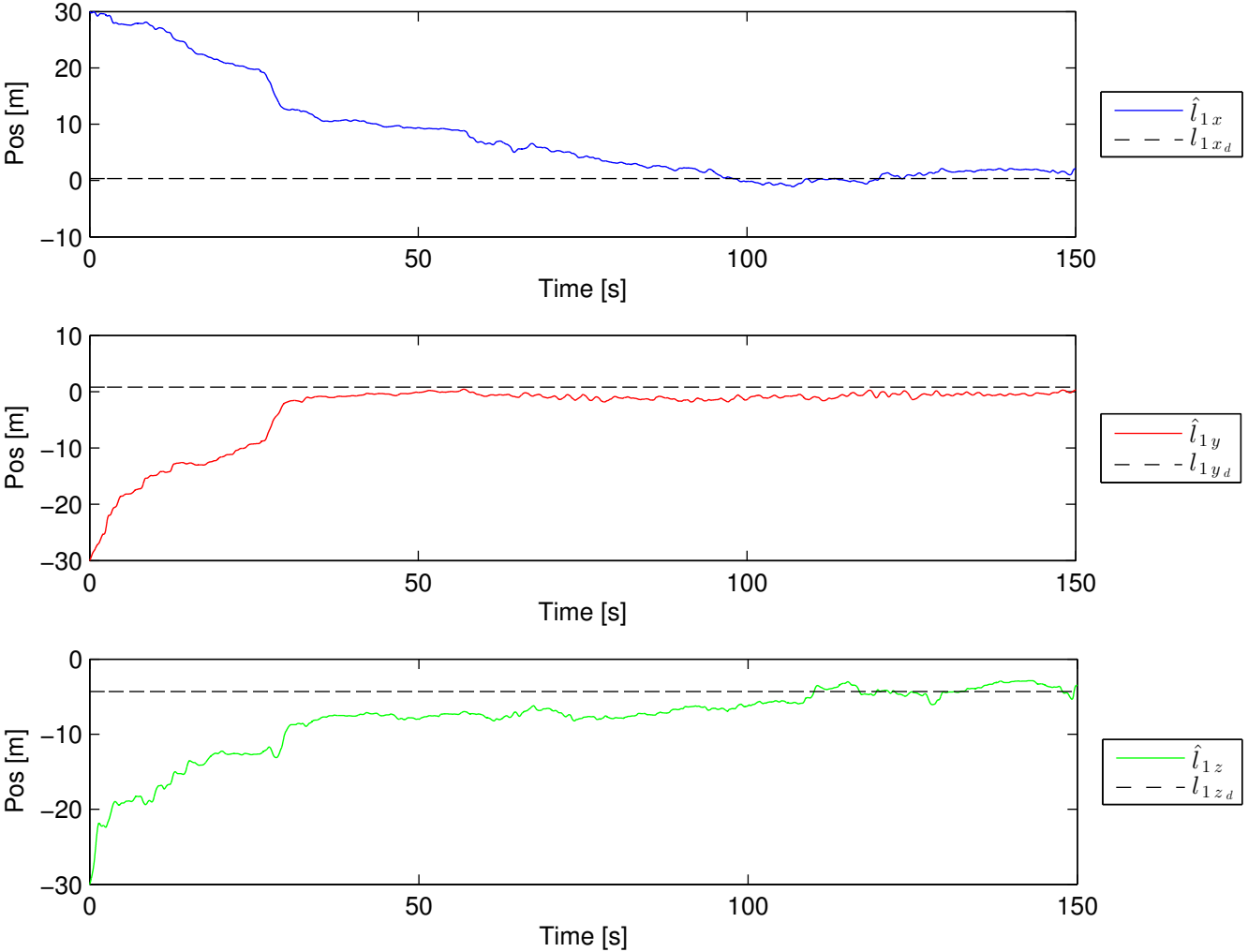
30
20
10
0
−10
Pos [m]
0
50
100
150
Time [s]
$\hat{l}_{1x}$
l_{1x_d}
10
0
−10
−20
−30
Pos [m]
0
50
100
150
Time [s]
$\hat{l}_{1y}$
l_{1y_d}
0
−10
−20
−30
Pos [m]
0
50
100
150
Time [s]
$\hat{l}_{1z}$
l_{1z_d}