

# ZIVID

3D TECHNOLOGY BY ZIVID LABS

## QUICK USER GUIDE



[WWW.ZIVID.COM](http://WWW.ZIVID.COM)

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## **SAFETY** **01**

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- Please read the quick user guide before installation and use.
- Connections, assembly and settings must be performed by competent technicians.
- Do not connect external I/O signals to the device while it is powered. This may damage the device.

## **PRODUCT SPECIFICATIONS** **02**

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- The camera is primarily targeted at industrial applications, such as 3D machine vision, in-line inspection in manufacturing and 3D part localization for robots.
- Zivid acquires point cloud data (x, y, z) and RGB colors with the same sensor chip. One-to-one correspondence between color and depth. The device is factory calibrated and ready to use.

## **CONNECTIVITY I/O** **03**

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- The device should be connected to a 24 VDC power supply and a PC running Windows 7/8/10 via USB 3 interface.
- The Sync input is for future use.

## **SYSTEM REQUIREMENTS** **04**

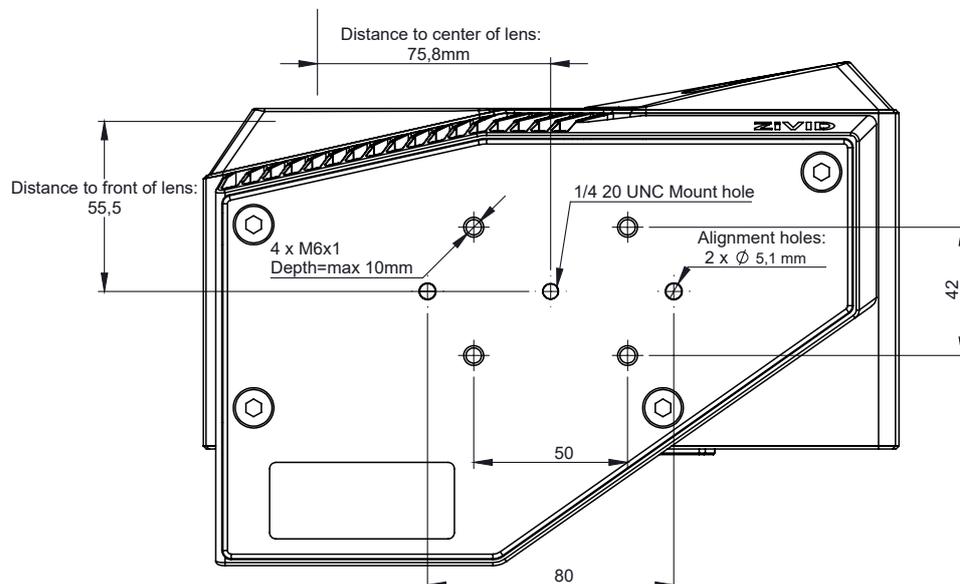
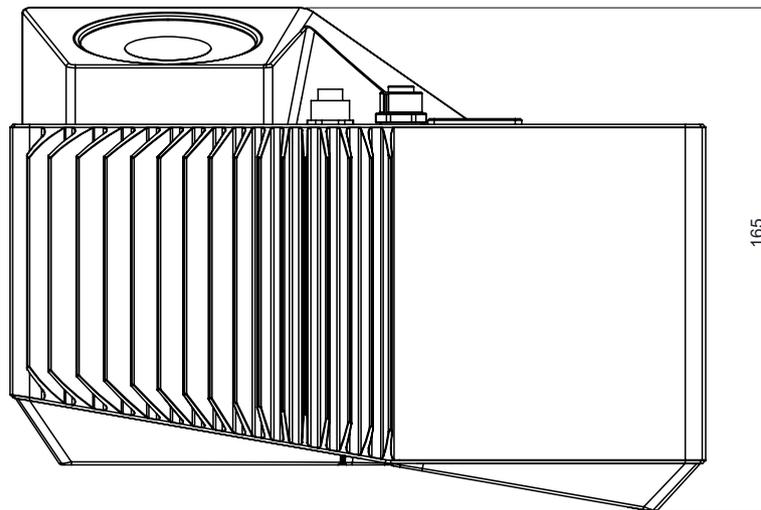
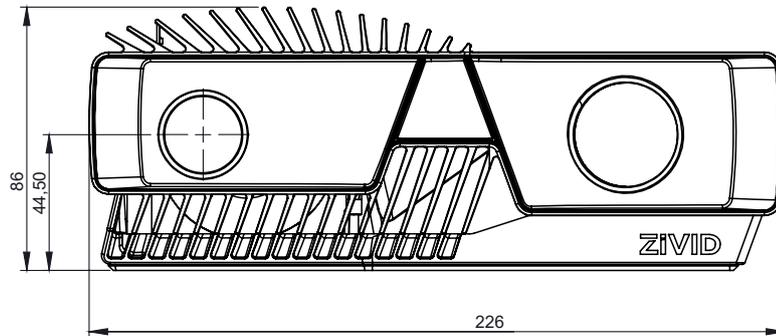
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- OS: Windows 7/8/10
- PC: DirectX 11 compatible graphics card and minimum 1xUSB3 SuperSpeed port available
- Interface: USB3 (SuperSpeed)



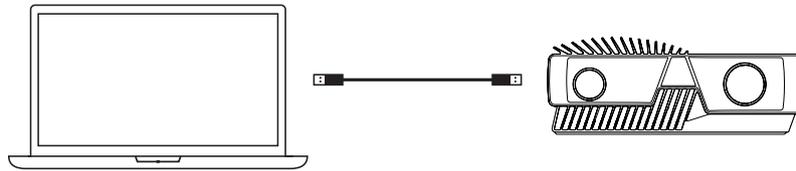
## DIMENSIONS AND MOUNTING

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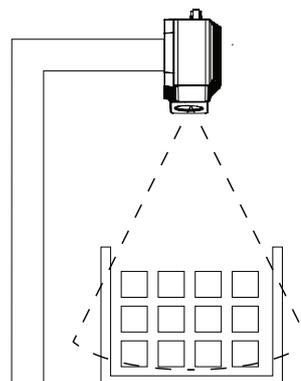
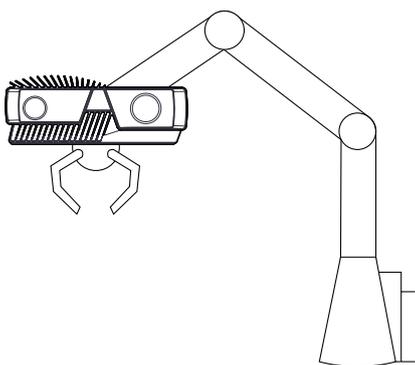


## INSTALLATION

06



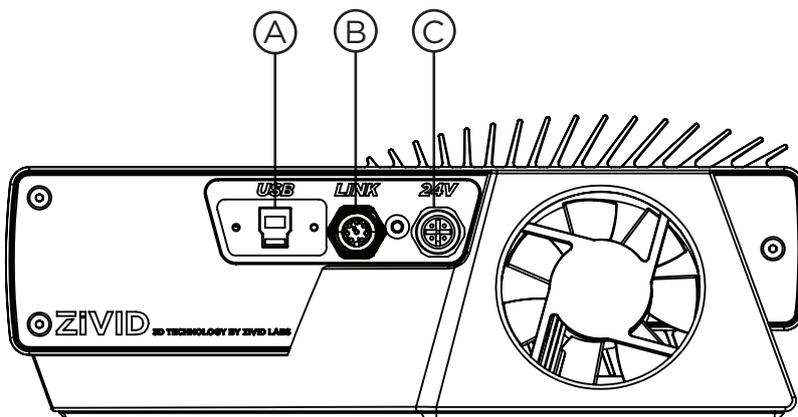
- Install the latest version of Zivid Software from [www.zivid.com/software](http://www.zivid.com/software). See further install instructions there.
- Mount the device using the interface bracket underneath the device.
- Connect the USB3 cable to the product and PC.
- Plug the power cable to the M12 connector (24VDC 5A).
- Connect the power supply to 100/240 VAC.
- For more guidance on installation and usage, please refer to [www.zivid.com/support](http://www.zivid.com/support).



## CONNECTIVITY

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- A : USB3: DATA
- B : M12-8: External Sync
- C : M12-5: Power (24VDC)



- For more guidance on usage and troubleshooting, please refer to [www.zivid.com/support](http://www.zivid.com/support).

A: DATA. USB SuperSpeed USB-B (USB3.0 Camera interface, USB2.0 Control Interface).

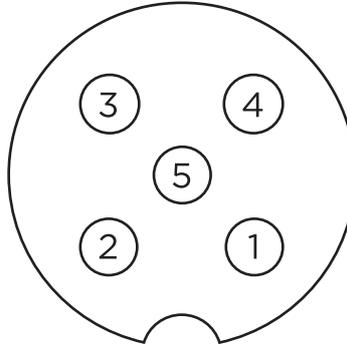
- USB SuperSpeed type-B receptacle for PC connection. Note: PC must support USB 3.0 SuperSpeed. Cables need to be “USB3 Vision” compliant.

B: SYNC. Interface Connector (for future use).

- Synchronization and external trigger interface.

C: 24V. Power Connector 24V, 5A DC





| Pin |                         |
|-----|-------------------------|
| 1   | 24V DC +/- 20% (Max 4A) |
| 2   | 24V DC +/- 20% (Max 4A) |
| 3   | GND                     |
| 4   | GND                     |
| 5   | SENSE SIGNAL (optional) |

- Power-supply interface for the Zivid unit. Exceeding the limit values may cause permanent damage. Please note the power ratings if power is provided from other sources than the supplied AC/DC converter.
- The unit is protected against reverse polarity.
- The unit is protected against overheating by a thermistor that physically removes the power.

Optional mating connector : TE Connectivity AMP, 1838275-3 (Digikey: A97645-ND)



## SERVICE AND MAINTENANCE

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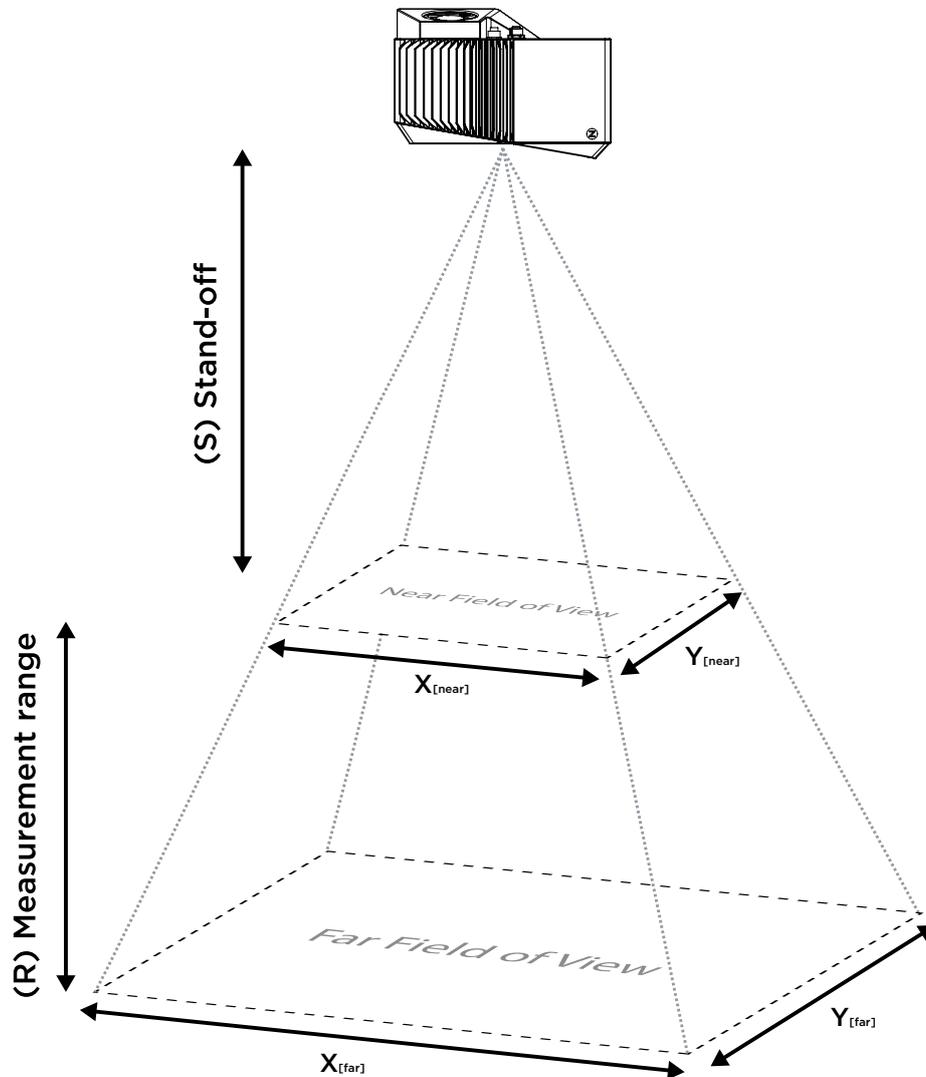
08

- The device contains no user serviceable parts inside. The warranty of the product will be void if opened.
- Check screw connections and connectors at regular intervals.
- Do not block the air opening on the front and rear side of the product.
- The device is dust resistant thus completely sealed. However, in case there are dust or other particles building up on the front glasses or in between the ribs of the heat sink, you should either use a small vacuum cleaner or a small canister of compressed air to remove the unwanted particles.
- In case of unit failure, please contact:  
**[support@zivid.com](mailto:support@zivid.com)**



## VOLUME OF VIEW

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| Zivid  | Distances    |
|--|--------------|
| (S) Stand-off distance [overlap]                                 | 600 mm       |
| (R) Measurement range [overlap]                                  | 500 mm       |
| (S+R) Maximum distance [overlap]                                 | 1100 mm      |
| Near Field of View image area ( $X_{[near]} \times Y_{[near]}$ ) | 430 x 270 mm |
| Far Field of View image area ( $X_{[far]} \times Y_{[far]}$ )    | 780 x 490 mm |

Only optimal ranges are listed which includes full overlap between the field-of-view of the projector and the imaging sensor. The 3D camera can work beyond these limits both at closer range and above the maximum overlap distance at 1100 mm. However, outside these ranges there's only partial overlap and certain loss in quality can be expected at the far ranges.



## TECHNICAL DATA

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| Zivid                    | Specifications  |
|--------------------------|---|
| Output                   | 2.3 Mpixels 3D RGB image (x,y,z and RGB for each pixel)   |
| Acquisition rate         | ≥10 Hz, 100 ms snapshot   |
| Optimal Working Distance | 0.6 m - 1.1 m   |
| Depth Resolution         | 0.1 mm @ 0.6 m  |
| Software APIs            | C++, C#, .NET, Python, MATLAB   |
| OS                       | Windows 7/8/10  |
| Housing                  | Rugged aluminum<br>Water & dust resistant   |
| Dimensions               | 226 x 165 x 86 mm   |
| Weight                   | 2 kg  |
| Input                    | 24 VDC, 5A  |
| Interfaces & Connectors  | USB 3.0: Data I/O<br>M12-5: Power & Status<br>M12-8: Sync I/O                                   |
| Available USB 3.0 cables | 5m USB High Flex [standard]<br>10m Optical USB 3.0 [optional]<br>25m Optical USB 3.0 [optional] |
| PC requirements          | DirectX11 compatible,<br>USB3 SuperSpeed  |
| Safety standards         | EN60950, UL950,<br>FCC class A, CE  |
| Environmental            | According to IEC60068   |



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