

**Progress week 13 and 14**

Cabinet mounted and electrical installation almost done.

Pipes cutted and new brackets are made.

Surface: google maps working and can get coordinates from waypoints.

ROV: Ready and fully working, raspberry pi replaced with a new one. With good result.

**Future progress week 15 and 16**

Program autopilot and get everything on the platform working (Equipment).

Surface: Communication and backend programming.

Map pressure sensors and mount sensors on dockinghead.

Mount winch stepper motor.