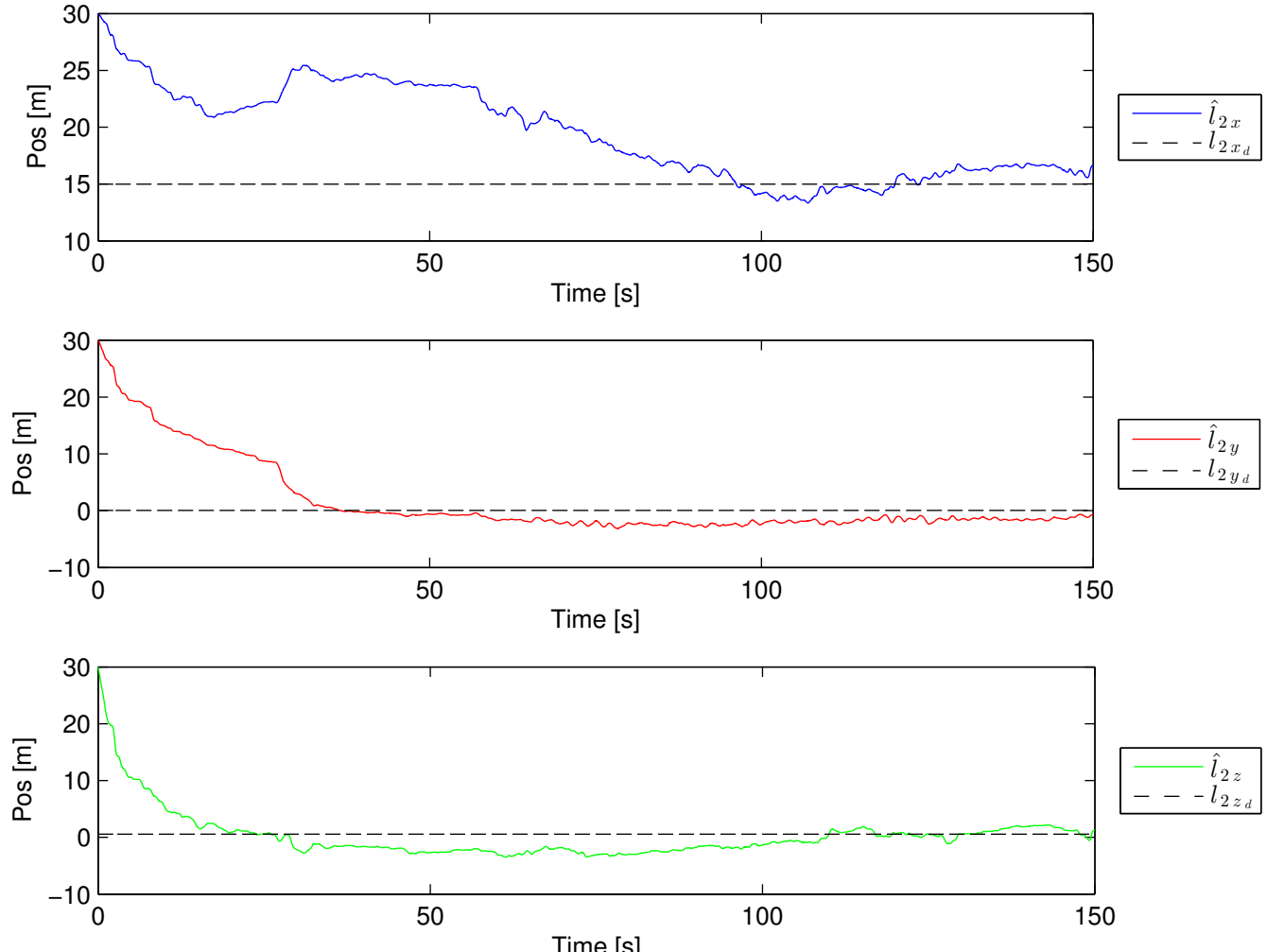
30
25
20
15
10
Pos [m]
0
50
100
150
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
30
20
10
0
−10
Pos [m]
0
50
100
150
Time [s]
$\hat{l}_{2y}$
l_{2y_d}
30
20
10
0
−10
Pos [m]
0
50
100
150
Time [s]
$\hat{l}_{2z}$
l_{2z_d}