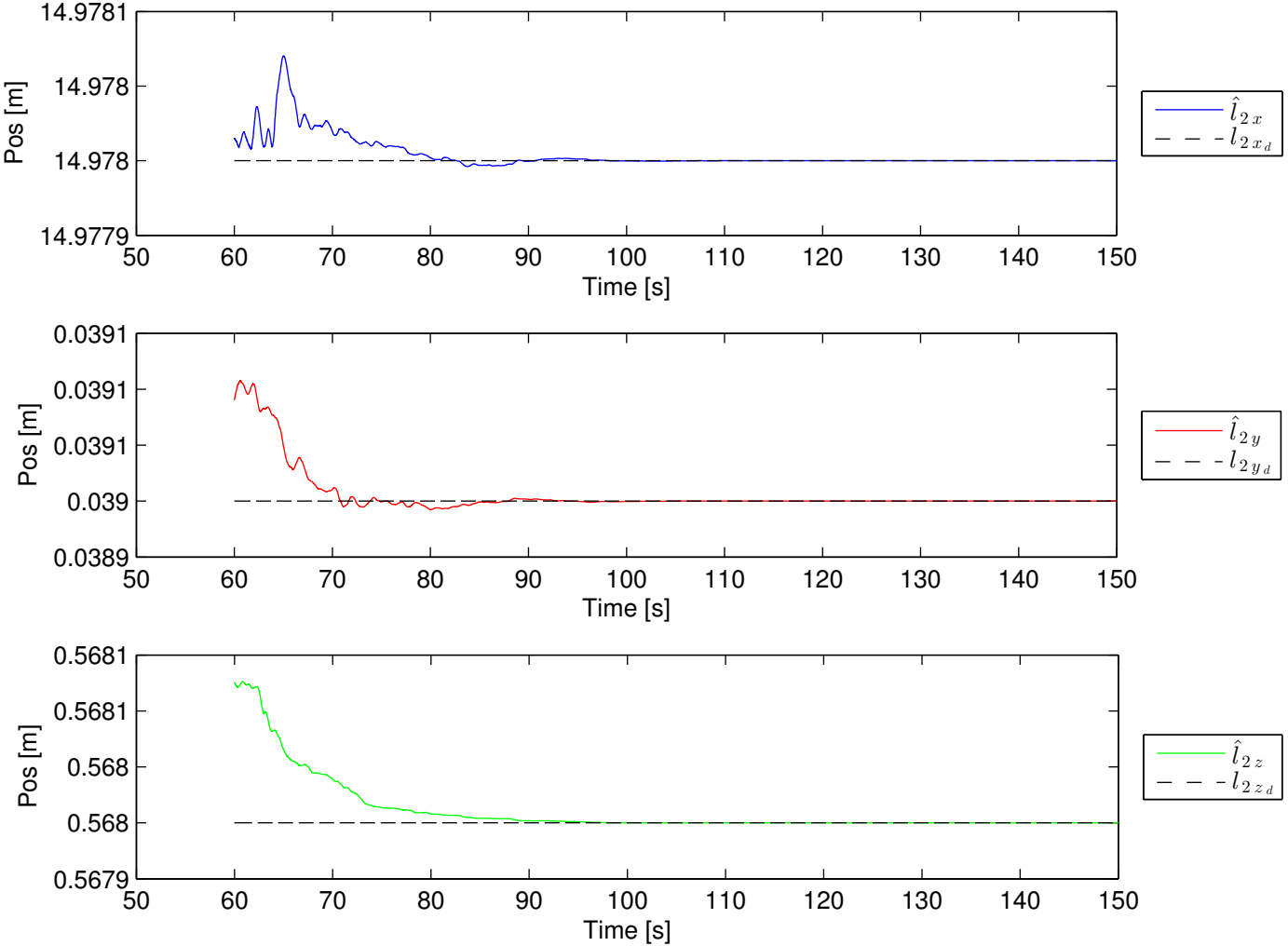
14.9781
14.978
14.978
14.9779
Pos [m]
50
60
70
80
90
100
110
120
130
140
150
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
0.0391
0.0391
0.0391
0.039
0.0389
Pos [m]
Time [s]
$\hat{l}_{2y}$
l_{2y_d}
0.5681
0.5681
0.568
0.568
0.5679
Pos [m]
Time [s]
$\hat{l}_{2z}$
l_{2z_d}