

<b>Subject: TELE 3031</b>		<b>Date: 15.01.21</b>
<b>Project:</b> Bachelor thesis, Hybrid Obstacle-Aided Locomotion (HOAL)		
<b>Activity:</b> Preliminary project		<b>Activity nr:</b> 05
<b>Start date:</b> 12.01.2021		<b>End date:</b> 15.02.2021
<b>Dependency:</b>	<b>Previous activity:</b> Create Gantt diagram, read up on snake robot, Risk evaluation.	
	<b>Next activity:</b> Find relevant sensors.	
<b>Goal:</b> Creating a detailed document which contains general information about the project, such as technical specifications and project management.		
<b>Job description:</b> Create a LaTeX document for the preliminary project. Divide the LaTeX document into multiple subchapters: <ul style="list-style-type: none"><li>- Introduction</li><li>- Technical part</li><li>- Project management</li></ul> Add the Gantt diagram and work packages to the preliminary project.		
<b>Number of hours:</b> 150 h		<b>Distribution:</b> Entire group
<b>Cost:</b> Time		
<b>Resources:</b> PC, LaTeX		
<b>Risk:</b>		
<b>Academic responsibility:</b> Jostein Løwer (JL)/Pål Mathisen (PM)		
<b>Project participants:</b> Joel Mörlin (JM) Victor Melhuus (VM) Oscar Mørk (OM)		