



## Physics-based Analytical Engineering Models of Graphene Micro- and Nanostrip Lines

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# Physics-based Analytical Engineering Models of Graphene Micro- and Nanostrip Lines

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**Abstract**—In this paper, new approximate analytical models of graphene-based micro- and nanostrip transmission lines are given. These models are based on the representation of the mentioned lines by a parallel-plate waveguide embedded into an effective frequency-dependent permittivity media. Our theory allows analytical calculation of complex propagation constant and characteristic impedance of the main quasi-TM mode of graphene strip transmission lines. The developed approach is verified by comparisons with the thin-film lossy microstrips, for which the measurements and theory are available for frequencies up to 1 THz and with parallel-plate graphene waveguides. For very-narrow lines, the developed model is improved by a correction tuning technique. The obtained analytical formulas for complex propagation constant and characteristic impedance are interesting for calculations of electronically controlled graphene-based interconnects, microwave and millimeter wave attenuators, antennas, and transistors.

**Index Terms**— graphene microstrip line, graphene nanostrip line, an analytical model

## I. INTRODUCTION

GRAPHENE material [1] is interesting in the developments of new electronics and optoelectronics, including microwave and terahertz transistors [2]-[4]. An attractive feature of graphene components is their low signal delay and the possibility of tuning of their parameters using the electric or/and magnetic biasing of graphene's chemical potential and the conductivity of graphene layers [4],[5]. For instance, even loss of graphene interconnects can be decreased, tuning the chemical potential that is shown in measurements and simulations [6],[7]. Many linear and nonlinear graphene devices are published for analog microwave integrations [2],[4],[8],[9].

Similarly to that made for conventional electronics, the models of graphene components for computer-aided design (CAD) software tools should be created for the design system libraries [5]. The most analytically studied transmission line is the parallel-plate waveguide, where the graphene-one-atom layers are separated by a dielectric and biased by electric or/and magnetic fields [10]-[15]. Approximate analytical models for graphene microstrips are unknown, unlike conventional microstrips. There are some papers on numerical simulations using the integral equation method, technique of Fourier transform, method of lines, and the use of commercial software tools are published [5],[13]-[21]. Experimental results on

graphene-based components are with electronically controlled antennas, attenuators, filters, field-effect transistors [4]. Some papers are on the measurements of graphene microstrip transmission lines [21]-[23].

Analytical calculation of microstrip interconnects [24],[25] encounters some difficulties caused by the known and still unsolved problems in the theory of printed transmission lines complicated by loss properties of scalar or anisotropic graphene layers.

In this paper, a new approximate analytical physics-based model of graphene microstrip proposed allowing to calculate the complex propagation constant and characteristic impedance.

## II. THEORETICAL MODEL OF A GRAPHENE MICROSTRIP LINE

The cross-section of the modeled graphene microstrip line is shown in Fig. 1a.

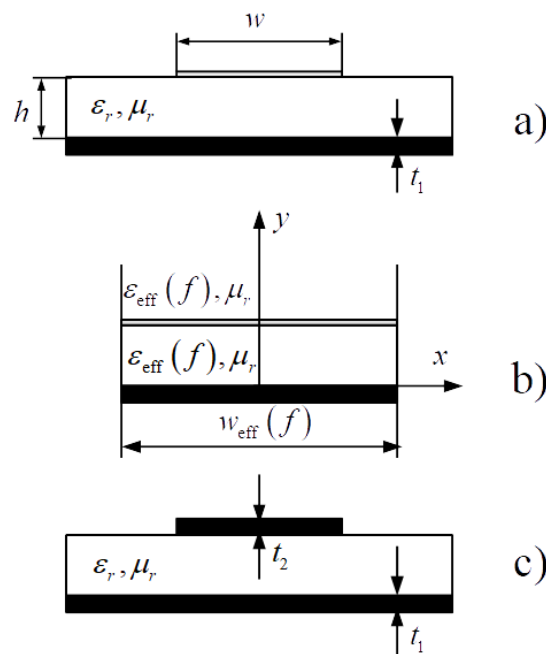


Fig. 1. Cross-sections of the studied integrated transmission lines. a) Graphene microstrip (nanostrip) line; b) Equivalent parallel plate model of graphene microstrip (nanostrip) line with the ideal magnetic walls placed at the effective width  $w_{\text{eff}}(f)$  from each other; c) Thin-film microstrip line.

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The atomic-thick graphene signal strip conductor (in grey color) of the width  $w$  placed on the surface of the substrate of the relative permittivity  $\epsilon_r$ , relative permeability  $\mu_r = 1$ , and the height  $h$ .

In general case, the graphene layer properties are anisotropic and described with a conductivity tensor  $\underline{\sigma}$  [18], [26]:

$$\underline{\sigma} = \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{pmatrix}. \quad (1)$$

Another side of this substrate is covered with a thin metal layer of the specific conductivity  $\sigma_1^{(s)}$  and thickness  $t_1$ , or it can be assumed as a perfect conductor with  $\sigma_1^{(s)} = \infty$ .

The first theories of conventional microstrip lines relate to the beginning of the 50<sup>th</sup> of the last century when, firstly, the strip-line cross-section was transformed into a parallel plate geometry on a complex plane, and the potential, electric field, and characteristic impedance of the main transversal electromagnetic (TEM) mode were calculated. Microstrip lines have the layered dielectric design, and they can be calculated by the method of conformal mapping only in an approximate manner. For this purpose, the line is filled by an effective dielectric media uniformly, and again the same method allows to calculate the modal parameters. The hybrid nature of mode is considered by introducing the frequency-dependent effective permittivity. To analyze the microstrip discontinuities, the microstrips are represented by parallel-plate waveguide filled by the effective modal permittivity, and even multi-modal diffraction effects are described in this manner using the mathematical means or equivalent circuits of discontinuities [27].

Loss calculation in microstrips is a rather challenging problem, especially in a wide frequency band. Many models are known and used in engineering practice. One of them is our parallel-plate approximation validated by published measurement at frequencies up to 150 GHz, and by comparisons with some numerical simulations up to 1 THz [24],[25]. In this model, parallel-conductor plates are substituted by equivalent impedance walls, and no field is supposed outside the cross-section of this parallel-plate waveguide filled with an effective permittivity media and lined by magnetic walls placed at a certain effective distance  $w_{\text{eff}}$  from each other. The theory gives the complex propagation constant and characteristic impedance, and it is accurate for the wide thin-film conductor and electrically thin-substrate microstrips used in microwave integrated electronics.

Direct application of this model to graphene microstrip shows its inaccuracy because electromagnetic (EM) field penetrates the atomically thin graphene, and it is strong over this layer, and, at the difference to conventional conductors, this field should be considered when we are formulating a parallel-plate model of the graphene microstrip line.

The main idea of this contribution is that the parallel-plate geometry of the microstrip model is embedded into the uniform

effective permittivity media (Fig. 2), and it allows to obtain analytical expressions for the complex modal propagation constant and characteristic impedance. Otherwise, placing this mentioned geometry into a layered media allows getting the dispersion equations solved only numerically regarding complex longitudinal propagation constant  $k_z$ .

Before to provide the EM treatment for this model (Fig. 2), let's consider the parameters of all components of this equivalent waveguide. It is supposed that it is filled with the effective frequency-dependent permittivity media  $\epsilon_{\text{eff}}(f)$  (see Appendix A for the calculation formulas), and it is of the effective frequency-depending width  $w_{\text{eff}}(f)$ .

Considering the anisotropic graphene and lossy ground conductor represented with its surface impedance, the field of the main mode in the parallel-plate waveguide (Fig. 1b) is hybrid, and it has all six field components. This field is written using two vector potential functions for each layer, supposing the independence of the field according to the  $x$ -direction:

$$\Phi^{(1,2)}(y, z) = \mathbf{y}_0 \Phi_y^{(1,2)}(y) e^{-jk_z z}, \quad (2)$$

$$\Psi^{(1,2)}(y, z) = \mathbf{y}_0 \Psi_y^{(1,2)}(y) e^{-jk_z z} \quad (3)$$

where  $k_z$  is the unknown longitudinal propagation constant.

For our further treatment, we need only the fields  $\mathbf{E}_\tau = \mathbf{x}_0 E_x + \mathbf{z}_0 E_z$  and  $\mathbf{H}_\tau = \mathbf{x}_0 H_x + \mathbf{z}_0 H_z$ , which are tangential to the plates of the waveguide (Fig. 1b):

$$\begin{aligned} E_x^{(1,2)}(y, z) &= jk_z \Psi_y^{(1,2)}(y) e^{-jk_z z}, \\ E_z^{(1,2)}(y, z) &= -\frac{k_z}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} \frac{\partial^2 \Phi_y^{(1,2)}(y)}{\partial y^2} e^{-jk_z z}, \\ H_x^{(1,2)}(y, z) &= jk_z \Phi_y^{(1,2)}(y) e^{-jk_z z}, \\ H_z^{(1,2)}(y, z) &= -\frac{k_z}{\omega \mu_0 \mu_r} \frac{\partial \Psi_y^{(1,2)}(y)}{\partial y} e^{-jk_z z} \end{aligned} \quad (4)$$

with

$$\begin{aligned} \Phi_y^{(1)}(y) &= (A \cos k_y y + B \sin k_y y), \\ \Psi_y^{(1)}(y) &= (C \cos k_y y + D \sin k_y y), \\ \Phi_y^{(2)}(y) &= E e^{-jk_y(y-h)}, \\ \Psi_y^{(2)}(y) &= F e^{-jk_y(y-h)} \end{aligned} \quad (5)$$

where  $j = \sqrt{-1}$ ,  $\epsilon_0$  is the vacuum absolute permittivity,  $\mu_0$  and  $\mu_r$  are the vacuum absolute and media's relative permeabilities, correspondingly,  $k_y = \sqrt{k_0^2 \epsilon_{\text{eff}}(f) \mu_r - k_z^2}$ ,  $k_0 = \omega/c$ ,  $c$  is the light velocity in mm/s, and  $\omega = 2\pi f$ , and  $f$  is the driving frequency in Hertz. The constants  $A, B, C, D, E, F$ , and  $k_z$  are unknown, and they are obtained from the boundary conditions.

The first two of them are on the tangential to the boundary fields  $\mathbf{E}_\tau^{(1)}(y=0)$  and  $\mathbf{H}_\tau^{(1)}(y=0)$  matched at the surface of

the ground layer using the Leontovich's boundary condition that gives two equations:

$$\mathbf{E}_r^{(1)}(y=0) + Z_s^{(1)} \left[ \mathbf{H}_r^{(1)}(y=0) \times \mathbf{n}_1 \right] = 0 \quad (6)$$

where  $Z_s^{(1)}$  is the surface impedance of the ground layer specified below in formula (13),  $\mathbf{n}_1$  is the normal vector to the boundary 1 and oriented along the  $y$  - axis.

Other four boundary equations are written for the graphene layer supposing its zero thickness:

$$\begin{aligned} \mathbf{E}_r^{(2)}(y=h) - \mathbf{E}_r^{(1)}(y=h) &= 0, \\ \mathbf{H}_r^{(2)}(y=h) - \mathbf{H}_r^{(1)}(y=h) &= \sigma_2 \mathbf{E}_r^{(2)}(y=h). \end{aligned} \quad (7)$$

These boundary conditions (6) and (7) give the six linear algebraic equations regarding  $A, B, C, D, E, F$ . The determinant of this homogeneous system delivers a transcendental equation for the propagation constant  $k_z$  of the treated waveguide (Fig. 2) filled with  $\varepsilon_{\text{eff}}(f)$  and being equivalent to the graphene microstrip line (Fig. 1a). This system order can be decreased down to four if the ground layer is considered being perfect.

#### A. Anisotropic Graphene-Perfect Ground Layer Line

In this case, the two potential functions for two layers are:

$$\begin{aligned} \Phi_y^{(1)}(y) &= B \cos k_y y, \\ \Psi_y^{(1)}(y) &= D \sin k_y y, \\ \Phi_y^{(2)}(y) &= E e^{-jk_y(y-h)}, \\ \Psi_y^{(2)}(y) &= F e^{-jk_y(y-h)}. \end{aligned} \quad (8)$$

These functions provide the fields satisfying the boundary condition on the ideal metal; the other four equations are on the boundary with the graphene layer (see Equ. (7)). It gives the following eigenvalue equation regarding the longitudinal propagation constant  $k_z$ :

$$\det \begin{pmatrix} 0 & \sin(k_y h) & 0 & -1 \\ -\sin(k_y h) & 0 & j & 0 \\ 0 & \frac{k_y \cos(k_y h)}{\omega \mu_0 \mu_r} & \frac{-jk_y \sigma_{12}}{\omega \varepsilon_0 \varepsilon_{\text{eff}}(f)} & \frac{k_y}{\omega \mu_0 \mu_r} + j\sigma_{11} \\ -\cos(k_y h) & 0 & 1 + \frac{\sigma_{22} k_y}{\omega \varepsilon_0 \varepsilon_{\text{eff}}(f)} & -\sigma_{21} \end{pmatrix} = 0 \quad (9)$$

Supposing that the substrate is electrically thin,  $|k_y h| \ll 1$ ,  $\sin(k_y h) \approx k_y h$ ,  $\cos(k_y h) \approx 1$ , the analytical treatment of the determinant (9) gives:

$$k_y^2 \frac{h \sigma_{22}}{k_0^2 \varepsilon_{\text{eff}}(f) \mu_r} + k_y \frac{h(j-1)}{\omega \mu_0 \mu_r} - \left( \sigma_{11} h + \frac{1}{\omega \mu_0 \mu_r} \right) = 0. \quad (10)$$

This quadratic eigenvalue equation is solved regarding  $k_y$  analytically, and one of the roots corresponds to the quasi-TM main mode of the considered transmission line. It is seen that although  $\sigma_{12}$  and  $\sigma_{2,1}$  are not seen in this formula, the influence of anisotropy of conductivity remains in hybrid nature of the main mode caused by this conductivity, and it needs to be considered in the theory of graphene microstrip line if its conductivity is anisotropic that is in correspondence to the conclusion of [18].

The longitudinal propagation constant  $k_z$  is derived immediately from  $k_z = \sqrt{k_0 \varepsilon_{\text{eff}}(f) \mu_r - k_y^2}$  choosing the needed branch of the imaginary part of this propagation constant properly.

For calculation of the characteristic impedance for the main mode, the boundary equations (6) and (7) should be solved if the propagation constant  $k_z$  is found from (9) or (10). Then, this parameter is found as a relationship between the graphene current and line voltage. An example of such formulas is shown below.

#### B. Scalar Graphene-Imperfect Ground Layer Line

Another important variant is the biasing of the graphene layer by only the electric field. At sub-Terahertz region, graphene, according to the opinions of many authors, can be described by scalar conductivity  $\sigma_2$ . Then, in the parallel-plate waveguide, the electric and magnetic types of modes can be classed independently regarding the  $y$  - axis [14],[15].

Consider the correspondence of these modes to the main mode of the graphene microstrip line. It is obvious that this mode should have a strong  $E_y$  component similarly to the conventional microstrip. Due to the loss in ground and graphene, the main mode should have the longitudinal component of the electric field, and this mode can be related to the quasi-TM modes [24],[25]. Then, to model this main mode of graphene microstrip, the  $E_y$  - lowest mode of equivalent the parallel plate waveguide is used for our further treatment. To describe this mode, the following potential functions are chosen:

$$\begin{aligned} \Phi_y^{(1)} &= A \cos k_y y + B \sin k_y y, \\ \Phi_y^{(2)} &= C e^{-jk_y(y-h)}. \end{aligned} \quad (11)$$

Using (4) and (11) for only  $\Phi_e^{(1,2)}(y, z)$  and the boundary conditions (6) and (7), one can obtain the following eigenvalue equation for  $k_z$ :

$$\det \begin{pmatrix} -\cos(k_y h) & -\sin(k_y h) & 1 - \frac{\sigma_2 k_y}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} \\ -\sin(k_y h) & \cos k_y h & j \\ jZ_s^{(1)} & \frac{-k_y}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} & 0 \end{pmatrix} = 0 \quad (12)$$

where

$$Z_s^{(1)} = -jZ_{0M}^{(1)} \cot(k_1 t_1), \quad (13)$$

$$Z_{0M}^{(1)} = (1+j) \sqrt{\frac{\omega \mu_0 \mu_r^{(1)}}{2\sigma_1^{(s)}}}, \text{ and } k_1 = \frac{1-j}{\sqrt{\omega \mu_0 \mu_r^{(1)} \sigma_1^{(s)}/2}},$$

$\mu_r^{(1)}$  is the conductor's relative permeability constant,  $\sigma_1^{(s)}$  is the ground conductor's specific conductivity, and  $t_1$  is the ground conductor thickness.

The scalar conductivity  $\sigma_2$  of an isolated carbon sheet is calculated using one of the known approximate formulas, for instance, from [18]:

$$\sigma_2 = \frac{-je^2 k_B T}{\pi \hbar^2 (\omega - j\tau^{-1})} \ln \left( 2 \left( 1 + \cosh \left( \frac{\mu_c(E_{\text{bias}})}{k_B T} \right) \right) \right), \quad (14)$$

which is valid for  $k_B \ll |\mu_c|, \hbar \omega$ . In this formula,  $e$  is the electron charge,  $k_B$  is the Boltzmann constant,  $T$  is the absolute temperature in Kelvin,  $\hbar$  is the reduced Planck constant,  $\tau$  is the scattering rate constant,  $m$  is the electron mass, and  $\mu_c(E_{\text{bias}})$  is the graphene chemical potential that can be controlled applying the biasing electric field  $E_{\text{bias}}$ .

Supposing that the substrate is electrically thin and  $|k_y h| \ll 1$ , the analytical treatment of the determinant (12) gives

$$\begin{aligned} & k_y^3 \frac{\sigma_2 h}{(\omega \epsilon_0 \epsilon_{\text{eff}}(f))^2} - k_y^2 \frac{h}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} \\ & + k_y \left( j \frac{1 + \sigma_2 Z_s^{(1)}}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} + h Z_s^{(1)} \right) - j Z_s^{(1)} = 0. \end{aligned} \quad (15)$$

Analysis of this equation shows that the conductivity parameter  $\sigma_2$  is a coefficient multiplying the cubic term. It means that solution may be highly sensitive towards the inaccuracy of graphene conductivity model. An additional means of accuracy control is the calculation of the determinant (12) at the root found with (15).

This cubic equation is solved analytically with the Cardano's formulas [28]. If  $k_y$  is found, the longitudinal propagation constant  $k_z$  is derived immediately from  $k_z = \sqrt{k_0 \epsilon_{\text{eff}}(f) \mu_r - k_y^2}$  choosing the needed branch of the imaginary part of this propagation constant properly.

In *Matlab*, the roots of the cubic equation are derived using the function *roots*, and it gives three values of complex  $k_y$ . The

first two of them are equal, and they are the sought mode transversal propagation constant  $k_y$ . The third complex root is small in its value, and it gives the longitudinal propagation constant  $k_z$  with  $\text{Re}(k_z) \approx k_0 \sqrt{\epsilon_{\text{eff}}(f) \mu_r}$  and the negligibly small imaginary part of this constant.

If the boundary equation problem has been solved, the characteristic impedance for this mode is obtained as:

$$Z_c = \frac{U}{I} = \frac{\int_0^h E_y^{(1)}(y) dy}{\int_0^w (H_x^{(2)}(y=h) - H_x^{(1)}(y=h)) dx} = \frac{\int_0^h E_y^{(1)}(y) dy}{\sigma_2 \int_0^{w_{\text{eff}}} E_z^{(2)}(y=h) dx} \quad (16)$$

with

$$\begin{aligned} E_y^{(2)}(y) &= \frac{-jk_z^2}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} \Phi_y^{(1)}(y), \\ E_z^{(2)}(y) &= \frac{jk_z}{\omega \epsilon_0 \epsilon_{\text{eff}}(f)} \frac{d\Phi_y^{(2)}}{dy}. \end{aligned} \quad (17)$$

As seen from (15), the calculation of complex propagation constant  $k_z$  in wide frequency band requires the formulas for loss-less microstrip line that take into account the frequency dependence of the effective permittivity  $\epsilon_{\text{eff}}(f)$  and the effective strip width  $w_{\text{eff}}(f)$ . In Appendix A, these engineering formulas are chosen considering many published papers according to the Author's experience and comparisons with the available numerical and experimental data.

### III. VERIFICATION OF THE DEVELOPED MODEL

#### A. Comparisons with the Thin-film Lossy Microstrip Line Full-wave, Analytical, and Measurement Results

Equ. (15) is obtained for infinitely thin graphene strips embedded into uniform effective dielectric media. This technique has not been known before, and it should be tested. For instance, it can be verified with the results known for thin-film microstrips [24],[25],[29],[30]. Before to compare, the correspondence infinitely thin resistive microstrip model should be found to the thin-film ones. For this purpose, the conductivity  $\sigma_2$  is calculated from the specific conductivity of signal conductors of testing microstrips as  $\sigma_2 = \sigma_s^{(2)} t_2$  where  $t_2$  is the conductor thickness.

The comparisons are shown in Figs 2-6 obtained for microstrips with  $w/h = 4.7$  and  $2.74$ . The ground layer is lossy for all calculations, and it is modeled according (13). For these thin film microstrips, the experimental, full-wave and analytical results are given at frequencies up to 1 THz.

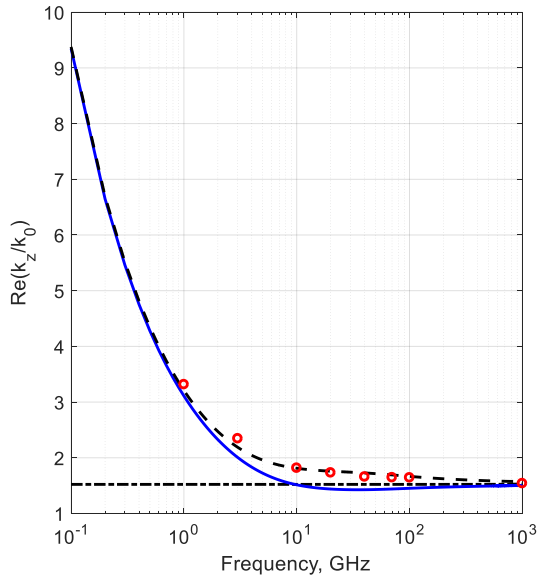


Fig. 2. The real part of  $k_z$  versus frequency. Solid violet line: formula (15); dash-dot black line: ideal conductor microstrip [31],[32],[33]; dash black line: thin-film microstrip analytical model [24],[25], and Appendix B; red circles: full-wave from [29]. Microstrip data:  $\epsilon_r = 2.7$ ,  $\mu_r = 1$ ,  $\tan \delta = 0.015$ ,  $h = 1.7 \mu\text{m}$ ,  $w = 8 \mu\text{m}$ ,  $t_1 = t_2 = 0.8 \mu\text{m}$ ,  $\sigma_1^{(s)} = \sigma_2^{(s)} = 2.5 \cdot 10^4 \text{ Sim} \cdot \text{mm}^{-1}$ .

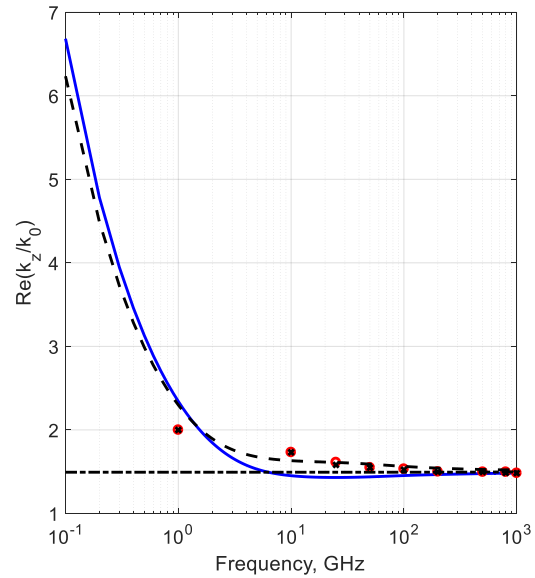


Fig. 4. The real part of  $k_z$  versus frequency. Solid violet line: formula (15); dash-dot black line: ideal conductor microstrip calculated according to [30],[31],[32]; dash black line: thin-film microstrip analytical model [24],[25], and Appendix B; red circles: numerical data from [30]; crosses: measurements from [30]. Microstrip data:  $\epsilon_r = 2.7$ ,  $\mu_r = 1$ ,  $\tan \delta = 0.015$ ,  $h = 2.7 \mu\text{m}$ ,  $w = 7.4 \mu\text{m}$ ,  $t_1 = t_2 = 0.8 \mu\text{m}$ ,  $\sigma_1^{(s)} = \sigma_2^{(s)} = 3 \cdot 10^4 \text{ Sim} \cdot \text{mm}^{-1}$ .

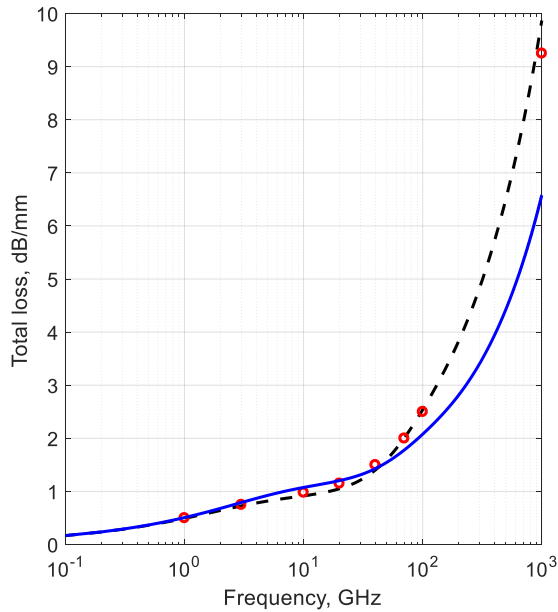


Fig. 3. Microstrip total (conductor+dielectric) loss  $\alpha_t$  versus frequency. Solid violet line: formula (15); dash black line: thin-film microstrip analytical model [24],[25], and Appendix B; red circles: full-wave data from [28]. Microstrip data:  $\epsilon_r = 2.7$ ,  $\mu_r = 1$ ,  $\tan \delta = 0.015$ ,  $h = 1.7 \mu\text{m}$ ,  $w = 8 \mu\text{m}$ ,  $t_1 = t_2 = 0.8 \mu\text{m}$ ,  $\sigma_1^{(s)} = \sigma_2^{(s)} = 2.5 \cdot 10^4 \text{ Sim} \cdot \text{mm}^{-1}$ .

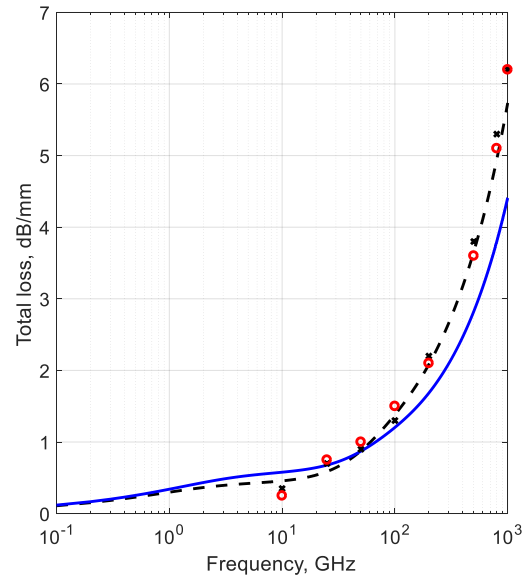


Fig. 5. Microstrip total (conductor+dielectric) loss  $\alpha_t$  versus frequency. Solid violet line: formula (15); dash black line: thin-film microstrip analytical model [24],[25], and Appendix B; red circles: full-wave data from [30]; crosses: experimental from [29]. Microstrip data:  $\epsilon_r = 2.7$ ,  $\mu_r = 1$ ,  $\tan \delta = 0.015$ ,  $h = 2.7 \mu\text{m}$ ,  $w = 7.4 \mu\text{m}$ ,  $t_1 = t_2 = 0.8 \mu\text{m}$ ,  $\sigma_1^{(s)} = \sigma_2^{(s)} = 3 \cdot 10^4 \text{ Sim} \cdot \text{mm}^{-1}$ .

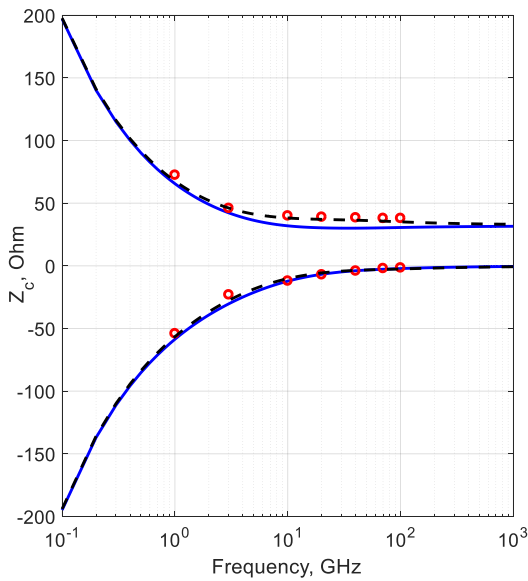


Fig. 6. The complex characteristic impedance of thin-film microstrip line versus frequency. Positive values are for the real part, and negative ones are for the imaginary part. Solid violet line: formula (16); dash black line: the approximate model of thin-film microstrip from [24],[25]; Red circles: full-wave results from [29]. Microstrip data are the same as at Figs. 3 and 4.

It is seen that the zero-thickness analytical model calculates the phase constant of the main mode and its characteristic impedance with good accuracy in the large frequency range comparing the full-wave, experimental, and approximate analytical results.

The loss is computed with less accuracy especially at frequencies over 100 GHz, and its reason is obvious. The thickness of all conductors and the skin effect must be taken into account in such thin-film microstrips. In the case of graphene lines with the atomically-thin signal conductor, this effect is expected to disappear, and this wide strip graphene lines should be calculated with good accuracy.

### B. Modeling of Wide Graphene Microstrips and Comparisons with the Parallel-plate Analytical Results

The ultimate case of a wide-strip line is the parallel-plate waveguide treated analytically in many papers [5],[10],[12],[14],[17]. In [10], an analytical formula is given for a parallel-plate graphene line (see [10], p. 2, formula (15)). It is obtained under the assumptions  $|k_y h| \ll 1$  and  $|\sigma k_y / \omega \epsilon_0 \epsilon_r| \gg 1$ . Its both plates made of graphene layers, but this formula is pertinent to calculate the odd TEM mode of this waveguide. In this case, the cross-section of this line can be separated by an ideal electric wall. Our model can calculate this geometry as well, and the analytical results of G.W. Hanson compared with our simulation of a very wide ( $w/h=8$ ) air-filled strip line. The results (Fig. 7) are close to each other at increased frequencies, but different at low ones because our theory is free of the restriction  $|\sigma k_y / \omega \epsilon_0 \epsilon_r| \gg 1$ .

As seen from our simulations and published parallel-plate modeling, the graphene line has a rather strong loss at low-frequency microwaves. This loss is decreased with frequency

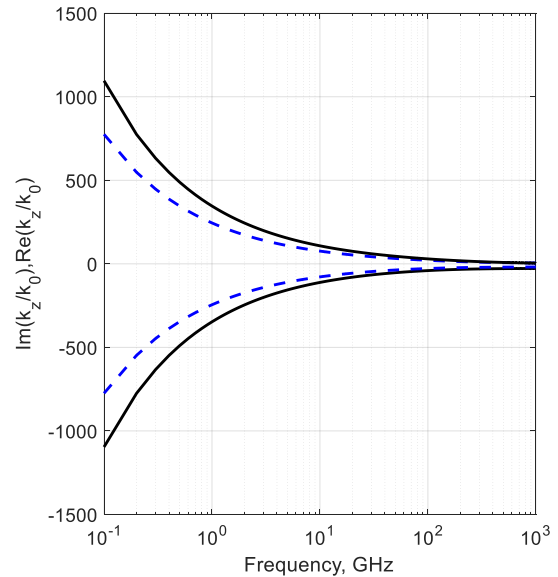


Fig. 7. The imaginary and real part of propagation constants versus frequency. Solid black lines: analytical results according to Hanson's formula; dash violet line: our results. The waveguide geometry and graphene's data:  $h = 0.5 \mu\text{m}$ ,  $w = 20 \mu\text{m}$ ,  $\epsilon_r = 1$ ,  $\mu_r = 1$ ,  $\tan \delta = 0$ ,  $\mu_c = 0$ ,  $\tau = 0.5 \text{ ps}$ ,  $T = 300 \text{ K}$ .

and with the chemical potential controlled by the electric DC field.

Figs. 8, 9 shows the complex propagation constant and characteristic impedance for two values  $\mu_c$ . It is seen that growing this parameter leads to the loss decrease compared with those brought by imperfect ground (Fig. 8). At the same time, it allows tuning the characteristic impedance to the values typical for conventional microstrips (Fig. 9) at the difference to the lines based on carbon nanotubes.

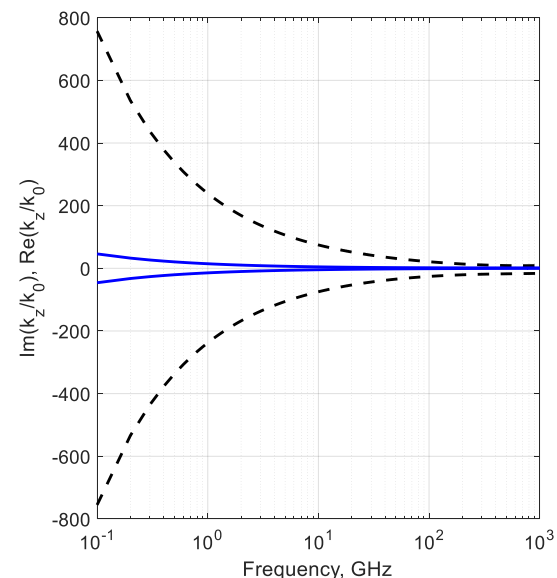
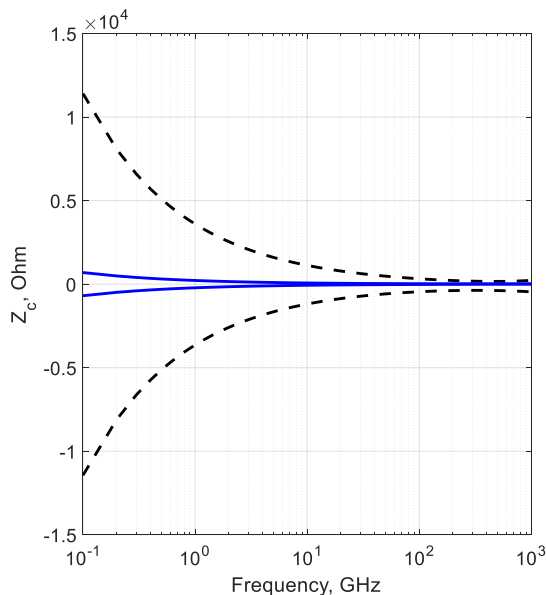


Fig. 8. Normalized complex propagation constant of microstrip line versus frequency. Positive values are for the real part, and the negative one is for the

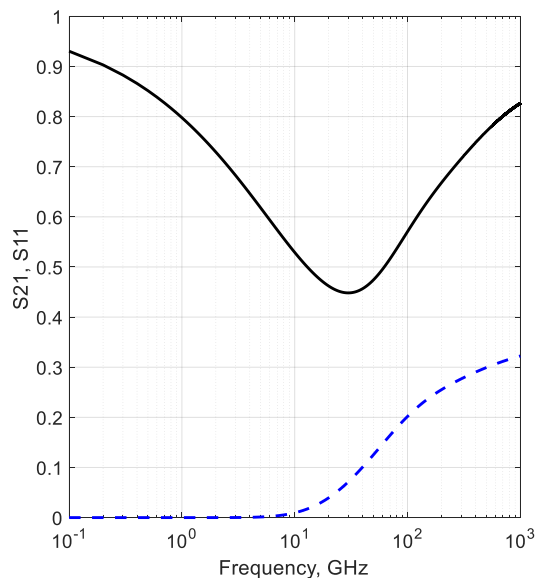


1 imaginary part. Dash black line  $\mu_c = 0$  eV; solid blue line  $\mu_c = 10$  eV. Other  
 2 parameters:  $T = 300$  K,  $\tau = 0.5$  ps,  $\epsilon_r = 3.9$ ,  $\mu_r = 1$ ,  $\tan \delta = 0$ ,  $h = 1.7$   $\mu\text{m}$ ,  
 3  $w = 8$   $\mu\text{m}$ ,  $t_1 = 0.8$   $\mu\text{m}$ ,  $\sigma_1^{(s)} = 2.5 \cdot 10^4$  Sim  $\cdot \text{mm}^{-1}$ .



4 Fig. 9. Complex characteristic impedance versus frequency. Positive values are  
 5 for the real part, and the negative one is for the imaginary part. Dash black line  
 6  $\mu_c = 0$  eV; solid blue line  $\mu_c = 10$  eV.  $\text{Re}(Z_c) \approx 50$  Ohm is at 20.7 GHz for  
 7  $\mu_c = 10$  eV. Other parameters of microstrip and graphene are the same as at  
 8 Fig. 8.

9 On Fig. 10, it is shown the S-matrix element dependence  
 10 of a short length ( $L = 1$  mm) of a graphene microstrip joined  
 11 to  $50\text{-}\Omega$  ports.



12 Fig. 10. The dependence of modules of the transmission ( $S_{21}$ ) and reflection  
 13 ( $S_{11}$ ) coefficients of a length of the graphene transmission line. Parameters of  
 14 microstrip and graphene conductors are the same as at Fig. 9.

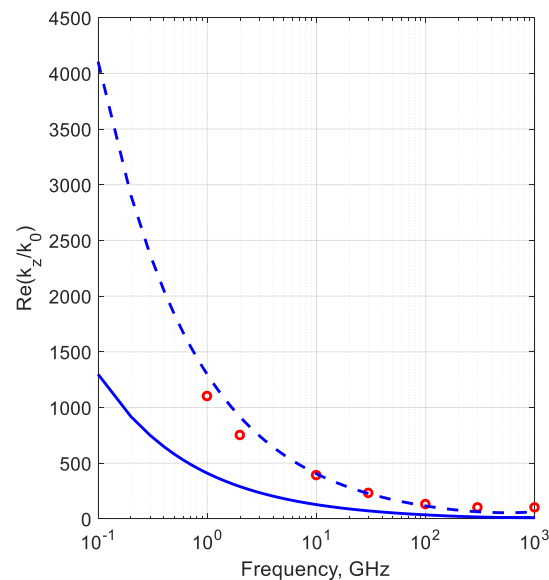
15 It is seen that the reflection coefficient minimum occurs at  
 16 a frequency near 30 GHz if the real impedance part of graphene

17 microstrip characteristic impedance is tuned to  $50\text{-}\Omega$  at 20.7  
 18 GHz.

### 19 C. Comparisons with the Full-wave Simulations of the 20 Narrow Graphene Micro- and Nanostrip Lines

21 The available in the literature full-wave results are for  
 22 narrow-width ( $w/h < 2-3$ ) microstrip graphene lines which  
 23 are difficult to be modeled by the equivalent parallel-plate  
 24 approach. Usually, it is improved using the correction factors as  
 25 in [24],[25]. The reason is that the ideal microstrip is modeled  
 26 with the effective permittivity model. If the conductors have  
 27 loss their conductivity should be substituted by its effective  
 28 value one. Such models are not available, and up to now, the  
 29 conductivity of conductor-surface impedances have been  
 30 corrected empirically matching the models to the full-wave or  
 31 measurement results. Physically, the currents in narrow strips  
 32 are seriously distorted by edges and current-crowding effect,  
 33 and the resistance of strips increases. The nonuniform  
 34 distribution of current on the ground conductor can be taken as  
 35 well [34]. To compensate it, the equivalent conductance of strip  
 36 should be introduced. In practical modeling, the conductance of  
 37 the strip can be reduced using the empirically found coefficients  
 38 similarly to [24],[25].

39 To test our model, a very narrow ( $w/h = 0.2$ ) nanostrip is  
 40 chosen as the worst-case scenario for our approach. This line is  
 41 simulated using the integral equation method in [18]. As  
 42 expected, our model provides the rather large difference,  
 43 especially at frequencies below 100 GHz for the real (Fig. 11)  
 44 and imaginary (Fig. 12) parts of propagation constant, and the  
 45 equivalent parallel-plate model in the case of narrow strips  
 46 should be corrected.



47 Fig. 11. The real part of normalized propagation constant versus frequency.  
 48 Solid blue line: analytical calculations according (15). Red circles: simulations  
 49 taken from [18] with graphical accuracy. Dash blue line: calculations with  
 50 corrected graphene conductivity ( $K_s = 0.1$ ). Microstrip parameters:



$\epsilon_r = 3.9, \mu_r = 1, \mu_c = 1, \tan \delta = 0, h = 0.5 \mu\text{m}, w = 100 \text{ nm}, T = 300 \text{ K},$   
 $\tau = 0.5 \text{ ps}, \mu_c = 0, \sigma_1^{(s)} = \infty,$  and  $\sigma_2$  is calculated according (14).

The correction approach is chosen according to the above-described mechanism of the influence of non-uniformity of the current distribution along the strip width. By introducing the equivalent strip conductivity and correction of its value by  $K_s = 0.1$ , it is allowed to tune the results close to the full-wave calculations (Figs. 11 and 12). Of course, to make a complete tuning technique, there are more full-wave results needed to be obtained for a variety of microstrip geometries and physical parameters.

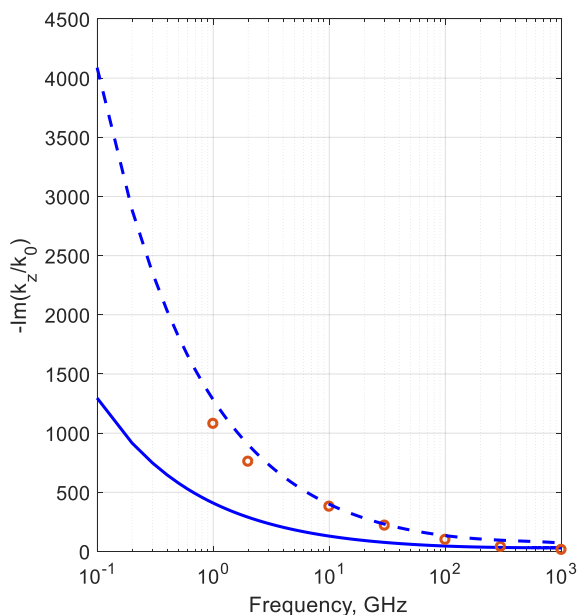


Fig. 12. The imaginary part of normalized propagation constant versus frequency. Solid violet line: analytical calculations according (15). Dash violet line: calculations with corrected graphene conductivity ( $K_s = 0.1$ ); Red circles: full-wave simulations taken from [18] with graphical accuracy. Microstrip parameters:  $\epsilon_r = 3.9, \mu_r = 1, \tan \delta = 0, h = 0.5 \mu\text{m}, w = 100 \text{ nm}, T = 300 \text{ K}, \tau = 0.5 \text{ ps}, \mu_c = 0, \sigma_1^{(s)} = \infty,$  and  $\sigma_2$  is calculated according (14).

Because of the approximate nature of our modeling approach, it has some other limitations. For instance, the trigonometrical functions are represented by only first terms in their expansions considering the smallness of their arguments  $|k_y h| \ll 1$ . Accuracy can be increased considering more terms in analytical formulas if such solutions are available, or the equations (9) and (12) should be used.

The formula (15) is obtained considering the quasi-TM mode approximation. At increased frequencies, the six-field-component theory should be used. The skin effect models of the ground conventional conductors should be reconsidered as well using the Drude model of metals, for instance. Dielectric parameters would be better taken from the measurements at terahertz frequencies. For graphene applications, a conductivity

theory of graphene placed on the surface of dielectrics is highly required. Otherwise, the conductivity parameters should be obtained from the measurements and populated for specified manufacturing technology.

#### IV. CONCLUSION

The approximate analytical formulas for complex propagation constant of graphene thin-substrate micro- and nanostrip transmission lines have been obtained, analyzed, and simulated. The first one is given for the tensor-conductivity graphene strips and ideal ground, and the second one is for “scalar” strip and imperfect ground layer. It has been shown that at the frequencies, where the strip conductivity is anisotropic, even the thin substrate microstrips are influenced by this anisotropy, and it needs to be modeled using the hybrid representation of EM field. Scalar conductivity micro- and nanostrip lossy lines, for which the full-wave and measurement results are available in the literature, have been modeled using the obtained analytical formulas, and good correspondence has been found in comparisons up 1 THz for wide-strip lines. It has been proposed to obtain the engineering formulas with empirically found correction factors for the narrow-strip graphene lines using the full-wave and measurement results. The obtained results can be used in practical calculations of graphene and lossy thin-film micro- and nanostrip lines, and as a means for the initial approximation of complex roots of eigenequations in full-wave computations.

#### V. APPENDIX A

To calculate the graphene microstrip line with above-given formulas, the ideal microstrip line parameters are needed. Ones of them are given in [33], and they are verified up to 1 THz comparing the numerical full-wave results from [29].

Considering that  $k_z = \beta$ , then, for an ideal microstrip

$$\sqrt{\epsilon_{\text{eff}}(f)} = \frac{\beta}{k_0} = \frac{\sqrt{\epsilon_r} - \sqrt{\epsilon_{\text{eff}}}}{1 + 4F^{-1.5}} + \sqrt{\epsilon_{\text{eff}}} \quad (18)$$

where

$F = \frac{4hc\sqrt{\epsilon_r - 1}}{f} \left[ 0.5 + \left\{ 1 + 2 \cdot \lg \left( 1 + \frac{w}{h} \right) \right\}^2 \right]$ , and  $\epsilon_{\text{eff}}$  is the quasi-static effective permittivity of the microstrip line. This quasi-static permittivity is calculated according to the well-known engineering formulas [31].

$$\epsilon_{\text{eff}} = \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{2} \left( 1 + \frac{10}{u} \right)^{-ab} \quad (19)$$

where

$$u = w/h, a = 1 + \frac{1}{49} \log \frac{u^4 + (u/52)^2}{u^4 + 0.432} + \frac{1}{18.7} \log \left[ 1 + \left( \frac{1}{18.1} \right)^3 \right],$$

$$b = 0.564 \left( \frac{\epsilon_r - 0.9}{\epsilon_r + 3} \right)^{0.053}.$$

The characteristic impedance calculations require the frequency-dependent effective width  $w_{\text{eff}}(f)$  [25],[31]

$$w_{\text{eff}}(f) = w + (w_{\text{eff}} - w) \left[ 1 + \left( \frac{f}{f_c} \right)^2 \right]^{-1} \quad \text{where} \quad (20)$$

$$w_{\text{eff}} = \frac{120\pi h}{\sqrt{\epsilon_{\text{eff}} Z_c}}, f_c = c / (2w_{\text{eff}} \sqrt{\epsilon_{\text{eff}}}), Z_c = \frac{60}{\sqrt{\epsilon_{\text{eff}}}} \log \left[ \frac{p}{u} + \sqrt{1 + \left( \frac{2}{u} \right)^2} \right],$$

$$p = 6 + (2\pi - 6) \exp \left[ - \left( \frac{30.666}{u} \right)^{0.7528} \right].$$

In (20), the thickness of the one-atom graphene strip layer is ignored.

## VI. APPENDIX B

Approximate analytical formulas for calculation of complex propagation constant  $k_z$  and characteristic impedance  $Z_c$  of the main mode in thin-film microstrip lines are proposed and verified with measurements and full-wave simulations in [24] and [25]. For the convenience of Readers, it is shown below.

$$k_z^2 \approx k_0^2 \epsilon_{\text{eff}}(f) - (Z_s^{(1)} + K \cdot Z_s^{(2)}) \frac{j\omega \epsilon_0 \epsilon_{\text{eff}}(f)}{h} + Z_s^{(1)} (K \cdot Z_s^{(2)}) (j\omega \epsilon_0 \epsilon_{\text{eff}}(f))^2 \quad (21)$$

where  $Z_s^{(1,2)}$  is the surface impedance of conductors calculated according (13). The correction coefficient  $K$  is defined for narrow microstrip lines:

$$K = \begin{cases} 1, & w/h > 3...4 \\ 0.72, & w/h < 3...4 \end{cases} \quad (22)$$

The frequency dependent effective permittivity  $\epsilon_{\text{eff}}(f)$  is with formulas from Appendix A. The dielectric loss  $\alpha_d$  is calculated using formulas of M.V. Schneider [32]:

$$\alpha_d = 27.3 \frac{\epsilon_r}{\epsilon_r + 1} \frac{\epsilon_{\text{eff}}(f) - 1}{\sqrt{\epsilon_{\text{eff}}(f)}} \frac{\tan \delta}{\lambda_0 [\text{mm}]}, \quad [\text{dB/mm}] \quad (23)$$

where  $\lambda_0$  is the wavelength in vacuum. The conductor loss  $\alpha_c$  is derived as

$$\alpha_c = -10 \lg \left( \exp \left( -2 \cdot \text{Im}(k_z \cdot (l = 1 \text{ mm})) \right) \right), \quad [\text{dB/mm}]. \quad (24)$$

The total loss  $\alpha_t$  is a sum of these partial losses.

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