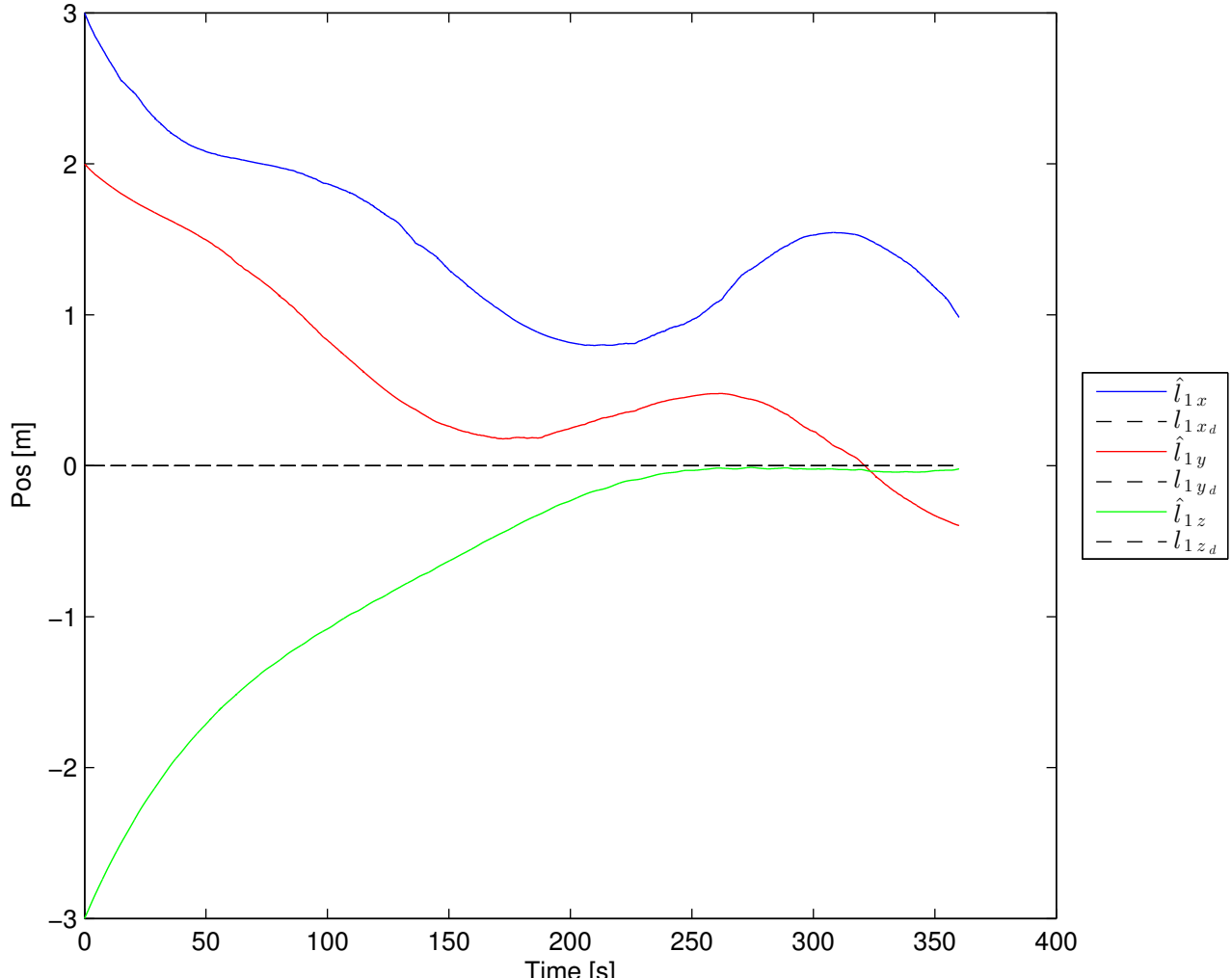
3
2
1
0
−1
−2
−3
Pos [m]
0
50
100
150
200
250
300
350
400
Time [s]
$\hat{l}_{1x}$
l_{1x_d}
$\hat{l}_{1y}$
l_{1y_d}
$\hat{l}_{1z}$
l_{1z_d}