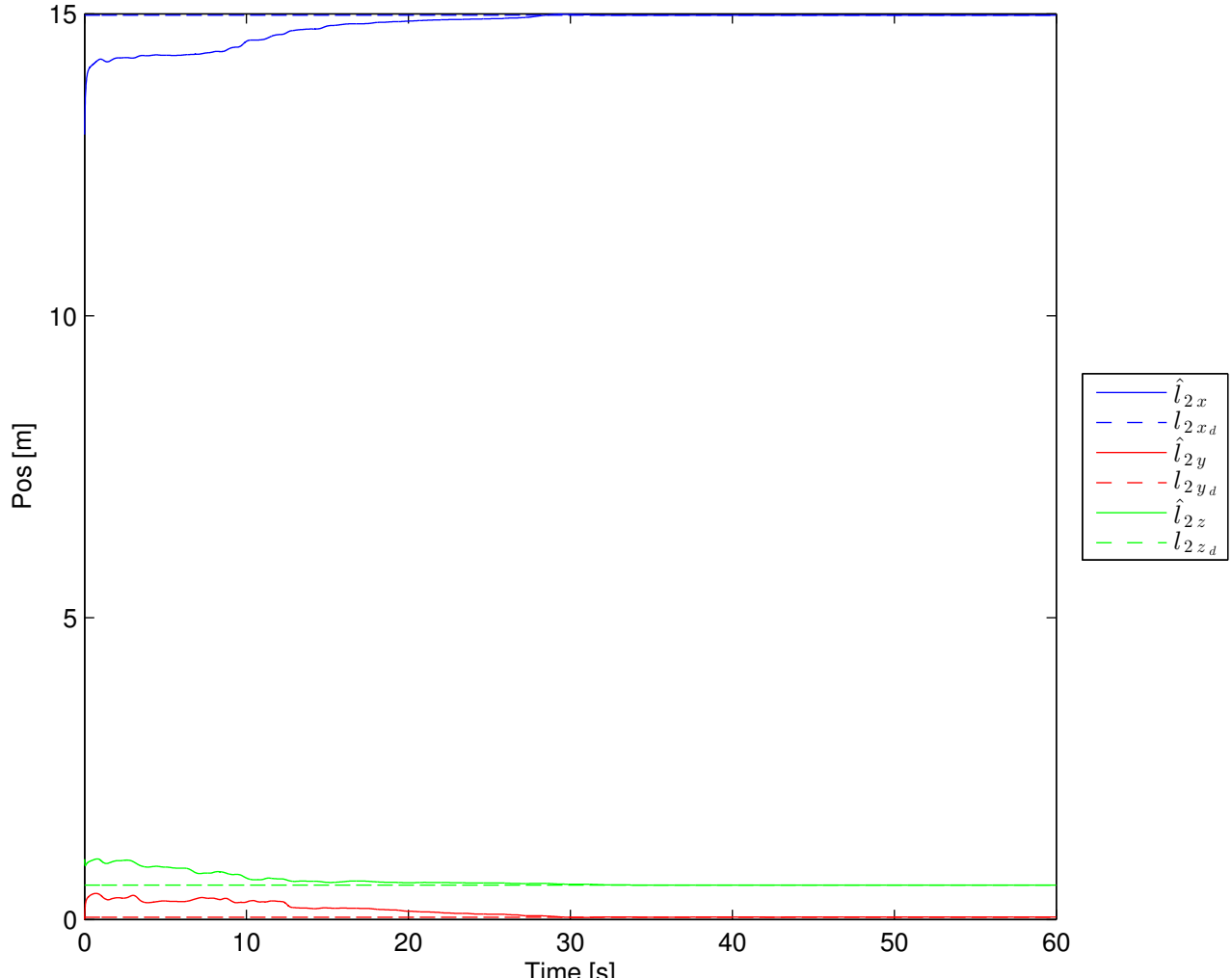
15
10
5
0
Pos [m]
0
10
20
30
40
50
60
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
$\hat{l}_{2y}$
l_{2y_d}
$\hat{l}_{2z}$
l_{2z_d}