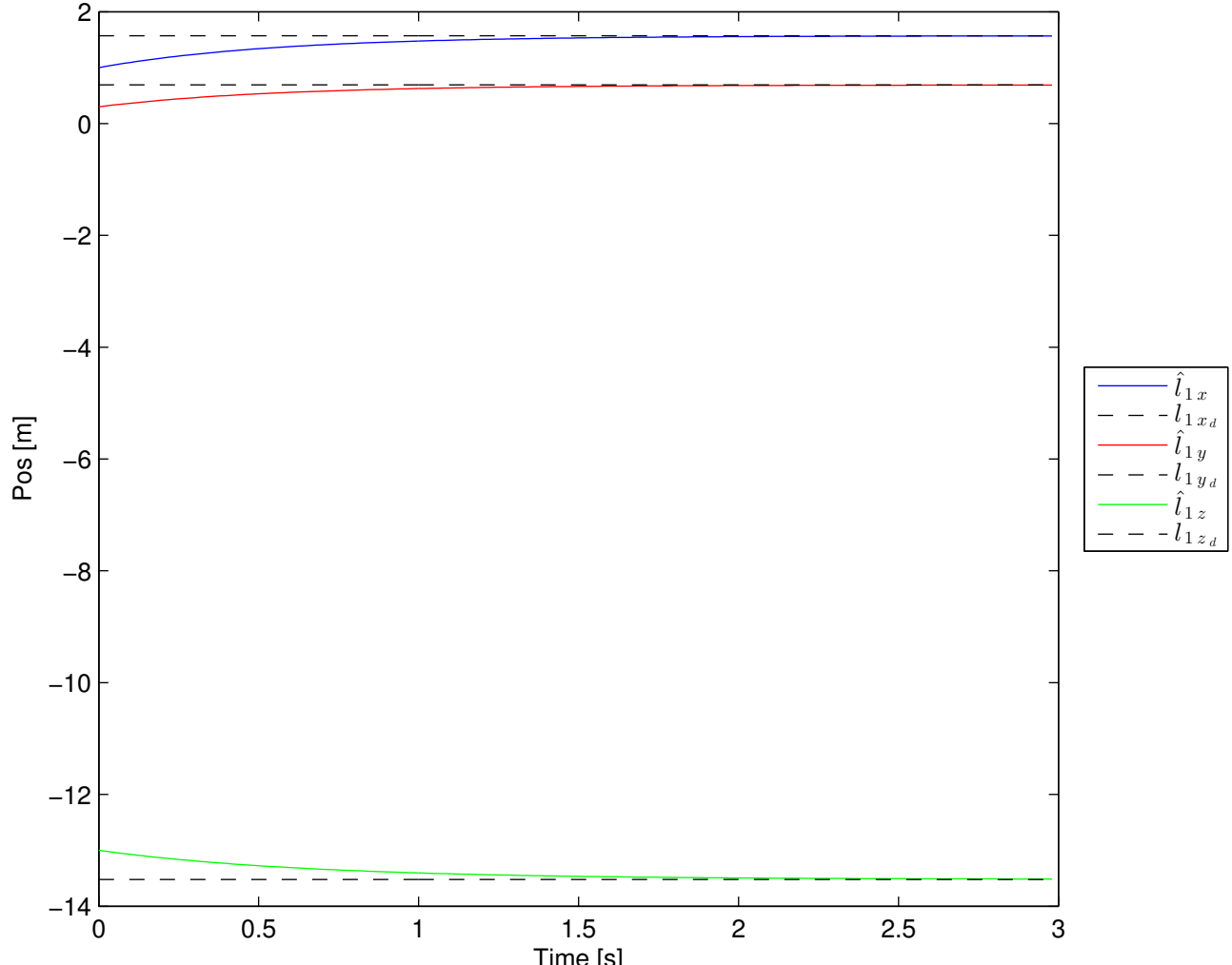
2
0
−2
−4
−6
−8
−10
−12
−14
Pos [m]
0
0.5
1
1.5
2
2.5
3
Time [s]
$\hat{l}_{1x}$
l_{1x_d}
$\hat{l}_{1y}$
l_{1y_d}
$\hat{l}_{1z}$
l_{1z_d}