

Subject: TELE 3031		Dato: 18.01.21
Project: Bachelor thesis, Hybrid Obstacle-Aided Locomotion (HOAL)		
Activity: Build a testbench in LabView for testing the snake		Activity nr: 08
Start date: 15.03.2021		End date: 15.04.2021
Dependency:	Previous activity: Research the market for necessary sensors.	
	Next activity: Build a test model of the snake robot for testing.	
Goal: To create a testbench in LabView which can be used for testing of the sensor system.		
Job description: Shape and design a test program which can collect the necessary information about the system such as force and torque over time		
Number of hours: 100 h		Distribution: Entire group
Cost: Time		
Resources: PC, LabView		
Risk:		
Academic responsibility: Jostein Løwer (JL)/Pål Mathisen (PM)		
Project participants: Joel Mörlin (JM) Victor Melhuus (VM) Oscar Mørk (OM)		