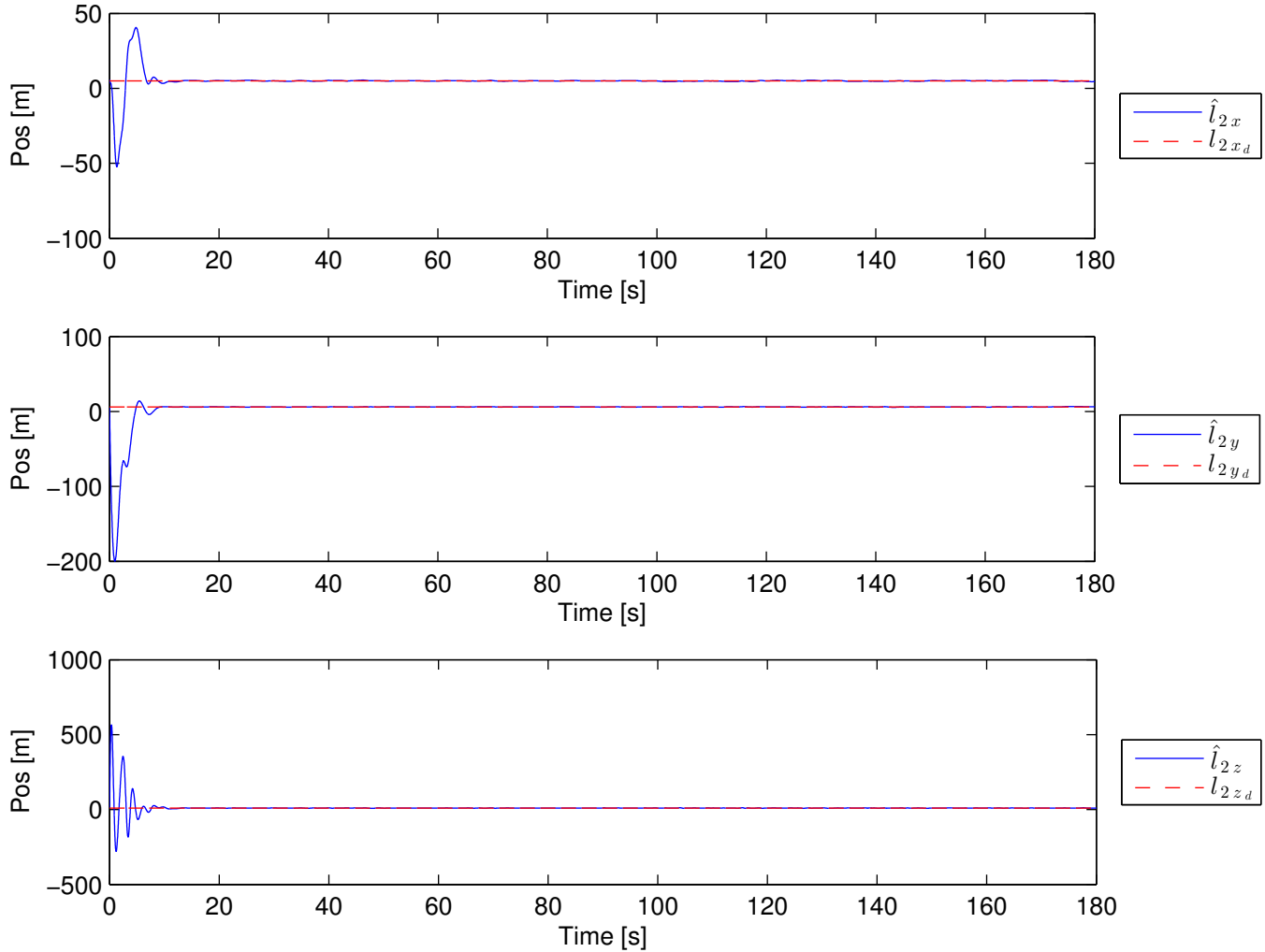
50
0
−50
−100
Pos [m]
0
20
40
60
80
100
120
140
160
180
Time [s]
$\hat{l}_{2x}$
l_{2x_d}
100
0
−100
−200
Pos [m]
Time [s]
$\hat{l}_{2y}$
l_{2y_d}
1000
500
0
−500
Pos [m]
Time [s]
$\hat{l}_{2z}$
l_{2z_d}