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Modeling time to population extinction when individual reproduction is autocorrelated

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Abstract

35	In nature, individual reproductive success is seldom independent from year to
36	year, due to factors such as reproductive costs and individual heterogeneity.
37	However, population projection models that incorporate temporal
38	autocorrelations in individual reproduction can be difficult to parameterize,
39	particularly when data are sparse. We therefore examine whether such
40	models are necessary to avoid biased estimates of stochastic population
41	growth and extinction risk, by comparing output from a matrix population
42	model that incorporates reproductive autocorrelations to output from a
43	standard age-structured matrix model that does not. We use a range of
44	parameterizations, including a case study using moose data, treating
45	probabilities of switching reproductive class as either fixed or fluctuating.
46	Expected time to extinction from the two models is found to differ by only
47	small amounts (under $10\%)$ for most parameterizations, indicating that
48	explicitly accounting for individual reproductive autocorrelations is in most
49	cases not necessary to avoid bias in extinction estimates.

50 INTRODUCTION

The stochastic dynamics and structure of populations is determined by patterns of 51 variation in fecundity and survival over the lifetime of individuals. Age-dependence 52 is one important source of such patterns, and age-structured population models are 53 therefore extensively used in studies of population dynamics (e.g. Caswell 2001). 54 However, survival and reproduction are realized at the level of individuals, and 55 individual demographic rates are not necessarily independent. This gives rise to 56 correlations in individual demographic rates, potentially influencing population 57 dynamics. For instance, trade-offs between reproduction and survival have been 58 widely documented (Stearns 1989), and simulation studies have shown that these 59 trade-offs can have major effects on population dynamics (Proaktor et al. 2008; 60 Kuparinen et al. 2012). Similarly, trade-offs between current and future 61 reproduction have frequently been documented (Stearns 1989; Roff 2002), but 62 population effects of these trade-offs are more difficult to study using traditional 63 population models, due to the temporal aspect of the correlation. 64

Correlations in individual reproductive success from one year (or time 65 step) to the next (hereafter "reproductive autocorrelations") are found in a wide 66 range of taxa, including birds (Cam et al. 1998; Veran & Beissinger 2009), 67 mammals (Boyd et al. 1995; Hamel et al. 2010), amphibians (Yurewicz et al. 2004), 68 reptiles (Rivalan et al. 2005) and plants (Obeso 2002). Such autocorrelations can 69 be produced by different underlying biological processes. If reproduction carries a 70 cost in terms of energy use (Stearns 1992; Edward & Chapman 2011) we might 71 expect negative reproductive autocorrelation if offspring production in one year 72

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reduces the energy an individual has available for offspring production the next 73 year, or if energy from non-breeding years can be saved up for future breeding (Roff 74 2002; Yurewicz et al. 2004; Hamel et al. 2010). Individual heterogeneity in female 75 quality is more likely to cause positive autocorrelation with some females 76 consistently producing more offspring than others (Högstedt 1980; Weladji et al. 77 2008). There are two main explanations for individual heterogeneity. There may be 78 differences among individuals that are fixed from birth or shortly after ("fixed 79 heterogeneity"; e.g., individuals with different probabilities of producing offspring), 80 or differences may be the outcome of stochastic processes with identical underlying 81 fitness traits ("dynamic heterogeneity"; e.g., individuals with the same underlying 82 probability of producing offspring but with different realized offspring production) 83 (Tuljapurkar et al. 2009; Cam et al. 2016). Although we generally assume one or 84 the other in population models, it is likely that both types of heterogeneity are 85 present in real populations (Steiner et al. 2010; Plard et al. 2015; Cam et al. 2016). 86 Previous studies have shown that temporal autocorrelation in the 87 environment can affect the dynamics and expected time to extinction of 88 populations (Petchey et al. 1997; Levine & Rees 2004; Ruokolainen et al. 2009). 89 However, empirical studies suggest that long-term effects on population growth of 90 vital rate autocorrelations caused by stochastic environments are small (Morris 91 et al. 2011; Ferguson et al. 2016), and theoretical analyses indicate that the 92 temporal scaling of environmental autocorrelation must be long to have real impact 93 on long-term population growth rates (Engen et al. 2013). Environmental 94 fluctuations affect vital rates of all individuals in a population simultaneously (but 95

not necessarily identically), and can therefore create autocorrelations in the total 96 reproductive output of the population. The environmental variance, σ_e^2 , captures 97 this by measuring among-year variation in the expected individual contributions to 98 the future population, caused by temporal fluctuations in the environment (Engen 99 et al. 2009). In contrast, the within-individual reproductive autocorrelations we 100 focus on here create (or are created by) differences among individuals, and can be 101 more stable over time. These autocorrelations in individual reproductive histories 102 can be expected to affect the demographic variance, σ_d^2 , which measures the 103 temporal mean of the within-year variance in individual contributions (calculated 104 from the variance in individual contributions to the future population from within 105 each class, as well as covariances between them, weighted by the stable stage 106 structure; see Engen et al. (2009) and Appendix S1) (Kendall & Fox 2002; 107 Vindenes et al. 2008). Both environmental and demographic stochasticity 108 (measured by σ_e^2 and σ_d^2) act to decrease long-run stochastic population growth 109 (Lande et al. 2003). It is therefore important to account for them when analyzing 110 stochastic population dynamics and extinction risk. 111

In the presence of reproductive autocorrelations, age-structured projection matrices are no longer independent across time steps, potentially introducing biases in estimated stochastic population dynamics. Models that classify individuals by reproductive success or stage in addition to age can be used to project population dynamics in the presence of reproductive autocorrelations (Cam et al. 2002; Jenouvrier et al. 2005, 2015; Steiner et al. 2010; Waugh et al. 2015), but they require estimation of a large number of parameters, requiring high-quality long-term data sets that are available for a limited number of populations. This
raises the question of how much individual reproductive autocorrelations affect
stochastic population dynamics, and how much bias is likely to be introduced into
estimates of extinction dynamics if such autocorrelations are present without being
accounted for in our models.

Here, we examine the effect of incorporating autocorrelations in individual 124 reproductive rates when calculating population growth rates and expected time to 125 extinction. We derive the demographic variance in a stochastic matrix population 126 model that incorporates different types of autocorrelation in individual 127 reproductive rates, and analyze different parameterizations of this model, with and 128 without environmental fluctuations. Calculated growth rates and extinction times 129 are compared to those obtained from a standard age-structured model without 130 autocorrelations. Finally, we present a case study, parameterizing the model with 131 estimates from a wild population of moose, *Alces alces*, that show positive 132 reproductive autocorrelations. 133

134 MATERIAL AND METHODS

135 General model

Consider an age-structured population model with a stochastic projection matrix, L, such that $n_{\tau+1} = Ln_{\tau}$ describes the population vector at time $\tau + 1$, given the population vector at time τ . The population vector is a column vector of the number of females in each of k age classes, $n_{\tau} = (n_1, n_2, \dots, n_k)^T$, where the superscript T indicates a transposed vector. Each age class is further divided into classes based on number of offspring produced, such that $n_i = n_{i,0}, n_{i,1}, \ldots, n_{i,\alpha_i}$, where the second subscript indicates the number of offspring, and α_i is the maximum number of offspring produced by a female of age *i*. As presented, this model is most useful for species with low α_i -values (but see Appendix S2).

We assume individuals are counted after reproduction, so that the number 145 of offspring produced by each individual is known. However, in contrast to ordinary 146 postbreeding census models (Caswell 2001), this model does not have a class of 147 newborns. Offspring that survive their first year enter the class of one-year-olds one 148 time step after they are born. Up until that point they are included in the model 149 through their mother only. Since females are classified according to number of 150 offspring produced, the count of females in different classes also contains 151 information about the number of newborn offspring in the population. The last age 152 class is assumed to have 0 survival. 153

In the classical, age-structured case, all surviving individuals of age i enter 154 the single class of (i + 1)-year-olds at the next time step. However, in our model 155 there are α_{i+1} possible classes for surviving *i*-year-olds to enter, depending on their 156 offspring production at age i + 1. Thus, transitions are driven by the product of 157 survival probability and the probability of producing m offspring at time $\tau + 1$. 158 Both of these probabilities could depend on the number of offspring produced at 159 time τ . Let $s_{i,j}$ (for i > 0) be the survival probability from age i to i + 1 of an 160 individual that produced j offspring at age i, and let $q_{i,mj}$ be the probability of 161 such an individual producing m offspring at age i + 1, given survival. Note that the 162

comma in the subscripts separates age indices from reproductive class indices. 163 Then, an individual from age class i that produced j offspring has probabilities 164 $(s_{i,j}q_{i,0j}; s_{i,j}q_{i,1j}; ...; s_{i,j}q_{i,\alpha_{i+1}j})$ of surviving and producing $0, 1, ..., \alpha_{i+1}$ offspring, 165 respectively, at age i + 1, as well as a probability $1 - s_{i,j}$ of not surviving. The 166 mean projection matrix has the same general form as a standard Leslie matrix, 167 with fecundities b_1, \ldots, b_k in the first row, and survival and transition into the next 168 age class, p_1, \ldots, p_{k-1} , on the subdiagonal (Caswell 2001). However, instead of each 169 entry being a single number, as in the classical age-structured case, each entry now 170 consists of a submatrix of the form 171

$$p_{i} = \begin{bmatrix} s_{i,0}q_{i,00} & \dots & s_{i,\alpha_{i}}q_{i,0\alpha_{i}} \\ \vdots & \ddots & \vdots \\ s_{i,0}q_{i,\alpha_{i+1}0} & \dots & s_{i,\alpha_{i}}q_{i,\alpha_{i+1}\alpha_{i}} \end{bmatrix},$$
(1)

where each possible combination of offspring production at age i and i + 1 has an entry, resulting in a projection matrix with $\sum_{i=1}^{k} (\alpha_i + 1)$ rows and $\sum_{i=1}^{k} (\alpha_i + 1)$ columns. The $q_{i,mj}$ sum to one within each column. The exact form of the submatrices depends on assumptions of the model (see Appendix S2).

If we can assume that one-year-olds do not reproduce, such that all offspring enter the same class, the b_i entries are $b_1 = 0$, and

 $b_i = (s_0 \cdot 0, s_0 \cdot 1, \dots, s_0 \cdot \alpha_i) = (0, s_0, \dots, s_0 \alpha_i)$ for i > 1, where s_0 is the probability of newborns being female and surviving to age one. Since the model only keeps track of females, we have merged offspring survival and sex ratio into a single rate to simplify notation. The number of offspring born is given directly by the class of mothers $(0, 1, ..., \alpha_i)$ within each age. If one-year-olds do reproduce we must keep track of both which class the mother is in, and which class the offspring end up in. Then, each b_i can be written as

$$b_{i} = \begin{bmatrix} 0 & s_{0}t_{0} & \dots & s_{0}\alpha_{i}t_{0} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & s_{0}t_{\alpha_{1}} & \dots & s_{0}\alpha_{i}t_{\alpha_{1}} \end{bmatrix},$$
(2)

where t_k is the probability of a one-year-old producing k offspring. Some useful expansions of this model are presented in Appendix S2. Derivation of the demographic and environmental variances is presented in Appendix S1.

188 Model analysis

We used our model to calculate σ_d^2 for several systems with autocorrelations in 189 reproductive success, and compared these quantities to σ_d^2 calculated from a 190 standard age-structured model (Leslie matrix) of the same systems (equation 4 in 191 Engen et al. 2009). The survival and fecundity parameters for the Leslie matrix 192 were calculated from the parameters for each subclass in the more complicated 193 reproductive autocorrelation model by weighting them by the stable stage structure 194 (found from the right eigenvector of the mean projection matrix; Caswell 2001). 195 We calculated the distribution of expected time to extinction using the equation 196

$$P(T_{ext} \le \tau) = \exp\left[-\frac{2N_0 \ln(\lambda)}{\sigma_d^2 (1 - e^{-\ln(\lambda)\tau})}\right],\tag{3}$$

where T_{ext} is time to extinction, τ is time, and N_0 is the population size at time 0 197 (Cox & Miller 1970; Engen et al. 2005b). This equation utilizes the fact that a 198 diffusion approximation with just three parameters (the expected growth rate and 199 the demographic and environmental variances) gives accurate estimates of the 200 distribution of population size over time in age-structured populations (Engen 201 et al. 2005b). We confirmed that this also holds for the model with reproductive 202 autocorrelations by comparing simulated population trajectories with diffusion 203 approximations (Appendix S3). The estimated distributions from equation 3 204 matched time to extinction found from simulations of the full system (Appendix 205 S3). In systems with environmental stochasticity, expected time to extinction was 206 found by simulation. We selected systems to cover a range from extreme levels of 207 reproductive autocorrelation to moderate levels that we expect to be common in 208 natural populations, focusing on systems with relatively long-lived individuals 209 where lifetime reproductive success is gained through several reproductive events. 210

We tested the sensitivity of our results to the choice of survival parameters 211 by calculating the maximum deviation in mean expected time to extinction 212 $(\max(\Delta T_{ext}))$; i.e. how much the expected time to extinction deviated from that of 213 the Leslie model in the most extreme case of each model) when s_0 and then s_i were 214 varied one at a time. Here, $\Delta \bar{T}_{ext} = (\bar{T}_{ext,Les} - \bar{T}_{ext,Rac})/\bar{T}_{ext,Les}$, where $\bar{T}_{ext,Les}$ and 215 $T_{ext,Rac}$ are the calculated mean expected time to extinction in the plain 216 age-structured model (Les) and the model with reproductive autocorrelations 217 (Rac), respectively. The number of age classes in the model was adjusted such that 218 the proportion of individuals expected to reach the last age class (after which they 219

all die) was just under 0.05.

System 1, Switching or staying: In our first system females produced 0 221 or 1 offspring, and the probability of switching reproductive status, w, was the 222 same for all ages and in both directions (i.e., the probability of transitioning from 223 breeder to nonbreeder equaled the probability of transitioning from nonbreeder to 224 breeder; Appendix S4). Survival was set relatively high $(s_0 = 0.25, s_i = 0.85)$, and 225 results were found for a range of w, from 0.0001 to 0.9999. Here, w = 0.5 describes 226 a system without reproductive autocorrelations, w < 0.5 gives positive 227 autocorrelations (at any time step individuals are more likely to stay in the same 228 reproductive class than to switch), and w > 0.5 gives negative autocorrelations 229 (probability of switching reproductive status is greater than probability of not 230 switching). All remaining individuals were assumed to die at age 11. We added 231 environmental stochasticity by letting the probability of breeding at age 1, t_1 , vary 232 over time according to a symmetric beta distribution with mean 0.5 and different 233 variances. This gives a hump-shaped distribution centered on 0.5 (see Fig. S5.1 in 234 Appendix S5). As the variance increases, the distribution eventually becomes 235 uniform (flat) between 0 and 1. 236

System 2, Individual heterogeneity: In our second system, females could produce 0 or 1 offspring at age one, and 0, 1 or 2 offspring at older ages. The probability of staying in the same breeding class from one time step to the next, h, varied from 0.49 to 0.96, while the probability of going from nonbreeder (0 offspring) to highly successful (2 offspring) or back was very low (0.02). This created varying degrees of heterogeneity among individuals (see Appendix S4 for full transition matrix). We adjusted t_1 to hold λ constant as h varied. This was not necessary in the first system due to symmetry in the transition probabilities. We calculated the demographic variance and expected time to extinction given the different values of h, and then calculated a new time to extinction when h was allowed to vary stochastically through time according to a symmetric beta distribution with mean 0.725.

System 3, Gradual increase in reproductive success: Finally, we 249 analyzed a system where individuals were likely to improve their breeding situation 250 over time, such that highly successful breeders were likely to remain successful, 251 females with a single offspring were likely to produce one or two offspring at the 252 next time step, and nonbreeders were likely to either remain as nonbreeders or 253 produce one offspring. We expect this to be a common situation in long-lived 254 species. The probability of transitioning to a more successful state increased as h255 was varied from 0.49 to 0.96 (Appendix S4). λ was again held constant by 256 adjusting t_1 . 257

All calculations were performed in R 3.3.2 (R Core Team 2016). R code for setting up and analyzing matrix models with reproductive autocorrelations is provided in Appendix S6.

261 **RESULTS**

In systems without reproductive autocorrelations our model gave the same demographic variance, σ_d^2 , as an age-structured Leslie model (Fig. 1a), but as

reproductive autocorrelations became stronger (positive or negative) the 264 demographic variance deviated from that found from a Leslie matrix (Fig. 1a, 2a). 265 Positive autocorrelations increased the demographic variance (Fig. 1a, 2a) and 266 shortened the expected time to extinction (Fig. 1b, 2b), whereas negative 267 autocorrelations decreased the demographic variance (Fig. 1a) and hence increased 268 expected time to extinction (Fig. 1b). However, these deviations were small in all 269 but the most extreme cases. In the "Switching or staying" system, the calculated 270 σ_d^2 ranged from 0.69 when the probability of switching reproductive status 271 w = 0.0001 to 0.32 when w = 0.9999 (Fig. 1a), causing the mean expected time to 272 extinction of a population starting at 100 females to range from 47.3 to 57.2 (Fig. 273 1b). The equivalent Leslie matrix model gave $\sigma_d^2 = 0.35$ and mean time to 274 extinction 56.0. Thus, in the most extreme case (w = 0.0001), the mean expected 275 time to extinction was reduced by 15.5% compared to that calculated from the 276 Leslie matrix model, but in most cases the deviation was much lower (4.5%) when 277 w = 0.2). Adjusting the size of the initial population caused only minor changes in 278 these results (for example, the 15.5% became 12.7% at $N_0 = 50$ and 17.8% at 279 $N_0 = 300$). The "Individual heterogeneity" and "Gradual increase in reproductive 280 success" systems showed only minor deviations in all cases (Fig. 2a,b, maximum 281 deviation 8.0%; Fig. 3a,b, maximum deviation 2.3%). 282

The deviations in mean time to extinction $(\Delta \bar{T}_{ext})$ showed little sensitivity to specific parameter choices. When survival was particularly high, "Switching or staying" systems with extremely low probability of switching reproductive status (w = 0.0001) reached deviations of 18% (Fig. 1b,c; $s_0 = 0.322$ and $s_i = 0.85$ gave max $(\Delta \bar{T}_{ext}) = 0.181$; $s_0 = 0.25$ and $s_i = 0.888$ gave max $(\Delta \bar{T}_{ext}) = 0.175$). In these cases, λ was close to 1 (0.988 and 0.987). Increasing w to 0.2 brought max $(\Delta \bar{T}_{ext})$ in these cases down to 0.069 and 0.057. Deviations in the other two systems never exceeded 12.8% ("Individual heterogeneity") and 2.4% ("Gradual increase in reproductive success") (Fig. 2b,c 3b,c).

Introducing environmental stochasticity in the probability of one-year-olds 292 producing offspring (i.e. letting the *t*-values vary over time) showed only small 293 increases in the environmental variance ($\sigma_e^2 = 0.011$ when w = 0.0001 and t_1 varied 294 according to a uniform distribution between 0 and 1. Other values were smaller; see 295 Fig. S5.2a in Appendix S5), and negligible change in expected time to extinction 296 (Fig. S5.2b in Appendix S5). Letting the probability of remaining in the same 297 breeding class from one time step to the next fluctuate stochastically within the 298 range 0.49-0.96 also had no measurable effects on time to extinction (Fig. S5.2d in 299 Appendix S5), as would be expected given the weak influence of h on the 300 demographic variance (Fig. 2a). 301

³⁰² Moose Case Study

We applied our model to data from a population of moose (*Alces alces*) on the island of Vega off the coast of northern Norway. Females in this population can give birth to up to two calves per year from the time they are two years old. Estimates of transition probabilities between different breeding states (0, 1 or 2 calves) in this population show that the probability of twinning increases with the

number of offspring produced at the previous time step, making it an example of 308 the "Gradual increase in reproductive success" type of system (System 3 above) 309 (Table 1). Transition and survival estimates were obtained from multistate models 310 run in E-SURGE (Appendix S7, Choquet et al. 2009). Mortality in the system 311 comes mainly from hunting. It has previously been shown that environmental 312 stochasticity has little effect on the dynamics of this population (Sæther et al. 313 2007). Environmental effects were therefore ignored. More details of the multistate 314 models can be found in Appendix S7. 315

In order to isolate the effect of reproductive autocorrelations on the 316 demographic variance, we first parameterized the model assuming no covariation 317 between survival and fecundity. In other words, survival was estimated for each age 318 class, but was assumed not to differ among breeding states within an age class 319 (Appendix S7). We parameterized the model with these estimates, calculated the 320 demographic variance, and then compared this to the demographic variance 321 calculated from the model parameterized with the same survival estimates but 322 simple age-specific fecundity rates (Appendix S7). Using estimated parameters 323 directly in the model without incorporating uncertainty gave estimates of $\sigma_d^2 = 0.33$ 324 when accounting for reproductive autocorrelations and $\sigma_d^2 = 0.29$ from the standard 325 age-structured model. Such high estimates of σ_d^2 are quite common in long-lived 326 species with positive growth rates (Sæther et al. 2013). Next, we incorporated 327 uncertainty in the parameter estimates by repeating the analysis, drawing 10000 328 values from the distributions for each parameter and performing the calculations 329 for each of the 10000 sets of parameters. The resulting distributions of σ_d^2 showed 330

³³¹ only a very slight difference between the two models (Fig. 4a).

Finally, we investigated the effect of incorporating covariance in survival 332 and fecundity. In the model with reproductive autocorrelations this meant allowing 333 survival estimates to differ among the different breeding states (Appendix S7). In 334 the standard age-structured models this was accounted for by adding a covariance 335 term in the expression for σ_d^2 (Engen et al. 2009). The moose show positive 336 covariance between survival and fecundity because hunters prefer to shoot 337 individuals without calves (Appendix S7, Sæther & Haagenrud 1983). Adding this 338 covariance to the model increased estimates of σ_d^2 (Fig. 4b). The increase was 339 greatest in the standard age-structured model which treats this type of variation as 340 random variation among average individuals, whereas the model with demographic 341 autocorrelations treats this as systematic structured differences among breeding 342 states (Fox & Kendall 2002; Lee et al. 2017). 343

344 DISCUSSION

Demographic and environmental stochasticity both have negative effects on
population growth rates (Lande et al. 2003), necessitating population models that
accurately incorporate stochastic effects, in particular when predicting expected
impacts of environmental changes on the population size of threatened or
endangered species (Doak et al. 2005; Engen et al. 2005b; Morris et al. 2008;
Jenouvrier 2013). However, as models become more complex the number of
parameters that must be estimated increases, causing challenges when applying the

³⁵² models to sparse population data. We have therefore examined how much the use ³⁵³ of standard age-structured models that do not account for autocorrelations in ³⁵⁴ individual reproductive success biases estimates of expected time to extinction ³⁵⁵ when used on populations where such autocorrelations are present. Our results ³⁵⁶ show that such biases can be assumed to be small in all but the most extreme cases.

In extreme cases, we found that reproductive autocorrelations could 357 shorten the expected time to extinction by nearly 20% (Fig. 1c,d). However, this 358 required that females have an extremely low probability of switching reproductive 359 status between years, and that they be long-lived. In real populations, we would 360 expect probabilities of switching reproductive status to be less extreme and less 361 consistent over time and age. In a more realistic scenario, expected time to 362 extinction was reduced by just over 2% (Fig. 3b). Overall, most of the systems we 363 studied showed decreases in expected time to extinction that were well under 10%364 (Fig. 2b,c 3b,c). Given the uncertainty that is typically present in estimates of 365 stochastic population dynamics and extinction risk from population data, such 366 small differences in the theoretical time to extinction are in most cases unlikely to 367 merit the use of these more complex models. This conclusion is supported by our 368 case study on moose, where differences in σ_d^2 were less pronounced after accounting 369 for uncertainty in the parameter estimates (Fig. 4a). The differences in σ_d^2 370 estimated for the moose case study using mean parameter estimates without 371 accounting for uncertainty were of the magnitude predicted by our theoretical 372 results (Fig. 3a). 373

374

For simplicity, our theoretical results focus on systems in which adults have

constant (expected) vital rates, independent of age. However, probabilities of 375 breeding are known to depend on age in many species (e.g., Sedinger et al. 2001; 376 Beauplet et al. 2006; Arroyo et al. 2007). Our model is constructed to accomodate 377 this, and can be used to quantify the effect of reproductive autocorrelations in 378 systems with more complicated structure (see e.g the moose case study). However, 379 in general we expect even smaller differences in the demographic variance when 380 breeding probabilities vary with age, compared to the systems studied here. For 381 example, if the switching probability in Fig. 1 were 0.0001 for some ages, but 382 higher for others, the demographic variance would be lower than shown, causing 383 less change in the expected time to extinction. 384

Our results indicate that reproductive autocorrelations must be very strong 385 to have any measurable effect on long-term population growth. This is consistent 386 with empirical findings and theoretical results on related questions. For example, in 387 the California spotted owl (Strix occidentalis occidentalis) it has been shown that 388 negative reproductive autocorrelation caused by costly breeding has the potential 389 to create biennial cycles in population-level reproductive output in the presence of 390 environmental variation (Stoelting et al. 2015), but lasting cycles only occured 391 when the autocorrelation was very strong. Morris et al. (2011) found that effects of 392 vital rate autocorrelations caused by stochastic environments on long-term fitness 393 in seven primate species were extremely weak, and theoretical analyses have shown 394 that long-term population growth rates are only affected by environmental 395 autocorrelations when the temporal scaling is long (Engen et al. 2013). In addition, 396 it has been shown that the realized correlation between the reproductive stages of 397

an individual over time is quite low in many species (Tuljapurkar et al. 2009).
Thus, our results give a good indication that using models that do not incorporate
reproductive autocorrelations should give reasonable estimates of demographic
variance and expected time to extinction in most populations.

Models that classify individuals by reproductive success or stage in 402 addition to age, such as the one used here, require estimation of a large number of 403 parameters. Obtaining accurate estimates of all these parameters is challenging, 404 particularly in small, endangered populations, causing high uncertainty in results. 405 Thus, it may be good news that simple age-structured models seem to give good 406 estimates of expected time to extinction in the face of reproductive 407 autocorrelations. However, it is essential to note that these results were based on 408 accurate estimates of mean fecundity for each age class in the model. Only the 409 autocorrelations were ignored. In the wild, breeders and nonbreders often have 410 different detection probabilities (Katzner et al. 2011). Failing to account for this, or 411 estimating fecundity based on a non-random subset of the population (e.g., only 412 breeders), introduces much more serious biases than those examined here (Lee 413 et al. 2017). Models that classify individuals by reproductive success therefore have 414 an important role in analyzing the dynamics of certain types of populations. 415

In the wild, environmental conditions have been shown to affect breeding probabilites of both first-time breeders (e.g., Reed et al. 2003) and adults (e.g., Cubaynes et al. 2011), as well as survival rates (e.g., Cayuela et al. 2014). One might therefore expect the strength of reproductive autocorrelations to vary from year to year, for example if differences among individuals were more pronounced in

years with poor (or conversely, with good) environmental conditions (Pfister & 421 Wang 2005; Hamel et al. 2009b; Pesendorfer et al. 2016). We analyzed a system 422 where the probability of staying in the same breeding class from one time step to 423 the next varied stochastically from year to year, causing the reproductive 424 autocorrelations to vary in strength over time. We found that this caused the 425 effects of the reproductive autocorrelations to be so weak that estimates of 426 expected time to extinction were practically identical in the models with and 427 without such environmental fluctuations (Fig. S5.2d in Appendix S5). It has 428 previously been shown that the deterministic population growth rate tends to be 429 less sensitive to changes in breeding probabilities than to changes in survival, 430 particularly in long-lived species (Lee et al. 2017). Then we would also expect 431 fluctuations in breeding probabilities to have less effect on population growth and 432 extinction, thus weakening the selection pressures that may lead to demographic 433 buffering (Pfister 1998; Gaillard et al. 2000). 434

Survival rates that differ among reproductive classes give rise to covariance 435 between survival and reproduction (Lee et al. 2017). This covariance can be 436 directly accounted for when estimating the demographic variance from a standard 437 age-structured model (Engen et al. 2009; Lee et al. 2017). However, structured 438 variation of this type can actually decrease the demographic variance compared to 439 that found in homogeneous populations ("variance reduction effect", Fox & Kendall 440 2002; Lee et al. 2017). Thus, increases in estimates of σ_d^2 caused by this covariance, 441 such as that seen in figure 4b do not necessarily reflect increases in the random 442 variation among individuals. Negative covariance between survival and 443

reproduction can allow populations to persist in a wider range of environmental
conditions, through demographic compensation (Doak et al. 2005; Villellas et al.
2015).

In our model, heterogeneity in individual life history trajectories is driven 447 by stochastic transition processes between reproductive classes (dynamic 448 heterogeneity; Tuljapurkar et al. 2009; Cam et al. 2016). When reproductive costs 449 and individual heterogeneity are both present in a population, positive and 450 negative autocorrelations could cancel each other out, masking the underlying 451 processes (Beauplet et al. 2006; Hamel et al. 2009a). Although population 452 dynamics depend only on the realized autocorrelations, this creates a challenge for 453 understanding the individual processes (Hamel et al. 2009a). Thus, results from our 454 model cannot be used to infer for example an absence of reproductive costs directly. 455 It is also important to note that our results focus on differences in the demographic 456 variance calculated from models that either do or do not account for reproductive 457 autocorrelations. Reproductive autocorrelations can also affect the deterministic 458 growth rate of populations by affecting the proportion of breeders in the 459 population. This would be reflected in fecundity estimates and should therefore not 460 cause additional deviations between estimates from the two types of model. In our 461 analyses, the deterministic growth rate was held constant as we varied the strength 462 of reproductive autocorrelations in order to isolate the changes in the demographic 463 variance. Thus, our results do not imply that reproductive autocorrelations have 464 negligible effects on population growth itself. 465

466

As shown by Engen et al. (2005a) and Lee et al. (2011), the method we

used for deriving the demographic variance can also be used to study effective 467 population size. This requires including males in the model, and can be 468 accomplished following the logic of Lee et al. (2011), defining male reproduction by 469 number of mates. Number of offspring produced is treated as a property of the 470 females, and number of offspring per male is determined by his mates. The 471 demographic variance and generation time calculated from the two-sex model can 472 then be used to quantify genetic drift in the population (Engen et al. 2005a), and 473 thus to predict loss of genetic diversity. In general, small populations with low 474 demographic stochasticity are expected to lose genetic diversity at a lower rate 475 than small populations with high demographic stochasticity (Engen et al. 2005a). 476 In addition, Shpak (2007) showed that in finite populations selection tends to favor 477 genotypes that decrease demographic stochasticity. This might suggest that 478 positive reproductive autocorrelations could give a selective disadvantage in some 479 cases, but the effect would be weak. 480

In conclusion, although positive autocorrelations in individual reproduction 481 were shown to increase the demographic variance such that population models that 482 did not account for these autocorrelations overestimated the expected time to 483 extinction, the effects were found to be small. Environmental fluctuations in 484 transition rates between different breeding states were found to have negligible 485 effects on expected time to extinction. Thus, our results indicate that ignoring 486 reproductive autocorrelations in population models is unlikely to cause any serious 487 bias in estimates of population growth and expected time to extinction, except in 488 extreme cases. 489

24

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Figure 1:



Figure 2:



Figure 3:



Figure 4:

Figure 1: Model output for System 1 ("Switching or staying") with 11 age classes, 654 0 or 1 offspring produced per female at each time step ($\alpha = 1$), adult survival, 655 $s_i = 0.85$, offspring survival and probability of being female, $s_0 = 0.25$, and 656 probability of breeding at age 1, $t_1 = 0.5$. a) Demographic variance estimates from 657 our model with reproductive autocorrelations (solid line) compared to those from a 658 standard age structured model (grey dashed line). The probability of switching 659 reproductive status, w, is varied from 0.0001 to 0.9999. Points at w = 0.0001, 0.5660 and 0.9999 are marked by dots with fill corresponding to line types shown in panel 661 b. b) Distribution of time to extinction, starting with 100 females, when 662

w = 0.0001 (solid line), 0.5 (dashed line; equal to the Leslie model) and 0.9999 663 (dotted line) (i.e. points on panel a). $\lambda = 0.927$. c) Maximum deviation in mean 664 expected time to extinction $(\max(\Delta T_{ext}))$, found at w = 0.0001) when s_0 is varied 665 from 0.15 to 0.35 and the number of age classes is adjusted from 8 to 13 to ensure 666 that the proportion of individuals expected to reach the last age class stays just 667 under 0.05. λ varies from 0.789 to 0.998. d) Maximum deviation in mean expected 668 time to extinction (max($\Delta \overline{T}_{ext}$), found at w = 0.0001) when s_i is varied from 0.75 669 to 0.90 and the number of age classes is adjusted from 7 to 16 to ensure that the 670 proportion of individuals expected to reach the last age class stays just under 0.05. 671 λ varies from 0.780 to 0.997. 672

Figure 2: Model output for System 2 ("Individual heterogeneity") with 7 age 673 classes, 0 or 1 offspring produced per female at age 1, and 0, 1 or 2 offspring 674 thereafter $(\alpha_1 = 1, \alpha_{2-7} = 2)$, adult survival, $s_i = 0.75$, offspring survival and 675 probability of being female, $s_0 = 0.25$, and probability of breeding at age 1, t_1 676 adjusted to keep λ constant (t_1 varied from 0.262 to 0.696, $\lambda = 0.868$). a) 677 Demographic variance estimates from our model with reproductive autocorrelations 678 (solid line) compared to those from a standard age structured model (dashed grey 679 line). The probability of staying in the same breeding class, h, was varied from 0.49 680 to 0.96. Points at h = 0.49, 0.725 and 0.96 are marked by dots with fill 681 corresponding to line types shown in panel b. b) Distribution of time to extinction, 682 starting with 100 females, when h = 0.49 (dotted line), h = 0.725 (solid line) and 683 h = 0.96 (dashed line). The long-dashed grey line shows time to extinction 684

calculated from a standard age structured model without reproductive 685 autocorrelations. c) Maximum deviation in mean expected time to extinction 686 $(\max(\Delta T_{ext}))$, found at h = 0.96 when s_0 is varied from 0.23 to 0.38 and the 687 number of age classes is adjusted from 7 to 9 to ensure that the proportion of 688 individuals expected to reach the last age class stays just under 0.05. λ varies from 689 0.850 to 0.999. d) Maximum deviation in mean expected time to extinction 690 $(\max(\Delta \bar{T}_{ext}))$, found at h = 0.96) when s_i is varied from 0.70 to 0.835 and the 691 number of age classes is adjusted from 6 to 10 to ensure that the proportion of 692 individuals expected to reach the last age class stays just under 0.05. λ varies from 693 0.798 to 0.992. 694

Figure 3: Model output for System 3 ("Gradual increase in reproductive success") 695 with 7 age classes, 0 or 1 offspring produced per female at age 1, and 0, 1 or 2 696 offspring thereafter ($\alpha_1 = 1, \alpha_{2-7} = 2$), adult survival, $s_i = 0.75$, offspring survival 697 and probability of being female, $s_0 = 0.25$, and probability of breeding at age 1, t_1 698 adjusted to keep λ constant (t_1 varied from 0.890 to 0.137, $\lambda = 0.986$). a) 699 Demographic variance estimates from our model with reproductive autocorrelations 700 (solid line) compared to those from a standard age structured model (dashed line). 701 h, which here controls the probability of transitioning to a more successful state 702 (see Appendix S4 for more details), was varied from 0.49 to 0.96. b) Distribution of 703 time to extinction, starting with 100 females, when h = 0.588 (dotted line on panel 704 a). The long-dashed grey line shows time to extinction calculated from a standard 705 age structured model without reproductive autocorrelations. c) Maximum 706

deviation in mean expected time to extinction $(\max(\Delta \overline{T}_{ext}))$, found at h = 0.588) 707 when s_0 is varied from 0.15 to 0.26 and the number of age classes is adjusted from 5 708 to 7 to ensure that the proportion of individuals expected to reach the last age 709 class stays just under 0.05. λ varies from 0.788 to 0.996. d) Maximum deviation in 710 mean expected time to extinction $(\max(\Delta \overline{T}_{ext}))$, found at h = 0.588) when s_i is 711 varied from 0.59 to 0.76 and the number of age classes is adjusted from 5 to 7 to 712 ensure that the proportion of individuals expected to reach the last age class stays 713 just under 0.05. λ varies from 0.787 to 0.995. 714

Figure 4: Outlines of barplots showing distribution of estimated values of σ_d^2 from 10000 parameter draws for the moose population. Black lines (leftmost peak) are estimated from a model with reproductive autocorrelations. Grey lines (rightmost peak) are estimated from a standard age-structured model without accounting for reproductive autocorrelations a) Model without covariance between survival and fecundity. b) Model with positive covariance between survival and fecundity.