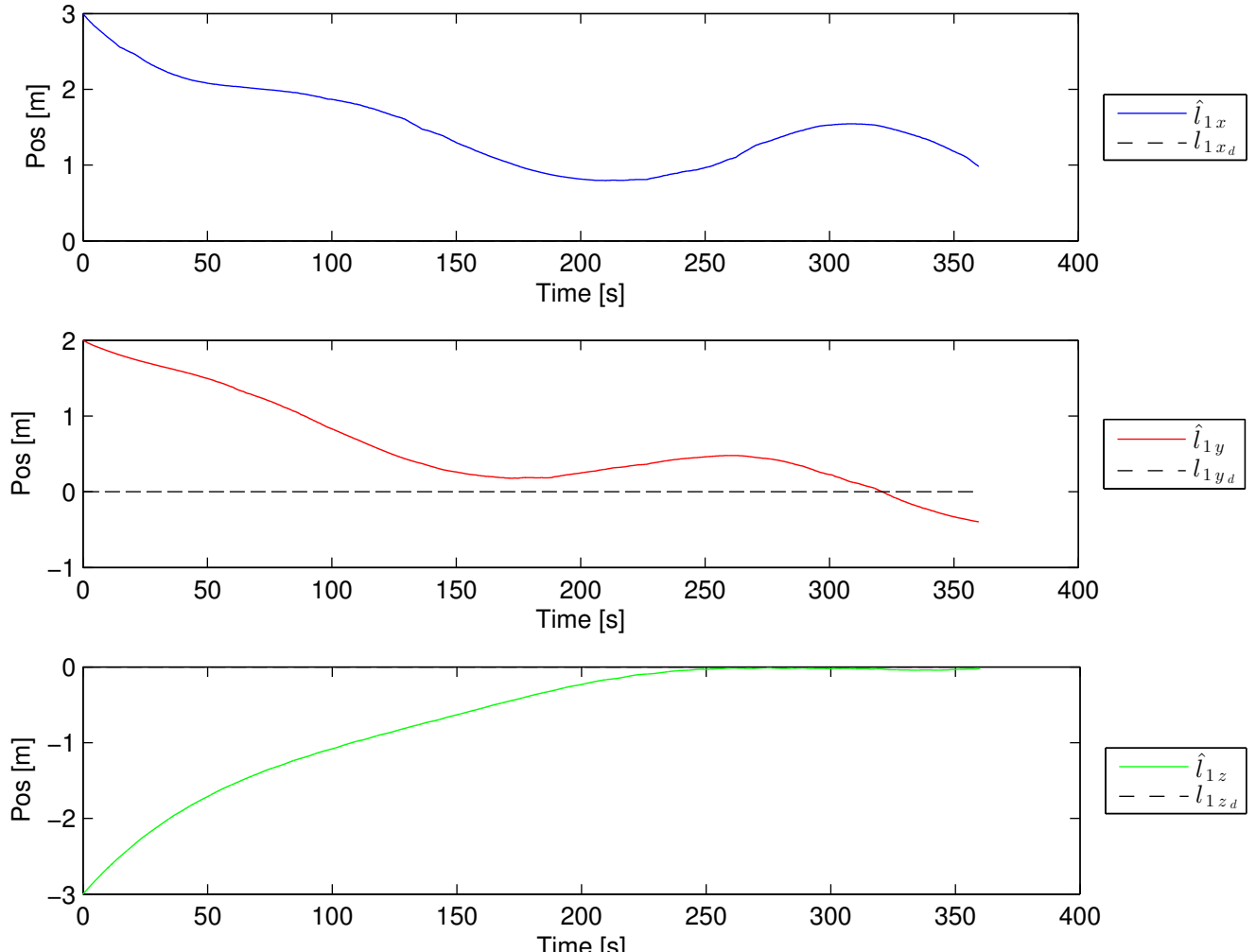
Pos [m]
Time [s]
$\hat{l}_{1x}$
$l_{1x_d}$
$\hat{l}_{1y}$
$l_{1y_d}$
$\hat{l}_{1z}$
$l_{1z_d}$