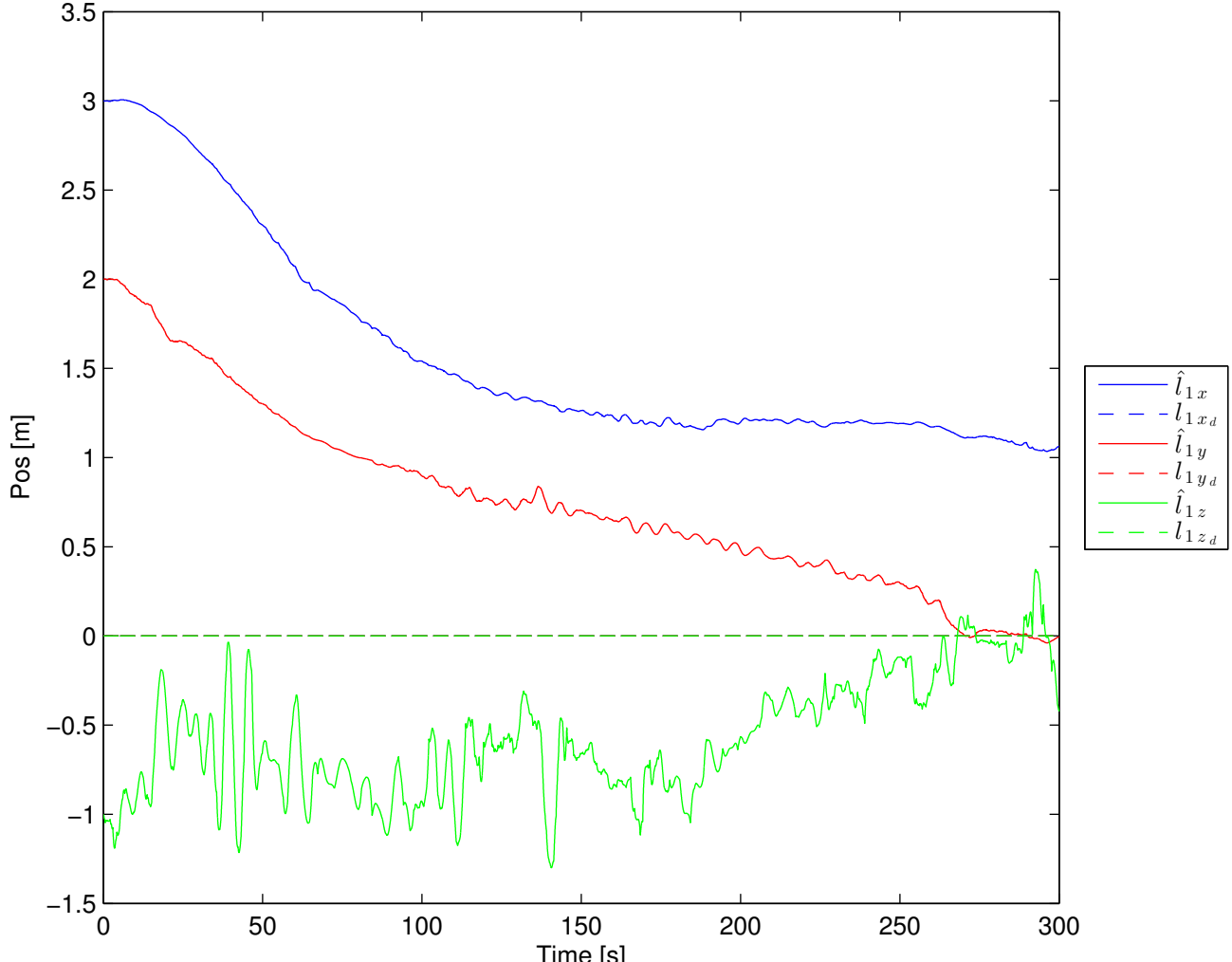
3.5
3
2.5
2
1.5
1
0.5
0
−0.5
−1
−1.5
Pos [m]
0
50
100
150
200
250
300
Time [s]
$\hat{l}_{1x}$
l_{1x_d}
$\hat{l}_{1y}$
l_{1y_d}
$\hat{l}_{1z}$
l_{1z_d}