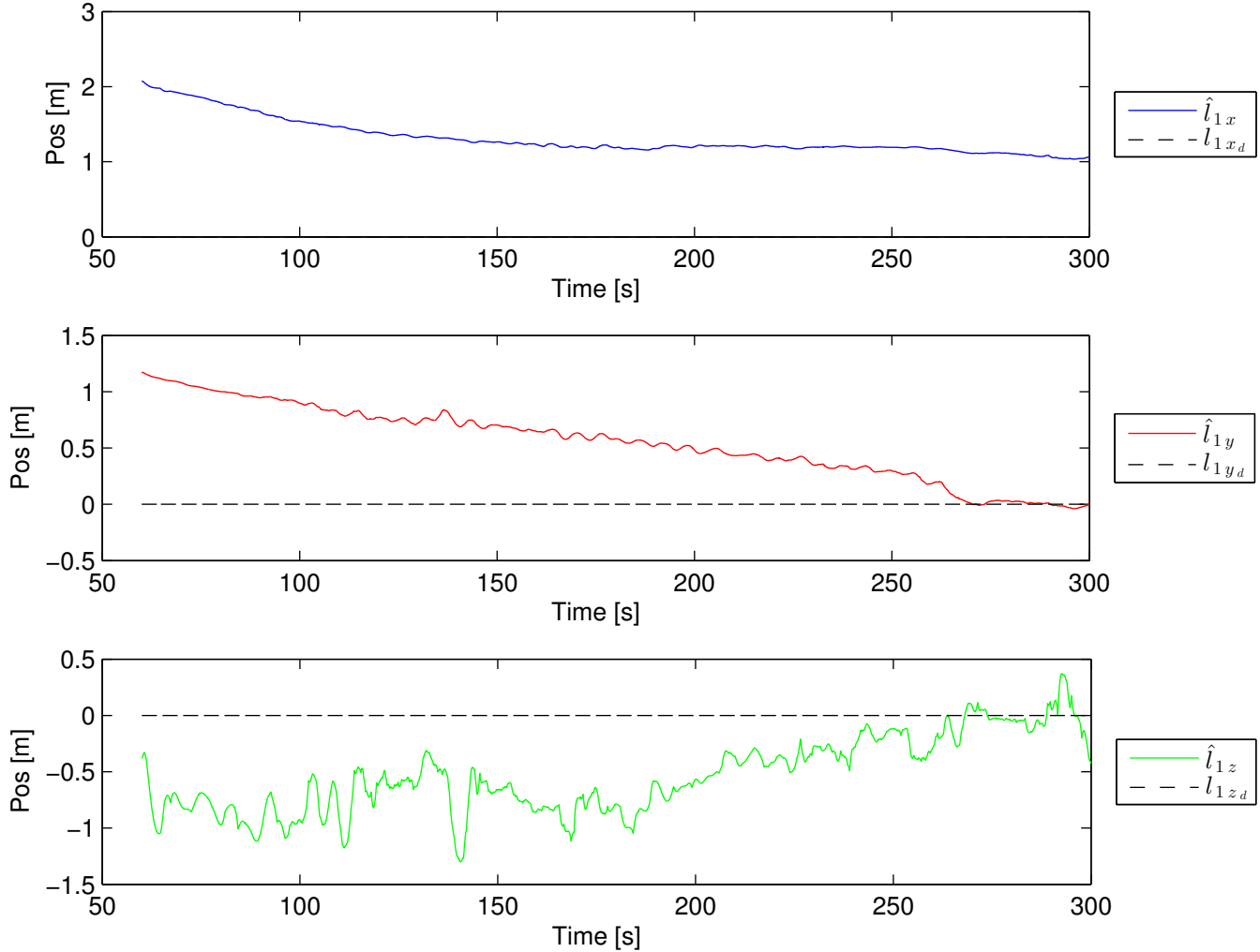
Pos [m]
Time [s]
$\hat{l}_{1x}$
l_{1x_d}
$\hat{l}_{1y}$
l_{1y_d}
$\hat{l}_{1z}$
l_{1z_d}