

```
1
2
3 from DataHandlerNew import datahandler
4 from UDPvideoStream import videoStream
5 import threading
6
7 #the main class of the ROV. Starts the datahandler and the
  viedeostreamThread
8
9 def main():
10     # Use the Ip adress of the machine running the GUI
    here
11     guiIpaddress= '192.168.0.103'
12     print("Starting")
13     #creates a thread of the UDP videostream
14     #t = threading.Thread(target=videoStream, name="
    thread1", args=(guiIpaddress, 12342))
15     #t.start()
16     #starts the datahandler
17     comm = datahandler(readGUIPort=9876,sendGUIDataPort=
    8765,iAdress=(guiIpaddress))
18
19 if __name__ == '__main__':
20     main()
21
```

```
1 import queue
2 import serial
3 from threading import Thread
4 import time
5
6 #Reads serialcom from the Arduino on the port "serialPort"
7 class SerialRead ():
8     def __init__(self,serialPort,semaPhore):
9
10         self.q = queue.LifoQueue()
11         self.semaphore = semaPhore
12         self.serialPort = serialPort
13         self.dataArduino = bytearray(23)
14
15     def start(self):
16
17         t = Thread(target=self.run,name="thread3", args=())
18         t.daemon = True
19         t.start()
20
21
22     #runns when called thread.start. reads data from arduino
    and setts the input to the arranged value
23
24     def run(self):
25         try :
26             while (True):
27                 self.semaphore.acquire()
28
29                 data = self.serialPort.read(23)
30                 self.semaphore.release()
31                 if data.__len__(>0) :
32
33
34                     arrangedData = self.checkDataArrangement
    (data)
35
36                     self.q.put(arrangedData)
37
38                     time.sleep(0.5)
39
40
41         except serial.SerialException as e :
42             print("SerialPortException i SerialRead")
43
```

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44
45     def getSerialData(self):
46
47         # Return the latest serialData
48         if not self.q.empty():
49             newCommand = self.q.get()
50
51         # while not self.q.empty():
52             # trashBin = self.q.get()
53
54         return newCommand
55     else:
56         #print("empty Queue in seiralRead")
57         nodata=bytearray(23)
58         return nodata
59
60     def queReady(self):
61         if not self.q.empty():
62             return True
63         else:
64             return False
65
66
67
68
69     #checs the position of dthe data read from arduino and
    sets it on the right place
70     #@param data
71     #@return arrangedData
72
73     def checkDataArrangement(self, data):
74         realData = bytearray(23)
75         for x in range(0,22):
76
77
78             #print(x)
79             #print(str(data[x])+"Xval= "+ str(x))
80             if data[x] == (128):
81                 if x == 22:
82                     realData[0] = data[x]
83                     realData[1] = data[x - 22]
84                     realData[2] = data[x - 21]
85                     realData[3] = data[x - 20]
86                     realData[4] = data[x - 19]
87                     realData[5] = data[x - 18]

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88         realData[6] = data[x - 17]
89         realData[7] = data[x - 16]
90         realData[8] = data[x - 15]
91         realData[9] = data[x - 14]
92         realData[10] = data[x - 13]
93         realData[11] = data[x - 12]
94         realData[12] = data[x - 11]
95         realData[13] = data[x - 10]
96         realData[14] = data[x - 9]
97         realData[15] = data[x - 8]
98         realData[16] = data[x - 7]
99         realData[17] = data[x - 6]
100        realData[18] = data[x - 5]
101        realData[19] = data[x - 4]
102        realData[20] = data[x - 3]
103        realData[21] = data[x - 2]
104        realData[22] = data[x - 1]
105
106        elif (x == 21):
107            realData[0] = data[x]
108            realData[1] = data[x + 1]
109            realData[2] = data[x - 21]
110            realData[3] = data[x - 20]
111            realData[4] = data[x - 19]
112            realData[5] = data[x - 18]
113            realData[6] = data[x - 17]
114            realData[7] = data[x - 16]
115            realData[8] = data[x - 15]
116            realData[9] = data[x - 14]
117            realData[10] = data[x - 13]
118            realData[11] = data[x - 12]
119            realData[12] = data[x - 11]
120            realData[13] = data[x - 10]
121            realData[14] = data[x - 9]
122            realData[15] = data[x - 8]
123            realData[16] = data[x - 7]
124            realData[17] = data[x - 6]
125            realData[18] = data[x - 5]
126            realData[19] = data[x - 4]
127            realData[20] = data[x - 3]
128            realData[21] = data[x - 2]
129            realData[22] = data[x - 1]
130
131        elif (x == 20):
132            realData[0] = data[x]
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133         realData[1] = data[x +1]
134         realData[2] = data[x +2]
135         realData[3] = data[x - 20]
136         realData[4] = data[x - 19]
137         realData[5] = data[x - 18]
138         realData[6] = data[x - 17]
139         realData[7] = data[x - 16]
140         realData[8] = data[x - 15]
141         realData[9] = data[x - 14]
142         realData[10] = data[x - 13]
143         realData[11] = data[x - 12]
144         realData[12] = data[x - 11]
145         realData[13] = data[x - 10]
146         realData[14] = data[x - 9]
147         realData[15] = data[x - 8]
148         realData[16] = data[x - 7]
149         realData[17] = data[x - 6]
150         realData[18] = data[x - 5]
151         realData[19] = data[x - 4]
152         realData[20] = data[x - 3]
153         realData[21] = data[x - 2]
154         realData[22] = data[x - 1]
155
156     elif (x == 19):
157         realData[0] = data[x]
158         realData[1] = data[x +1]
159         realData[2] = data[x +2]
160         realData[3] = data[x +3]
161         realData[4] = data[x - 19]
162         realData[5] = data[x - 18]
163         realData[6] = data[x - 17]
164         realData[7] = data[x - 16]
165         realData[8] = data[x - 15]
166         realData[9] = data[x - 14]
167         realData[10] = data[x - 13]
168         realData[11] = data[x - 12]
169         realData[12] = data[x - 11]
170         realData[13] = data[x - 10]
171         realData[14] = data[x - 9]
172         realData[15] = data[x - 8]
173         realData[16] = data[x - 7]
174         realData[17] = data[x - 6]
175         realData[18] = data[x - 5]
176         realData[19] = data[x - 4]
177         realData[20] = data[x - 3]
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```
178         realData[21] = data[x - 2]
179         realData[22] = data[x - 1]
180
181     elif (x == 18):
182         realData[0] = data[x]
183         realData[1] = data[x + 1]
184         realData[2] = data[x + 2]
185         realData[3] = data[x + 3]
186         realData[4] = data[x + 4]
187         realData[5] = data[x - 18]
188         realData[6] = data[x - 17]
189         realData[7] = data[x - 16]
190         realData[8] = data[x - 15]
191         realData[9] = data[x - 14]
192         realData[10] = data[x - 13]
193         realData[11] = data[x - 12]
194         realData[12] = data[x - 11]
195         realData[13] = data[x - 10]
196         realData[14] = data[x - 9]
197         realData[15] = data[x - 8]
198         realData[16] = data[x - 7]
199         realData[17] = data[x - 6]
200         realData[18] = data[x - 5]
201         realData[19] = data[x - 4]
202         realData[20] = data[x - 3]
203         realData[21] = data[x - 2]
204         realData[22] = data[x - 1]
205
206     elif (x == 17):
207         realData[0] = data[x]
208         realData[1] = data[x + 1]
209         realData[2] = data[x + 2]
210         realData[3] = data[x + 3]
211         realData[4] = data[x + 4]
212         realData[5] = data[x + 5]
213         realData[6] = data[x - 17]
214         realData[7] = data[x - 16]
215         realData[8] = data[x - 15]
216         realData[9] = data[x - 14]
217         realData[10] = data[x - 13]
218         realData[11] = data[x - 12]
219         realData[12] = data[x - 11]
220         realData[13] = data[x - 10]
221         realData[14] = data[x - 9]
222         realData[15] = data[x - 8]
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```
223         realData[16] = data[x - 7]
224         realData[17] = data[x - 6]
225         realData[18] = data[x - 5]
226         realData[19] = data[x - 4]
227         realData[20] = data[x - 3]
228         realData[21] = data[x - 2]
229         realData[22] = data[x - 1]
230
231     elif (x == 16):
232         realData[0] = data[x]
233         realData[1] = data[x + 1]
234         realData[2] = data[x + 2]
235         realData[3] = data[x + 3]
236         realData[4] = data[x + 4]
237         realData[5] = data[x + 5]
238         realData[6] = data[x + 6]
239         realData[7] = data[x - 16]
240         realData[8] = data[x - 15]
241         realData[9] = data[x - 14]
242         realData[10] = data[x - 13]
243         realData[11] = data[x - 12]
244         realData[12] = data[x - 11]
245         realData[13] = data[x - 10]
246         realData[14] = data[x - 9]
247         realData[15] = data[x - 8]
248         realData[16] = data[x - 7]
249         realData[17] = data[x - 6]
250         realData[18] = data[x - 5]
251         realData[19] = data[x - 4]
252         realData[20] = data[x - 3]
253         realData[21] = data[x - 2]
254         realData[22] = data[x - 1]
255
256     elif (x == 15):
257         realData[0] = data[x]
258         realData[1] = data[x + 1]
259         realData[2] = data[x + 2]
260         realData[3] = data[x + 3]
261         realData[4] = data[x + 4]
262         realData[5] = data[x + 5]
263         realData[6] = data[x + 6]
264         realData[7] = data[x + 7]
265         realData[8] = data[x - 15]
266         realData[9] = data[x - 14]
267         realData[10] = data[x - 13]
```

```
268         realData[11] = data[x - 12]
269         realData[12] = data[x - 11]
270         realData[13] = data[x - 10]
271         realData[14] = data[x - 9]
272         realData[15] = data[x - 8]
273         realData[16] = data[x - 7]
274         realData[17] = data[x - 6]
275         realData[18] = data[x - 5]
276         realData[19] = data[x - 4]
277         realData[20] = data[x - 3]
278         realData[21] = data[x - 2]
279         realData[22] = data[x - 1]
280
281     elif (x == 14):
282         realData[0] = data[x]
283         realData[1] = data[x + 1]
284         realData[2] = data[x + 2]
285         realData[3] = data[x + 3]
286         realData[4] = data[x + 4]
287         realData[5] = data[x + 5]
288         realData[6] = data[x + 6]
289         realData[7] = data[x + 7]
290         realData[8] = data[x + 8]
291         realData[9] = data[x - 14]
292         realData[10] = data[x - 13]
293         realData[11] = data[x - 12]
294         realData[12] = data[x - 11]
295         realData[13] = data[x - 10]
296         realData[14] = data[x - 9]
297         realData[15] = data[x - 8]
298         realData[16] = data[x - 7]
299         realData[17] = data[x - 6]
300         realData[18] = data[x - 5]
301         realData[19] = data[x - 4]
302         realData[20] = data[x - 3]
303         realData[21] = data[x - 2]
304         realData[22] = data[x - 1]
305
306     elif (x == 13):
307         realData[0] = data[x]
308         realData[1] = data[x + 1]
309         realData[2] = data[x + 2]
310         realData[3] = data[x + 3]
311         realData[4] = data[x + 4]
312         realData[5] = data[x + 5]
```



```
313         realData[6] = data[x + 6]
314         realData[7] = data[x + 7]
315         realData[8] = data[x + 8]
316         realData[9] = data[x + 9]
317         realData[10] = data[x - 13]
318         realData[11] = data[x - 12]
319         realData[12] = data[x - 11]
320         realData[13] = data[x - 10]
321         realData[14] = data[x - 9]
322         realData[15] = data[x - 8]
323         realData[16] = data[x - 7]
324         realData[17] = data[x - 6]
325         realData[18] = data[x - 5]
326         realData[19] = data[x - 4]
327         realData[20] = data[x - 3]
328         realData[21] = data[x - 2]
329         realData[22] = data[x - 1]
330
331     elif (x == 12):
332         realData[0] = data[x]
333         realData[1] = data[x + 1]
334         realData[2] = data[x + 2]
335         realData[3] = data[x + 3]
336         realData[4] = data[x + 4]
337         realData[5] = data[x + 5]
338         realData[6] = data[x + 6]
339         realData[7] = data[x + 7]
340         realData[8] = data[x + 8]
341         realData[9] = data[x + 9]
342         realData[10] = data[x + 10]
343         realData[11] = data[x - 12]
344         realData[12] = data[x - 11]
345         realData[13] = data[x - 10]
346         realData[14] = data[x - 9]
347         realData[15] = data[x - 8]
348         realData[16] = data[x - 7]
349         realData[17] = data[x - 6]
350         realData[18] = data[x - 5]
351         realData[19] = data[x - 4]
352         realData[20] = data[x - 3]
353         realData[21] = data[x - 2]
354         realData[22] = data[x - 1]
355
356     elif (x == 11):
357         realData[0] = data[x]
```

```
358         realData[1] = data[x +1]
359         realData[2] = data[x +2]
360         realData[3] = data[x +3]
361         realData[4] = data[x +4]
362         realData[5] = data[x +5]
363         realData[6] = data[x + 6]
364         realData[7] = data[x +7]
365         realData[8] = data[x +8]
366         realData[9] = data[x +9]
367         realData[10] = data[x +10]
368         realData[11] = data[x + 11]
369         realData[12] = data[x - 11]
370         realData[13] = data[x - 10]
371         realData[14] = data[x - 9]
372         realData[15] = data[x - 8]
373         realData[16] = data[x - 7]
374         realData[17] = data[x - 6]
375         realData[18] = data[x - 5]
376         realData[19] = data[x - 4]
377         realData[20] = data[x - 3]
378         realData[21] = data[x - 2]
379         realData[22] = data[x - 1]
380
381     elif (x == 10):
382         realData[0] = data[x]
383         realData[1] = data[x +1]
384         realData[2] = data[x +2]
385         realData[3] = data[x +3]
386         realData[4] = data[x +4]
387         realData[5] = data[x +5]
388         realData[6] = data[x + 6]
389         realData[7] = data[x +7]
390         realData[8] = data[x +8]
391         realData[9] = data[x +9]
392         realData[10] = data[x +10]
393         realData[11] = data[x + 11]
394         realData[12] = data[x +12]
395         realData[13] = data[x - 10]
396         realData[14] = data[x - 9]
397         realData[15] = data[x - 8]
398         realData[16] = data[x - 7]
399         realData[17] = data[x - 6]
400         realData[18] = data[x - 5]
401         realData[19] = data[x - 4]
402         realData[20] = data[x - 3]
```

```
403         realData[21] = data[x - 2]
404         realData[22] = data[x - 1]
405     elif (x == 9):
406         realData[0] = data[x]
407         realData[1] = data[x +1]
408         realData[2] = data[x +2]
409         realData[3] = data[x +3]
410         realData[4] = data[x +4]
411         realData[5] = data[x +5]
412         realData[6] = data[x + 6]
413         realData[7] = data[x +7]
414         realData[8] = data[x +8]
415         realData[9] = data[x +9]
416         realData[10] = data[x +10]
417         realData[11] = data[x + 11]
418         realData[12] = data[x +12]
419         realData[13] = data[x +13]
420         realData[14] = data[x - 9]
421         realData[15] = data[x - 8]
422         realData[16] = data[x - 7]
423         realData[17] = data[x - 6]
424         realData[18] = data[x - 5]
425         realData[19] = data[x - 4]
426         realData[20] = data[x - 3]
427         realData[21] = data[x - 2]
428         realData[22] = data[x - 1]
429     elif (x == 8):
430         realData[0] = data[x]
431         realData[1] = data[x +1]
432         realData[2] = data[x +2]
433         realData[3] = data[x +3]
434         realData[4] = data[x +4]
435         realData[5] = data[x +5]
436         realData[6] = data[x + 6]
437         realData[7] = data[x +7]
438         realData[8] = data[x +8]
439         realData[9] = data[x +9]
440         realData[10] = data[x +10]
441         realData[11] = data[x + 11]
442         realData[12] = data[x +12]
443         realData[13] = data[x +13]
444         realData[14] = data[x +14]
445         realData[15] = data[x - 8]
446         realData[16] = data[x - 7]
447         realData[17] = data[x - 6]
```

```
448         realData[18] = data[x - 5]
449         realData[19] = data[x - 4]
450         realData[20] = data[x - 3]
451         realData[21] = data[x - 2]
452         realData[22] = data[x - 1]
453     elif (x == 7):
454         realData[0] = data[x]
455         realData[1] = data[x + 1]
456         realData[2] = data[x + 2]
457         realData[3] = data[x + 3]
458         realData[4] = data[x + 4]
459         realData[5] = data[x + 5]
460         realData[6] = data[x + 6]
461         realData[7] = data[x + 7]
462         realData[8] = data[x + 8]
463         realData[9] = data[x + 9]
464         realData[10] = data[x + 10]
465         realData[11] = data[x + 11]
466         realData[12] = data[x + 12]
467         realData[13] = data[x + 13]
468         realData[14] = data[x + 14]
469         realData[15] = data[x + 15]
470         realData[16] = data[x - 7]
471         realData[17] = data[x - 6]
472         realData[18] = data[x - 5]
473         realData[19] = data[x - 4]
474         realData[20] = data[x - 3]
475         realData[21] = data[x - 2]
476         realData[22] = data[x - 1]
477
478     elif (x == 6):
479         realData[0] = data[x]
480         realData[1] = data[x + 1]
481         realData[2] = data[x + 2]
482         realData[3] = data[x + 3]
483         realData[4] = data[x + 4]
484         realData[5] = data[x + 5]
485         realData[6] = data[x + 6]
486         realData[7] = data[x + 7]
487         realData[8] = data[x + 8]
488         realData[9] = data[x + 9]
489         realData[10] = data[x + 10]
490         realData[11] = data[x + 11]
491         realData[12] = data[x + 12]
492         realData[13] = data[x + 13]
```

```
493         realData[14] = data[x +14]
494         realData[15] = data[x +15]
495         realData[16] = data[x +16]
496         realData[17] = data[x - 6]
497         realData[18] = data[x - 5]
498         realData[19] = data[x - 4]
499         realData[20] = data[x - 3]
500         realData[21] = data[x - 2]
501         realData[22] = data[x - 1]
502
503     elif (x == 5):
504         realData[0] = data[x]
505         realData[1] = data[x +1]
506         realData[2] = data[x +2]
507         realData[3] = data[x +3]
508         realData[4] = data[x +4]
509         realData[5] = data[x +5]
510         realData[6] = data[x + 6]
511         realData[7] = data[x +7]
512         realData[8] = data[x +8]
513         realData[9] = data[x +9]
514         realData[10] = data[x +10]
515         realData[11] = data[x + 11]
516         realData[12] = data[x +12]
517         realData[13] = data[x +13]
518         realData[14] = data[x +14]
519         realData[15] = data[x +15]
520         realData[16] = data[x +16]
521         realData[17] = data[x +17]
522         realData[18] = data[x - 5]
523         realData[19] = data[x - 4]
524         realData[20] = data[x - 3]
525         realData[21] = data[x - 2]
526         realData[22] = data[x - 1]
527
528     elif (x == 4):
529         realData[0] = data[x]
530         realData[1] = data[x +1]
531         realData[2] = data[x +2]
532         realData[3] = data[x +3]
533         realData[4] = data[x +4]
534         realData[5] = data[x +5]
535         realData[6] = data[x + 6]
536         realData[7] = data[x +7]
537         realData[8] = data[x +8]
```

```
538         realData[9] = data[x +9]
539         realData[10] = data[x +10]
540         realData[11] = data[x + 11]
541         realData[12] = data[x +12]
542         realData[13] = data[x +13]
543         realData[14] = data[x +14]
544         realData[15] = data[x +15]
545         realData[16] = data[x +16]
546         realData[17] = data[x +17]
547         realData[18] = data[x +18]
548         realData[19] = data[x - 4]
549         realData[20] = data[x - 3]
550         realData[21] = data[x - 2]
551         realData[22] = data[x - 1]
552
553     elif (x == 3):
554         realData[0] = data[x]
555         realData[1] = data[x +1]
556         realData[2] = data[x +2]
557         realData[3] = data[x +3]
558         realData[4] = data[x +4]
559         realData[5] = data[x +5]
560         realData[6] = data[x + 6]
561         realData[7] = data[x +7]
562         realData[8] = data[x +8]
563         realData[9] = data[x +9]
564         realData[10] = data[x +10]
565         realData[11] = data[x + 11]
566         realData[12] = data[x +12]
567         realData[13] = data[x +13]
568         realData[14] = data[x +14]
569         realData[15] = data[x +15]
570         realData[16] = data[x +16]
571         realData[17] = data[x +17]
572         realData[18] = data[x +18]
573         realData[19] = data[x +19]
574         realData[20] = data[x - 3]
575         realData[21] = data[x - 2]
576         realData[22] = data[x - 1]
577
578     elif (x == 2):
579         realData[0] = data[x]
580         realData[1] = data[x +1]
581         realData[2] = data[x +2]
582         realData[3] = data[x +3]
```

```
583         realData[4] = data[x +4]
584         realData[5] = data[x +5]
585         realData[6] = data[x + 6]
586         realData[7] = data[x +7]
587         realData[8] = data[x +8]
588         realData[9] = data[x +9]
589         realData[10] = data[x +10]
590         realData[11] = data[x + 11]
591         realData[12] = data[x +12]
592         realData[13] = data[x +13]
593         realData[14] = data[x +14]
594         realData[15] = data[x +15]
595         realData[16] = data[x +16]
596         realData[17] = data[x +17]
597         realData[18] = data[x +18]
598         realData[19] = data[x +19]
599         realData[20] = data[x +20]
600         realData[21] = data[x - 2]
601         realData[22] = data[x - 1]
602
603     elif (x == 1):
604         realData[0] = data[x]
605         realData[1] = data[x +1]
606         realData[2] = data[x +2]
607         realData[3] = data[x +3]
608         realData[4] = data[x +4]
609         realData[5] = data[x +5]
610         realData[6] = data[x + 6]
611         realData[7] = data[x +7]
612         realData[8] = data[x +8]
613         realData[9] = data[x +9]
614         realData[10] = data[x +10]
615         realData[11] = data[x + 11]
616         realData[12] = data[x +12]
617         realData[13] = data[x +13]
618         realData[14] = data[x +14]
619         realData[15] = data[x +15]
620         realData[16] = data[x +16]
621         realData[17] = data[x +17]
622         realData[18] = data[x +18]
623         realData[19] = data[x +19]
624         realData[20] = data[x +20]
625         realData[21] = data[x +21]
626         realData[22] = data[x - 1]
627
```

```
628                 else:
629                     realData = data
630
631
632
633         return realData
634
635
636
```



```

1 import serial
2 import queue
3 from threading import Thread
4
5
6
7
8 class SerialSend ():
9     def __init__(self,serialPort,semaPhore):
10
11         #Semaphore to avoid serail send/recieve collision.
12         self.semaphore = semaPhore
13         #Port of the serial(USB port)
14         self.serialPort = serialPort
15         #Data holder for the class
16         self.q = queue.LifoQueue()
17
18
19     #Creates an thread of the run function, and starts it.
20     def start(self):
21         # Start the thread send arduino data
22         t = Thread(target=self.run,name="thread2", args=())
23         t.daemon = True
24         t.start()
25
26     #sends data to the serialport.
27     def run(self):
28         try:
29
30             while (True):
31                 #checks if the queue contains any data
32                 if not self.q.empty():
33                     dataToArduino = self.getNewDataString(
34
35                         for x in range(0,5):
36                             print(dataToArduino[x])
37
38                     #aquires the semaphore so the
39                     serialport can be used.
40                     self.semaphore.acquire()
41
42                     print("SEND Serial " + str(
43                         dataToArduino))

```

```
42             #sends the data to the serialport
43             self.serialPort.write(dataToArduino)
44             #releases the semaphore so the
readerclass can use the port.
45             self.semaphore.release()
46
47         except serial.portNotOpenError:
48             print("SerialPortException i SerialSend")
49
50         # Updates the data to be sent to the SerialPort
51         def updateDataString(self,newData):
52             self.q.put(newData)
53
54         # Returns the lates queue object,and flushes the queue
. If there is none and empty array is returned.
55         def getNewDataString(self):
56
57             if not self.q.empty():
58                 newCommand = self.q.get()
59                 while not self.q.empty():
60                     trashBin = self.q.get()
61
62
63                 return newCommand
64             else:
65                 nodata=bytearray(6)
66                 return nodata
67
68
69
70
71
72
```

```

1 import queue
2 import socket
3 from threading import Thread
4 from struct import *
5
6
7 #Reads data sendt from GUI throug UDP com
8 class UDPreadGUI(Thread):
9
10     def __init__(self,Port):
11         Thread.__init__(self)
12         #UDP read port
13         self.port = Port
14         #byte array of 6 bytes
15         self.data = bytearray(6)
16         #UDP socket
17         self.sock = socket.socket(socket.AF_INET, #
Internet
18                                     socket.SOCK_DGRAM) # UDP
19         #connect to the socket with local adress
20         self.sock.bind(('',self.port))
21         #queue makes it possible to access data from the
thread without data collision.
22         self.q = queue.LifoQueue()
23
24     # Creates an thread of the run function, and starts it
.
25     def start(self):
26
27         t = Thread(target=self.run, args=())
28         t.daemon = True
29         t.start()
30
31
32     #runs this method when thread.start is called
33     #gets the data from GUI
34
35     def run(self):
36         while True:
37             try:
38
39                 #reads 6 bytes of data from socket.
40                 self.data = self.sock.recv(6)
41
42

```

```
43         for x in range(0, 6):
44             print(self.data[x])
45         # print("Read UDP: " + str(data2))
46
47         #puts the data to the queue
48         self.q.put(self.data)
49
50     except socket.error as e :
51         print("uhdfuhdf")
52
53
54
55
56     #retuns data recieved from GUI
57     # @return data
58
59
60     def getDataGUI(self):
61
62         # Return the latest queue data and removes the
63         # rest of the data if there is any left.
64         # #returns an empty array of 0 if the function is
65         # called without data in the queue.
66         if not self.q.empty():
67             newCommand = self.q.get()
68             while not self.q.empty():
69                 trashBin = self.q.get()
70
71             return newCommand
72         else:
73
74             nodata=bytearray(6)
75             return nodata
76
77     #checks if the queue contains new data.
78     def queReady(self):
79         if not self.q.empty():
80             return True
81         else:
82             return False
83
84
```

```
1 import queue
2 import socket
3 import time
4 from threading import Thread
5
6 class UDPSendData(Thread):
7     # class constructor
8     def __init__(self,Port,Adress):
9         Thread.__init__(self)
10        #UDP send port
11        self.port = Port
12        #Adress of the reciever
13        self.address = Adress
14        #data to be sent, array of 23 bytes
15        self.data = bytearray(23)
16        #queue storage variable for new data to be sent.
17        self.q = queue.LifoQueue()
18
19
20
21
22    def start(self):
23        # creates and UDP socket.
24        self.sock = socket.socket(socket.AF_INET, #
Internet
25                                socket.SOCK_DGRAM)
26        #Creates a thread of the run function and Starts
the thread
27        t = Thread(target=self.run, args=())
28        t.daemon = True
29        t.start()
30
31    def run(self):
32
33        while (True):
34            try:
35                #checks if there is any data to be sent
36                if self.queueReady():
37
38                    packet1 = self.getNewDataString()
39
40
41
42                    self.sock.sendto(packet1, (self.
address, self.port))
```

```
43             time.sleep(0.5)
44
45         except Exception as e:
46             print(e)
47
48
49
50     #Updates the data to be sent to the GUI
51     def updateDataString(self,newData):
52         self.q.put(newData)
53
54
55     # Returns the latest queue object. If there is none and
    empty array is returned.
56     def getNewDataString(self):
57
58
59         if not self.q.empty():
60             newCommand = self.q.get()
61             while not self.q.empty():
62                 trashBin = self.q.get()
63
64             return newCommand
65         else:
66             nodata=bytearray(23)
67
68             return nodata
69
70     #checks if the queue contains any data.
71     def queReady(self):
72         if not self.q.empty():
73             return True
74         else:
75             return False
76
77
```

```

1 import socket
2 import serial
3 from SerialRead import SerialRead
4 from SerialSend import SerialSend
5 from UDPsendData import UDPsendData
6 from UDPreadGUI import UDPreadGUI
7 import threading
8 from ThrusterControl import ThrusterControl
9 import time
10
11
12 class datahandler:
13     # class constructor
14     def __init__(self, readGUIPort, sendGUIDataPort, iAdress)
15     :
16         #setting up gui data variables
17         self.senderUDP = UDPsendData(sendGUIDataPort,
18 iAdress)
19         self.readerUDP = UDPreadGUI(readGUIPort)
20         #setting up serial variables
21         self.SerialSemaphore = threading.Semaphore()
22         self.senderSerial = SerialSend(serialPort=serial.
23 Serial('/dev/ttyUSB0', 19200, timeout=5), semaPhore=self.
24 SerialSemaphore)
25         self.readerSerial = SerialRead(serialPort=serial.
26 Serial('/dev/ttyUSB0', 19200, timeout=5), semaPhore=self.
27 SerialSemaphore)
28         self.thrusterControl = ThrusterControl()
29         self.startThreads()
30         #command variables from GUI thruster cmd:(fwd,
31 back etc..)power:0-100 thruster.
32         # Used in the ThrusterControl class
33         self.thrusterCmd = 0
34         self.thrusterPower = 0
35
36         #starting the While loop for logic
37         self.runDatahandler()
38
39
40 # starting the threads when called
41
42 def startThreads(self):
43     try:
44         #thrusterControl.start();

```

```

39         self.readerUDP.start()
40
41         self.senderSerial.start()
42         self.readerSerial.start()
43     except RuntimeError:
44         print("Cant Start Threads in Datahandler
45         StartThread functionn")
46     try: #Starts sending to GUI threadfo
47         self.senderUDP.start()
48     except RuntimeError:
49         print("Cant Start Threads in Datahandler
50         StartThread senderUDP and SerialCom")
51
52
53
54     #Setting the trustervalues
55     #@param command
56     #@param thrusterPower""""
57
58     def runDatahandler(self):
59         time.sleep(2)
60         while True:
61             if self.readerUDP.queueReady():
62                 #get reformat data to send to arduino
63                 self.guiReadData= self.dataToArduino()
64                 #update serial data to arduino
65                 self.senderSerial.updateDataString(self.
66                 guiReadData)
67                 #get last serial read array
68                 if self.readerSerial.queueReady():
69                     self.guiSendData= self.readerSerial.
70                     getSerialData()
71                     #send data to the gui
72                     self.senderUDP.updateDataString(self.
73                     guiSendData)
74
75     #Returns the Bytearray to be sendt to arduino
76     #@return dataToArduino
77
78     def dataToArduino(self):

```



```

79         data = self.readerUDP.getDataGUI()
80         #// ***** Thruster Variables
            ***** //
81         self.thrusterCmd = data[0]
82         self.thrusterPower = data[2]
83         self.thrusterControl.thrusterValues(self.
thrusterCmd, self.thrusterPower)
84
85         #//*****
            //
86         dataToArduino = bytearray(6)
87
88         dataToArduino[0] = 101    #//Flag byte ( 101 )
89         dataToArduino[1] = data[3]    #// Start byte ( 0
to 1 )
90         dataToArduino[2] = self.convertToSignedValues(
value=self.thrusterControl.getThrusterThree()) #//
Thruster 1 ( - 100 to 100 )
91         dataToArduino[3] = self.convertToSignedValues(
value=self.thrusterControl.getThrusterTwo())    #//
Thruster 2 ( - 100 to 100 )
92         dataToArduino[4] = self.convertToSignedValues(
value=self.thrusterControl.getThrusterOne())#// Thruster
3 ( - 100 to 100 )
93         dataToArduino[5] = data[1]
            #// Light control ( 0 - 100 ) vAR DATA[2]
94         return dataToArduino
95
96
97         #the arduino is using signe bytes, range: -128-127,
python is using unsigned range: 0-255
98         #in binary from 0-127 is the same in both arduino and
python.
99         # but over 128, reads as negativ by the arduino 128=-
128
100        #if i want to send -100, i will send 255-100 +1
101        def convertToSignedValues(self,value):
102            if value>=0:
103                return value
104            else:
105                newValue= 255+value+1
106                return newValue
107
108

```

109

110

```
1 import time
2 import socket
3 import cv2
4
5
6
7 def videoStream(ipaddress,port):
8     cam = cv2.VideoCapture(0)
9     #cam.set(cv2.CAP_PROP_FPS,30)
10    UDP_IP = ipaddress
11    UDP_PORT = port
12    sock = socket.socket(socket.AF_INET, socket.SOCK_DGRAM
13    )
14
15
16    # warmup camera
17    time.sleep(0.1)
18    while True:
19        ret_val, img = cam.read(0)
20
21        img = cv2.flip(img, 1)
22        img = cv2.resize(img, (320, 240))
23
24        x = [int(cv2.IMWRITE_JPEG_QUALITY), 80]
25        _, compressed = cv2.imencode(".jpg", img, x)
26        sock.sendto(compressed, (UDP_IP, UDP_PORT))
27
28    rawCapture.truncate(0)
29
30
31
```

```
1 class ThrusterControl(object):
2     # class constructor
3     def __init__(self):
4         self.selfthrusterOne = 0
5         self.thrusterTwo = 0
6         self.thrusterThree = 0
7
8
9
10
11
12
13 # sets the right thrustervalue from the command sendt
    from GUI.
14 # @param command  can be fwd,left,right ++
15 # @param power the persentage of the thrustervalue
16
17
18     def thrusterValues(self, command,power):
19
20         if (command == 2): # // FWD
21             self.thrusterOne = -power
22             self.thrusterTwo = power
23
24         elif (command == 18): # Slide FWD Right
25
26             self.thrusterTwo = power
27             self.thrusterThree = power
28         elif command == 16: # Right
29             calculationVar = power * 58 # ThrusterOne and
    ThrusterTwo need 58% of ThrusterThree's Power.
30             self.thrusterOne = round(calculationVar/(100))
31             self.thrusterTwo = round(calculationVar/(100))
32             self.thrusterThree = power
33
34         elif command == 20: # Slide Back Right
35             self.thrusterOne = power
36             self.thrusterThree = power
37         elif command == 4: # Back
38             self.thrusterOne = power
39             self.thrusterTwo = -power
40         elif command == 12: # Slide Back Left
41
42
43             self.thrusterTwo = -power
```

```
44         self.thrusterThree = -power
45     elif command == 8: #Left
46         calculationVar = power * 58 # ThrusterOne and
    ThrusterTwo need 58% of ThrusterThree's Power.
47         self.thrusterOne = round(-(calculationVar/(100
    )))
48         self.thrusterTwo = round(-(calculationVar/(100
    )))
49         self.thrusterThree = -power
50     elif command == 10: # Slide Fwd Left
51         self.thrusterOne = -power
52         self.thrusterThree = -power
53     elif (command == 32): # Rotate Left
54         self.thrusterOne = -power
55         self.thrusterTwo = -power
56         self.thrusterThree = power
57     elif (command == 64): # Rotate Right
58         self.thrusterOne = power
59         self.thrusterTwo = power
60         self.thrusterThree = -power
61     else:
62         # Do nothing
63         self.thrusterOne = 0
64         self.thrusterTwo = 0
65         self.thrusterThree = 0
66
67
68
69     # return the trusterone value
70     # @return thrusterOne
71
72     def getThrusterOne(self):
73         return self.thrusterOne
74
75
76
77     #return the trusterTwo value
78     #return thrusterTwo
79
80     def getThrusterTwo(self):
81         return self.thrusterTwo
82
83
84
85     #return the trusterTree value
```

```
86         #return thrusterThree
87
88     def getThrusterThree(self):
89         return self.thrusterThree
90
91
92
```

```
1 import time
2 import socket
3 import cv2
4
5
6 cam = cv2.VideoCapture(0)
7 cam.set(cv2.CAP_PROP_FPS,30)
8 UDP_IP = '192.168.0.103'
9 UDP_PORT = 12342
10 sock = socket.socket(socket.AF_INET, socket.SOCK_DGRAM)
11
12
13
14 # warmup camera
15 time.sleep(0.1)
16 while True:
17     ret_val, img = cam.read(0)
18
19     img = cv2.rotate(img,cv2.ROTATE_90_COUNTERCLOCKWISE)
20     img = cv2.resize(img, (320, 240))
21
22     x = [int(cv2.IMWRITE_JPEG_QUALITY), 80]
23     _, compressed = cv2.imencode(".jpg", img, x)
24     sock.sendto(compressed, (UDP_IP, UDP_PORT))
25
26 rawCapture.truncate(0)
27
28
29
30
```