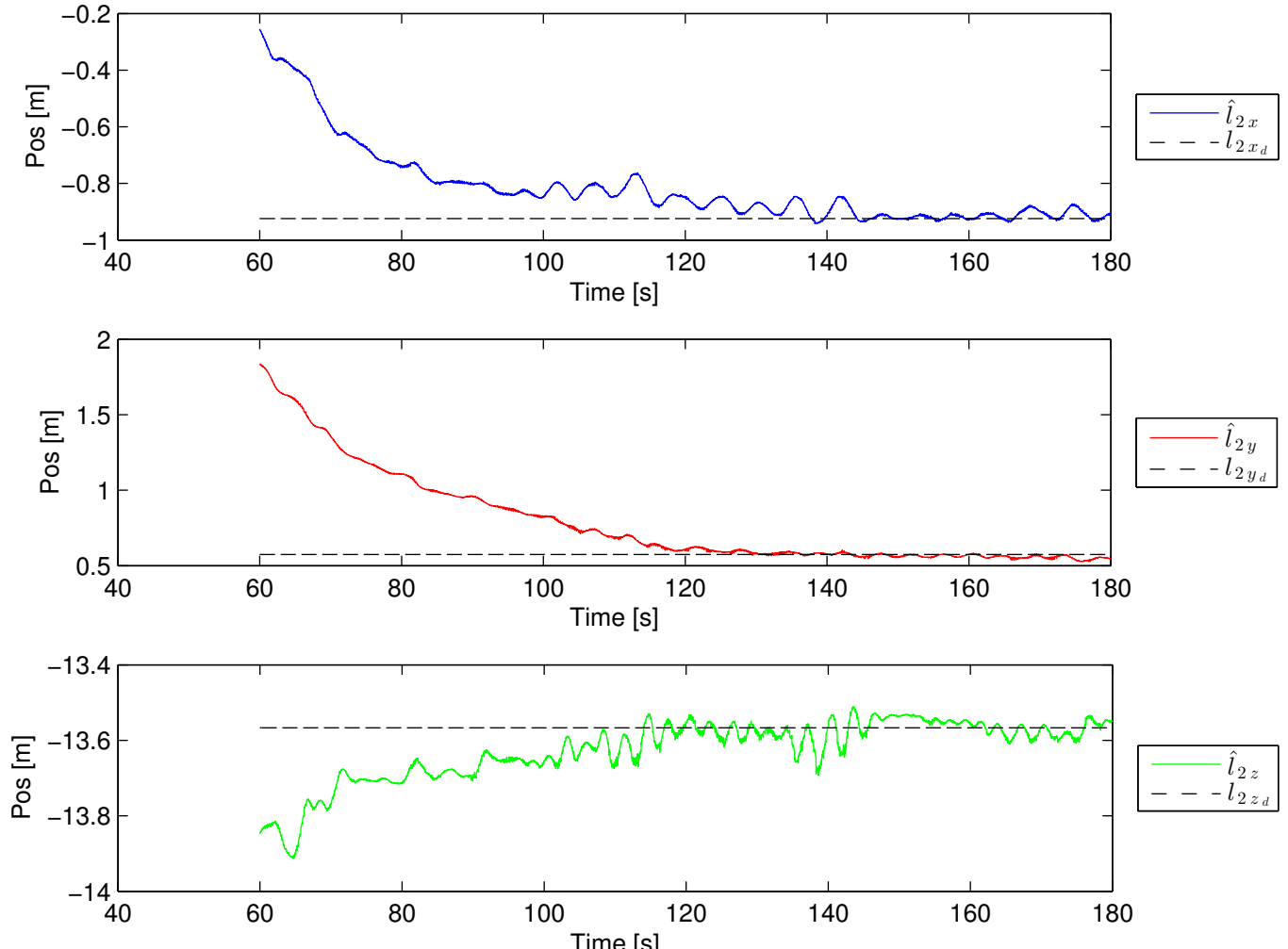
−0.2
−0.4
−0.6
−0.8
−1
Pos [m]
40
60
80
100
120
140
160
180
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
2
1.5
1
0.5
Pos [m]
Time [s]
$\hat{l}_{2y}$
l_{2y_d}
−13.4
−13.6
−13.8
−14
Pos [m]
Time [s]
$\hat{l}_{2z}$
l_{2z_d}