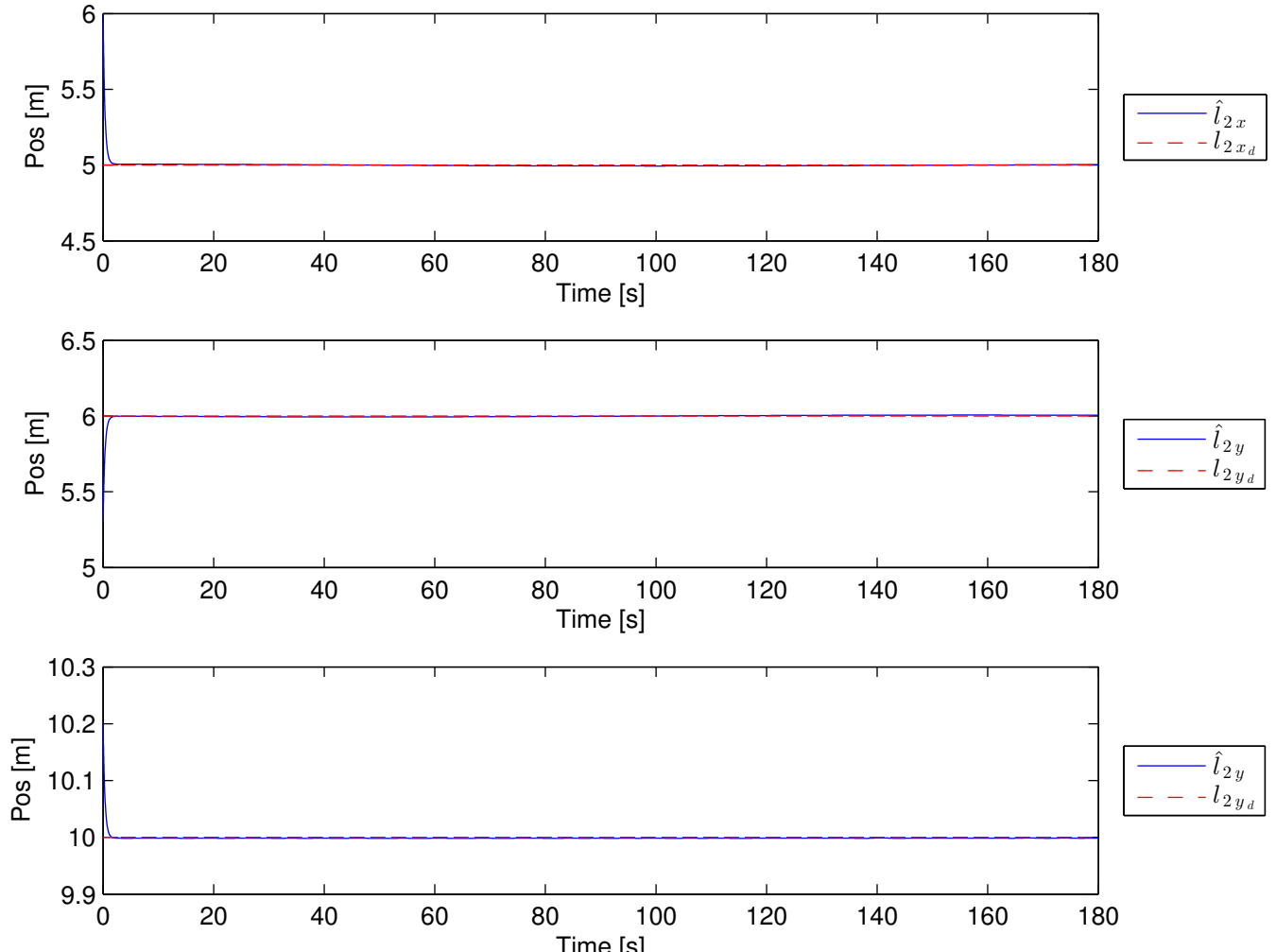
6
5.5
5
4.5
Pos [m]
0
20
40
60
80
100
120
140
160
180
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
6.5
6
5.5
5
Pos [m]
Time [s]
$\hat{l}_{2y}$
l_{2y_d}
10.3
10.2
10.1
10
9.9
Pos [m]
Time [s]
$\hat{l}_{2y}$
l_{2y_d}