

Subject: TELE 3031		Date: 15.01.21
Project: Bachelor thesis, Hybrid Obstacle-Aided Locomotion (HOAL)		
Activity: Find relevant sensors or parts for the sensor system		Activity nr: 06
Start date: 15.02.2021		End date: 15.03.2021
Dependency:	Previous activity: Preliminary project	
	Next activity: Research market for relevant sensors	
Goal: Getting familiar with wanted specifications for the mamba robot and find sensors and/or parts that fits the specifications.		
Job description: Become familiar with different sensors and parts which could be used for creating a fitting sensor system. Produce a list/document with information about the different parts/sensors which could be relevant and present them to the employer.		
Number of hours: 100 h		Distribution: Entire group
Cost: Time		
Resources: PC, Specifications of mamba robot		
Risk:		
Academic responsibility: Jostein Løwer (JL)/Pål Mathisen (PM)		
Project participants: Joel Mörlin (JM) Victor Melhuus (VM) Oscar Mørk (OM)		