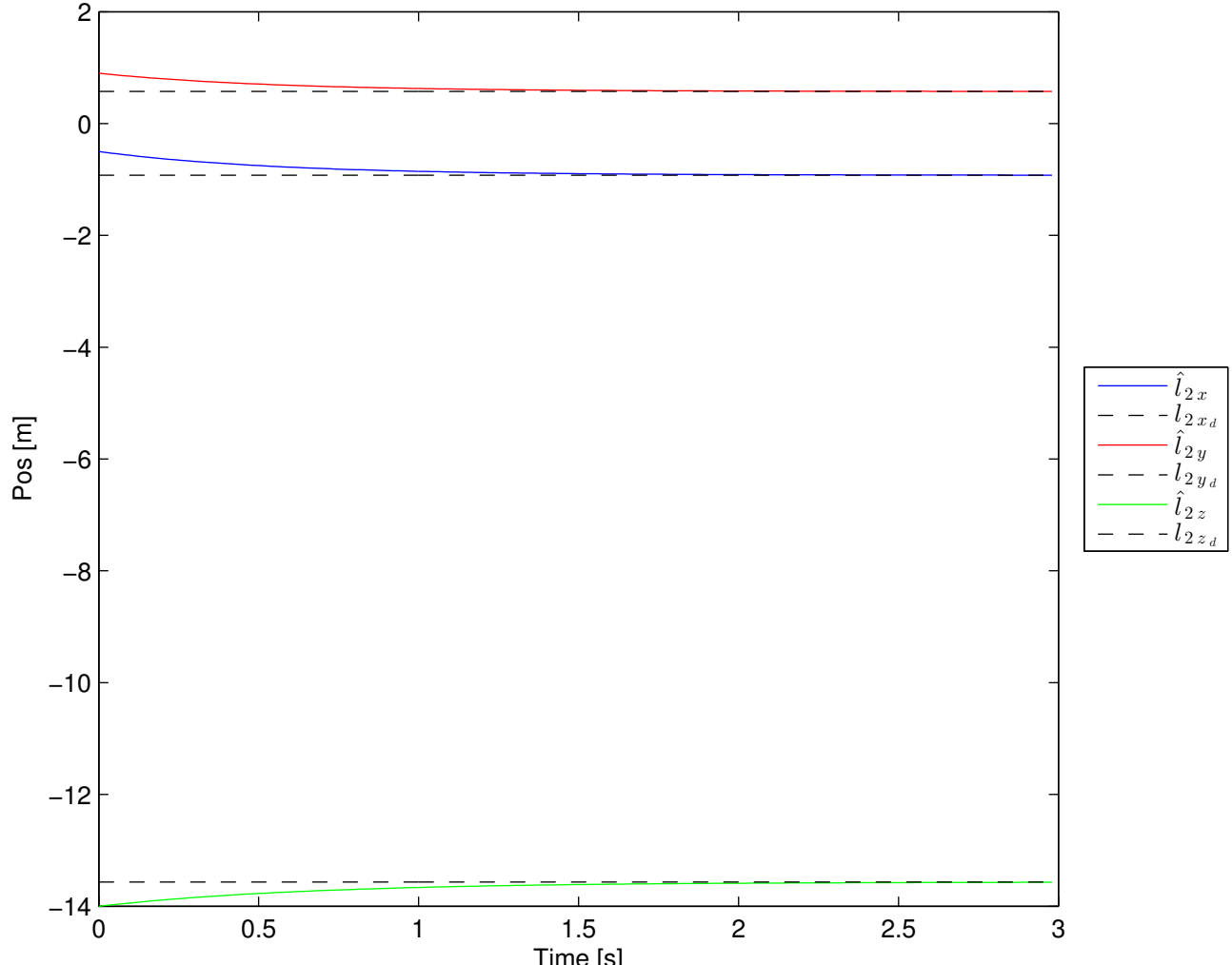
2
0
−2
−4
−6
−8
−10
−12
−14
Pos [m]
0
0.5
1
1.5
2
2.5
3
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
$\hat{l}_{2y}$
l_{2y_d}
$\hat{l}_{2z}$
l_{2z_d}