

1 **Door-to-door waste collection: analysis and recommendations for**
2 **improving ergonomics in an Italian case study**

3
4
5
6

7 Lucia Botti^{1*}. Daria Battini². Fabio Sgarbossa³. Cristina Mora⁴.

8 ¹ Interdepartment Research Center on Security and Safety (CRIS), University of Modena and Reggio Emilia,
9 Modena, Italy (e-mail: lucia.botti@unimore.it)

10 ²Department of Management and Engineering, University of Padua, Vicenza, Italy (e-mail: daria.battini@unipd.it)

11 ³ Department of Mechanical and Industrial Engineering, Norwegian University of Science and Technology,
12 Trondheim, Norway (e-mail: fabio.sgarbossa@ntnu.no)

13 ⁴ Department of Industrial Engineering, University of Bologna, Bologna, Italy (e-mail: cristina.mora@unibo.it)

14 *corresponding author.

15

16 **Abstract**

17 In the last decade, door-to-door waste collection methods have been largely applied by several
18 municipalities in Italy, with the main purpose to achieve higher rates of sorted waste. This
19 approach requires waste collectors to handle a high number of small waste containers during
20 their work-shift, especially in urban areas and historic city centres. Workers may experience
21 ergonomic issues during door-to-door waste collection ,due to the characteristics of the waste
22 containers, the waste collection equipment, the work organization and citizens' behaviour. If
23 not well planned and managed, this activity may expose waste collectors to ergonomic risk
24 factors for musculoskeletal disorders.

25 This study proposes a detailed investigation of the door-to-door waste collection strategy
26 operated in an Italian city centre for the collection of organic municipal solid waste, green

27 waste and residual waste. The aim is to investigate the impact of door-to-door waste
28 collection strategies on the health and safety of the workers involved in this activity.
29 The results show that the lack of proper waste collection equipment determines poor
30 ergonomics conditions during door-to-door collection of green waste. The poor design of
31 operations and technology is the cause of ergonomic issues in the door-to-door collection of
32 organic municipal solid waste and residual waste. Finally, work organization factors impact
33 on the safety and health of all the waste collectors involved in this study.
34 A set of recommendations and suggestions are provided to managers, workers and citizens
35 involved in door-to-door waste collection, showing that this activity can be sustainable if well
36 designed and managed.

37

38

39 **Keywords:** Solid Waste Management; Waste collection; Door-to-door collection;
40 Ergonomics; Human factors; Sustainability.

41

42 **1. Introduction**

43 Waste management is one of the key concepts at the core of sustainable development,
44 together with environmental sustainability and ergonomics. Sustainable development
45 promotes the integration of human development goals with the principles for sustaining and
46 preserving the ecosystem and the natural resources upon which the economy and our society
47 depend (Olawumi and Chan, 2018; Radjiyev et al., 2015). Sustainable organizations are
48 encouraged to improve their environmental efficiency adopting effective waste management
49 strategies, sustainable work practices and optimising the outcomes of human-system
50 interactions. From this perspective, a sustainable organization delivers sustainable products
51 and processes that meet environmental, organizational and ergonomics criteria, applying the

52 sustainability knowledge in waste management (Olawumi and Chan, 2018; Siemieniuch et al.,
53 2015).

54 Waste collection is the first part of the process of waste management, in which the waste is
55 transferred from the point of grouping to the point of treatment. Separate waste collection is
56 an essential requirement for sustainable waste management (Bartolacci et al., 2018). In the
57 last two decades, the development of material and energy recovery technologies sustained the
58 global efforts in supporting Municipal Solid Waste (MSW) management towards
59 sustainability (Shekdar, 2009). In 2010, the greenhouse gas inventory of the European Union
60 (EU-27) has stated that the waste sector accounted for around 3% of total direct greenhouse
61 gas emissions in the EU-27 (Punkkinen et al., 2012). The positive effect of the urban per
62 capita disposable income on carbon emissions was confirmed in China as well (Wang and
63 Geng, 2015). More recently, an investigation on integrated waste management scenarios
64 representative of the European situation evaluated possible trends in the net emission of
65 greenhouse gases and in the required landfill volume. The results revealed that high level of
66 separate collection is a critical factor for the success of integrated solid waste management
67 systems, together with efficient energy recovery in waste-to-energy plants and very limited
68 landfill disposal (Calabrò et al., 2015).

69 The European Union has encompassed an integrated approach to waste management,
70 promoting the development of an integrated network of waste collection groups that manage
71 recycling collection from the production phase to the recovery or final disposal. The European
72 Waste Directive 2008/98/EC imposes to the EU members different mandatory recycling
73 levels depending on the waste fraction. Citizens and companies are required to separate the
74 MSW by type, e.g. food waste, green waste and recyclable materials (paper, glass, plastics,
75 metals, etc.). Public authorities are strongly invited to comply with the collection
76 requirements for different waste streams set in the waste legislation (Teerioja et al., 2012).

77 The choice of the waste collection system adopted by the municipality is strategic as waste
78 collection cause a relevant part of the total MSW management costs (Sonesson, 2000). The
79 2019 Italian report on recycling and waste management reveals that the cost of waste
80 collection and transport accounts for the 13.2% of the total cost of unsorted MSW
81 management and the 23.4% of the cost of sorted MSW management (ISPRA, 2019).
82 MSW management is often performed with different modalities, depending on the agreement
83 between the local municipality and the waste management companies. There are different
84 collection systems, e.g. curbside bins, pneumatic systems and door-to-door. Specifically, door
85 to door refers to the collection system where citizens place domestic waste close to the street
86 in personal waste containers. Door-to-door collection allows higher results in terms of
87 collected waste volume and quality of separation (Agència de Residus de Catalunya and
88 Generalitat de Catalunya, 2017). A recent Finnish study has compared pneumatic and door-to-
89 door collection systems. The results show that, compared with the pneumatic system, the
90 economic performance of a vehicle-operated door-to-door waste collection system is higher
91 (Teerioja et al., 2012). Furthermore, a recent study showed that the greenhouse gas emissions
92 of pneumatic collection are three times higher than the values retrieved with door-to-door
93 collection (Mora et al., 2013). Hence, the door to door collection system is suggested to
94 replace the kerbside collection (Calabrò and Komilis, 2019).

95 The recent interest of institutions, public and private organizations and researchers in the role
96 of ergonomics for supporting sustainable development is addressing new areas of research,
97 aiming to understand and optimize the interactions between the human and the environment
98 (Battini et al., 2011; Botti et al., 2017). Waste collection work is associated with a variety of
99 physical, chemical, and biological hazards. Occupational accidents are frequent among waste
100 collectors (Poulsen et al., 1995). The risk of fatal occupation injuries of waste collectors is
101 higher than in general industry. Despite being a relatively small sector in terms of

102 employment, the fatal injury rate in waste collection is relevant. The UK Health and Safety
103 Executive (HSE) reports that the number of MSW workers fatally injured at work in the last
104 year has more than doubled in comparison to 2015/16 (Slow Elisabeth, 2017). Specifically,
105 the UK rate of fatal injuries in waste and recycling in 2016/2017 was the highest in
106 comparison with other industries as construction, agriculture and manufacturing (see Figure
107 A1 in Appendix A). The annual average fatal injury rate of waste and recycling, over the last
108 five years, is around nine times higher than the construction industry rate. The ankle sprain
109 while getting off the waste collection vehicle is a frequent non-fatal injury affecting waste
110 collectors. Other common injuries are fractures, ocular trauma, and bites (Dorevitch and
111 Marder, 2001). However, non-fatal injuries in waste collection are mainly Work-related
112 Musculoskeletal Disorders (WMSDs) due to Manual Material Handling (MMH) of waste
113 containers.

114 Waste collection requires MMH of loads, as lifting, lowering, pushing and pulling of
115 collection bins, bags and carts. The weight of such containers is variable, depending on the
116 waste typology, the container features, the collection frequency, the time of year and other
117 variable factors. Such characteristics impact on the workers' exposure to the risk of MMH of
118 waste containers and on the risk of developing WMSDs. In 2005, a research published by the
119 Washington State's Department of Labor and Industries revealed that WMSDs account for 41
120 percent of the cost of workers' compensation claims (Silverstein et al. 2005). From 1994 to
121 2002, waste management industry caused 769,989 lost work days in the U.S. and
122 \$147,302,364 in claims costs. In 2006, the UK Health and Safety Laboratory (HSL)
123 investigated the risks for developing WMSDs in door-to-door waste collection. The aim was
124 to provide authoritative guidance on control measures to limit risk within the existing waste
125 collection systems (Oxley et al., 2006). The HSL provided recommendations to waste

126 collection employers and employees for safe manual handling of MSW containers, regardless
127 the waste typology.

128 Waste collection is a challenging task due to, for example, varying topography, climatic
129 conditions, and limited space for waste containers and transportation vehicles (Teerioja et al.,
130 2012). In 2012, the University of Central Florida published the results of a comprehensive
131 ergonomics study on waste collection, with focus on the waste collection technology. The
132 research investigated three different modalities for waste collection, i.e. manual, semi-
133 automated and automated. The results reveal that waste collectors are exposed to severe
134 occupational injuries due to lifting, heavy load handling, repetition and awkward postures
135 (Mccauley Bush et al., 2012). In 2014, a research on the ergonomics of waste collection
136 investigated the interaction between waste collectors and collection vehicles for door-to-door
137 waste collection (Attaianese, 2014). The study compared the collection vehicle features (e.g.
138 platforms dimensions and height, handles, feet supports, etc.) and the anthropometric
139 measures of waste collectors. Results show that waste collectors are forced to assume
140 awkward postures of legs, back, arms and other articular segments because of the poor design
141 characteristics of waste collection vehicles. Both the study from the University of Central
142 Florida (2012) and the research from Attaianese (2014) focus on collection vehicles, giving
143 useful information and insights for practitioners and designers. However, neither research
144 study investigated other critical factors related to the design of waste collection strategies, that
145 may impact on workers' safety and health, e.g. the features of waste containers and work
146 organization.

147 In 2018, Battini et al. (2018) investigated the risk factors for WMSDs in door-to-door
148 collection of organic MSW in the historic city centre of an Italian city, focusing on the
149 characteristics of collection vehicles and equipment, e.g. the plastic containers provided to the
150 citizens. The case study introduced by Battini et al. (2018) was characterized by high number

151 of small waste containers that needed to be tipped into the waste collection vehicle. The
152 results reveal that multiple factors of door-to-door collection strategies impact on waste
153 collectors' safety and health, e.g. the characteristics of the collection vehicles, work
154 organization and the features of waste containers.

155 Based on the results of such research, this paper shows a deeper investigation on waste
156 management strategies and employees experiences during door-to-door waste collection. The
157 door-to-door collection strategies adopted in an Italian historic centre for the collection of
158 organic MSW, green waste and residual waste are introduced. The aim is to analyse the
159 impact of the decisional variables for the design of door-to-door collection strategies on the
160 health and safety of waste collectors.

161 The research questions addressed in this research are “Are door-to-door waste collectors
162 exposed to ergonomic risk factors?”, “Which is the impact of the decisional variables for the
163 design of door-to-door collection strategies on waste collectors' health and safety?” and “Is it
164 possible to prevent the presence of ergonomic risk factors during door-to-door waste
165 collection?”.

166 Four main categories of decisional variables have been identified:

167 *Organization*: the work organization, including the characteristics of the collection round, the
168 duration of the work-shift and the number of workers in the collection crew;

169 *Operations*: the modalities adopted by waste collectors to perform the MMH of the waste
170 containers (e.g. assumed postures and movements performed during door-to-door collection);

171 *Technology*: the characteristics of the collection vehicle, in terms of features of the collection
172 truck;

173 *Equipment*: the characteristics of the waste collection equipment, in terms of features and
174 weight of the waste containers.

175 An ergonomics analysis investigates the impact of such decisional variables on the exposure
176 of waste collectors to the risk for developing WMSDs, due to the door-to-door collection of
177 waste containers, in the reference case study. Results reveal that waste collectors experience
178 ergonomic issues during door-to-door waste collection. Such issues are related to the poor
179 design of door-to-door waste collection strategies, in terms of organization, operations,
180 technology and equipment. Hence, door-to-door waste collection can be a sustainable activity
181 if properly designed and managed.

182 The remainder of this paper is as follows. Section 2 introduces the characteristics of door-to-
183 door collection, together with the collection schemes, the methods and the tools adopted in
184 the reference case study. Section 3 shows and discusses the results of the ergonomics
185 analysis, providing a set of suggestions for obtaining a sustainable and safe door-to-door
186 collection system, even in Italian densely inhabited city centres. Finally, Section 4 concludes
187 the paper, showing the future developments of this research study.

188 **2. Methodology**

189 This section introduces the materials and the methods adopted in this study. The door-to-door
190 collection scheme investigated in this paper refers to the waste management strategy adopted
191 in the historic centre of a city in northern Italy with 80,000 inhabitants. Door-to-door waste
192 collection is operated by a waste management company, in collaboration with the local
193 municipality. The municipality involved in this study is one of the most pro-active in Italy,
194 i.e. it achieved the 88.5% rate of sorted waste collection in 2018 (the Italian mean national
195 rate is 55.5 % according to www.csaimpianti.it/ispra) with less than 500 kg of waste per
196 inhabitant per year.

197 This study focuses on the door-to-door collection schemes adopted by the waste management
198 company for the collection of organic MSW, green waste and residual waste. The
199 municipality requires the citizens to collect and separate the MSW in different types of

200 containers, according to the waste fraction. The activities performed by waste collectors
201 during a conventional work-shift include emptying the waste containers, driving between the
202 waste collection points in the collection area and transporting the collected waste to the
203 treatment plant or to the waste disposal.

204 *2.1. The door-to-door collection scheme in the reference case study*

205 Door-to-door collection in Italian urban areas is mainly performed with small standard waste
206 containers, e.g. 25-30 l plastic bins, because of the difficulty to store and handle large
207 containers in the narrow streets of the historic city centres. Residents are required to separate
208 different materials in the containers and to expose them on the street, close to the point of
209 production. The waste management company collects the containers on a weekly or bi-weekly
210 basis, depending on the waste typology and on the season. Each residential area of the city is
211 characterized by a collection round (CR). Following a defined CR, waste collectors reach
212 each waste container and collect waste into a collection vehicle.

213 Specifically, 14 crews operate the door-to-door collection for a total of 28 CRs. Each crew is
214 responsible for one CR per day. Door-to-door collection requires the waste collectors to
215 handle the containers at the kerbside, performing manual movements to lift the plastic bins
216 from the ground to the collection vehicle. The number of people in the crew depends on the
217 waste typology, e.g. either a single or two-person crew typically manages the CR of organic
218 and residual waste, while a three-person crew is necessary for the collection of green waste.
219 In case of single-person crew, the same waste operator drives the collection vehicle and
220 collects the waste containers on the kerbside. In the two and three-person crews, one worker
221 typically drives the collection vehicle and the other one or two collect the waste containers.
222 This collection strategy is preferred when the collection vehicle is a heavy truck and a special
223 driving licence is required. Waste collectors do not rotate among different crews during the
224 day. However, crew organization may vary during the year, i.e. the production of green waste

225 and organic MSW is limited during winter, when garden maintenance is less intensive as
226 compared to spring and summer, and the consumption of fruit and vegetables is more limited.
227 Consequently, the citizens expose a limited number of waste containers on the kerbside.

228 *2.2. Door-to-door collection of organic MSW*

229 *2.2.1. Organization*

230 Organic MSW is the biodegradable waste material originated by the residuals of food and
231 other biodegradable waste produced by the household. The waste management company in
232 the reference case study collects the organic MSW on a bi-weekly basis.

233 Waste collectors' activity consists of two main tasks: kerbside collection and driving the
234 vehicle to the waste treatment plant. The first task requires the workers to drive the waste
235 collection vehicle to the bins and tip the waste into the truck hopper. This task requires about
236 the 70% of the total time of MMH. One third of such 70% is necessary to drive the vehicle
237 from bin to bin. The second task is performed for the remaining time (Battini et al., 2018).

238 The ergonomics analysis focuses on the worker of the single-person crew performing the
239 door-to-door collection of the organic MSW. The worker starts the CR at about 5 am. The
240 work-shift finishes at about 11.30 am. Two breaks of 15 minutes each are possible in the
241 morning. Furthermore, workers stop collecting waste for about 50 minutes to reach the waste
242 treatment plant and unload the vehicle hopper once a day (twice in summer, from May to
243 July). The following Table 1 shows the characteristics of the door-to-door collection scheme
244 for the organic MSW.

245 **Table 1**

246 Characteristics of the door-to-door collection scheme for the organic MSW. Average values
247 of 28 CRs in summer, spring/autumn and winter seasons.

	Summer	Spring/Autumn	Winter
Average number of potential plastic bins in the residential area [bins]	813	813	813

Exposition rate [%]	70%	70%	70%
Collected waste [kg/day]	7024	3560	2853
Average weight of the plastic bin [kg]	7.99	3.47	2.76

248

249 The number of plastic bins in Table 1 refers to the average number of potential users in the
 250 residential area. Wheeled containers, e.g. waste containers provided to commercial activities
 251 as restaurants and grocery stores, are not included in this study.

252 The exposition rate is defined as the ratio between the actual number of waste containers
 253 exposed by the citizens on the kerbside and the total containers provided to residents.

254 Statistics from the waste management company involved in this study reveal an exposition
 255 rate for organic MSW equal to 70% (Table 1), i.e. the actual number of plastic bins tipped by
 256 the waste collectors is lower than the potential bins in the residential area. Data used for the
 257 ergonomic risk assessment refer to the waste collection activity performed in the reference
 258 case study, in summer, spring/autumn and winter seasons (Table 1). Specifically, door-to-
 259 door collection of organic MSW containers in spring and autumn seasons show similar
 260 working and weight conditions, i.e. the following analysis includes average data for these
 261 seasons. Table 1 shows that the average weight of the plastic bin containing the organic waste
 262 in summer is more than twice the weight of the same container in spring or winter. The
 263 presence of fruit and vegetables residuals with high content of water that characterizes the
 264 summer season may explain such difference.

265 *2.2.2. Operations*

266 The waste collector lifts each bin, transferring the organic waste inside a truck container
 267 attached to the collection vehicle, then returns the empty bin to the citizen (Figure 1).



268

269 **Fig. 1.** On the left, the collection vehicle. On the right, two-handed tip of the plastic bin into
270 the truck container on the back of a collection vehicle.

271

272 Each plastic bin is equipped with a plastic handle. Practice shows that waste collectors prefer
273 to lift the bin from the upper edge, rather than using the plastic handle.

274 *2.2.3. Technology*

275 The collection vehicles are small size truck (from 5 to 7 m³ of capacity) equipped with a rear
276 hopper and a lifting equipment. Different types of truck containers are attached to the bin
277 lifter where the operators unload the plastic bins. Figure 1 shows two types of collection
278 vehicles. Automatic lifters are present on the vehicle to overturn the waste into the hopper.

279 These lifting equipment are positioned on the back of the vehicle (Figure 1). The truck
280 container is integrated in the collection vehicle on the left side of Figure 1. A wheeled
281 container is attached to the lifting equipment in the collection vehicle on the right.

282 *2.2.4. Equipment*

283 The citizens collect organic waste in a 25-litre capacity plastic bin. The height of the upper
284 edge of the plastic bin is 43 cm. The operation assumptions adopted for the ergonomics
285 analysis are: the waste collector lifts and carries each plastic bin from the point of exposition
286 to the truck container; the height of the hands at the origin of the lifting task is 43 cm; the

287 horizontal distance of the hands from the body at the destination of the lifting movement is
288 about 30 cm; the horizontal distance of the hands from the body at the destination of the
289 lifting movement is about 55cm, i.e. the worker keeps the plastic bin distant from his body
290 aiming to avoid splash and squirts of the organic MSW; some torsion (30°) is present at the
291 destination of the lifting movement; the grip is poor, i.e. the waste collector lifts the plastic
292 bin from the upper edge of the container; the waste collector is a man between 18 and 45
293 years old. The characteristics of the environment contribute to increase the critical conditions
294 of organic MSW collection, e.g. extreme temperatures in summer and winter, and slippery
295 and irregular paving.

296 *2.3. Door-to-door collection of green waste*

297 *2.3.1. Organization*

298 Green waste includes grass clippings, tree trimmings, shrubs and leaves. This waste is
299 generated by pruning and leaf or other residuals of the maintenance activities performed in the
300 green areas. The waste management company collects green waste and other pruning
301 residuals on a weekly, bi-weekly or tri-weekly basis, depending on the residential area and on
302 the season. The municipality defines the green waste collection program with the support of
303 the waste management company. The average exposition rate of green waste, i.e. the number
304 of exposed containers over the overall number of potential containers exposed by the citizens,
305 is 17 %. Such value is the result of three investigations performed in the middle of the autumn
306 season (between October and November 2018) in the reference urban area. The high presence
307 of pruning residuals and leaf characterizes the autumn season in northern Italy. The average
308 weight of green waste at the end of the work-shift is 3820 kg. Each served user may expose
309 up to 3 waste containers.

310 *2.3.2. Operations*

311 A three-person collection crew operates the door-to-door collection of green waste in the
 312 reference case study. Specifically, one worker drives the collection vehicle and two workers
 313 collect the waste containers. The waste collectors lift the waste containers, transferring the
 314 green waste inside the hopper of the collection vehicle. Finally, waste collectors are required
 315 to return the empty containers to the citizens.

316 *2.3.3. Technology*

317 The collection vehicle adopted for door-to-door collection of green waste is a truck equipped
 318 with a rear hopper, in which the worker transfers the waste. In these trucks, no automatic
 319 lifters are present on the vehicle to overturn the waste into the hopper (see Figure A6 in
 320 Appendix A).

321 *2.3.4. Equipment*

322 The citizens collect green waste in different types of container, e.g. plastic bags, tubs, bundles
 323 and buckets (see Figure A2 in Appendix A). The municipality does not provide a standardized
 324 container for green waste, i.e. the choice of the container is up to the citizens. The following
 325 Table 2 shows the frequency of appearance of different types of waste containers used by the
 326 citizens to collect green waste.

327 **Table 2.**

328 Types of waste containers used by the citizens to collect green waste.

Waste container	Number expositions	of %
Plastic bag	42	38%
Tub	25	23%
Bundle	19	17%
Crate	11	10%
Bucket	9	8%
Other	4	4%
Total	110	100%

329

330 Data in Table 2 refer to a sample of 110 containers observed on the kerbside during an
331 inspection in mid-autumn 2018. The citizens prefer to collect green waste in plastic bags
332 (38%), followed by tubs (23%) and bundles (17%). Each container was weighted on site
333 during multiple investigations, using a digital force gauge (IMADA ZTA-500N, sample rate
334 2000 data/s, accuracy +/-0.2%F.S./-1 digit). This investigation allowed to determine the
335 range of the Frequency Independent Lifting Index (FILI) values for all of the sampled lifts,
336 for the ergonomics analysis (Waters et al., 2016, 2009). The 58% of the inspected waste
337 containers was less than 7 kg (see Figure A3 in Appendix A). Waste containers under 3 kg
338 were the 17% of the exposed containers. Weights under 3 kg are not included in this analysis
339 as they do not contribute to increase the risk for manual lifting (Haslam and Waterson, 2013).
340 The operation assumptions adopted for the ergonomics analysis are: the composition of the
341 exposed green waste, based on the weight of the waste containers, is in Figure A3; the
342 workers keep the waste container close to the body during the lifting task; the height of the
343 hands at the origin of the lifting task is variable between 20 cm and 110 cm; at the destination
344 on the truck hopper, the height of the hands varies between 125 cm e 140 cm; the grip is poor
345 since no handles are available; no torsions are performed while lifting the waste containers;
346 waste collectors are men between 18 and 45 years old.
347 The characteristics of the environment contribute to increase the critical conditions of green
348 waste collection, e.g. extreme temperatures in summer and winter, and slippery and irregular
349 paving. Other critical characteristics are the presence of cutting extremes or edges, and the
350 content instability of green waste containers.

351 *2.4. Door-to-door collection of residual waste*

352 *2.4.1. Organization*

353 Residual waste is the waste remaining after all recyclables have been collected. This waste
354 typology is bound to landfills and its production should be limited. The citizens collect

355 residual waste in plastic bins provided by the municipality. Wheeled containers, e.g. waste
 356 containers provided to commercial activities, are not included in this investigation. The tasks
 357 performed for the door-to-door collection of residual waste are similar to the activities
 358 performed for organic MSW collection, i.e. the two main tasks performed by the waste
 359 collector are kerbside collection and driving the vehicle to the landfill. The first task requires
 360 about the 70% of the total time. One third of such 70% is necessary to drive the vehicle from
 361 bin to bin. The second task is performed for the remaining time (Battini et al., 2018).
 362 The following Table 3 shows the characteristics of the door-to-door collection scheme for the
 363 residual waste.

364 **Table 3.**

365 Characteristics of the door-to-door collection of residual waste.

Parameter	Value
Average number of potential plastic bins [bins]	1907
Exposition rate	43 %
Collected waste [kg/day]	7730
Average weight of the plastic bin [kg]	9.4

366

367 The number of plastic bins in Table 3 refers to the average number of the users served by the
 368 waste management company for the door-to-door collection of residual waste in the reference
 369 case study. The exposition rate of the plastic bins containing residual waste is about 43 %.

370 These data are from the waste management company involved in this study.

371 *2.4.2. Operations*

372 The kerbside collection modalities depend on the type of the collection vehicle adopted
 373 during the CR. Collection vehicles with the truck container require the waste collector to lift
 374 each bin and to transfer the residual waste inside a truck container attached to the collection
 375 vehicle. Then, the waste collector returns the empty bin to the citizen. In case of collection

376 vehicles with no truck container, the waste collector transfers the content of the plastic bin
377 inside the hopper of the collection vehicle, then returns the empty container to the citizen.

378 *2.4.3. Technology*

379 The collection vehicles are small size truck (from 5 to 7 m³ of capacity) equipped with a rear
380 hopper and a lifting equipment. Different types of containers are attached to the bin lifter
381 where the operators can unload all the collected bins. When the container is full, the operator
382 activates the automatic lifter on the vehicle to overturn the waste into the hopper (see Figure
383 1).

384 *2.4.4. Equipment*

385 The citizens collect residual waste in a 30-litre capacity plastic bin. The height of the upper
386 edge of the plastic bin is 42 cm. The operation assumptions adopted for the ergonomics
387 analysis are: all the exposed waste containers for residual waste are plastic bins; the height of
388 the hands at the origin of the lifting task is 42 cm; the height of the hands at the destination of
389 the lifting movement (i.e. the hopper, in case of collection vehicles with no truck container, or
390 the truck container) varies with the typology of the adopted collection vehicle; the worker
391 keeps the plastic bin close to his body at the origin of the lifting movement (30 cm); the
392 horizontal distance of the hands from the body at the destination of the lifting movement is
393 about 40 cm; no torsions are performed while lifting the plastic bins; the grip is poor since the
394 waste collectors lift the plastic bins from the upper edge of the container; the collection
395 worker is a man between 18 and 45 years old.

396 The characteristics of the environment contribute to increase the critical conditions of residual
397 waste collection, e.g. extreme temperatures in summer and winter, and slippery and irregular
398 paving.

399 *2.5. Methodology for the ergonomics analysis*

400 The ergonomics analysis in this study includes the risk assessment methodology based on the
401 NIOSH Variable Lifting Index (VLI) for evaluating variable lifting tasks using the revised
402 NIOSH lifting equation (Waters, 1993; Waters et al., 2016, 2009). The VLI method allows
403 the assessment of highly variable manual lifting jobs in which the task characteristics, e.g. the
404 geometry of the lifting task and the weight of the lifted objects, vary during the work-shift.
405 Specifically, this method compares the actual weights lifted by waste collectors with the
406 recommended values derived from the NIOSH lifting equation, for the actual lifting
407 conditions. The reliability of the NIOSH VLI method relies on the epidemiological approach
408 developed by its authors to investigate the association between the NIOSH VLI values and
409 the health outcomes.

410 The postural assessment was performed with the OWAS method (Karhu et al., 1977). The
411 observational technique for evaluating working postures was a wearable motion capture
412 system consisting of 31 inertial sensors, placed on the whole body suit. In order to measure
413 with precision the human body postures during the door to door waste collection activity
414 under analysis, the authors applied the innovative full-body motion capture system (made up
415 by a suit and a software) traditionally used for the real-time ergonomics evaluations in
416 industrial environments as described in Battini et al. (2014) and Battini et al. (2018). This
417 system allows the analysis of the body movements when all parts of the body are interested
418 during the tasks execution. The system is based on inertial sensors with integrated
419 compensation of magnetic interference and long wireless connection that permit its use in
420 several kinds of industrial applications. When the operator wears the motion capture suit, the
421 system collects and shows in real time a large set of full-body motion data, that are used to
422 calculate the body posture parameters and the relative percentages required in several postural
423 assessment approaches like OWAS, OCRA and TACOs.

424 **3. Results and discussion**

425 The following subsections 3.1 and 3.2 introduce and discuss the results of the ergonomics
426 analysis, providing a set of suggestions and recommendations for improving ergonomics in
427 door-to-door waste collection. The ergonomic risk assessment after the introduction of the
428 proposed improvements is in Section 3.3. Punctual values of the resulting risk indices have
429 been omitted for privacy reasons.

430 *3.1. Ergonomics analysis*

431 *3.1.1. Door-to-door collection of organic MSW*

432 The ergonomic risk assessment for the door-to-door collection of organic MSW with the
433 NIOSH VLI investigates the ergonomic risks associated with the manual lifting and lowering
434 of the waste containers (Waters, 1993; Waters et al., 2016). Such risk is analysed considering
435 the average weight of the plastic bins. No punctual data on the weight of each plastic bin are
436 available. The authors are aware that using an average weight value may underestimate the
437 exposition of the workers to the risk of manual lifting. However, the aim is to investigate the
438 potential exposure of workers to ergonomic risk factors. If the risk assessment based on the
439 average weight of the plastic bins reveals the presence of some risks for the workers, then
440 such situation is confirmed in real lifting conditions.

441 The following Table 4 shows the resulting NIOSH VLI risk ranges for each CR at the origin
442 of the lifting task (lifting the plastic bin from the floor) and at the destination (tipping the
443 plastic bin into the truck container). The NIOSH VLI green range indicates a low exposure of
444 the workers to the risk of lifting and lowering, yellow indicates moderate risk, red indicates
445 high risk range and purple indicates the highest risk range.

446 **Table 4.**

447 Percentage of CRs for each NIOSH VLI risk range, at the origin (O: lifting the plastic bin
448 from the floor) and at the destination (D: tipping the plastic bin into the truck container), in
449 each investigated season.

	Risk range				
	Green (% of CRs)	Yellow (% of CRs)	Red (% of CRs)	Purple (% of CRs)	Total (% of CRs)
Summer					
NIOSH VLI O	64%	21%	14%	0%	100%
NIOSH VLI D	0%	0%	64%	36%	100%
Spring/Autumn					
NIOSH VLI O	100%	0%	0%	0%	100%
NIOSH VLI D	53%	33%	13%	0%	100%
Winter					
NIOSH VLI O	100%	0%	0%	0%	100%
NIOSH VLI D	93%	0%	7%	0%	100%

450

451 Table 4 confirms the presence of the ergonomic risk for waste collectors due to the manual
452 handling of the plastic bins, i.e. the NIOSH VLI is higher than 1 in several CRs. Specifically,
453 the most critical values of the NIOSH VLI are at the destination of the movement, when the
454 workers overturn the contents of the plastic bin into the truck container. The critical risk
455 factor due to the characteristics of the adopted equipment and technology is the vertical
456 distance of the hands from the ground (140 cm) when tipping the bin on the truck container,
457 i.e. waste collectors lift the arms almost at the shoulder level. This risk factor impacts on the
458 vertical dislocation of the lifting movement and on the final risk index. The critical risk factor
459 due to the characteristics of the operations performed by the waste collectors is the horizontal
460 distance between the hand and the body of the worker (55 cm), i.e. waste collectors keep the
461 load far from the body while tipping the bin, aiming to avoid squirts and splashes. Trunk
462 twisting and bad coupling contribute to increase the exposure of waste collectors to the risk of
463 lifting and lowering. Finally, lifting frequency is an organizational risk factor with high
464 impact on the resulting NIOSH VLI values.

465 The analysis reveals that summer is the most critical season, followed by spring/autumn and
466 winter, i.e. no CRs appear in the green or yellow risk ranges at the destination of the lifting
467 movement.

468 The OWAS method was adopted for identifying and evaluating working postures during
469 door-to-door collection of organic MSW. The motion capture system described in Section 2
470 collected the data related to the body movements, in a testing environment. The aim was to
471 reproduce the real case in which bins are located close to each other on both sides of the
472 street, as described in Battini et al. (2018). The results of the postural assessment with the
473 OWAS method reveal an acceptable risk range for neutral and bent forward postures during
474 kerbside collection. A slightly harmful condition is present for the twisted posture. Finally,
475 the bent and twisted postures reveal an extremely harmful condition (see Table A1 in
476 Appendix A for the time fractions of each investigated back posture).

477 *3.1.2. Door-to-door collection of green waste*

478 The results of the ergonomic risk assessment for the door-to-door collection of green waste
479 confirm the presence of the ergonomic risk, i.e. the NIOSH VLI values at the origin and at the
480 destination of the lifting movement are higher than 1 (see Table A2 in Appendix A).

481 Specifically, the NIOSH VLI value is in the yellow risk range (moderate risk) at the origin of
482 the lifting movement. The most critical lifting conditions are at the destination of the
483 movement, when the workers overturn the contents of the waste container into the truck
484 hopper, i.e. the NIOSH VLI value is in the purple risk range (very high risk). The main risk
485 factors are due to the characteristics of equipment and work organization. Waste collectors are
486 required to return the empty containers to the citizen, after unloading the green waste into the
487 collection vehicle. The absence of an ergonomic container for green waste is a critical issue.
488 The collection of green waste requires the assumption of awkward postures of back and upper
489 limbs. This activity requires the waste collectors to lift the arms at the shoulder level. In case

490 of bulky waste containers, e.g. big plastic bags, the vertical distance of the hands of the
491 workers from the feet level is 175 cm. This factor impacts on the vertical dislocation and on
492 the final risk index. Furthermore, the shaking/emptying of the containers into the trucks may
493 create injuries, respiratory and eye irritation problems for the waste collectors. An additional
494 safety issue is the risk of injuries due to the contact with thorns and cutting branches.
495 The fact that plastic bags and other containers are emptied before being disposed slows down
496 the collection process. Bad coupling contributes to increase the exposure of waste collectors
497 to the risk of lifting and lowering. Finally, lifting frequency is an organizational risk factor
498 with high impact on the resulting NIOSH VLI. Such lifting modalities reveal very high
499 critical conditions and no additional postural assessment with the motion capture system is
500 necessary to confirm the presence of the risk.

501 *3.1.3. Door-to-door collection of residual waste*

502 The results of the ergonomic risk assessment for the door-to-door collection of residual waste
503 with the NIOSH VLI confirm the presence of the ergonomic risk for waste collectors due to
504 the manual handling of the plastic bins (see Table A3 in Appendix A). The NIOSH VLI is in
505 the yellow risk range at the origin of the lifting movement. The most critical values are at the
506 destination of the movement, when the workers overturn the contents of the plastic bin into
507 the truck container or into the truck hopper. The main risk factors are due to the
508 characteristics of technology, operations and work organization. Specifically, the critical risk
509 factor due to the characteristics of technology is the vertical distance of the hands from the
510 ground when tipping the bin, i.e. waste collectors lift the arms almost at the shoulder level.
511 This risk factor impacts on the vertical dislocation of the lifting movement and on the final
512 risk index. Bad coupling contributes to increase the exposure of waste collectors to the risk of
513 manual lifting and lowering. The critical risk factor due to the characteristics of the operations
514 performed by the waste collectors is the horizontal distance between the hand and the body of

515 the worker (40 cm), i.e. the waste collectors keep the load far from the body while tipping the
 516 bin. Finally, lifting frequency is an organizational risk factor with high impact on the resulting
 517 NIOSH VLI values.

518 *3.2. Recommendations and suggestions for improving ergonomics in door-to-door waste*
 519 *collection*

520 The results of the ergonomics analysis reveal that waste collectors are exposed to the risk of
 521 developing WMSDs, due to the manual handling of the waste containers. The postural
 522 assessment confirms a high exposure to postural risk factors for the back in standing posture
 523 while collecting the plastic bins. These results suggest critical areas of improvement that
 524 waste collection managers should address to improve waste collectors' health and safety.
 525 Table 5 shows the impact of the introduced decisional variables, i.e. organization, operations,
 526 technology and equipment, on the ergonomics of door-to-door collection, for each
 527 investigated waste typology. Specifically, the investigation of the NIOSH VLI allows to
 528 determine the impact of each parameter concurring in the calculation of the risk indices, e.g.
 529 lifting frequency and vertical distance. The decisional variables are related to these
 530 parameters, e.g. the lifting frequency refers to the organization, and the vertical distance of the
 531 hands from the ground at the origin of the lifting movement is related to the equipment. The
 532 marks in Table 5 describe such impact.

533 **Table 5.**

534 Impact of the decisional variables for the design of the door-to-door collection strategy, on the
 535 ergonomics of door-to-door collection of organic MSW, green waste and residual waste.

	Organic MSW	Green waste	Residual waste
Organization	++	++	++
Operations	++	+	++
Technology	++	+	++
Equipment	+	++	+

536

537 From an organizational point of view, an increment in the collection frequency of the bins
538 during the week only in the most critical months, i.e. the summer time, for organic and green
539 waste, could provide a beneficial effect towards the reduction of the risk indices reported in
540 the ergonomics analysis. Moreover, results reveal that lifting frequency is an organizational
541 risk factor with high impact on the results of the ergonomics analysis for residual waste
542 collection. Using job rotation in the most critical months and adding a second worker to
543 single-person crews that may expose the workers to high risk for manual lifting of the waste
544 containers would reach a positive effect. The adoption of waste typology-based job rotation
545 programs in the most critical months is also suggested.

546 The main risk factor due to the door-to-door collection of organic MSW and residual waste is
547 the horizontal distance between the hands and the body of the worker, i.e. collectors keep the
548 plastic bin far from the body while tipping the container, aiming to avoid squirts and splashes.
549 Trunk twisting and bad coupling contribute to increase the exposure of waste collectors to the
550 risk of lifting and lowering plastic bins. Such risk factors are related to the operations
551 performed by waste collectors. Their reduction is possible by providing proper training. The
552 safety managers of the waste management companies should inform waste collectors about
553 the risks of incorrect lifting, and train their workers to lift the plastic bins keeping the load
554 close to the body (less than 25 cm) in front position.

555 The results of the ergonomics analysis reveal that the main risk factors due to the door-to-
556 door collection of residual waste are due to the characteristics of the adopted technology.
557 These results suggest that similar solutions for organic MSW and residual waste may be
558 adopted to reduce the impact of such risk factors. The vertical distance of the hands from the
559 feet-level determines an high impact on the resulting NIOSH VLI for both such waste
560 typologies. Waste collectors lift the arms almost at the shoulder level (140 cm) to tip the

561 plastic bins into the truck container attached on the back of the collection vehicle. This risk
562 factor is due to the characteristics of the adopted technology. The posture assessment with the
563 motion capture system allowed to track the position of the workers' hands while tipping the
564 plastic bins into the truck container, i.e. the results reveal that the adoption of a truck
565 container with a lower height from the ground would reduce the vertical distance of the hands
566 from the ground at the destination of the lifting movement (see Figures A4 and A5 in
567 Appendix A). The vertical dislocation and the necessity to rotate and extend the back would
568 reduce as well, leading to reduced fatigue and cycle time.

569 The poor design of equipment and work organization are the main cause of the ergonomic
570 issues related to the door-to-door collection of green waste. The absence of a standardized
571 waste container with a defined geometry and an ergonomic shape is a critical issue which
572 largely increases the risks associated with this activity, e.g. the assumption of awkward
573 postures of back and upper limbs, and the risk of injuries due to the contact with thorns and
574 cutting branches (see Figure A6 in Appendix A).

575 An additional ergonomics analysis was performed adopting wheeled containers for the door-
576 to-door collection of green waste. The methodology in the ISO 11228-2 (International
577 Standard Organization, 2007) was applied to investigate initial and sustained pushing forces
578 during the manual handling of a 2-wheels container with green waste. The maximum capacity
579 of the container was 120 l. An handle was positioned at 97 cm from the ground. Sixty pushing
580 trials were performed during a CR. Each trial consisted in pushing the container for 2 m. The
581 observed pushing frequency during the CR was 0.55 pushes for minute. A digital force gauge
582 equipped with two handles (IMADA ZTA-500N, sample rate 2000 data/s, accuracy +/-
583 0.2%F.S. +/-1digit) was employed to measure pushing forces, as required by the ISO 11228-2
584 (International Standard Organization, 2007). The resulting initial pushing force was 6.5 kg
585 and the sustained pushing force was 3.6 kg. Such values are lower than the recommend limits

586 for initial (25 kg) and sustained (17 kg) pushing forces suggested in the ISO 11228-2
 587 (International Standard Organization, 2007). Finally, a laboratory test was performed pushing
 588 a similar 2-wheels container with 120 l of residual waste for 10 m. The resulting pushing
 589 forces were lower than the recommended limits in the ISO 11228-2 (International Standard
 590 Organization, 2007) for the investigated pushing task. Specifically, the resulting initial
 591 pushing force was 16 kg and the sustained pushing force was 9 kg.

592 *3.3. Ergonomic risk assessment after improvements*

593 By applying the improvement solutions discussed in Section 3.2 for the collection of organic
 594 MSW, e.g. introducing a lower truck container and providing worker training about proper
 595 lifting practices, it is possible to calculate the new NIOSH VLIs after 3 months of analysis, as
 596 reported in Table 6.

597 **Table 6.**

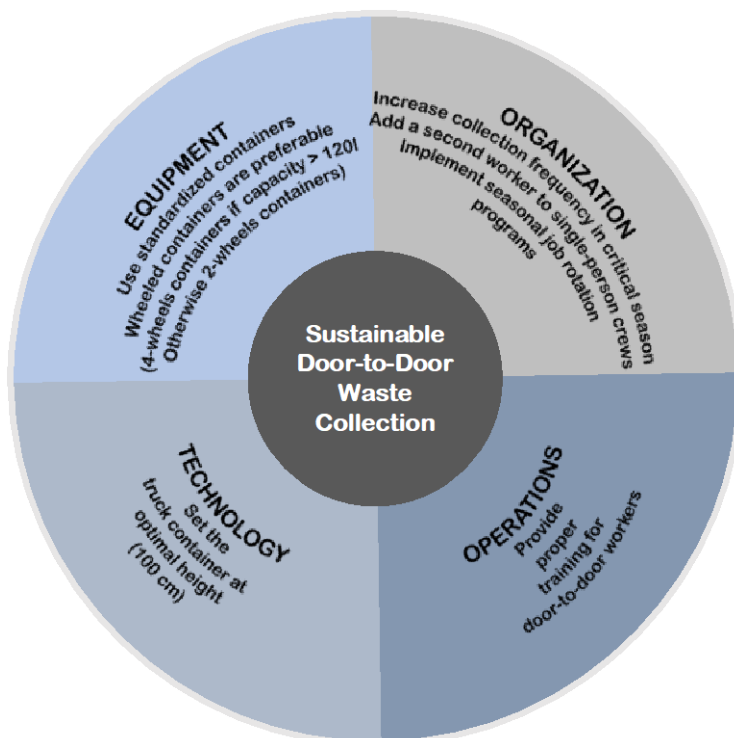
598 Number of CRs for each NIOSH VLI risk range, at the origin (O: lifting the plastic bin from
 599 the floor) and at the destination (D: tipping the plastic bin into the truck container).

	Risk range				
	Green	Yellow	Red	Purple	Total
	(% of CRs)	(% of CRs)	(% of CRs)	(% of CRs)	(% of CRs)
Summer					
NIOSH VLI O	93%	4%	4%	0%	100%
NIOSH VLI D	93%	4%	4%	0%	100%
Spring/Autumn					
NIOSH VLI O	100%	0%	0%	0%	100%
NIOSH VLI D	100%	0%	0%	0%	100%
Winter					
NIOSH VLI O	100%	0%	0%	0%	100%

NIOSH VLI D	100%	0%	0%	0%	100%
-------------	------	----	----	----	------

600

601 Table 6 shows the resulting NIOSH VLI risk ranges at the origin of the lifting task (lifting the
 602 plastic bin from the floor) and at the destination, for the investigated CRs. These results
 603 describe a lower exposure of the workers to the risk of lifting and lowering the plastic bins,
 604 for all the CRs in spring/autumn and winter. Low exposure is confirmed in the 93% of the
 605 CRs in summer. Such results reveal a huge improvement of the safety conditions during
 606 manual lifting of the plastic bins with the proposed solutions. Minor adjustments would
 607 significantly improve the ergonomics of the investigated activity. Specifically, a limited
 608 number of CRs would expose the workers to high ergonomic risk due to lifting activity. Such
 609 risk could be additionally reduced by increasing the collection frequency during the week
 610 only in the summer time and by adopting specific job-rotation programs that ensure proper
 611 recovery for the workers during the work-shift. These corrections would positively impact on
 612 the results of the postural assessment, as well. The following Figure 2 gathers the precautions
 613 and the improvements demonstrated in this work.



614

615 **Fig.2.** Guidelines for sustainable door-to-door waste collection.

616

617 *Organization:* increase the collection frequency of the bins during the week only in the most
618 critical months, that is the summer season for organic waste bins; add a second worker to
619 single-person crews that may expose the workers to high risk for manual lifting of the waste
620 containers; use waste typology-based job rotation programs in the most critical months
621 aiming to schedule the CRs that allow workers to alternate the waste typology to retrieve;

622 *Operations:* provide proper training to waste collectors explaining the correct working
623 procedures and proper lifting practices, in order to avoid awkward postures, incorrect
624 movements and person-dependent working approaches that can lead to person-dependent risk
625 levels;

626 *Technology:* the collection truck should be equipped with lifting containers in order to permit
627 an unloading height of bins equal to 100 cm.

628 *Equipment:* the municipality or the waste management company should provide the citizens
629 with standardized containers for green waste. The wheeled containers have been demonstrated
630 to be safe and preferable to the others. A second alternative includes the use of disposable
631 containers, e.g. biodegradable bags with limited dimensions, which could be easily dumped in
632 the collection vehicle.

633 A citizen aware of the risks for waste collectors due to the door-to-door collection activity
634 may help in improving the working conditions and reducing such risk factors. A set of
635 suggestions and directions for the citizens should include: do not expose the waste containers
636 containing green waste to the weather conditions; do not leave the waste containers on the
637 kerbside two or more days before the collection; use rigid containers for the collection of
638 cutting and sharp brunches and thorns; do not expose bulky and heavy containers.

639 **4. Conclusions**

640 This paper provides the results of an investigation on the door-to-door collection modalities
641 for organic municipal solid waste, green waste and residual waste, operated in an Italian
642 historic city centre. An ergonomics analysis was performed, aiming to investigate the
643 presence of ergonomic risk factors due to the manual lifting of the waste containers. Results
644 confirm that waste collectors are exposed to ergonomic risk during door-to-door collection of
645 the investigated waste typologies. The postural assessment revealed very high exposure to
646 postural risk factors for the back in standing posture. The results here provided suggest that
647 the door-to-door waste collection activity can become sustainable and ergonomic if a set of
648 improvements and precautions are adequately and timely put in practice by the municipality
649 and by the waste management companies.

650 Four areas of improvements have been identified: organization, operations, technology and
651 equipment. In these areas, all the three major actors involved in the waste collection process
652 are asked to make a step forward: the municipality, the collection companies and the workers
653 are all involved and mutually linked each other towards the sustainability challenge. Even the
654 citizens are not excluded: they need to be educated to behave in the most correct way in order
655 to permit an efficient and sustainable door to door waste collection activity. The results of a
656 behavioural survey conducted in 2019 in an Italian city revealed that citizens that practice
657 door-to-door separation have a higher recycling conscience and are more satisfied with the
658 city waste management system, compared with the ones that practice kerbside separation
659 (Calabrò and Komilis, 2019). Hence, this research does not mean to question the benefits of
660 door-to-door collection in terms of high amount of collected waste and quality of separation.

661 The solutions proposed for reducing the exposure to the identified ergonomic risk factors, as
662 collection vehicles with lower truck containers or wheeled containers for the collection of
663 green waste, are present in other cities, both inside and outside the Italian territory. The waste
664 management company involved in this study adopts some of the proposed solutions in other

665 municipalities. However, no information are available about the decisional variables that lead
666 such municipalities to prefer wheeled containers for green waste containers to plastic bags or
667 other containers. This study aims to increase the sensitivity of decision makers, designers and
668 researchers towards the design and the choice of safer alternatives that ensure safe and healthy
669 work conditions during door-to-door waste collection. Ergonomics and human factors are
670 critical decisional variables for the design of door-to-door waste collection strategies, in the
671 same way as financial and economic parameters.

672 Finally, this is the first step of an ongoing research on ergonomics of door-to-door collection.
673 Future developments of this research will integrate the introduced results with further
674 investigations about other typologies of waste, e.g. plastic, paper, metal and glass waste, and
675 additional guidelines for the design of safe door-to-door waste collection strategies.

676

677

678 **References**

- 679 Agència de Residus de Catalunya, Generalitat de Catalunya, 2017. Door to door selective
680 collection [WWW Document]. URL
681 http://residus.gencat.cat/en/ambits_dactuacio/recollida_selectiva/models_de_recollida/se
682 [gons_sistema_de_recollida/recollida_selectiva_porta_a_porta/index.html](http://residus.gencat.cat/en/ambits_dactuacio/recollida_selectiva/models_de_recollida/se) (accessed
683 2.26.19).
- 684 Attaianese, E., 2014. Criticità ergonomiche dei veicoli per la raccolta dei rifiuti urbani, in:
685 Fiera Ecomondo. Rimini.
- 686 Bartolacci, F., Paolini, A., Quaranta, A.G., Soverchia, M., 2018. Assessing factors that
687 influence waste management financial sustainability. *Waste Manag.*
688 <https://doi.org/10.1016/j.wasman.2018.07.050>
- 689 Battini, D., Botti, L., Mora, C., Sgarbossa, F., 2018. Ergonomics and human factors in waste

690 collection: analysis and suggestions for the door-to-door method. IFAC-PapersOnLine.
691 <https://doi.org/10.1016/j.ifacol.2018.08.443>

692 Battini, D., Faccio, M., Persona, A., Sgarbossa, F., 2011. New methodological framework to
693 improve productivity and ergonomics in assembly system design. *Int. J. Ind. Ergon.* 41,
694 30–42. <https://doi.org/10.1016/j.ergon.2010.12.001>

695 Battini, D., Persona, A., Sgarbossa, F., 2014. Innovative real-time system to integrate
696 ergonomic evaluations into warehouse design and management. *Comput. Ind. Eng.* 77,
697 1–10. <https://doi.org/10.1016/j.cie.2014.08.018>

698 Botti, L., Mora, C., Regattieri, A., 2017. Application of a mathematical model for ergonomics
699 in lean manufacturing. *Data Br.* 14. <https://doi.org/10.1016/j.dib.2017.06.050>

700 Calabrò, P.S., Gori, M., Lubello, C., 2015. European trends in greenhouse gases emissions
701 from integrated solid waste management. *Environ. Technol. (United Kingdom)*.
702 <https://doi.org/10.1080/09593330.2015.1022230>

703 Calabrò, P.S., Komilis, D., 2019. A standardized inspection methodology to evaluate
704 municipal solid waste collection performance. *J. Environ. Manage.*
705 <https://doi.org/10.1016/j.jenvman.2019.05.142>

706 Dorevitch, S., Marder, D., 2001. Occupational hazards of municipal solid waste workers.
707 *Occup. Med.* 16, 125–33.

708 Haslam, R., Waterson, P., 2013. Ergonomics and Sustainability. *Ergonomics* 56, 343–347.
709 <https://doi.org/10.1080/00140139.2013.786555>

710 International Standard Organization, 2007. ISO 11228-2:2007. Ergonomics — Manual
711 handling — Part 2: Pushing and pulling.

712 ISPRA, 2019. Rapporto Rifiuti Urbani. Edizione 2019. Roma, Italy. <https://doi.org/ISPRA>,
713 Rapporti 314/2019

714 Karhu, O., Kansil, P., Kuorinka, I., 1977. Correcting working postures in industry: A practical

715 method for analysis. *Appl. Ergon.* 8, 199–201. <https://doi.org/10.1016/0003->
716 6870(77)90164-8

717 Mccauley Bush, P., Reinhart, D., Investigator, C.-P., Maimoun, M., Gammoh, F., 2012.
718 Ergonomic & Environmental Study of Solid Waste Collection Final Report.

719 Mora, C., Manzini, R., Gamberi, M., Cascini, A., 2013. Environmental and economic
720 assessment for the optimal configuration of a sustainable solid waste collection system: a
721 ‘kerbside’ case study. *Prod. Plan. Control* 25, 737–761.
722 <https://doi.org/10.1080/09537287.2012.750386>

723 Olawumi, T.O., Chan, D.W.M., 2018. A scientometric review of global research on
724 sustainability and sustainable development. *J. Clean. Prod.*
725 <https://doi.org/10.1016/j.jclepro.2018.02.162>

726 Oxley, L., Pinder, A.D., Cope, M.T., 2006. Manual handling in kerbside collection and
727 sorting of recyclables HSL/2006/25. Harpur Hill, Buxton, Derbyshire.

728 Poulsen, O.M., Breum, N.O., Ebbenhøj, N., Hansen, Å.M., Ivens, U.I., van Lelieveld, D.,
729 Malmros, P., Matthiasen, L., Nielsen, B.H., Nielsen, E.M., Schibye, B., Skov, T.,
730 Stenbaek, E.I., Wilkins, K.C., 1995. Sorting and recycling of domestic waste. Review of
731 occupational health problems and their possible causes. *Sci. Total Environ.*
732 [https://doi.org/10.1016/0048-9697\(95\)04521-2](https://doi.org/10.1016/0048-9697(95)04521-2)

733 Punkkinen, H., Merta, E., Teerioja, N., Moliis, K., Kuvaja, E., 2012. Environmental
734 sustainability comparison of a hypothetical pneumatic waste collection system and a
735 door-to-door system. <https://doi.org/10.1016/j.wasman.2012.05.003>

736 Radjiyev, A., Qiu, H., Xiong, S., Nam, K.H., 2015. Ergonomics and sustainable development
737 in the past two decades (1992-2011): Research trends and how ergonomics can
738 contribute to sustainable development. *Appl. Ergon.*
739 <https://doi.org/10.1016/j.apergo.2014.07.006>

740 Shekdar, A. V., 2009. Sustainable solid waste management: An integrated approach for Asian
741 countries. *Waste Manag.* <https://doi.org/10.1016/j.wasman.2008.08.025>

742 Siemieniuch, C.E., Sinclair, M.A., Henshaw, M.J.C., 2015. Global drivers, sustainable
743 manufacturing and systems ergonomics. *Appl. Ergon.*
744 <https://doi.org/10.1016/j.apergo.2015.04.018>

745 Slow Elisabeth, 2017. Waste sector fatalities soar in 2016/17 [WWW Document]. URL
746 <https://www.letsrecycle.com/news/latest-news/waste-sector-fatalities-soar/> (accessed
747 11.8.17).

748 Sonesson, U., 2000. Modelling of waste collection - a general approach to calculate fuel
749 consumption and time. *Waste Manag. Res.* 18, 115–123.
750 <https://doi.org/10.1177/0734242X0001800203>

751 Teerioja, N., Moliis, K., Kuvaja, E., Ollikainen, M., Punkkinen, H., Merta, E., 2012.
752 Pneumatic vs. door-to-door waste collection systems in existing urban areas: A
753 comparison of economic performance. *Waste Manag.* 32, 1782–1791.
754 <https://doi.org/10.1016/j.wasman.2012.05.027>

755 Wang, Z., Geng, L., 2015. Carbon emissions calculation from municipal solid waste and the
756 influencing factors analysis in China. *J. Clean. Prod.*
757 <https://doi.org/10.1016/j.jclepro.2015.05.062>

758 Waters, T., 1993. Revised NIOSH equation for the design and evaluation of manual lifting
759 tasks. *Ergonomics* 36, 749–776. <https://doi.org/10.1080/00140139308967940>

760 Waters, T., Occhipinti, E., Colombini, D., Alvarez-Casado, E., Fox, R., 2016. Variable
761 Lifting Index (VLI): A New Method for Evaluating Variable Lifting Tasks. *Hum.*
762 *Factors.* <https://doi.org/10.1177/0018720815612256>

763 Waters, T., Occhipinti, E., Colombini, D., Alvarez-Casado, E., Hernandez-Soto, A., 2009.
764 The variable lifting index (VLI): A new method for evaluating variable lifting tasks

765 using the revised NIOSH lifting equation, in: Proceedings of the 17th Triennial Congress
766 of the International Ergonomics Association. ROC: International Ergonomics
767 Association, Beijing, China., pp. 1–3.

768 Waters, T.R., Putz-Anderson, V., Garg, A., 1994. Applications Manual for the Revised
769 NIOSH Lifting Equation.

770