



Master's thesis

Trondheim, 2013

Master's thesis

Torgrim Aalvik Lien

NTNU
Norwegian University of
Science and Technology
Faculty of Information Technology,
Mathematics and Electrical Engineering
Department of Engineering Cybernetics

Torgrim Aalvik Lien

Mobile Robotics in Precision Agriculture

A CAN bus interface implementation of differential drive and exploration of localization, pose estimation and autonomous navigation.

Trondheim, July 2013

