

Master's thesis

Trondheim, 2012

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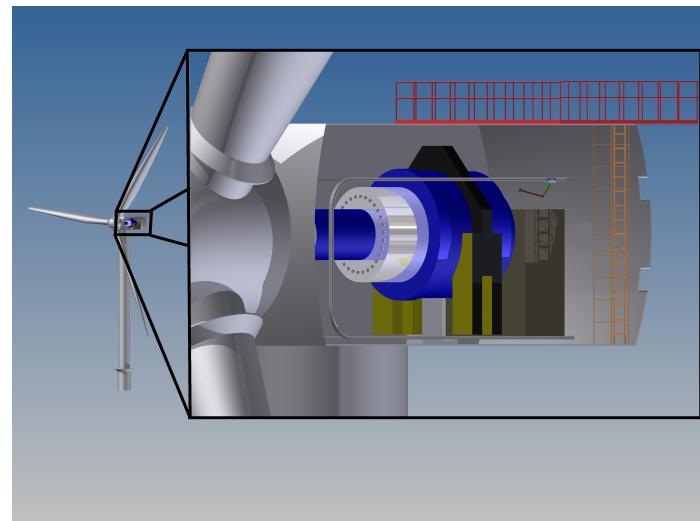
Master's thesis

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Norwegian University of
Science and Technology
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Development of a Predictive
Display Interface to assist control
of a Robot Arm in a Telepresence
System

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