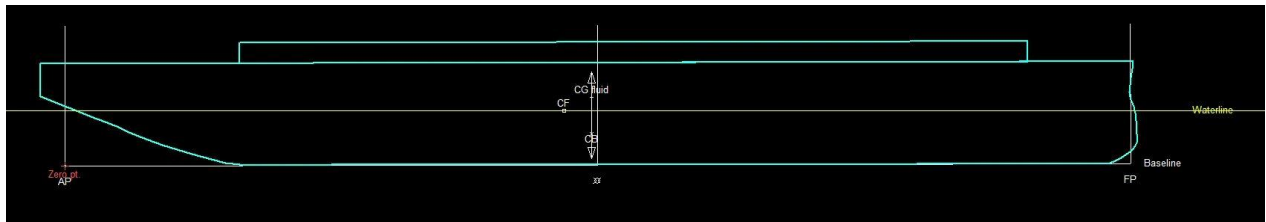


Figure 4.9 LC Arrival Port NH₃ waterline

4.6.6 LC Departure Port Ballast

The main results from the hydrostatics, longitudinal strength and stability for the departure port with ballast loading condition are presented in Table 4.9 below.

Table 4.9 LC Departure Port Ballast hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
14 701 tons	7,2 m	6,2 m	5,3 m	+2,0 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
224 258 kNm		Hogging moment		
Stability				
Initial GMt		Max GZ	Angle of max GZ	
2,23 m		1,60 m	45,0 deg	

The resulting waterline for the departure port with ballast loading condition is shown in Figure 4.10 below.

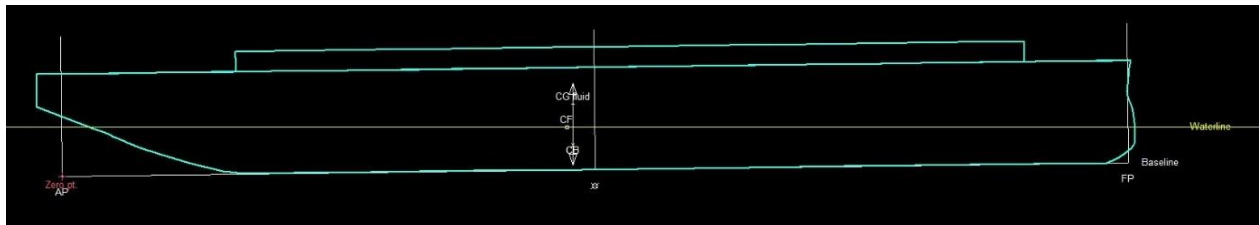


Figure 4.10 LC Departure Port Ballast waterline

4.6.7 LC Arrival Port Ballast

The main results from the hydrostatics, longitudinal strength and stability for the arrival port with ballast loading condition are presented in Table 4.10 below.

Table 4.10 LC Arrival Port Ballast hydrostatics, longitudinal strength, and stability

Hydrostatics				
Displacement	Draft at AP	Draft Amidships	Draft at FP	Trim
15 042 tons	7,7 m	6,3 m	5,0 m	+2,7 m
Longitudinal Strength				
Stillwater bending moment		Type of bending moment		
204 684 kNm		Hogging moment		
Stability				
Initial GMt	Max GZ		Angle of max GZ	
2,81 m	2,02 m		45,9 deg	

The resulting waterline for the arrival port with ballast loading condition is shown in Figure 4.11 below.

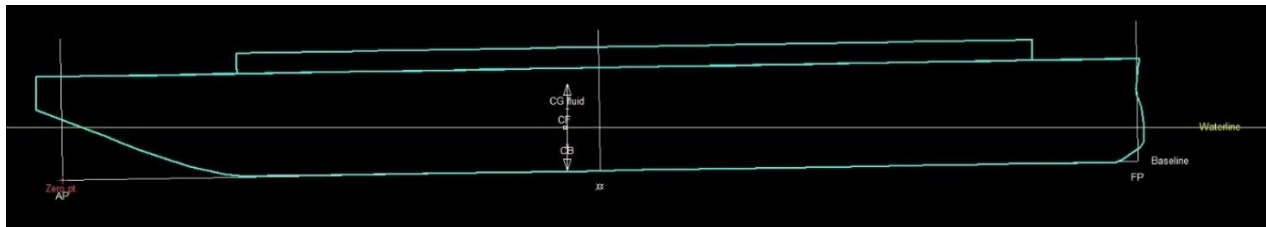


Figure 4.11 LC Arrival Port Ballast waterline

5 Conclusion

The result in this project is a ship design that fulfils the specifications and mission requirements given by Horisont Energi. The transport logistics analysis showed that three ships are needed to annually transport the amount of cargo as specified. The ships are designed for a design speed of 15 knots. However, the speed used in the logistics is 13 knots. After the completement of three rounds in the design spiral, the final ship design is a design that complies with IMO stability regulations. Also, the maximum cargo capacity is 16 950 m³, which is 30 m³ more than required from the logistics analysis. This makes the three ships and their final design capable of annually transporting the required amount of cargo.

Acronyms and Nomenclature

Acronyms

AP	Aft perpendicular
CCS	Carbon capture and storage
CO₂	Carbon dioxide
DWT	Deadweight
FP	Fore perpendicular
GHG	Greenhouse gas
HE	Horisont Energi
HFO	Heavy fuel oil
HFO	Heavy fuel oil
HHV	Higher heating value
ICE	Internal Combustion Engine
IMO	International Maritime Organization
LCB	Longitudinal centre of buoyancy
LCG	Longitudinal centre of gravity
LHV	Lower heating value
LNG	Liquefied natural gas
LPG	Liquefied petroleum gas
LWT	Lightweight
MGO	Marine gas oil
N₂O	Nitrous Oxide
NH₃	Ammonia
PTH	Power take home

PTI	Power take in
PTO	Power take out
SCR	Selective Catalytic Reduction
SDP	Structural design procedure
SFOC	Specific fuel oil consumption
SOLAS	Safety of Life at Sea
VCG	Vertical centre of gravity

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Appendix A

High Season - 3 ships												
Leg	Cargo	Loading rate [m3/h]	Loading time [h]	Volume cargo [m3]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]		
Loading Hammerfest	NH3	1200	8	9600	6547,2				8,0		219806	
Hammerfest - Rotterdam	NH3				6547,2	1400		13	115,7	4,8		
Unloading Rotterdam	NH3	1200	8	-9600	-6547,2				123,7	5,2		
Rotterdam - Stockholm	Purging				0	1050		13	204,5	8,5		
Loading Stockholm	CO2	1200	14,1	16920	19542,6				218,6	9,1		
Stockholm - Hammerfest	CO2				19542,6	2100		13	380,1	15,8		
Unloading Hammerfest	CO2	1200	14,1	-16920	-19542,6				394,2	16,4		
Purging Hammerfest	Purging		24		0				418,2	17,4		
Arrival period [days]		5,81		19516		11,2		33,6 NH3		33816		219806
CO2 in storage [ton]		8,7		19479		3,9		7,8 NH3		60676		151691
CO2												
Low Season - 2 ships												
Leg	Cargo	Loading rate [m3/h]	Loading time [h]	Volume cargo [m3]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]		
Loading Hammerfest	NH3	1200	13	15600	10639,2				13,0	0,5		
Hammerfest - Rotterdam	NH3				10639,2	1400		11,8	131,6	5,5		
Unloading Rotterdam	NH3	1200	13	-15600	-10639,2				144,6	6,0		
Rotterdam - Stockholm	Purging				0	1050		11,8	233,6	9,7		
Loading Stockholm	CO2	1200	14,1	16920	19542,6				247,7	10,3		
Stockholm - Hammerfest	CO2				19542,6	2100		11,8	425,7	17,7		
Unloading Hammerfest	CO2	1200	14,1	-16920	-19542,6				439,8	18,3		
Purging Hammerfest	Purging		24						463,8	19,3		
Arrival period [days]		9,66		19479		3,9		7,8 NH3		33033		82582
CO2 in storage [ton]		8,7		19479		3,9		7,8 NH3		60676		151691
CO2												
Off Season - 1 ship												
Leg	Cargo	Loading rate [m3/h]	Loading time [h]	Volume cargo [m3]	Weight cargo [ton]	Distance [nm]	Speed [kn]	Voyage time [h]	Accumulated voyage time [h]	Accumulated voyage time [days]		
Loading Hammerfest	NH3	1200	14,1	16920	11539,44				14,1	0,6		
Hammerfest - Rotterdam	NH3				11539,44	1400		12,7	124,3	5,2		
Unloading Rotterdam	NH3	1200	14,1	-16920	-11539,44				138,4	5,8		
Rotterdam - Hammerfest	No cargo				0	1400		12,7	248,7	10,4		
Arrival period [days]		10,4		0		8,7		8,7 NH3		33411		100233
CO2 in storage [ton]		8,7		0		8,7		8,7 NH3		0		0
CO2												

Costings		
Cargo	Cost per ton trsp [\$/ton]	Total project cost 15 years [€]
NH3	\$ 43,43	\$ 664 241 268
CO2	\$ 43,30	\$ 664 241 268

Total cargo transported per year		
Transported cargo	per year [ton]	
NH3	402621	
CO2	807784	

Steel weight calculation - aftship section

Project Bacheloroppgave NH3/CO2 combination carrier
Date: 17.11.2021
By: A.Torheim

* LCG's measured from AP
* VCG's measured from Baseline

Item	Quantity	Unit weight [t]	Total weight [t]	LCG [m]	VCG [m]	LMOM [tm]	VMOM [tm]	Comment
Tween deck	1	53,27	53,3	18,20	7,00	970	373	627,6 m ² , 10,61 mm
2nd tween deck	1	69,72	69,72	15,08	12,00	1051,3776	836,64	830 m ² , 7 mm, faktor 1.5
Main deck	1	164,81	164,8	17,33	15,00	2856	2472	931,8 m ² , 22,11 mm
Aft peak bulkhead	1	18,50	18,5	5,40	8,50	100	157	206 m ² , 8 mm, faktor 1.4
Engine room bulkhead	1	26,20	26,2	25,80	6,50	676	170	292 m ² , 8 mm, faktor 1.4
			0,0			0	0	
			0,0			0	0	
Sum without margins			332,5	17,00	12,06	5653	4009	

Steel weight calculation - midship section

Project Bacheloroppgave NH3/CO2 combination carrier
Date: 17.11.2021
By: A.Torheim

* LCG's measured from AP
* VCG's measured from Baseline

Item	Quantity	Unit weight [t]	Total weight [t]	LCG [m]	VCG [m]	LMOM [tm]	VMOM [tm]	Comment
Tween deck	1	30,14	30,1	80,99	7,00	2441	211	355,2 m ² , 10,61 mm
2nd tween deck	1	33,70	33,70	81,50	12,00	2746,55	404,4	401,2 m ² , 7 mm, faktor 1.5
Main deck	1	127,55	127,6	82,20	15,00	10485	1913	721,1 m ² , 22,11 mm
Bulkhead 1	1	28,90	28,9	64,80	5,80	1873	168	323 m ² , 8 mm, faktor 1.4
Bulkhead 2	1	28,90	28,9	103,20	5,80	2982	168	323 m ² , 8 mm, faktor 1.4
			0,0			0	0	
			0,0			0	0	
Sum without margins			249,2	82,38	11,49	20527	2864	

Steel weight calculation - foreship section

Project Bacheloroppgave NH3/CO2 combination carrier
Date: 17.11.2021
By: A.Torheim

* LCG's measured from AP
* VCG's measured from Baseline

Item	Quantity	Unit weight [t]	Total weight [t]	LCG [m]	VCG [m]	LMOM [tm]	VMOM [tm]	Comment
Tween deck	1	5,31	5,3	137,66	7,00	731	37	62,54 m ² , 10,61 mm
2nd tween deck	1	17,27	17,27	139	12	2400,53	207,24	205,6 m ² , 7 mm, faktor 1.5
Main deck	1	57,52	57,5	135,60	15,00	7800	863	325,2 m ² , 22,11 mm
Bulkhead 3	1	17,00	17,0	142,20	6,70	2417	114	189,8 m ² , 8 mm, faktor 1.4
Bulkhead 4	1	14,00	14,0	145,20	6,90	2033	97	156,2 m ² , 8 mm, faktor 1.4
Collision bulkhead	1	9,00	9,0	150,00	7,10	1350	64	100,6 m ² , 8 mm, faktor 1.4
			0,0			0	0	
			0,0			0	0	
Sum without margins			120,1	139,31	11,50	16731	1382	

Steel weight calculation - superstructure

Project Bacheloroppgave NH3/CO2 combination carrier
Date: 17.11.2021
By: A.Torheim

* LCG's measured from AP
* VCG's measured from Baseline

Item	Quantity	Unit weight [t]	Total weight [t]	LCG [m]	VCG [m]	LMOM [tm]	VMOM [tm]	Comment
Deck 1	1	66,4	66,4	12,90	15,00	857	996	791 m ² , 7 mm, faktor 1.5
Deck 2	1	30,4	30,4	13,30	18,00	404	547	362 m ² , 7 mm, faktor 1.5
Deck 3	1	30,4	30,4	13,20	21,00	401	638	362 m ² , 7 mm, faktor 1.5
Deck 4	1	30,4	30,4	13,20	24,00	401	730	362 m ² , 7 mm, faktor 1.5
Wheelhouse deck	1	23,2	23,2	17,70	27,00	411	626	276 m ² , 7 mm, faktor 1.5
Wheelhouse top	1	30,5	30,5	17,70	30,00	540	915	363 m ² , 7 mm, faktor 1.5
						0	0	
Front bulkhead	1	12,0	12,0	24,60	21,00	295	252	192 m ² , 6 mm, faktor 1.3
Side bulkheads	1	32,1	32,1	13,40	20,50	430	658	515 m ² , 6 mm, faktor 1.3
Aft bulkheads lower	1	9,0	9,0	0,60	19,50	5	176	144 m ² , 6 mm, faktor 1.3
Aft bulkheads upper	1	3,0	3,00	10,80	25,50	32	77	48 m ² , 6 mm, faktor 1.3
Wheelhouse bulkheads	1	14,5	14,5	17,70	28,50	257	413	232 m ² , 6 mm, faktor 1.3
Funnel above superstructure	1	7,7	7,7	3,30	27,50	25	212	123 m ² , 6 mm, faktor 1.3
Funnel inner bulkheads	1	7,6	7,6	3,70	19,50	28	148	122 m ² , 6 mm, faktor 1.3
Sum without margins			297,2	13,75	21,49	4087	6388	

Appendix C

For technology readiness level (TRL), the following definitions apply (EU)

- TRL 1 - basic principles observed
- TRL 2 - technology concept formulated
- TRL 3 - experimental proof of concept
- TRL 4 - technology validated in lab
- TRL 5 - technology validated in relevant environment (industrially relevant environment in the case of key enabling technologies)
- TRL 6 - technology demonstrated in relevant environment (industrially relevant environment in the case of key enabling technologies)
- TRL 7 - system prototype demonstration in operational environment
- TRL 8 - system complete and qualified
- TRL 9 - actual system proven in operational environment (competitive manufacturing in the case of key enabling technologies; or in space)

Source: (DNV, 2021c)

Appendix E

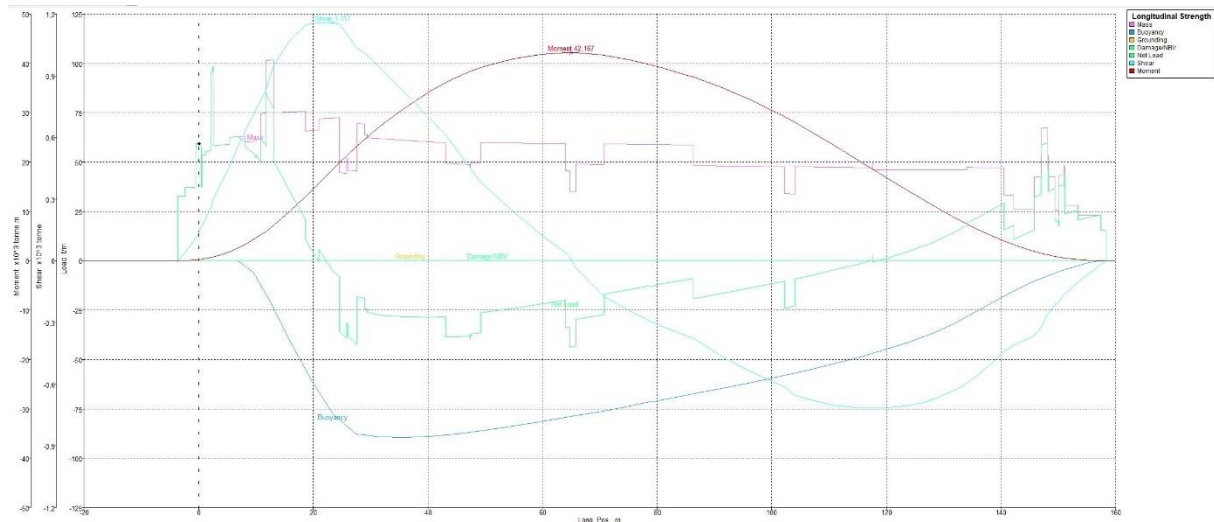
Styrkeberegning CO2/NH3 carrier											
					s [mm]	600		s/l		0,25	
					l [mm]	2400					
					Design Bending moments						
					Parametere		Cw	9			
							L	157,4			
							B	24			
							Cb	0,7			
							alpha	1			
					Stillwater		Regelmoment		Moment fra kritisk lastkondisjon		
					Ms sagging [kNm]		-486973	-938817			
					Ms hogging [kNm]		599351	998619			
					Wave loads						
					Mw sagging [kNm]		-824108				
					Mw hogging [kNm]		711729				
					Total Design Bending moments						
					M_design_sag		1762925				
					M_design_hog		1710348				
					Beregning NA						
					Element		Areal [mm^2]	Lokal NA abbl [mm]	Tregghetsmoment [mm4]		
L [m]					157,4		Bunn	268480	11,19	1,70E+13	
B [m]					24		TT	0	0	0	
T [m]					10,5		Dekk	117174,1667	14988,95	5,77E+12	
D [m]					15		Side ytre	335600	7500	4,17E+12	
Flytspenning [MPa]					235		Side indre nedre	98633,88408	3500	1,97E+12	
Sikkerhetsfaktor mot flyt					1,5		Side indre øvre	53050	9500	1,24E+11	
Cb					0,7		Sidebærer	16800	615	9,42E+11	
hdb					1000 dobbelbunnshøyde		Senterbærer	16800	615	9,42E+11	
					Bredde dekk 5300 m		Tank hus side	89936,20	16500	6,60E+12	
							Tank hus top	130830,00	17985,46	1,31E+13	
f1					1,00					5,07E+13	
Bunn							NA		mm abbl		7969
t_0_bunn					mm 12		Tregghetsmoment		Halve tv.snitt		5,07E+13
stdim_bunn					mm2 6224 HP 340 x 13		I		Hele tv.snitt		1,01E+14
t_eqv_bunn					mm 22,37333		Motstandsmoment				
							Z_bunn		mm3		1,27E+10
							Z_dekk		mm3		1,44E+10
							Z_tank_hus_top		mm3		1,01E+10
Side bærer							Sigma_max_bunn		MPa		138,68
t_0_SidBaer					mm 12		Sigma_max_dekk		MPa		122,37
Høyde					mm 1000		Sigma_max_tank_hus_top		MPa		174,57
Bredde flens					mm 400		Spenningsfaktor f2				
Senter bærer							f2_bunn				0,79047008
t_0_SentBaer					mm 12		f2_dekk				0,697480568
Høyde					mm 1000		F2_tank_hus_top				0,995070697
Bredde flens					mm 400						
Skuteside ytre											
t_0_SkutSid_y					mm 12						
stdim_SkutSid_y					mm2 6224 HP 340 x 13						
t_eqv_SkutSid_y					mm 22,37333						
Skuteside indre nedre											
t_0_SkutSid_i_n					mm 7						
stdim_SkutSid_i_n					mm2 3489 HP 240 x 11						
t_eqv_SkutSid_i_n					mm 12,815						
Skuteside indre øvre											
t_0_SkutSid_i_o					mm 6						
stdim_SkutSid_i_o					mm2 2766 HP 200 x 11						
t_eqv_SkutSid_i_o					mm 10,61						
Dekk 15m											
t_0_Dekk					mm 12						
stdim_Dekk					mm2 6065 HP 320 x 14						
t_eqv_Dekk					mm 22,108						
Tank hus side											
t_0_Tk_hus_sid					mm 13						
stdim_Tk_hus_sid					mm2 6705 HP 320 x 16						
t_eqv_Tk_hus_sid					mm 24,175						
Tank hus top											
t_0_Tk_hus_top					mm 17						
stdim_Tk_hus_top					mm2 7244 HP 340 x 16						
t_eqv_Tk_hus_top					mm 29,07333						

Lokale krav basert på f2											
Bunn og dobbeltbunn			137,2542								
C 701 Bottom longitudinals											
p	kN/m2	126,9818									
Sigma	N/mm2	1,22E+02	max 160*f	160							
Z	cm3	298,0 OK									
C 302 Bottom plating			304 not be less than								
p	kN/m2	126,9818	t	11,3 OK							
Sigma	N/mm2	120									
ka		1,076406									
t	mm	10,5									
Sider											
C 101 Side plating											
Sigma_bunn	N/mm2	120									
Sigma_dekk	N/mm2	120									
Sigma_tkhutp	N/mm2	95,64									
t_bunn	mm	10,5									
t_dekk	mm	4,4									
t_tkhutp	mm	3,3									
C 301 Longitudinals											
Sigma_bunn	N/mm2	122,24	max 160*f	160							
Sigma_dekk	N/mm2	305,01	max 160*f	160							
Sigma_tkhutp	N/mm2	387,84	max 160*f	160							
Z_bunn	cm3	298,0 OK	min	15							
Z_dekk	cm3	40,9 OK	min	15							
Z_tkhutp	cm3	18,3 OK	min	15							
Dekk											
C 102 deck plating			Strength deck								
p	kN/m2	22,8	C 104 not be less than	t	8,6 OK						
Sigma	N/mm2	120									
t	mm	4,4									
C 301 Longitudinals											
p	kN/m2	22,8									
Sigma	N/mm2	134,3275	max 160*f1	160							
Z	cm3	48,7 OK	min	15							
Tank hus											
C202 deck plating above strength deck, minimumskrav til t											
t	mm	5,5 OK									
C301 Longitudinals for tank hus											
p	kN/m2	5									
Sigma	N/mm2	95,64081	max 160*f1	160							
Z	cm3	15,0	min	15 OK							

Appendix F

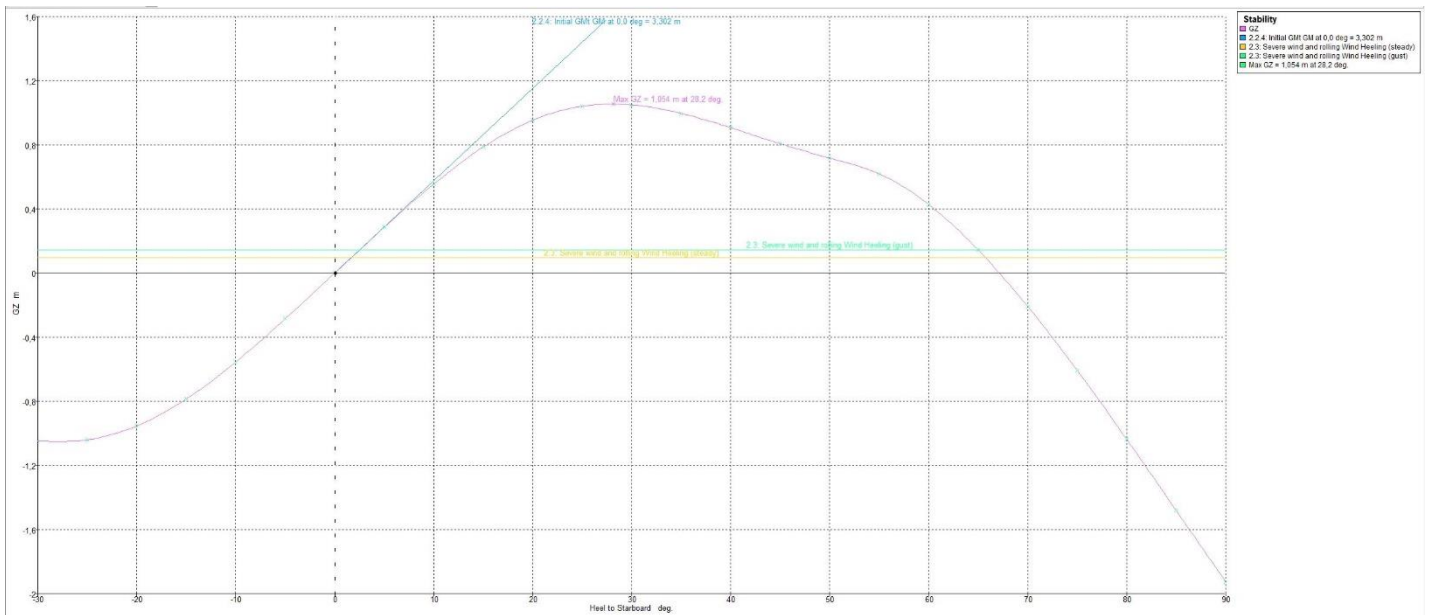
LC Lightship

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	150,545	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	4,11	m			
	GMf, Stability calculated	3,302	m			
	VCG, Stability calculated	11,016	m			
	CB, Stability calculated	0,466				
	Ak, keel area, user spec.	10,8	m ²			
	Method for k factor	Tabulated value for k				
	Evaluates to	22,9	deg			
	Intermediate values					
	B / d			5,828		
	100 Ak / L / B			0,3		
	C		IMO units	0,442		
	T		s	11,662		
OG, Centre of gravity above WL		m	6,907			
X1		IMO units	0,8			
X2		IMO units	0,773			
k tabulated		IMO units	0,994			
r		IMO units	1,738			
s		IMO units	0,067			
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30 from the greater of spec. heel angle	0	deg	0		Pass
	to the lesser of spec. heel angle	30	deg	30		
	angle of vanishing stability shall not be less than (>=)	67,1	deg			
		3,1513	m.deg	20,8568	Pass	561,85
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40 from the greater of spec. heel angle	0	deg	0		Pass
	to the lesser of spec. heel angle	40	deg	40		
	first downflooding angle	n/a	deg			
	angle of vanishing stability shall not be less than (>=)	67,1	deg			
	5,1566	m.deg	30,7512	Pass	496,35	
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40 from the greater of spec. heel angle	30	deg	30		Pass
	to the lesser of spec. heel angle	40	deg	40		
	first downflooding angle	n/a	deg			
	angle of vanishing stability shall not be less than (>=)	67,1	deg			
	1,7189	m.deg	9,8943	Pass	475,62	
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater				Pass	

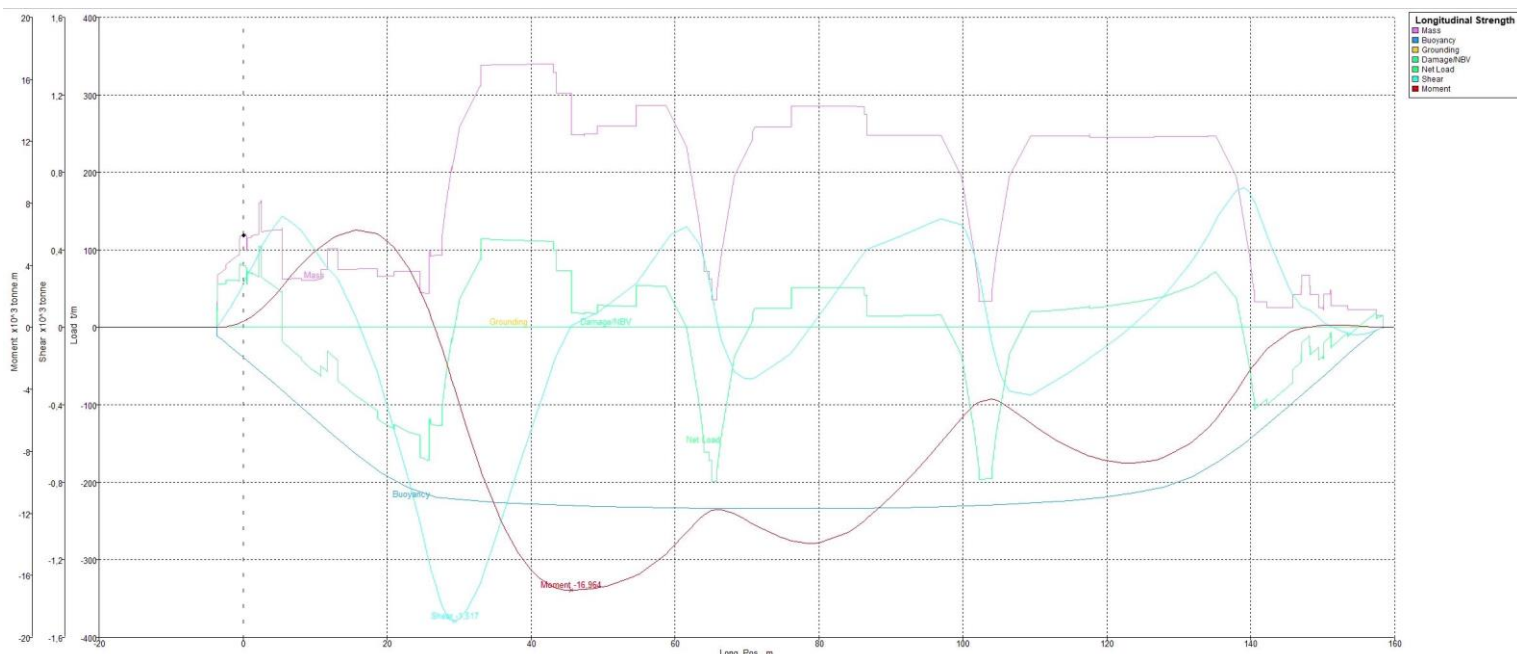
	in the range from the greater of spec. heel angle to the lesser of spec. heel angle	30 deg	30	
	angle of max. GZ shall not be less than (>=)	90 deg	90	
	Intermediate values	28,2 deg		
	angle at which this GZ occurs	0,2 m	1,048	Pass 424
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ shall not be less than (>=)	25 deg	28,2	Pass 12,73
267(85) Ch2 - General Criteria	2.2.4: Initial GMT spec. heel angle shall not be less than (>=)	0 deg		Pass
		0,15 m	3,302	Pass 2101,33
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling			Pass
	Wind arm: $a = P A (h - H) / (g \text{ disp.}) \cos^n(\phi)$			
	constant: a =	0,99966		
	wind pressure: P =	504 Pa		
	area centroid height (from zero point): h =	15,8 m		
	total area: A =	1139,1 m ²		
	H = mean draft / 2	2,055 m		
	cosine power: n =	0		
	gust ratio	1,5		
	Area2 integrated to the lesser of			
	2.3: IMO roll back angle from equilibrium (with steady heel arm)	22,9 (-21,3)	deg	-21,3
	Area 1 upper integration range, to the lesser of:			
	first downflooding angle	n/a	deg	
	angle of vanishing stability (with gust heel arm)		65 deg	65
	Angle for GZ(max) in GZ ratio, the lesser of:			
	angle of max. GZ	28,2 deg	28,2	
	Select required angle for angle of steady heel ratio:	DeckEdgeImmersionAngle		
	Criteria:			Pass
	Angle of steady heel shall not be greater than (<=)	16 deg	1,7	Pass 89,65
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)	80 %	3,49	Pass 95,64
	Area1 / Area2 shall not be less than (>=)	100 %	247,55	Pass 147,55
	Intermediate values			
	Heel arm amplitude	m	0,095	
	Equilibrium angle with gust heel arm	deg	2,5	
	Deck edge immersion angle	deg	47,4	
	Area1 (under GZ), from 2,5 to 65,0 deg.	m.deg	46,1198	
	Area1 (under HA), from 2,5 to 65,0 deg.	m.deg	8,9347	
	Area1, from 2,5 to 65,0 deg.	m.deg	37,1851	
	Area2 (under GZ), from -21,3 to 2,5 deg.	m.deg	-11,6269	
	Area2 (under HA), from -21,3 to 2,5 deg.	m.deg	3,3943	
	Area2, from -21,3 to 2,5 deg.	m.deg	15,0212	



1	Draft Amidships m	4,110
2	Displacement t	8442
3	Heel deg	0,0
4	Draft at FP m	2,142
5	Draft at AP m	6,077
6	Draft at LCF m	4,216
7	Trim (+ve by stem) m	3,935
8	WL Length m	150,54
9	Beam max extents on WL m	22,067
10	Wetted Area m ²	3156,6
11	Waterpl. Area m ²	2772,8
12	Prismatic coeff. (Cp)	0,626
13	Block coeff. (Cb)	0,466
14	Max Sect. area coeff. (Cm)	0,777
15	Waterpl. area coeff. (Cwp)	0,835
16	LCB from zero pt. (+ve fwd) m	69,235
17	LCF from zero pt. (+ve fwd) m	74,472
18	KB m	2,607
19	KG fluid m	11,016
20	Bmt m	11,713
21	BML m	488,88
22	GMt corrected m	3,301
23	GML m	480,47
24	KMl m	14,317
25	KML m	491,33
26	Immersion (TPC) tonne/cm	28,422
27	MTC tonne m	257,70
28	RM at 1deg = GMT.Disp.sin(1) tonne.	486,40
29	Max deck inclination deg	1,4321
30	Trim angle (+ve by stern) deg	1,4321

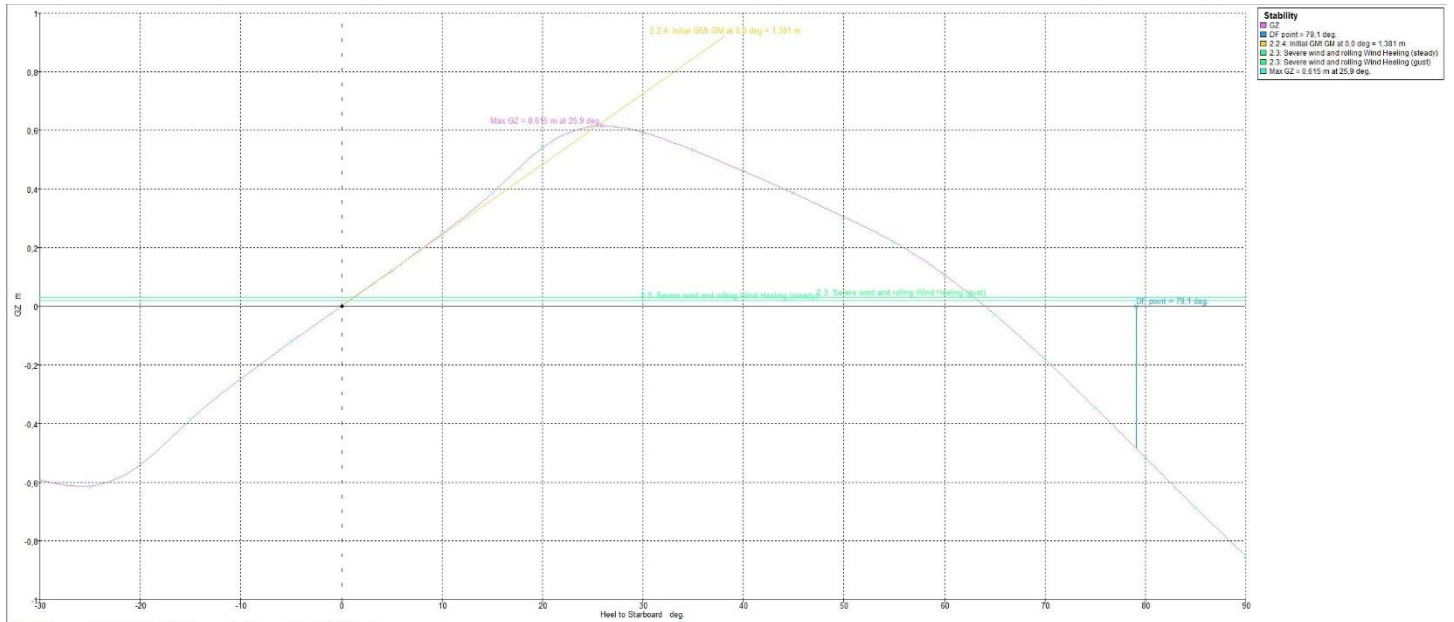
LC Departure Port CO2

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016
2	Tk 1 Fore peak	0%	268,986	0,000	151,467			0,000
3	Tk 2 BW 1 Port	0%	9,009	0,000	147,280			0,000
4	Tk 3 BW 1 Stb	0%	9,009	0,000	147,280			0,000
5	Tk 4 BW 2 Port	0%	8,895	0,000	143,611			0,000
6	Tk 5 BW 2 Stb	0%	8,895	0,000	143,611			0,000
7	Cargo Tank 1 CO2	100%	6525,714	6525,714	122,237			9,100
8	Cargo Tank 2 CO2	100%	6525,714	6525,714	84,022			9,100
9	Cargo Tank 3 CO2	100%	6525,716	6525,716	45,807			9,100
10	Cargo Tank 1 NH3	0%	3853,280	0,000	122,237			1,600
11	Cargo Tank 2 NH3	0%	3853,280	0,000	84,022			1,600
12	Cargo Tank 3 NH3	0%	3853,280	0,000	45,807			1,600
13	Tk 6 BW 3 Port	0%	95,054	0,000	122,461			0,871
14	Tk 7 BW 3 STB	0%	95,054	0,000	122,461			0,871
15	Tk 8 BW 4 Port	0%	290,196	0,000	103,309			0,682
16	Tk 9 BW 4 STB	0%	290,196	0,000	103,309			0,682
17	Tk 10 BW 5 Port	0%	334,810	0,000	84,109			0,619
18	Tk 11 BW 5 STB	0%	334,810	0,000	84,109			0,619
19	Tk 12 BW 6 Port	0%	341,475	0,000	76,828			0,616
20	Tk 13 BW 6 STB	0%	341,475	0,000	76,828			0,616
21	Tk 14 BW 7 Port	0%	332,123	0,000	64,691			0,643
22	Tk 15 BW 7 STB	0%	332,123	0,000	64,691			0,643
23	Tk 16 BW 8 Port	75%	304,408	228,306	36,199			3,592
24	Tk 17 BW 8 STB	75%	304,408	228,306	36,199			3,592
25	Tk BW Aft Upper Port	100%	260,457	260,457	1,304			10,699
26	TK BW Aft Upper STB	100%	260,457	260,457	1,304			10,699
27	Fuel Aft STB	1	140,600	140,600	38,250	33,000	43,500	20,650
28	Fuel Aft Port	1	140,600	140,600	38,250	33,000	43,500	20,650
29	Fuel mid STB	1	140,600	140,600	59,850	54,600	65,100	20,650
30	Fuel mid Port	1	140,600	140,600	59,850	54,600	65,100	20,650
31	Fuel fore STB	1	140,600	140,600	81,450	76,200	86,700	20,650
32	Fuel fore Port	1	140,600	140,600	81,450	76,200	86,700	20,650
33	Tk 18 BW 3 Port Upper	0%	94,369	0,000	127,016			7,000
34	Tk 19 BW 3 STB Upper	0%	94,369	0,000	127,016			7,000
35	Tk 20 BW 4 Port Upper	0%	229,105	0,000	112,367			7,000
36	Tk 21 BW 4 STB Upper	0%	229,105	0,000	112,367			7,000
37	Tk 22 BW 5 Port Upper	0%	260,105	0,000	93,456			7,000
38	Tk 23 BW 5 STB Upper	0%	260,105	0,000	93,456			7,000
39	Tk 24 BW 6 Port Upper	0%	273,705	0,000	74,367			7,000
40	Tk 25 BW 6 STB Upper	0%	273,705	0,000	74,367			7,000
41	Tk 26 BW 7 Port Upper	0%	273,733	0,000	55,270			7,000
42	Tk 27 BW 7 STB Upper	0%	273,733	0,000	55,270			7,000
43	Tk 28 BW 8 Port Upper	100%	276,148	276,148	35,711			9,560
44	Tk 29 BW 8 STB Upper	100%	276,148	276,148	35,711			9,560
45	Total Loadcase			30392,39	76,288			9,906



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	160,929	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	10,995	m			
	GMf, Stability calculated	1,381	m			
	VCG, Stability calculated	9,909	m			
	CB, Stability calculated	0,704				
	Ak, keel area, user spec.	10,8	m ²			
	Method for k factor	Tabulated value for k				
	Evaluates to	20,1	deg			
	Intermediate values					
	B / d			2,178		
	100 Ak / L / B			0,28		
	C		IMO units	0,354		
T		s	14,425			
OG, Centre of gravity above WL		m	-1,086			
X1		IMO units	1			
X2		IMO units	1			
k tabulated		IMO units	0,994			
r		IMO units	0,671			
s		IMO units	0,051			
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30				Pass	
	from the greater of spec. heel angle	0	deg	0		
	to the lesser of spec. heel angle	30	deg	30		
	angle of vanishing stability shall not be less than (>=)	64	deg			
		3,1513	m.deg	11,0839	Pass	251,72
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40				Pass	
	from the greater of spec. heel angle	0	deg	0		
	to the lesser of spec. heel angle	40	deg	40		
	first downflooding angle	79,1	deg			
	angle of vanishing stability shall not be less than (>=)	64	deg			
		5,1566	m.deg	16,3833	Pass	217,72
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40				Pass	
	from the greater of spec. heel angle	30	deg	30		
	to the lesser of spec. heel angle	40	deg	40		
	first downflooding angle	79,1	deg			
	angle of vanishing stability shall not be less than (>=)	64	deg			
		1,7189	m.deg	5,2994	Pass	208,3
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater				Pass	

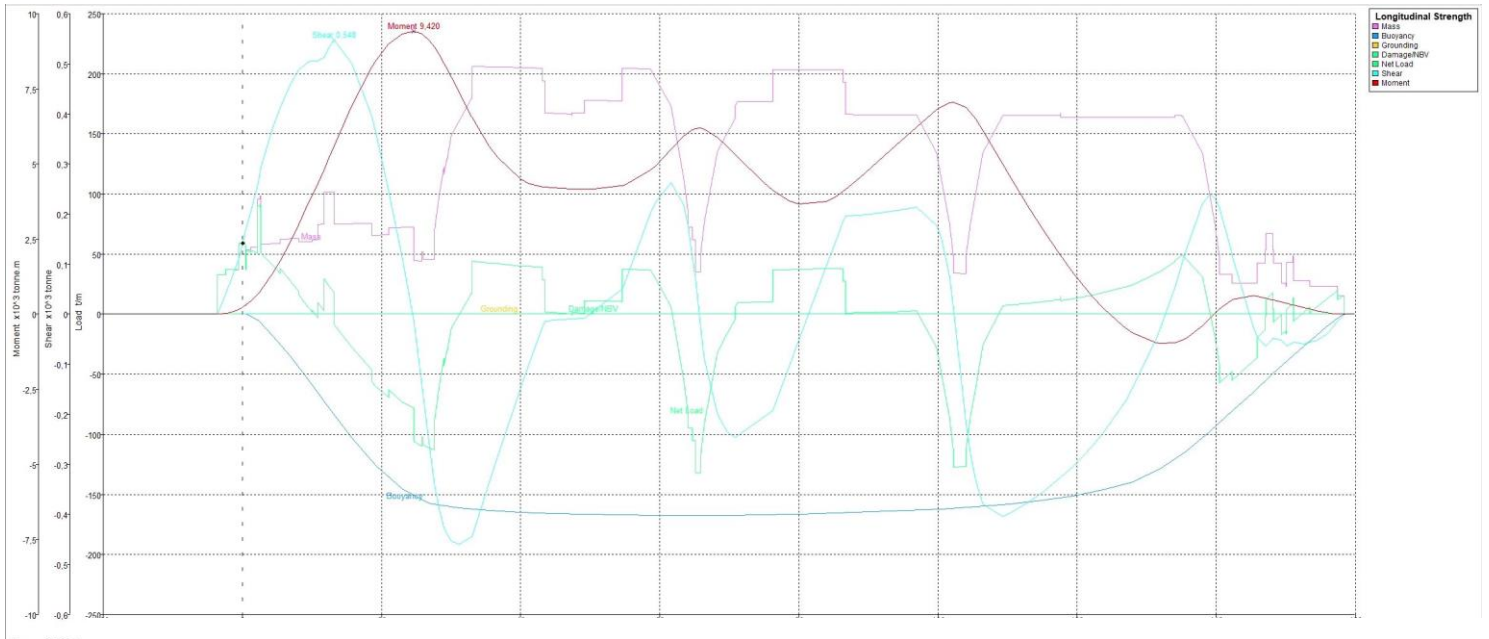
	in the range of the greater of				
	spec. heel angle		30 deg	30	
	to the lesser of				
	spec. heel angle		90 deg	90	
	angle of max. GZ		25,9 deg		
	shall not be less than (>=)		0,2 m	0,593 Pass	196,5
	Intermediate values				
	angle at which this GZ occurs		deg	30	
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ			Pass	
	shall not be less than (>=)		25 deg	25,9 Pass	3,64
267(85) Ch2 - General Criteria	2.2.4: Initial GMt			Pass	
	spec. heel angle		0 deg		
	shall not be less than (>=)		0,15 m	1,381 Pass	820,67
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling			Pass	
	Wind arm: a P A (h - H) / (g disp.) cos^n(phi)				
	constant: a =		0,99966		
	wind pressure: P =		504 Pa		
	area centroid height (from zero point): h =		15,8 m		
	total area: A =		1139,1 m^2		
	H = mean draft / 2		5,498 m		
	cosine power: n =		0		
	gust ratio		1,5		
	Area2 integrated to the lesser of				
	2.3: IMO roll back angle from equilibrium (with steady heel arm)		20,1 (-19,2)	deg	-19,2
	Area 1 upper integration range, to the lesser of:				
	first downflooding angle		79,1 deg		
	angle of vanishing stability (with gust heel arm)		62,9 deg	62,9	
	Angle for GZ(max) in GZ ratio, the lesser of:				
	angle of max. GZ		25,9 deg	25,9	
	Select required angle for angle of steady heel ratio:	DeckEdgeImmersionAngle			
	Criteria:			Pass	
	Angle of steady heel shall not be greater than (<=)		16 deg	0,8 Pass	94,84
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)		80 %	4,38 Pass	94,53
	Area1 / Area2 shall not be less than (>=)		100 %	390,53 Pass	290,53
	Intermediate values				
	Heel arm amplitude		m	0,02	
	Equilibrium angle with gust heel arm		deg	1,2	
	Deck edge immersion angle		deg	18,8	
	Area1 (under GZ), from 1,2 to 62,9 deg.		m.deg	22,5467	
	Area1 (under HA), from 1,2 to 62,9 deg.		m.deg	1,8363	
	Area1, from 1,2 to 62,9 deg.		m.deg	20,7104	
	Area2 (under GZ), from -19,2 to 1,2 deg.		m.deg	-4,6939	
	Area2 (under HA), from -19,2 to 1,2 deg.		m.deg	0,6093	
	Area2, from -19,2 to 1,2 deg.		m.deg	5,3032	



1	Draft Amidships m	10.995
2	Displacement t	30392
3	Heel deg	0.0
4	Draft at FP m	11.039
5	Draft at AP m	10.951
6	Draft at LCF m	10.990
7	Trim (+ve by stern) m	-0.088
8	WL Length m	160.92
9	Beam max extents on WL m	23.714
10	Wetted Area m^2	5628.7
11	Waterpl. Area m^2	3468.7
12	Prismatic coeff. (Cp)	0.807
13	Block coeff. (Cb)	0.704
14	Max Sect. area coeff. (Cm)	0.879
15	Waterpl. area coeff. (Cwp)	0.906
16	LCB from zero pt. (+ve fwd) m	76.292
17	LCF from zero pt. (+ve fwd) m	70.450
18	KB m	6.252
19	KG fluid m	9.909
20	BMT m	5.039
21	BML m	215.76
22	GMt corrected m	1.382
23	GML m	212.10
24	KML m	11.291
25	KVL m	222.01
26	Immersion (TPc) tonne/cm	35.452
27	MTc tonne m	409.55
28	RM at 1deg = GMt.Disp sin(1) tonne.	732.85
29	Max deck inclination deg	0.0319
30	Trim angle (+ve by stern) deg	-0.031

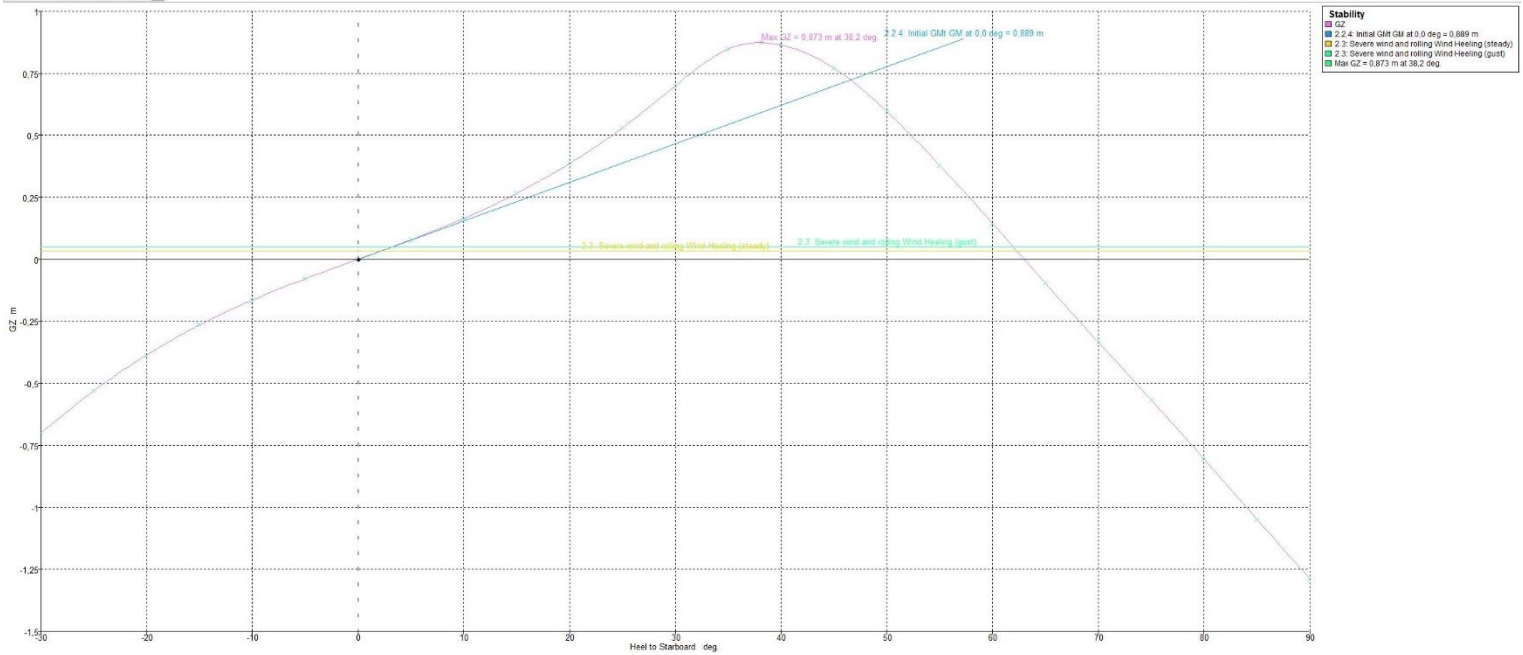
LC Departure Port NH3

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016
2	Tk 1 Fore peak	0%	268,986	0,000	151,467			0,000
3	Tk 2 BW 1 Port	0%	9,009	0,000	147,280			0,000
4	Tk 3 BW 1 Stb	0%	9,009	0,000	147,280			0,000
5	Tk 4 BW 2 Port	0%	8,895	0,000	143,611			0,000
6	Tk 5 BW 2 Stb	0%	8,895	0,000	143,611			0,000
7	Cargo Tank 1 CO2	0%	6525,714	0,000	122,237			1,600
8	Cargo Tank 2 CO2	0%	6525,714	0,000	84,022			1,600
9	Cargo Tank 3 CO2	0%	6525,716	0,000	45,807			1,600
10	Cargo Tank 1 NH3	100%	3853,280	3853,280	122,237			9,100
11	Cargo Tank 2 NH3	100%	3853,280	3853,280	84,022			9,100
12	Cargo Tank 3 NH3	100%	3853,280	3853,280	45,807			9,100
13	Tk 6 BW 3 Port	0%	95,054	0,000	122,461			0,871
14	Tk 7 BW 3 STB	0%	95,054	0,000	122,461			0,871
15	Tk 8 BW 4 Port	0%	290,196	0,000	103,309			0,682
16	Tk 9 BW 4 STB	0%	290,196	0,000	103,309			0,682
17	Tk 10 BW 5 Port	0%	334,810	0,000	84,109			0,619
18	Tk 11 BW 5 STB	0%	334,810	0,000	84,109			0,619
19	Tk 12 BW 6 Port	0%	341,475	0,000	76,828			0,616
20	Tk 13 BW 6 STB	0%	341,475	0,000	76,828			0,616
21	Tk 14 BW 7 Port	0%	332,123	0,000	64,691			0,643
22	Tk 15 BW 7 STB	0%	332,123	0,000	64,691			0,643
23	Tk 16 BW 8 Port	0%	304,408	0,000	45,488			0,771
24	Tk 17 BW 8 STB	0%	304,408	0,000	45,488			0,771
25	Tk BW Aft Upper Port	0%	260,457	0,000	2,735			9,100
26	TK BW Aft Upper STB	0%	260,457	0,000	2,735			9,100
27	Fuel Aft STB	1	140,600	140,600	38,250	33,000	43,500	20,650
28	Fuel Aft Port	1	140,600	140,600	38,250	33,000	43,500	20,650
29	Fuel mid STB	1	140,600	140,600	59,850	54,600	65,100	20,650
30	Fuel mid Port	1	140,600	140,600	59,850	54,600	65,100	20,650
31	Fuel fore STB	1	140,600	140,600	81,450	76,200	86,700	20,650
32	Fuel fore Port	1	140,600	140,600	81,450	76,200	86,700	20,650
33	Tk 18 BW 3 Port Upper	0%	94,369	0,000	127,016			7,000
34	Tk 19 BW 3 STB Upper	0%	94,369	0,000	127,016			7,000
35	Tk 20 BW 4 Port Upper	0%	229,105	0,000	112,367			7,000
36	Tk 21 BW 4 STB Upper	0%	229,105	0,000	112,367			7,000
37	Tk 22 BW 5 Port Upper	0%	260,105	0,000	93,456			7,000
38	Tk 23 BW 5 STB Upper	0%	260,105	0,000	93,456			7,000
39	Tk 24 BW 6 Port Upper	0%	273,705	0,000	74,367			7,000
40	Tk 25 BW 6 STB Upper	0%	273,705	0,000	74,367			7,000
41	Tk 26 BW 7 Port Upper	0%	273,733	0,000	55,270			7,000
42	Tk 27 BW 7 STB Upper	0%	273,733	0,000	55,270			7,000
43	Tk 28 BW 8 Port Upper	0%	276,148	0,000	35,715			7,000
44	Tk 29 BW 8 STB Upper	0%	276,148	0,000	35,715			7,000
45	Total Loadcase			20845,27	77,141			10,343



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	157,335	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	8,191	m			
	GMf, Stability calculated	0,889	m			
	VCG, Stability calculated	10,343	m			
	CB, Stability calculated	0,665				
	Ak, keel area, user spec.	10,8	m ²			
	Method for k factor	Tabulated value for k				
	Evaluates to	17,4	deg			
	Intermediate values					
	B / d			2,924		
	100 Ak / L / B			0,287		
	C		IMO units	0,373		
	T		s	18,934		
	OG, Centre of gravity above WL		m	2,153		
X1		IMO units	0,908			
X2		IMO units	0,979			
k tabulated		IMO units	0,994			
r		IMO units	0,888			
s		IMO units	0,037			
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30				Pass	
	from the greater of					
	spec. heel angle	0	deg	0		
	to the lesser of					
	spec. heel angle	30	deg	30		
angle of vanishing stability	63	deg				
shall not be less than (>=)	3,1513	m.deg	8,8368	Pass	180,42	
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40				Pass	
	from the greater of					
	spec. heel angle	0	deg	0		
	to the lesser of					
	spec. heel angle	40	deg	40		
first downflooding angle	n/a	deg				
angle of vanishing stability	63	deg				
shall not be less than (>=)	5,1566	m.deg	17,0792	Pass	231,21	
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40				Pass	
	from the greater of					
	spec. heel angle	30	deg	30		
	to the lesser of					
	spec. heel angle	40	deg	40		
first downflooding angle	n/a	deg				
angle of vanishing stability	63	deg				
shall not be less than (>=)	1,7189	m.deg	8,2423	Pass	379,51	
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater				Pass	

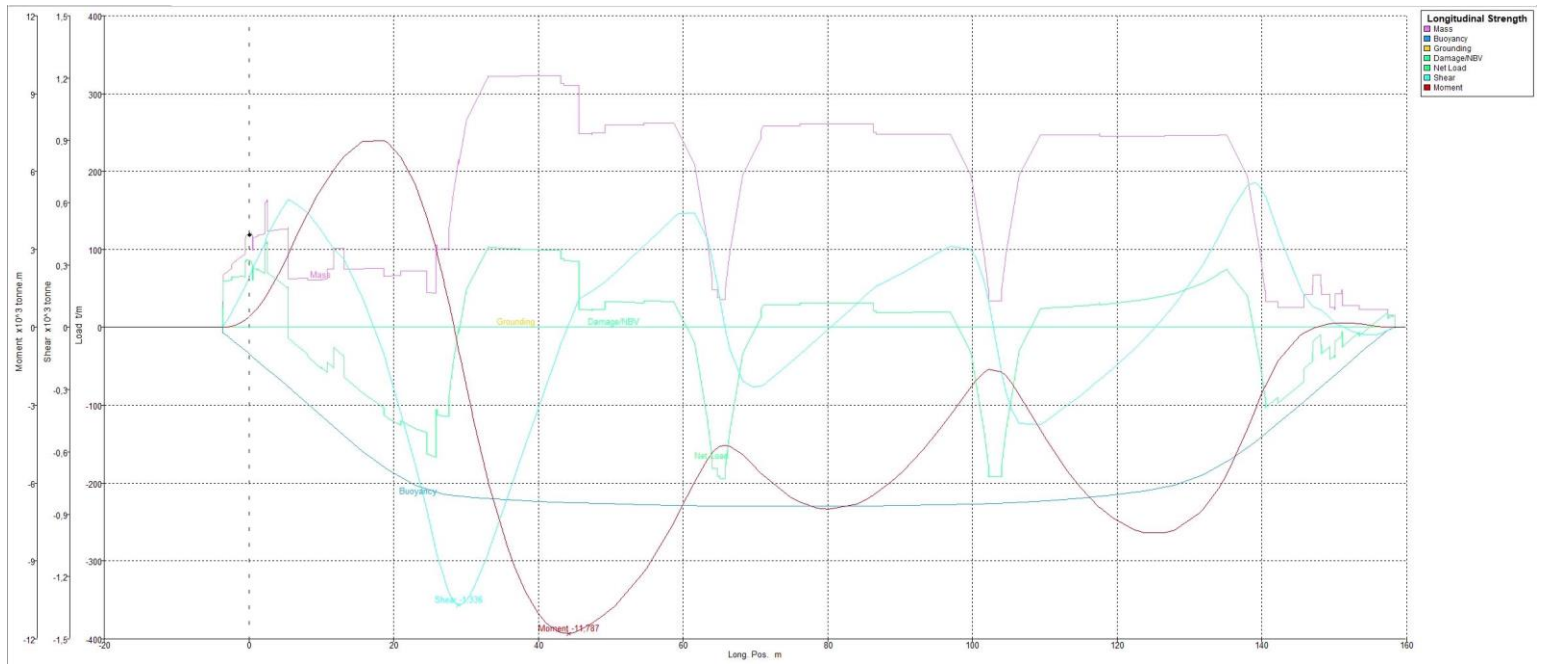
	in the range from the greater of spec. heel angle to the lesser of spec. heel angle angle of max. GZ shall not be less than (>=)		30 deg	30		
	Intermediate values angle at which this GZ occurs		deg	38,2		
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ shall not be less than (>=)		25 deg	38,2	Pass	52,73
267(85) Ch2 - General Criteria	2.2.4: Initial GMT spec. heel angle shall not be less than (>=)		0 deg	0,15 m	0,889	Pass 492,67
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling Wind arm: a P A (h - H) / (g disp.) cos^n(phi) constant: a = wind pressure: P = area centroid height (from zero point): h = total area: A = H = mean draft / 2 cosine power: n = gust ratio		0,99966 504 Pa 15,8 m 1139,1 m^2 4,095 m 0 1,5			Pass
	Area2 integrated to the lesser of 2.3: IMO roll back angle from equilibrium (with steady heel arm)		17,4 (-15,2)	deg	-15,2	
	Area 1 upper integration range, to the lesser of: first downflooding angle angle of vanishing stability (with gust heel arm)		n/a	deg 62 deg		62
	Angle for GZ(max) in GZ ratio, the lesser of: angle of max. GZ		38,2 deg		38,2	
	Select required angle for angle of steady heel ratio: Criteria:		DeckEdgelmersionAngle			Pass
	Angle of steady heel shall not be greater than (<=)		16 deg		2,1	Pass 86,78
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)		80 %		6,78	Pass 91,53
	Area1 / Area2 shall not be less than (>=)		100 %		928,88	Pass 828,88
	Intermediate values					
	Heel arm amplitude		m		0,033	
	Equilibrium angle with gust heel arm		deg		3,2	
	Deck edge immersion angle		deg		31,2	
	Area1 (under GZ), from 3,2 to 62,0 deg.		m.deg		28,5248	
	Area1 (under HA), from 3,2 to 62,0 deg.		m.deg		2,8987	
	Area1, from 3,2 to 62,0 deg.		m.deg		25,6261	
	Area2 (under GZ), from -15,2 to 3,2 deg.		m.deg		-1,8519	
	Area2 (under HA), from -15,2 to 3,2 deg.		m.deg		0,9069	
	Area2, from -15,2 to 3,2 deg.		m.deg		2,7588	



1	Draft Amidships m	8,191
2	Displacement t	20845
3	Heel deg	0,0
4	Draft at FP m	7,877
5	Draft at AP m	8,505
6	Draft at LCF m	8,213
7	Trim (+ve by stern) m	0,629
8	WL Length m	157,32
9	Beam max extents on WL m	23,392
10	Wetted Area m^2	4609,0
11	Waterpl. Area m^2	3243,0
12	Prismatic coeff. (Cp)	0,792
13	Block coeff. (Cb)	0,665
14	Max Sect. area coeff. (Cm)	0,849
15	Waterpl. area coeff. (Cwp)	0,881
16	LCB from zero pt. (+ve fwd) m	77,129
17	LCF from zero pt. (+ve fwd) m	73,104
18	KB m	4,712
19	KG fluid m	10,343
20	BMT m	6,520
21	BML m	270,10
22	GMT corrected m	0,888
23	GML m	264,47
24	KMlt m	11,232
25	KML m	274,81
26	Immersion (TPC) tonne/cm	33,242
27	MTC tonne.m	350,26
28	RM at 1deg = GMT Disp sin(1) tonne	323,16
29	Max deck inclination deg	0,2288
30	Trim angle (+ve by stern) deg	0,2288

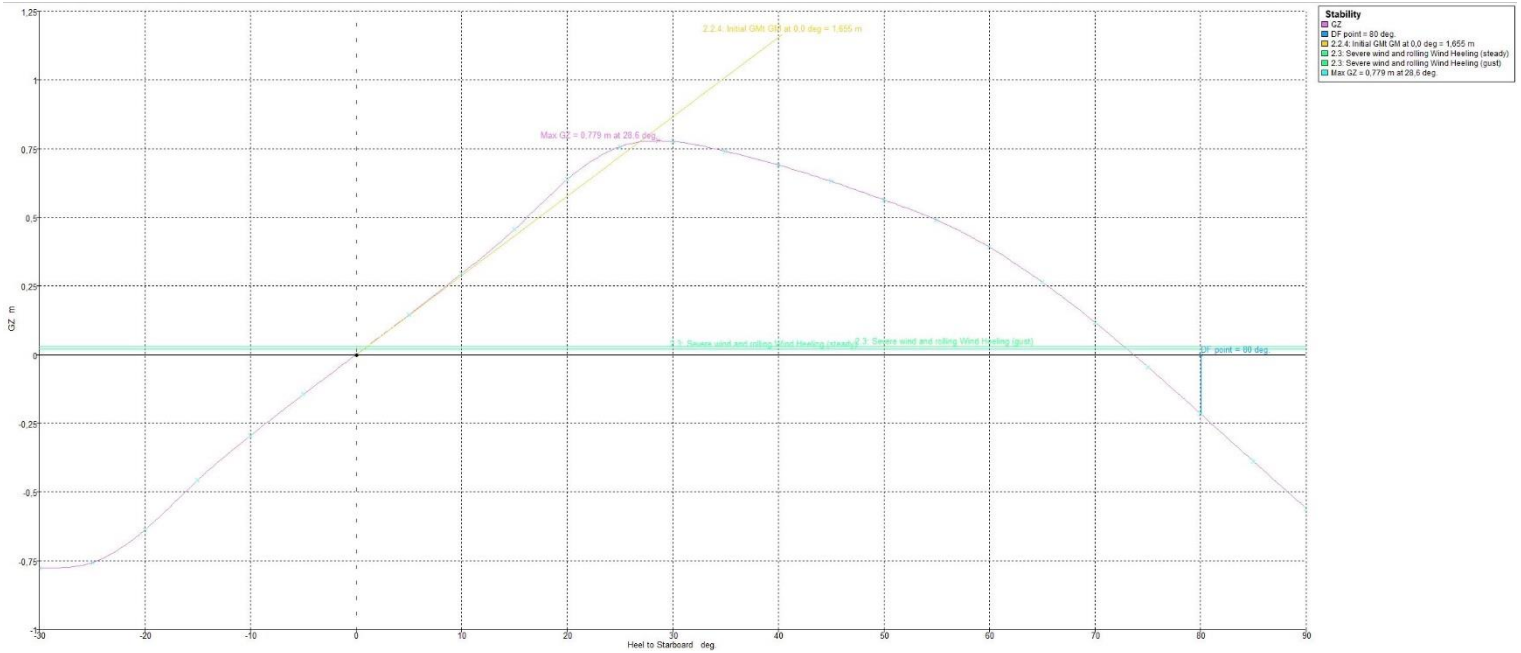
Arrival Port CO2

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016
2	Tk 1 Fore peak	0%	268,986	0,000	151,467			0,000
3	Tk 2 BW 1 Port	0%	9,009	0,000	147,280			0,000
4	Tk 3 BW 1 Stb	0%	9,009	0,000	147,280			0,000
5	Tk 4 BW 2 Port	0%	8,895	0,000	143,611			0,000
6	Tk 5 BW 2 Stb	0%	8,895	0,000	143,611			0,000
7	Cargo Tank 1 CO2	100%	6525,714	6525,714	122,237			9,100
8	Cargo Tank 2 CO2	100%	6525,714	6525,714	84,022			9,100
9	Cargo Tank 3 CO2	100%	6525,716	6525,716	45,807			9,100
10	Cargo Tank 1 NH3	0%	3853,280	0,000	122,237			1,600
11	Cargo Tank 2 NH3	0%	3853,280	0,000	84,022			1,600
12	Cargo Tank 3 NH3	0%	3853,280	0,000	45,807			1,600
13	Tk 6 BW 3 Port	0%	95,054	0,000	122,461			0,871
14	Tk 7 BW 3 STB	0%	95,054	0,000	122,461			0,871
15	Tk 8 BW 4 Port	0%	290,196	0,000	103,309			0,682
16	Tk 9 BW 4 STB	0%	290,196	0,000	103,309			0,682
17	Tk 10 BW 5 Port	0%	334,810	0,000	84,109			0,619
18	Tk 11 BW 5 STB	0%	334,810	0,000	84,109			0,619
19	Tk 12 BW 6 Port	0%	341,475	0,000	76,828			0,616
20	Tk 13 BW 6 STB	0%	341,475	0,000	76,828			0,616
21	Tk 14 BW 7 Port	0%	332,123	0,000	64,691			0,643
22	Tk 15 BW 7 STB	0%	332,123	0,000	64,691			0,643
23	Tk 16 BW 8 Port	100%	304,408	304,408	36,080			4,262
24	Tk 17 BW 8 STB	100%	304,408	304,408	36,080			4,262
25	Tk BW Aft Upper Port	100%	260,457	260,457	1,304			10,699
26	TK BW Aft Upper STB	100%	260,457	260,457	1,304			10,699
27	Fuel Aft STB	0,1	140,600	14,060	38,250	33,000	43,500	20,650
28	Fuel Aft Port	0,1	140,600	14,060	38,250	33,000	43,500	20,650
29	Fuel mid STB	0,1	140,600	14,060	59,850	54,600	65,100	20,650
30	Fuel mid Port	0,1	140,600	14,060	59,850	54,600	65,100	20,650
31	Fuel fore STB	0,1	140,600	14,060	81,450	76,200	86,700	20,650
32	Fuel fore Port	0,1	140,600	14,060	81,450	76,200	86,700	20,650
33	Tk 18 BW 3 Port Upper	0%	94,369	0,000	127,016			7,000
34	Tk 19 BW 3 STB Upper	0%	94,369	0,000	127,016			7,000
35	Tk 20 BW 4 Port Upper	0%	229,105	0,000	112,367			7,000
36	Tk 21 BW 4 STB Upper	0%	229,105	0,000	112,367			7,000
37	Tk 22 BW 5 Port Upper	0%	260,105	0,000	93,456			7,000
38	Tk 23 BW 5 STB Upper	0%	260,105	0,000	93,456			7,000
39	Tk 24 BW 6 Port Upper	0%	273,705	0,000	74,367			7,000
40	Tk 25 BW 6 STB Upper	0%	273,705	0,000	74,367			7,000
41	Tk 26 BW 7 Port Upper	0%	273,733	0,000	55,270			7,000
42	Tk 27 BW 7 STB Upper	0%	273,733	0,000	55,270			7,000
43	Tk 28 BW 8 Port Upper	100%	276,148	276,148	35,711			9,560
44	Tk 29 BW 8 STB Upper	100%	276,148	276,148	35,711			9,560
45	Total Loadcase			29785,36	76,500			9,613



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	160,921	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	10,827	m			
	GMf, Stability calculated	1,655	m			
	VCG, Stability calculated	9,613	m			
	CB, Stability calculated	0,699				
	Ak, keel area, user spec.	10,8	m^2			
	Method for k factor	Tabulated value for k				
	Evaluates to	21,2	deg			
	Intermediate values					
	B / d				2,212	
	100 Ak / L / B				0,28	
	C			IMO units	0,355	
	T			s	13,206	
	OG, Centre of gravity above WL			m	-1,214	
	X1			IMO units	1	
X2			IMO units	0,999		
k tabulated			IMO units	0,994		
r			IMO units	0,663		
s			IMO units	0,058		
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30 from the greater of spec. heel angle to the lesser of spec. heel angle					Pass
	angle of vanishing stability shall not be less than (>=)	0	deg	0		
		30	deg	30		
		73,6	deg			
		3,1513	m.deg	13,4601	Pass	327,13
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40 from the greater of spec. heel angle to the lesser of spec. heel angle					Pass
	first downflooding angle	0	deg	0		
	angle of vanishing stability shall not be less than (>=)	40	deg	40		
		80	deg			
		73,6	deg			
		5,1566	m.deg	20,842	Pass	304,18
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40 from the greater of spec. heel angle to the lesser of spec. heel angle					Pass
	first downflooding angle	30	deg	30		
	angle of vanishing stability shall not be less than (>=)	40	deg	40		
		80	deg			
		73,6	deg			
		1,7189	m.deg	7,3819	Pass	329,45
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater					Pass

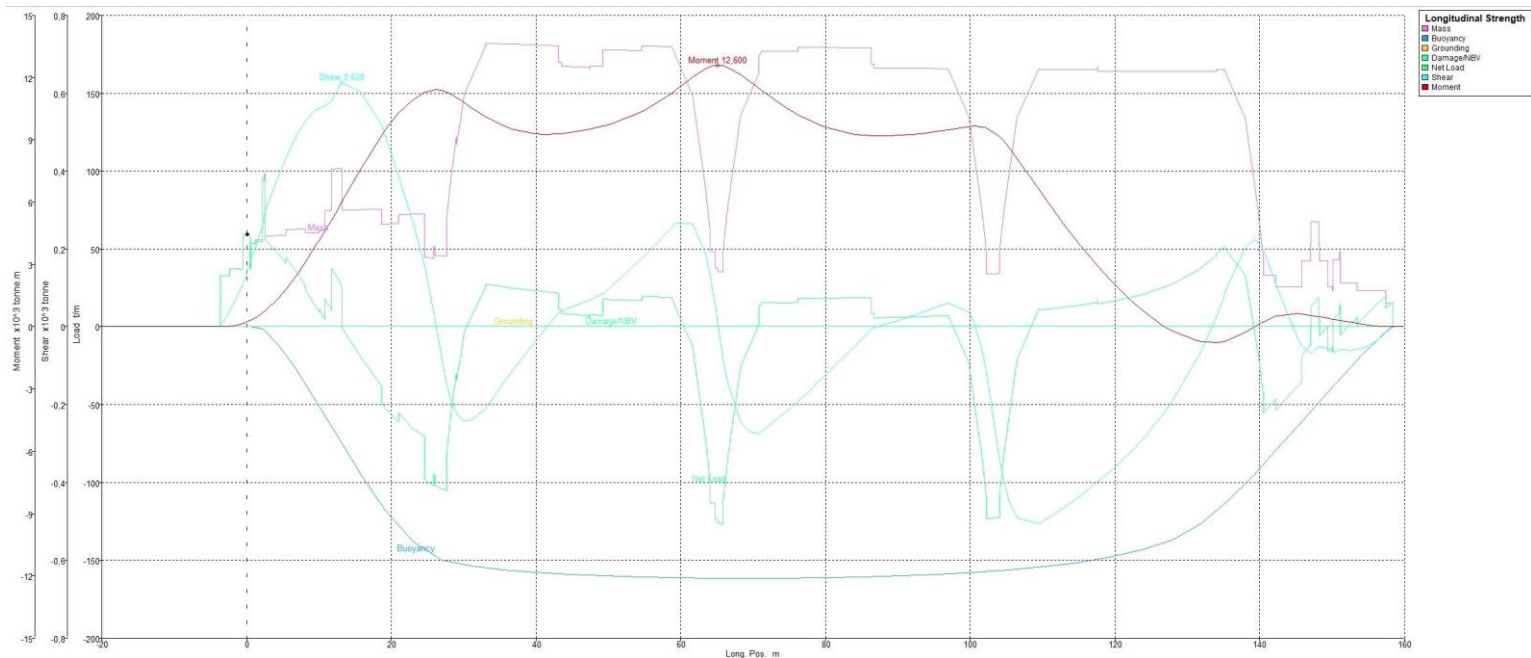
	in the range from the greater of				
	spec. heel angle		30 deg	30	
	to the lesser of				
	spec. heel angle		90 deg	90	
	angle of max. GZ		28,6 deg		
	shall not be less than (>=)		0,2 m	0,776	Pass 288
	Intermediate values				
	angle at which this GZ occurs		deg	30	
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ				Pass
	shall not be less than (>=)		25 deg	28,6	Pass 14,54
267(85) Ch2 - General Criteria	2.2.4: Initial GMt				Pass
	spec. heel angle		0 deg		
	shall not be less than (>=)		0,15 m	1,655	Pass 1003,33
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling				Pass
	Wind arm: $a P A (h - H) / (g \text{ disp.} \cos^n(\phi))$				
	constant: a =		0,99966		
	wind pressure: P =		504 Pa		
	area centroid height (from zero point): h =		15,8 m		
	total area: A =		1139,1 m ²		
	H = mean draft / 2		5,414 m		
	cosine power: n =		0		
	gust ratio		1,5		
	Area2 integrated to the lesser of				
	2.3: IMO roll back angle from equilibrium (with steady heel arm)		21,2 (-20,5)	deg	-20,5
	Area 1 upper integration range, to the lesser of:				
	first downflooding angle		80 deg		
	angle of vanishing stability (with gust heel arm)		72,7 deg		72,7
	Angle for GZ(max) in GZ ratio, the lesser of:				
	angle of max. GZ		28,6 deg		28,6
	Select required angle for angle of steady heel ratio:		DeckEdgeImmersionAngle		
	Criteria:				Pass
	Angle of steady heel shall not be greater than (<=)		16 deg		0,7
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)		80 %		3,62
	Area1 / Area2 shall not be less than (>=)		100 %		463,97
	Intermediate values				
	Heel arm amplitude		m		0,02
	Equilibrium angle with gust heel arm		deg		1,1
	Deck edge immersion angle		deg		19,5
	Area1 (under GZ), from 1,1 to 72,7 deg.		m.deg		34,7802
	Area1 (under HA), from 1,1 to 72,7 deg.		m.deg		2,1927
	Area1, from 1,1 to 72,7 deg.		m.deg		32,5875
	Area2 (under GZ), from -20,5 to 1,1 deg.		m.deg		-6,3641
	Area2 (under HA), from -20,5 to 1,1 deg.		m.deg		0,6596
	Area2, from -20,5 to 1,1 deg.		m.deg		7,0237



1	Draft Amidships m	10.827
2	Displacement t	29785
3	Heel deg	0.0
4	Draft at FP m	10.904
5	Draft at AP m	10.749
6	Draft at LCF m	10.819
7	Trim (+ve by stern) m	-0.155
8	WL Length m	160.92
9	Beam max extents on WL m	23.697
10	Wetted Area m ²	5568.2
11	Waterpl. Area m ²	3451.1
12	Prismatic coeff. (Cp)	0.805
13	Block coeff. (Cb)	0.699
14	Max Sect. area coeff. (Cm)	0.877
15	Waterpl. area coeff. (Cwp)	0.905
16	LCB from zero pt. (+ve fwd) m	76.504
17	LCF from zero pt. (+ve fwd) m	70.511
18	KB m	6.157
19	KG fluid m	9.613
20	BMT m	5.112
21	BML m	219.12
22	GMT corrected m	1.655
23	GML m	215.66
24	KMt m	11.269
25	KML m	225.28
26	Immersion (TPC) tonne/cm	35.374
27	MTC tonne m	408.11
28	RM at 1deg = GMt Disp sin(1) tonne.	860.48
29	Max deck inclination deg	0.0564
30	Trim angle (+ve by stern) deg	-0.056

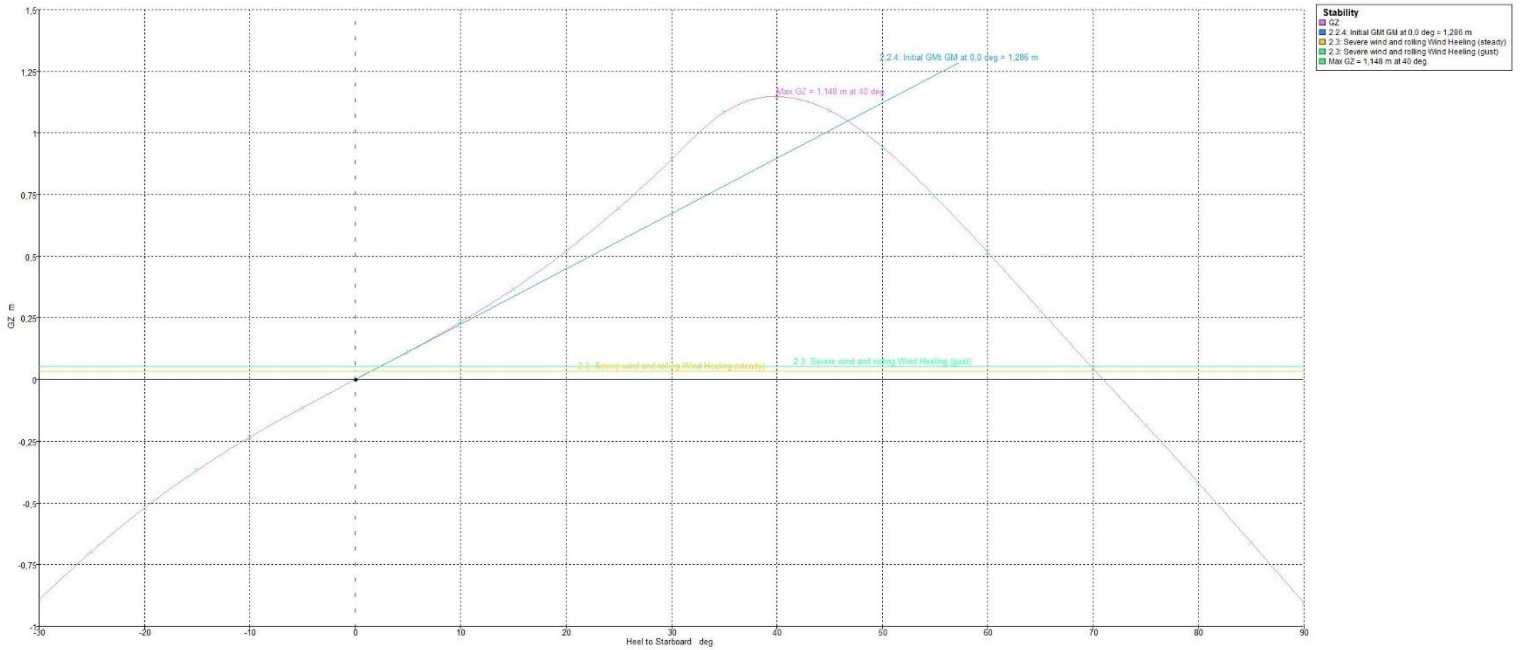
Arrival Port NH3

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016
2	Tk 1 Fore peak	0%	268,986	0,000	151,467			0,000
3	Tk 2 BW 1 Port	0%	9,009	0,000	147,280			0,000
4	Tk 3 BW 1 Stb	0%	9,009	0,000	147,280			0,000
5	Tk 4 BW 2 Port	0%	8,895	0,000	143,611			0,000
6	Tk 5 BW 2 Stb	0%	8,895	0,000	143,611			0,000
7	Cargo Tank 1 CO2	0%	6525,714	0,000	122,237			1,600
8	Cargo Tank 2 CO2	0%	6525,714	0,000	84,022			1,600
9	Cargo Tank 3 CO2	0%	6525,716	0,000	45,807			1,600
10	Cargo Tank 1 NH3	100%	3853,280	3853,280	122,237			9,100
11	Cargo Tank 2 NH3	100%	3853,280	3853,280	84,022			9,100
12	Cargo Tank 3 NH3	100%	3853,280	3853,280	45,807			9,100
13	Tk 6 BW 3 Port	0%	95,054	0,000	122,461			0,871
14	Tk 7 BW 3 STB	0%	95,054	0,000	122,461			0,871
15	Tk 8 BW 4 Port	0%	290,196	0,000	103,309			0,682
16	Tk 9 BW 4 STB	0%	290,196	0,000	103,309			0,682
17	Tk 10 BW 5 Port	0%	334,810	0,000	84,109			0,619
18	Tk 11 BW 5 STB	0%	334,810	0,000	84,109			0,619
19	Tk 12 BW 6 Port	0%	341,475	0,000	76,828			0,616
20	Tk 13 BW 6 STB	0%	341,475	0,000	76,828			0,616
21	Tk 14 BW 7 Port	0%	332,123	0,000	64,691			0,643
22	Tk 15 BW 7 STB	0%	332,123	0,000	64,691			0,643
23	Tk 16 BW 8 Port	0%	304,408	0,000	45,488			0,771
24	Tk 17 BW 8 STB	0%	304,408	0,000	45,488			0,771
25	Tk BW Aft Upper Port	0%	260,457	0,000	2,735			9,100
26	TK BW Aft Upper STB	0%	260,457	0,000	2,735			9,100
27	Fuel Aft STB	0,1	140,600	14,060	38,250	33,000	43,500	20,650
28	Fuel Aft Port	0,1	140,600	14,060	38,250	33,000	43,500	20,650
29	Fuel mid STB	0,1	140,600	14,060	59,850	54,600	65,100	20,650
30	Fuel mid Port	0,1	140,600	14,060	59,850	54,600	65,100	20,650
31	Fuel fore STB	0,1	140,600	14,060	81,450	76,200	86,700	20,650
32	Fuel fore Port	0,1	140,600	14,060	81,450	76,200	86,700	20,650
33	Tk 18 BW 3 Port Upper	0%	94,369	0,000	127,016			7,000
34	Tk 19 BW 3 STB Upper	0%	94,369	0,000	127,016			7,000
35	Tk 20 BW 4 Port Upper	0%	229,105	0,000	112,367			7,000
36	Tk 21 BW 4 STB Upper	0%	229,105	0,000	112,367			7,000
37	Tk 22 BW 5 Port Upper	0%	260,105	0,000	93,456			7,000
38	Tk 23 BW 5 STB Upper	0%	260,105	0,000	93,456			7,000
39	Tk 24 BW 6 Port Upper	0%	273,705	0,000	74,367			7,000
40	Tk 25 BW 6 STB Upper	0%	273,705	0,000	74,367			7,000
41	Tk 26 BW 7 Port Upper	0%	273,733	0,000	55,270			7,000
42	Tk 27 BW 7 STB Upper	0%	273,733	0,000	55,270			7,000
43	Tk 28 BW 8 Port Upper	0%	276,148	0,000	35,715			7,000
44	Tk 29 BW 8 STB Upper	0%	276,148	0,000	35,715			7,000
45	Total Loadcase			20086,03	77,795			9,954



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	156,415	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	7,971	m			
	GMf, Stability calculated	1,286	m			
	VCG, Stability calculated	9,954	m			
	CB, Stability calculated	0,671				
	Ak, keel area, user spec.	10,8	m ²			
	Method for k factor	Tabulated value for k				
	Evaluates to	19	deg			
	Intermediate values					
	B / d			3,005		
	100 Ak / L / B			0,288		
	C		IMO units	0,375		
	T		s	15,838		
	OG, Centre of gravity above WL		m	1,983		
X1		IMO units	0,899			
X2		IMO units	0,983			
k tabulated		IMO units	0,994			
r		IMO units	0,879			
s		IMO units	0,045			
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30				Pass	
	from the greater of					
	spec. heel angle	0	deg	0		
	to the lesser of					
	spec. heel angle	30	deg	30		
angle of vanishing stability	71	deg				
shall not be less than (>=)	3,1513	m.deg	11,8484	Pass	275,99	
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40				Pass	
	from the greater of					
	spec. heel angle	0	deg	0		
	to the lesser of					
	spec. heel angle	40	deg	40		
first downflooding angle	n/a	deg				
angle of vanishing stability	71	deg				
shall not be less than (>=)	5,1566	m.deg	22,4558	Pass	335,48	
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40				Pass	
	from the greater of					
	spec. heel angle	30	deg	30		
	to the lesser of					
	spec. heel angle	40	deg	40		
first downflooding angle	n/a	deg				
angle of vanishing stability	71	deg				
shall not be less than (>=)	1,7189	m.deg	10,6074	Pass	517,1	
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater				Pass	

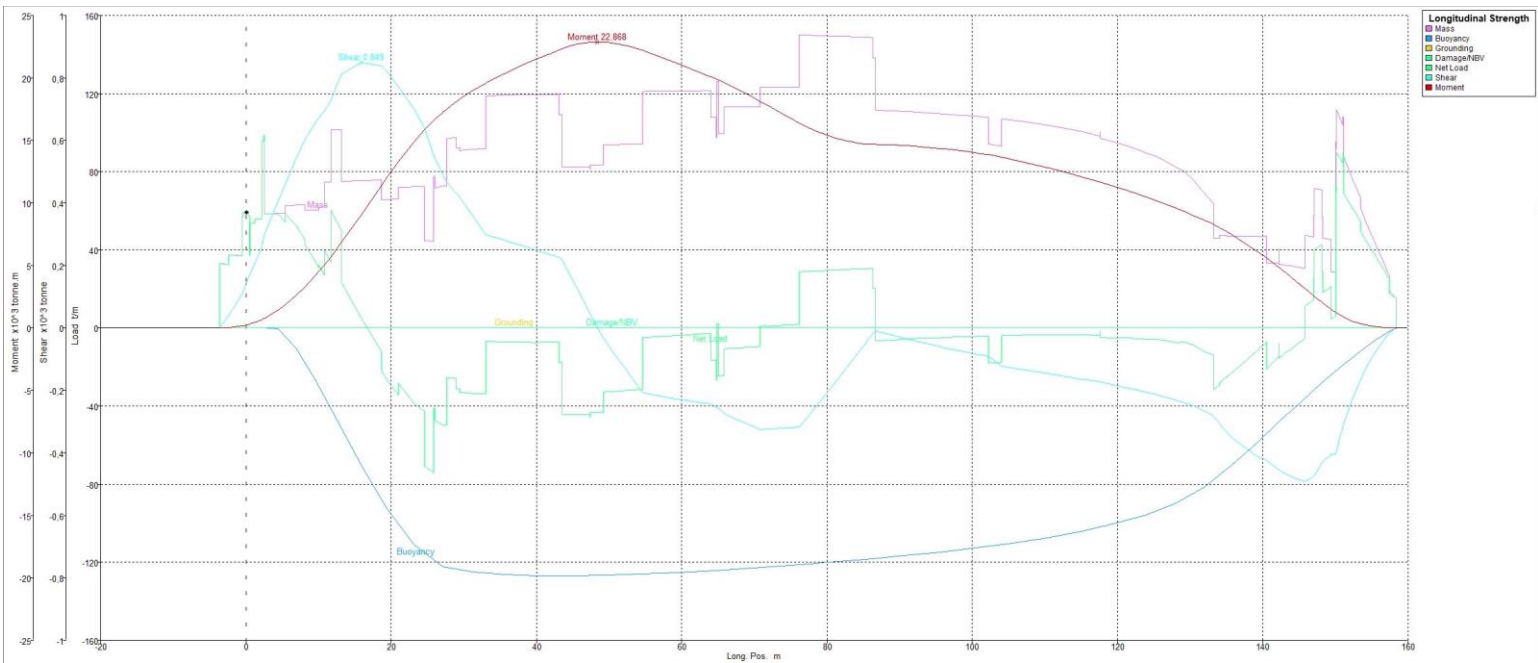
	in the range from the greater of spec. heel angle		30 deg	30		
	to the lesser of spec. heel angle		90 deg			
	angle of max. GZ		40 deg	40		
	shall not be less than (>=)		0,2 m	1,148	Pass	474
	Intermediate values					
	angle at which this GZ occurs		deg	40		
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ				Pass	
	shall not be less than (>=)		25 deg	40	Pass	60
267(85) Ch2 - General Criteria	2.2.4: Initial GMt				Pass	
	spec. heel angle		0 deg			
	shall not be less than (>=)		0,15 m	1,286	Pass	757,33
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling				Pass	
	Wind arm: $a P A (h - H) / (g \text{ disp.}) \cos^n(\phi)$					
	constant: a =		0,99966			
	wind pressure: P =		504 Pa			
	area centroid height (from zero point): h =		15,8 m			
	total area: A =		1139,1 m ²			
	H = mean draft / 2		3,986 m			
	cosine power: n =		0			
	gust ratio		1,5			
	Area2 integrated to the lesser of					
	2.3: IMO roll back angle from equilibrium (with steady heel arm)		19,0 (-17,5)	deg	-17,5	
	Area 1 upper integration range, to the lesser of:					
	first downflooding angle		n/a	deg		
	angle of vanishing stability (with gust heel arm)		69,8	deg	69,8	
	Angle for GZ(max) in GZ ratio, the lesser of:					
	angle of max. GZ		40 deg	40		
	Select required angle for angle of steady heel ratio:		DeckEdgeImmersionAngle			
	Criteria:				Pass	
	Angle of steady heel shall not be greater than (<=)		16 deg	1,5	Pass	90,43
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)		80 %	4,79	Pass	94,01
	Area1 / Area2 shall not be less than (>=)		100 %	868,26	Pass	768,26
	Intermediate values					
	Heel arm amplitude		m	0,034		
	Equilibrium angle with gust heel arm		deg	2,3		
	Deck edge immersion angle		deg	32		
	Area1 (under GZ), from 2,3 to 69,8 deg.		m.deg	43,3343		
	Area1 (under HA), from 2,3 to 69,8 deg.		m.deg	3,4881		
	Area1, from 2,3 to 69,8 deg.		m.deg	39,8462		
	Area2 (under GZ), from -17,5 to 2,3 deg.		m.deg	-3,5695		
	Area2 (under HA), from -17,5 to 2,3 deg.		m.deg	1,0197		
	Area2, from -17,5 to 2,3 deg.		m.deg	4,5892		



1	Draft Amidships m	7,971
2	Displacement t	20086
3	Heel deg	0,0
4	Draft at FP m	7,806
5	Draft at AP m	8,137
6	Draft at LCF m	7,982
7	Trim (+ve by stern) m	0,331
8	WL Length m	156,40
9	Beam max extents on WL m	23,344
10	Wetted Area m ²	4516,5
11	Waterpl. Area m ²	3206,5
12	Prismatic coeff. (Cp)	0,795
13	Block coeff. (Cb)	0,671
14	Max Sect. area coeff. (Cm)	0,847
15	Waterpl. area coeff. (Cwp)	0,878
16	LCB from zero pt. (+ve fwd) m	77,791
17	LCF from zero pt. (+ve fwd) m	73,759
18	KB m	4,583
19	KG fluid m	9,954
20	Bmt m	6,657
21	BML m	272,28
22	Gmt corrected m	1,285
23	GML m	266,91
24	KMt m	11,239
25	KML m	276,87
26	Immersion (TPc) tonne/cm	32,867
27	MTC tonne.m	340,62
28	RM at 1deg = GMt Disp.sin(1) tonne	450,51
29	Max deck inclination deg	0,1203
30	Trim angle (+ve by stern) deg	0,1203

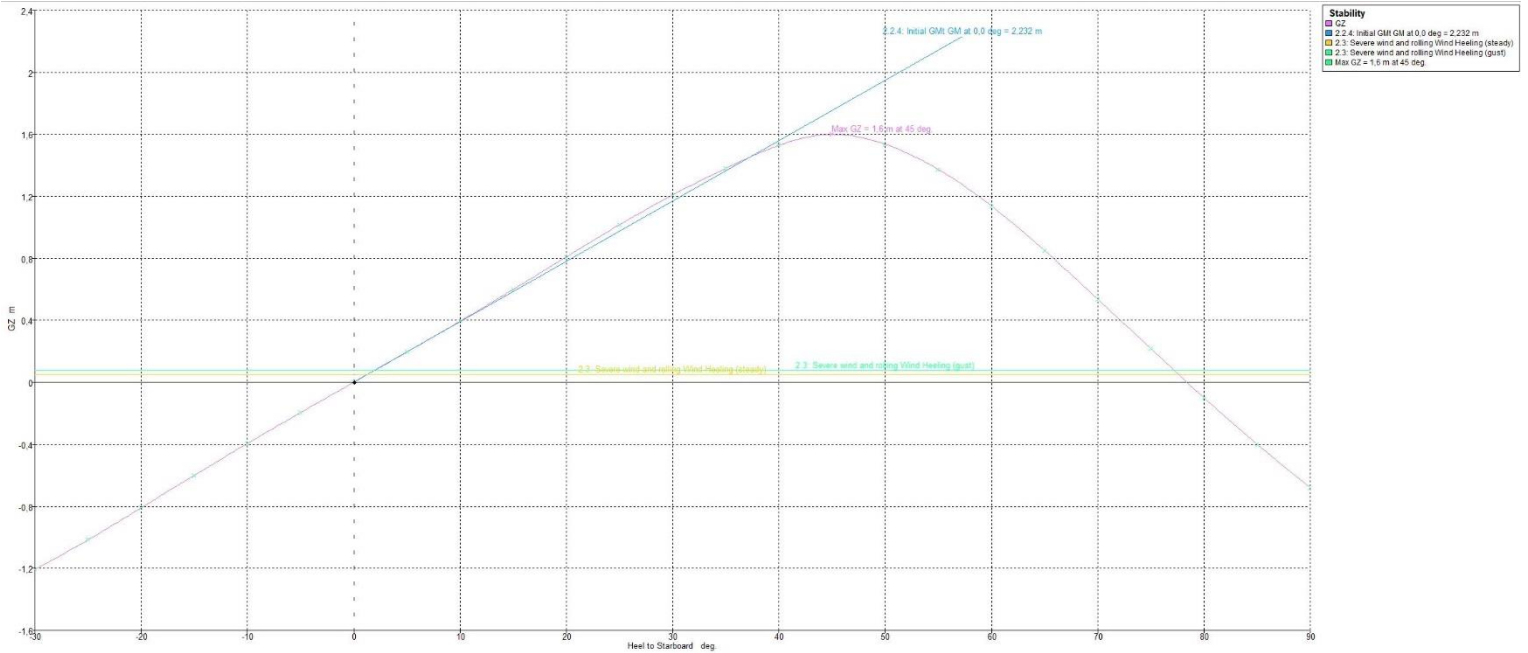
Departure Port Ballast

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016
2	Tk 1 Fore peak	100%	268,986	268,986	152,599			7,061
3	Tk 2 BW 1 Port	100%	9,009	9,009	147,336			1,067
4	Tk 3 BW 1 Stb	100%	9,009	9,009	147,336			1,067
5	Tk 4 BW 2 Port	100%	8,895	8,895	143,627			1,051
6	Tk 5 BW 2 Stb	100%	8,895	8,895	143,627			1,051
7	Cargo Tank 1 CO2	0%	6525,714	0,000	122,237			1,600
8	Cargo Tank 2 CO2	0%	6525,714	0,000	84,022			1,600
9	Cargo Tank 3 CO2	0%	6525,716	0,000	45,807			1,600
10	Cargo Tank 1 NH3	0%	3853,280	0,000	122,237			1,600
11	Cargo Tank 2 NH3	0%	3853,280	0,000	84,022			1,600
12	Cargo Tank 3 NH3	0%	3853,280	0,000	45,807			1,600
13	Tk 6 BW 3 Port	100%	95,054	95,054	126,922			4,226
14	Tk 7 BW 3 STB	100%	95,054	95,054	126,922			4,226
15	Tk 8 BW 4 Port	100%	290,196	290,196	112,335			4,025
16	Tk 9 BW 4 STB	100%	290,196	290,196	112,335			4,025
17	Tk 10 BW 5 Port	100%	334,810	334,810	93,524			4,013
18	Tk 11 BW 5 STB	100%	334,810	334,810	93,524			4,013
19	Tk 12 BW 6 Port	100%	341,475	341,475	74,406			4,048
20	Tk 13 BW 6 STB	100%	341,475	341,475	74,406			4,048
21	Tk 14 BW 7 Port	100%	332,123	332,123	55,285			4,080
22	Tk 15 BW 7 STB	100%	332,123	332,123	55,285			4,080
23	Tk 16 BW 8 Port	100%	304,408	304,408	36,080			4,262
24	Tk 17 BW 8 STB	100%	304,408	304,408	36,080			4,262
25	Tk BW Aft Upper Port	0%	260,457	0,000	2,735			9,100
26	TK BW Aft Upper STB	0%	260,457	0,000	2,735			9,100
27	Fuel Aft STB	1	140,600	140,600	38,250	33,000	43,500	20,650
28	Fuel Aft Port	1	140,600	140,600	38,250	33,000	43,500	20,650
29	Fuel mid STB	1	140,600	140,600	59,850	54,600	65,100	20,650
30	Fuel mid Port	1	140,600	140,600	59,850	54,600	65,100	20,650
31	Fuel fore STB	1	140,600	140,600	81,450	76,200	86,700	20,650
32	Fuel fore Port	1	140,600	140,600	81,450	76,200	86,700	20,650
33	Tk 18 BW 3 Port Upper	100%	94,369	94,369	127,295			9,684
34	Tk 19 BW 3 STB Upper	100%	94,369	94,369	127,295			9,684
35	Tk 20 BW 4 Port Upper	100%	229,105	229,105	112,486			9,581
36	Tk 21 BW 4 STB Upper	100%	229,105	229,105	112,486			9,581
37	Tk 22 BW 5 Port Upper	100%	260,105	260,105	93,475			9,550
38	Tk 23 BW 5 STB Upper	100%	260,105	260,105	93,475			9,550
39	Tk 24 BW 6 Port Upper	100%	273,705	273,705	74,359			9,544
40	Tk 25 BW 6 STB Upper	100%	273,705	273,705	74,359			9,544
41	Tk 26 BW 7 Port Upper	0%	273,733	0,000	55,270			7,000
42	Tk 27 BW 7 STB Upper	0%	273,733	0,000	55,270			7,000
43	Tk 28 BW 8 Port Upper	0%	276,148	0,000	35,715			7,000
44	Tk 29 BW 8 STB Upper	0%	276,148	0,000	35,715			7,000
45	Total Loadcase			14700,92	75,461			9,704



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	154,331	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	6,248	m			
	GMf, Stability calculated	2,232	m			
	VCG, Stability calculated	9,704	m			
	CB, Stability calculated	0,595				
	Ak, keel area, user spec.	10,8	m^2			
	Method for k factor	Tabulated value for k				
	Evaluates to	20,8	deg			
	Intermediate values					
	B / d			3,834		
	100 Ak / L / B			0,292		
	C		IMO units	0,395		
	T		s	12,66		
	OG, Centre of gravity above WL		m	3,456		
	X1		IMO units	0,8		
	X2		IMO units	0,944		
	k tabulated		IMO units	0,994		
	r		IMO units	1,062		
	s		IMO units	0,061		
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30 from the greater of spec. heel angle to the lesser of spec. heel angle				Pass	
	angle of vanishing stability shall not be less than (>=)	0 deg		0		
		30 deg		30		
		78,4 deg				
		3,1513 m.deg		18,0991	Pass	474,34
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40 from the greater of spec. heel angle to the lesser of spec. heel angle				Pass	
	first downflooding angle	n/a				
	angle of vanishing stability shall not be less than (>=)	40 deg		40		
		78,4 deg				
		5,1566 m.deg		31,8679	Pass	518
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40 from the greater of spec. heel angle to the lesser of spec. heel angle				Pass	
	first downflooding angle	n/a				
	angle of vanishing stability shall not be less than (>=)	30 deg		30		
		40 deg		40		
		78,4 deg				
		1,7189 m.deg		13,7688	Pass	701,02
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater				Pass	

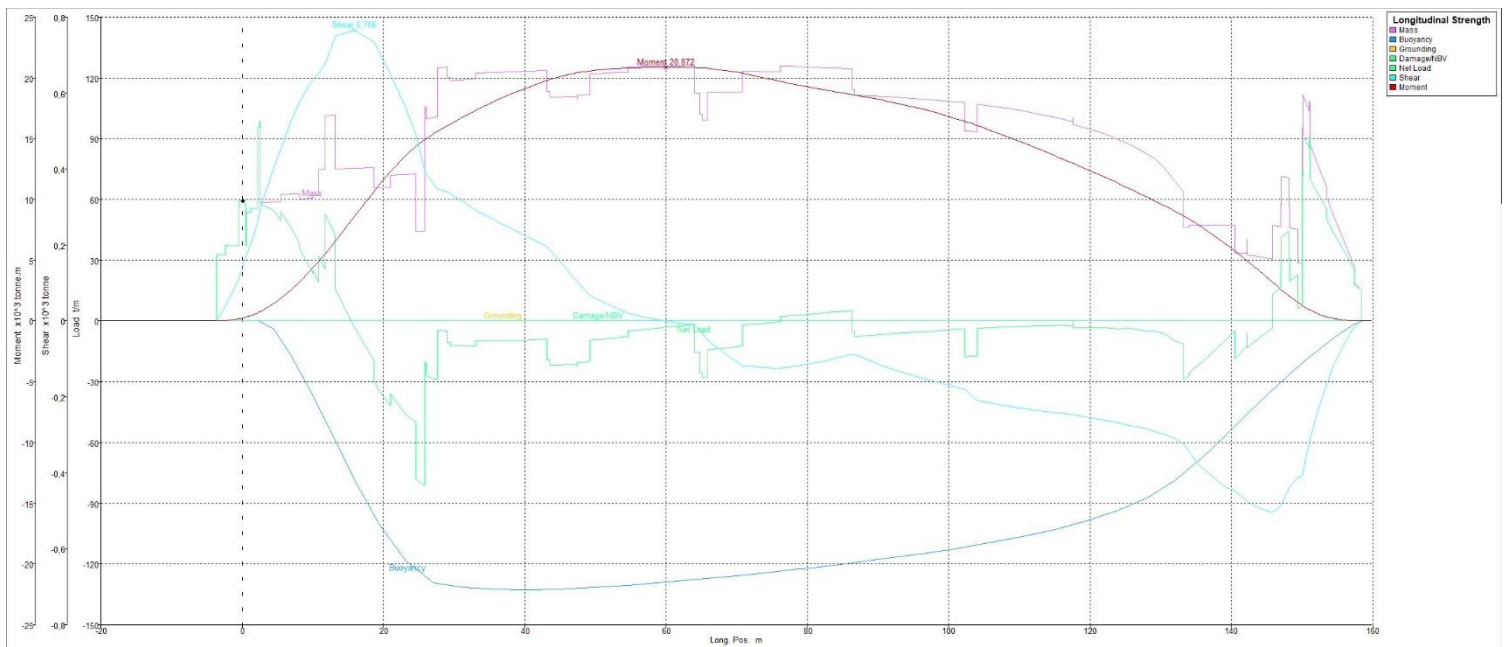
	in the range from the greater of spec. heel angle to the lesser of spec. heel angle	30 deg	30	
	angle of max. GZ shall not be less than (>=)	45 deg	45	
	Intermediate values	0,2 m	1,6	Pass 700
	angle at which this GZ occurs	deg	45	
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ shall not be less than (>=)	25 deg	45	Pass 80
267(85) Ch2 - General Criteria	2.2.4: Initial GMT spec. heel angle shall not be less than (>=)	0 deg		Pass
		0,15 m	2,232	Pass 1388
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling			Pass
	Wind arm: a PA (h - H) / (g disp.) cos^n(phi)			
	constant: a =	0,99966		
	wind pressure: P =	504 Pa		
	area centroid height (from zero point): h =	15,8 m		
	total area: A =	1139,1 m^2		
	H = mean draft / 2	3,124 m		
	cosine power: n =	0		
	gust ratio	1,5		
	Area2 integrated to the lesser of			
	2.3: IMO roll back angle from equilibrium (with steady heel arm)	20,8 (-19,5)	deg	-19,5
	Area 1 upper integration range, to the lesser of:			
	first downflooding angle	n/a	deg	
	angle of vanishing stability (with gust heel arm)	77,2	deg	77,2
	Angle for GZ(max) in GZ ratio, the lesser of:			
	angle of max. GZ	45	deg	45
	Select required angle for angle of steady heel ratio:	DeckEdgeImmersionAngle		Pass
	Criteria:			
	Angle of steady heel shall not be greater than (<=)	16	deg	1,3 Pass 91,91
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)	80	%	3,29 Pass 95,89
	Area1 / Area2 shall not be less than (>=)	100	%	723,63 Pass 623,63
	Intermediate values			
	Heel arm amplitude	m	0,05	
	Equilibrium angle with gust heel arm	deg	1,9	
	Deck edge immersion angle	deg	39,4	
	Area1 (under GZ), from 1,9 to 77,2 deg.	m.deg	71,8335	
	Area1 (under HA), from 1,9 to 77,2 deg.	m.deg	5,697	
	Area1, from 1,9 to 77,2 deg.	m.deg	66,1365	
	Area2 (under GZ), from -19,5 to 1,9 deg.	m.deg	-7,5139	
	Area2 (under HA), from -19,5 to 1,9 deg.	m.deg	1,6256	
	Area2, from -19,5 to 1,9 deg.	m.deg	9,1395	



1	Draft Amidships m	6,248
2	Displacement t	14701
3	Heel deg	0,0
4	Draft at FP m	5,255
5	Draft at AP m	7,242
6	Draft at LCF m	6,300
7	Trim (+ve by stern) m	1,987
8	WL Length m	154,33
9	Beam max extents on WL m	22,920
10	Wetted Area m^2	3914,6
11	Waterpl. Area m^2	3052,5
12	Prismatic coeff. (Cp)	0,750
13	Block coeff. (Cb)	0,595
14	Max Sect. area coeff. (Cm)	0,822
15	Waterpl. area coeff. (Cwp)	0,863
16	LCB from zero pt. (+ve fwd) m	75,386
17	LCF from zero pt. (+ve fwd) m	74,571
18	KB m	3,670
19	KG fluid m	9,704
20	BMT m	8,267
21	BML m	335,73
22	GMt corrected m	2,232
23	GML m	329,70
24	KMlt m	11,936
25	KML m	339,38
26	Immersion (TPc) tonne/cm	31,289
27	MTC tonne m	307,94
28	RM at 1deg = GMt.Disp.sin(1) tonne.	572,59
29	Max deck inclination deg	0,7233
30	Trim angle (+ve by stern) deg	0,7233

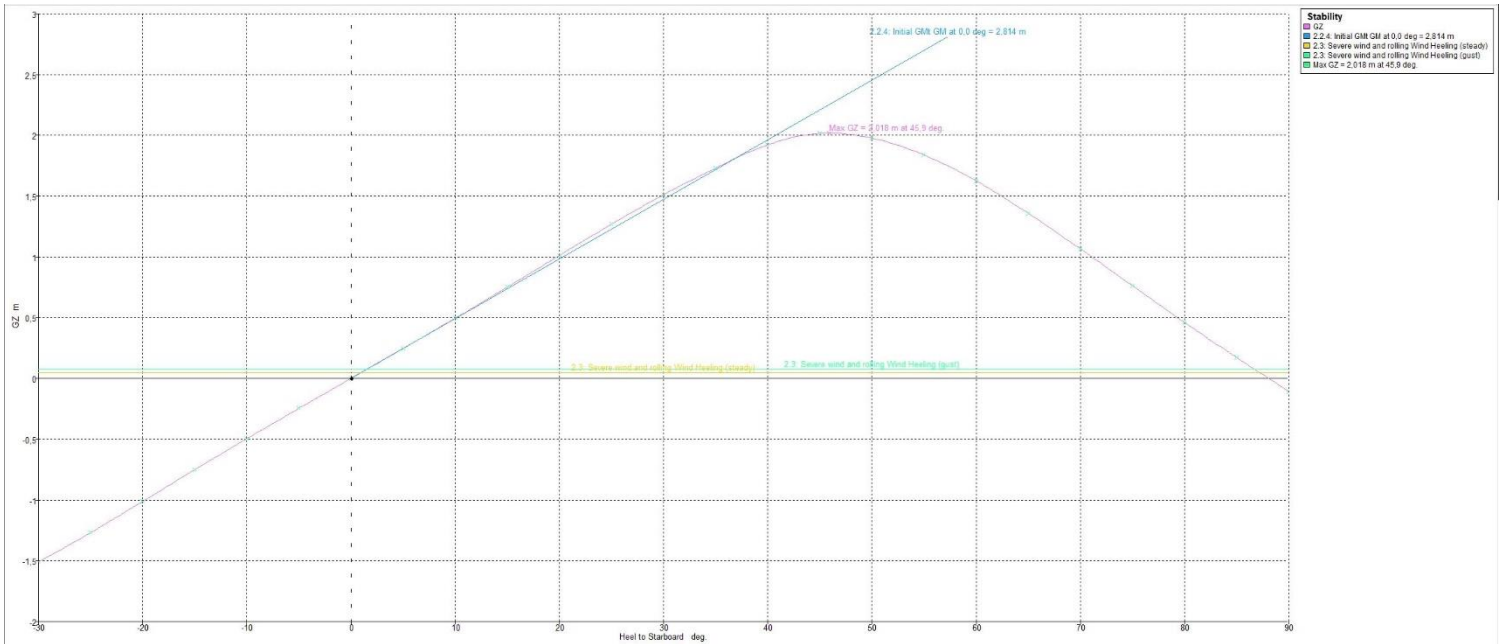
Arrival Port Ballast

	Item Name	Quantity	Unit Mass tonne	Total Mass tonne	Long. Arm m	Aft. Limit m	Fwd. Limit m	Vert. Arm m
1	Lightship	1	8441,830	8441,830	69,446			11,016
2	Tk 1 Fore peak	100%	268,986	268,986	152,599			7,061
3	Tk 2 BW 1 Port	100%	9,009	9,009	147,336			1,067
4	Tk 3 BW 1 Stb	100%	9,009	9,009	147,336			1,067
5	Tk 4 BW 2 Port	100%	8,895	8,895	143,627			1,051
6	Tk 5 BW 2 Stb	100%	8,895	8,895	143,627			1,051
7	Cargo Tank 1 CO2	0%	6525,714	0,000	122,237			1,600
8	Cargo Tank 2 CO2	0%	6525,714	0,000	84,022			1,600
9	Cargo Tank 3 CO2	0%	6525,716	0,000	45,807			1,600
10	Cargo Tank 1 NH3	0%	3853,280	0,000	122,237			1,600
11	Cargo Tank 2 NH3	0%	3853,280	0,000	84,022			1,600
12	Cargo Tank 3 NH3	0%	3853,280	0,000	45,807			1,600
13	Tk 6 BW 3 Port	100%	95,054	95,054	126,922			4,226
14	Tk 7 BW 3 STB	100%	95,054	95,054	126,922			4,226
15	Tk 8 BW 4 Port	100%	290,196	290,196	112,335			4,025
16	Tk 9 BW 4 STB	100%	290,196	290,196	112,335			4,025
17	Tk 10 BW 5 Port	100%	334,810	334,810	93,524			4,013
18	Tk 11 BW 5 STB	100%	334,810	334,810	93,524			4,013
19	Tk 12 BW 6 Port	100%	341,475	341,475	74,406			4,048
20	Tk 13 BW 6 STB	100%	341,475	341,475	74,406			4,048
21	Tk 14 BW 7 Port	100%	332,123	332,123	55,285			4,080
22	Tk 15 BW 7 STB	100%	332,123	332,123	55,285			4,080
23	Tk 16 BW 8 Port	100%	304,408	304,408	36,080			4,262
24	Tk 17 BW 8 STB	100%	304,408	304,408	36,080			4,262
25	Tk BW Aft Upper Port	0%	260,457	0,000	2,735			9,100
26	TK BW Aft Upper STB	0%	260,457	0,000	2,735			9,100
27	Fuel Aft STB	0,1	140,600	14,060	38,250	33,000	43,500	20,650
28	Fuel Aft Port	0,1	140,600	14,060	38,250	33,000	43,500	20,650
29	Fuel mid STB	0,1	140,600	14,060	59,850	54,600	65,100	20,650
30	Fuel mid Port	0,1	140,600	14,060	59,850	54,600	65,100	20,650
31	Fuel fore STB	0,1	140,600	14,060	81,450	76,200	86,700	20,650
32	Fuel fore Port	0,1	140,600	14,060	81,450	76,200	86,700	20,650
33	Tk 18 BW 3 Port Upper	100%	94,369	94,369	127,295			9,684
34	Tk 19 BW 3 STB Upper	100%	94,369	94,369	127,295			9,684
35	Tk 20 BW 4 Port Upper	100%	229,105	229,105	112,486			9,581
36	Tk 21 BW 4 STB Upper	100%	229,105	229,105	112,486			9,581
37	Tk 22 BW 5 Port Upper	100%	260,105	260,105	93,475			9,550
38	Tk 23 BW 5 STB Upper	100%	260,105	260,105	93,475			9,550
39	Tk 24 BW 6 Port Upper	100%	273,705	273,705	74,359			9,544
40	Tk 25 BW 6 STB Upper	100%	273,705	273,705	74,359			9,544
41	Tk 26 BW 7 Port Upper	100%	273,733	273,733	55,238			9,550
42	Tk 27 BW 7 STB Upper	100%	273,733	273,733	55,238			9,550
43	Tk 28 BW 8 Port Upper	100%	276,148	276,148	35,711			9,560
44	Tk 29 BW 8 STB Upper	100%	276,148	276,148	35,711			9,560
45	Total Loadcase			15041,44	74,054			9,141



Code	Criteria	Value	Units	Actual	Status	Margin %
267(85) Ch2 - General Criteria	2.3: IMO roll back angle					
	L, Stability calculated	155,413	m			
	B, Stability calculated	23,953	m			
	d, Stability calculated	6,337	m			
	GMf, Stability calculated	2,814	m			
	VCG, Stability calculated	9,141	m			
	CB, Stability calculated	0,575				
	Ak, keel area, user spec.	10,8	m ²			
	Method for k factor	Tabulated value for k				
	Evaluates to	21,1	deg			
	Intermediate values					
	B / d			3,78		
	100 Ak / L / B			0,29		
	C		IMO units	0,393		
	T		s	11,225		
OG, Centre of gravity above WL		m	2,804			
X1		IMO units	0,8			
X2		IMO units	0,92			
k tabulated		IMO units	0,994			
r		IMO units	0,995			
s		IMO units	0,07			
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 30				Pass	
	from the greater of spec. heel angle		0 deg	0		
	to the lesser of spec. heel angle		30 deg	30		
	angle of vanishing stability shall not be less than (>=)		88,1 deg			
			3,1513 m.deg	22,6499	Pass	618,75
267(85) Ch2 - General Criteria	2.2.1: Area 0 to 40				Pass	
	from the greater of spec. heel angle		0 deg	0		
	to the lesser of spec. heel angle		40 deg	40		
	first downflooding angle	n/a	deg			
	angle of vanishing stability shall not be less than (>=)		88,1 deg			
		5,1566 m.deg	39,9183	Pass	674,12	
267(85) Ch2 - General Criteria	2.2.1: Area 30 to 40				Pass	
	from the greater of spec. heel angle		30 deg	30		
	to the lesser of spec. heel angle		40 deg	40		
	first downflooding angle	n/a	deg			
	angle of vanishing stability shall not be less than (>=)		88,1 deg			
		1,7189 m.deg	17,2685	Pass	904,62	
267(85) Ch2 - General Criteria	2.2.2: Max GZ at 30 or greater				Pass	

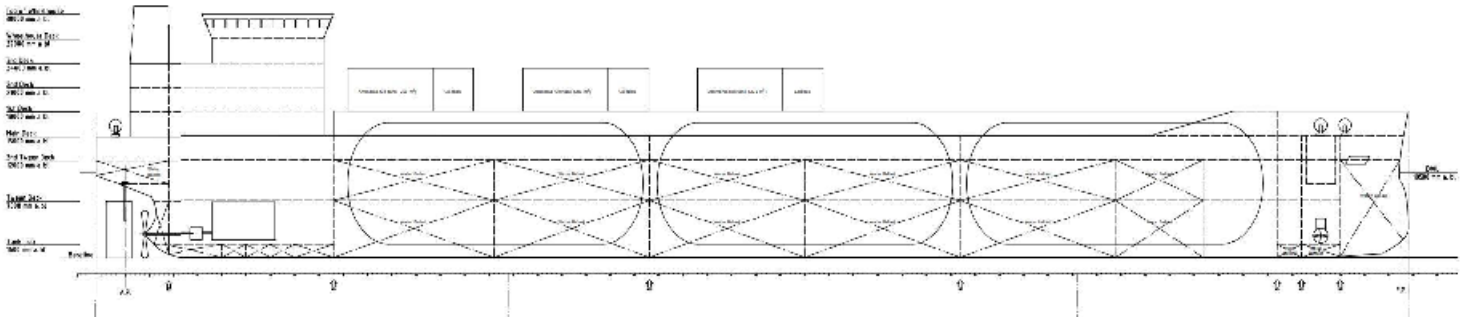
	in the range from the greater of spec. heel angle to the lesser of spec. heel angle		30 deg	30		
	angle of max. GZ shall not be less than (>=)		45,9 deg	45,9		
	Intermediate values		0,2 m	2,018	Pass	909
	angle at which this GZ occurs		deg	45,9		
267(85) Ch2 - General Criteria	2.2.3: Angle of maximum GZ shall not be less than (>=)		25 deg	45,9	Pass	83,64
267(85) Ch2 - General Criteria	2.2.4: Initial GMt				Pass	
	spec. heel angle		0 deg			
	shall not be less than (>=)		0,15 m	2,814	Pass	1776
267(85) Ch2 - General Criteria	2.3: Severe wind and rolling				Pass	
	Wind arm: $a P A (h - H) / (g \text{ disp.}) \cos^n(\phi)$					
	constant: a =		0,99966			
	wind pressure: P =		504 Pa			
	area centroid height (from zero point): h =		15,8 m			
	total area: A =		1139,1 m ²			
	H = mean draft / 2		3,169 m			
	cosine power: n =		0			
	gust ratio		1,5			
	Area2 integrated to the lesser of					
	2.3: IMO roll back angle from equilibrium (with steady heel arm)		21,1 (-20,1)	deg	-20,1	
	Area 1 upper integration range, to the lesser of:					
	first downflooding angle	n/a		deg		
	angle of vanishing stability (with gust heel arm)		86,8	deg	86,8	
	Angle for GZ(max) in GZ ratio, the lesser of:					
	angle of max. GZ		45,9	deg	45,9	
	Select required angle for angle of steady heel ratio:	DeckEdgeImmersionAngle				
	Criteria:				Pass	
	Angle of steady heel shall not be greater than (<=)		16	deg	1	Pass 93,75
	Angle of steady heel / Deck edge immersion angle shall not be greater than (<=)		80	%	2,71	Pass 96,61
	Area1 / Area2 shall not be less than (>=)		100	%	812,88	Pass 712,88
	Intermediate values					
	Heel arm amplitude		m		0,049	
	Equilibrium angle with gust heel arm		deg		1,5	
	Deck edge immersion angle		deg		36,9	
	Area1 (under GZ), from 1,5 to 86,8 deg.		m.deg		101,0139	
	Area1 (under HA), from 1,5 to 86,8 deg.		m.deg		6,2848	
	Area1, from 1,5 to 86,8 deg.		m.deg		94,7291	
	Area2 (under GZ), from -20,1 to 1,5 deg.		m.deg		-10,0592	
	Area2 (under HA), from -20,1 to 1,5 deg.		m.deg		1,5943	
	Area2, from -20,1 to 1,5 deg.		m.deg		11,6535	



1	Draft Amidships m	6.337
2	Displacement t	15042
3	Heel deg	0.0
4	Draft at FP m	5.011
5	Draft at AP m	7.663
6	Draft at LCF m	6.421
7	Trim (+ve by stern) m	2.652
8	WL Length m	155.42
9	Beam max extents on WL m	23.041
10	Wetted Area m ²	3965.6
11	Waterpl. Area m ²	3088.0
12	Prismatic coeff. (Cp)	0.729
13	Block coeff. (Cb)	0.575
14	Max Sect. area coeff. (Cm)	0.820
15	Waterpl. area coeff. (Cwp)	0.862
16	LCB from zero pt. (+ve fwd) m	73.952
17	LCF from zero pt. (+ve fwd) m	73.698
18	KB m	3.751
19	KG fluid m	9.141
20	BMt m	8.205
21	BML m	338.24
22	GMt corrected m	2.815
23	GML m	332.85
24	KMlt m	11.955
25	KML m	341.94
26	Immersion (IPc) tonne/cm	31.652
27	MTc tonne.m	318.08
28	RM at 1deg = GMt Disp sin(1) tonne	738.90
29	Max deck inclination deg	0.9654
30	Trim angle (+ve by stern) deg	0.9654

Appendix G

NH3 & CO2 Gas Carrier Spesification



Main Particulars	
DWT [ton]	20 018 ton
LWT [ton]	8 442 ton
Displacement [ton]	28 460 ton
L _{pp} [m]	157,4 m
L _{oa} [m]	162 m
B [m]	24 m
T [m]	10,5 m
D [m]	15 m
C _B [-]	0,70
L/B [-]	6,56
B/T [-]	2,29
B/D [-]	1,60
L/D [-]	10,49

Machinery and Propulsion System	
Main Engine	MAN 2-stroke ammonia engine
Power Transmission	Mechanical shaft
Propeller	1 x Fixed Pitch Propeller
Electricity Production	Shaft Generator (PTO/PFI/PTH) & Wärtsilä 4-stroke ammonia generator sets
Bow Thruster	Electric thruster motor

Loading Capacity	
Cargo	19 577 tons / 16 950 m ³
Fuel	843 tons / 1 237 m ³
Ballast	7 036 tons / 6 865 m ³

