

Dissociation between postrhinal cortex and downstream parahippocampal regions in the representation of egocentric boundaries

Xenia Gofman^{1*}, Gilad Tocker^{1, 2*‡}, Shahaf Weiss^{1, 3†}, Charlotte N. Boccara⁴, Li Lu⁵,
May-Britt Moser⁵, Edvard I. Moser⁵, Genela Morris¹, Dori Derdikman^{1‡}

Affiliations:

¹*Rappaport Faculty of Medicine and Research Institute, Technion – Israel Institute of Technology. Haifa, 31096, Israel.*

²*Gonda Multidisciplinary Brain Research Center, Bar Ilan University. Ramat Gan, 52900, Israel.*

³*Department of Zoology, Tel Aviv University. Tel Aviv, 69978, Israel.*

⁴*Institute of Basic Medical Sciences, University of Oslo. Oslo, 0372, Norway.*

⁵*Kavli Institute for Systems Neuroscience and Centre for Neural Computation, Norwegian University of Science and Technology. Trondheim, 7030, Norway.*

* These authors contributed equally to this work.

‡Lead contact: Email: derdik@technion.ac.il

‡Present address: Department of Neurobiology, Northwestern University, Evanston 60208, Illinois.

†Present address: Max Planck Institute for Brain Research, Frankfurt am Main, 60438, Germany.

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Summary:

Navigation requires the integration of many sensory inputs to form a multi-modal cognitive map of the environment, which is believed to be implemented in the hippocampal region by spatially tuned cells [1-10]. These cells encode various aspects of the environment in a world-based (*allocentric*) reference frame. While the cognitive map is represented in allocentric coordinates, the environment is sensed through diverse sensory organs, mostly situated in the animal's head, and therefore, represented in sensory and parietal cortices in head-centered *egocentric* coordinates. Yet, it is not clear how and where the brain transforms these head-centered egocentric representations to map-like allocentric representations computed in the hippocampal region. Theoretical modeling has predicted a role for both egocentric and head direction (HD) information in performing an egocentric-allocentric transformation [11-15]. A previous study demonstrated that conjunctive head-direction and border cells in the dorsal presubiculum (dPrS) could be interpreted as both allocentric and egocentric [16]. Furthermore, egocentric representation of objects and borders has been found in the lateral entorhinal cortex (LEC) [17]. Here we show that the postrhinal cortex (POR) contains a population of pure egocentric boundary cells (EBC). This contrasts with the conjunctive EBC x HD cells, which we found downstream mostly in the parasubiculum (PaS) and in the medial entorhinal cortex (MEC). Our finding corroborates the idea of a brain network performing an egocentric to allocentric transformation by head-direction cells. This is a fundamental building block in the formation of the brain's internal cognitive map.

Results and Discussion:

We recorded single units from visual area V2, the POR, the PaS, and the dPrS, in Long-Evans (LE) rats (N=19), while they performed open field foraging in square and circular arenas. We identified in these areas a cell type, which encodes the boundaries of the environment in an egocentric reference frame. We subsequently analyzed a large dataset of PaS, dPrS, and MEC units, previously published by Boccara et al. [18], recorded in a similar task. In total, we analyzed 2183 single units: 453 in V2, 106 in POR, 606 in dPrS, 375 in PaS, and 119 in MEC, as well as 524 units that were recorded in border areas and thus were anatomically unclassified. All recorded units underwent a commonly used allocentric analysis procedure, in which 2D firing rate maps and HD

polar plots were calculated (see STAR Methods). In addition, the units underwent an egocentric analysis, in which their firing rate was calculated as a function of the rat's distance from the wall at different egocentric angles (Figure 1A to F; see STAR Methods). Some cells showed egocentric tuning, while the allocentric tuning was missing (Figure 2A). Others showed conjunctive representation of allocentric properties (such as head-direction and position) and egocentric tuning to walls as boundaries (Figure 2B). Statistical significance of the egocentric tuning of each cell was estimated by two distinct and unbiased methods: the first classification method was a generalized linear model (GLM) (or linear-nonlinear-Poisson; LNP model) [19] with an adaptation of an addition of egocentric boundary dimensions (see STAR Methods). The GLM enabled us to examine the extent to which egocentric coding was independent of allocentric variables (such as position, head-direction and speed). Cells that exhibited a significant egocentric component were classified as egocentric boundary cells (EBCs). As a second method we used a shuffling procedure, in which spikes were randomly shifted in time (see STAR Methods).

Overall, the GLM was successful in fitting a model to 968/2183 cells, of which 301 cells had an egocentric component (Figure 3A).

EBCs were found in both square and circular environments (Figure S1, B). All egocentric angles were represented, with some overrepresentation of the front hemi field (front-right and front-left (N=156) vs. back, back-right and back-left (N=62) ($\chi^2(1) = 40.53$; $p < 0.0001$) (Figure 3B). No difference was observed in the distributions of egocentric angles encoding contralateral (122/301) vs. ipsilateral (105/301) hemi fields between the hemispheres ($\chi^2(1) = 1.27$; $p = 0.26$) (Figure S1, B). Additionally, we did not see a difference in the direction of egocentric tuning between 'pure' EBCs vs. conjunctive EBC x HD cells ($\chi^2(7) = 13.12$; $p=0.11$) (Figure S1 C, D). Sixty-eight percent of the recorded EBCs (N=206) responded to walls that were in close proximity to the rat (≤ 15 cm.), while the rest (N=95, 32%) responded to walls at larger distances (>15 cm; Figure 3C). Ninety-one percent of EBCs (N=274) showed stable egocentric border representations within the recording session (see STAR Methods). The existence of cells that represent walls at large distances from the animal may indicate that EBCs also integrate information from modalities other than the somatosensory one. Additionally, 14% of cells recorded in dark sessions were classified as EBCs (Figure S1 E and Table S2). We next examined the proportions of EBCs in the various brain regions. The POR differed from the other recorded regions (V2, dPrS, PaS and MEC)

in its high percentages of pure EBCs ($\chi^2(4) = 128.8$; $p < 0.0001$). Indeed, the most prominent population of pure EBCs was found in the POR, where 22% of the cells were classified as pure EBCs ($N=23$). In V2 only 5% of cells were classified as EBCs ($N=20$), a percentage that is close to the chance level of the GLM classification. In dPrS, PaS and MEC less than 1% of cells were identified as 'pure' EBCs (Figure 3D). The recorded structures also differed in their proportions of conjunctive EBC x HD cells ($\chi^2(4) = 135.04$, $p < 0.0001$). Populations of EBC x HD were found in POR ($N=34$, 33%), PaS ($N=21$, 6%) and in the MEC ($N=14$, 12%), and to a lesser extent in the dPrS ($N=21$, 4%). No conjunctive cells were identified in V2 (Figure 3D). Our results on conjunctive EBC x HD cells are consistent with conjunctive border x HD cells documented in the dPrS in a previous study [16], which demonstrated very different firing rates when the rats were running in opposite directions along the walls. To test the directionality of the conjunctive cells, we examined the HD Rayleigh scores for cells that were classified as EBC x HD in the different regions. In POR, the mean Rayleigh score of these cells was 0.13, much lower than in the dPrS (0.55), the PaS (0.48) and the MEC (0.48) (1-way ANOVA; $F(3) = 27.89$, $p < 0.0001$). Post-hoc comparison revealed that the value in the POR was significantly different from other groups ($p < 0.0001$, Bonferroni corrected). Note that there was a lower modulation of the HD signal in EBC cells in the POR relative to the other regions (Figure 3E).

Taken together, this suggests a general picture in which, out of the regions we recorded, pure EBCs were found in the POR, while conjunctive EBC x HD cells were found mostly in the MEC, the PaS and, with lower HD Rayleigh scores, also in the POR. The data reflects different levels of integration of egocentric and HD information in different parahippocampal regions. We analyzed the same population of cells using a shuffling analysis, and the relation between 'pure' EBCs and conjunctive EBC x HD cells in the different areas resembled the results from the GLM classification (Compare Figure S2 to Figure 3D). Our findings thus indicate a dissociation of the POR, containing many EBCs, with the PaS, the MEC (and a small portion in the dPrS), containing mostly conjunctive EBC x HD cells. The POR has extensive anatomical connections with visual and parietal cortices [20], which both encode information in an egocentric reference frame [21, 22]. Based on our results and preliminary anatomical evidence [23], we propose that a main route of information transformation from egocentric to allocentric representation of borders occurs in the known pathway between sensory and parietal cortices to the POR, and from there to the PaS and the

MEC. Recent evidence shows the existence of an egocentric representation in the LEC, suggesting that the egocentric information may also be routed to this region [17]. Theoretical studies have used border (or boundary vector) cells to explain the emergence of other spatially-tuned cells [24, 25]. However, the formation of border cells is itself poorly understood. Previous models have suggested that HD cells can participate in the generation of an egocentric-allothetic transformation in various regions [11, 14, 26, 27]. Therefore, we propose that allocentric border cells may be formed by the integration of conjunctive EBC x HD cells, with different combinations of egocentric boundary tuning and HD selectivity (Figure 4A). EBC x HD cells could, in turn, be formed by combining inputs from HD cells and pure EBCs. The EBCs that we recorded in the POR, and the EBC x HD cells that we recorded in the PaS and MEC, could represent the stages of such an integration process. To explore the feasibility of this process, we first simulated generation of EBC x HD cells by using the tuning curves of recorded HD cells as gates for firing of pure EBCs from our data. As one would expect, we obtained a population of EBC x HD cells (Figure S4 C, D and STAR Methods). We further examined the feasibility of the suggested egocentric – to – allocentric transformation by calculating the combined sum of angles of the preferred egocentric angle and the HD angle of conjunctive EBC x HD cells. We then pooled the allocentric rate maps of cells with a similar range of calculated angles (representing North, East, South and West). Indeed, the firing map that was established for each range of angles showed tuning to a specific border of the arena in an allocentric reference frame (Figure 4B, C and STAR Methods). We suggest that egocentric sensory input entering the system feeds into EBCs, which are in turn combined with the HD signal to form a conjunctive representation in EBC x HD cells. The organized summation of such information could lead to the downstream formation of allocentric border cells observed in dPrS, PaS and MEC.

Our results demonstrate an egocentric spatial representation upstream of and within the hippocampal region, supporting the notion that the EBCs play a role in the transformation between egocentric and allocentric reference frames, using the HD signal. This indicates an additional role for the HD cells in the navigation system: they are not only used as an internal compass, but also play a pivotal role in the transformation of egocentric signals into the allocentric cognitive map. Future work is needed to establish this role of HD cells and the role of egocentric representations in

the formation of other spatially-tuned cells. The current and future work will set a foundation for understanding the formation of the cognitive map through coordinate transformations in the brain.

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Author Contributions

Conceptualization, D.D. and G.T and X.G., Methodology, X.G., G.T and D.D., Software, X.G., S.W. and G.T., Investigation, X.G., G.T. and D.D., Data Curation, X.G., G.T., S.W., C.N.B., L.L., Writing – Original Draft, X.G. and G.T., Writing – Review & Editing, D.D., G.M., C.N.B., M-B.M., E.I.M, Visualization, X.G., Supervision, D.D., Funding Acquisition, D.D.

Declaration of Interests

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

Main figure titles and legends

Figure 1: Egocentric analysis for egocentric boundary cells (EBCs). (A) In an allocentric reference frame, the rat's position in the arena was encoded in world-centered coordinates. For example, here the rat was in the northeast quadrant near the center of the box. In an egocentric reference frame, the rat's position in the arena was encoded in an egocentric coordinate system. In this example, the closest wall was on the front-left of the rat. For every egocentric angle from the rat (θ), we calculated the distance (d) of the wall in that direction. (B) Egocentric time map: for each time frame, the rat's distance to each point on the border of the arena at given egocentric

angles was summed up in polar coordinates (egocentric angle vs. distance). (C) Egocentric spike map, produced in a similar way to panel B, using the spike times. (D) Egocentric firing map was calculated by dividing the spike map by the time map. The vertical and horizontal dashed lines represent the optimal wall distance and angle, chosen according to the bin with the maximal firing rate. (E) Egocentric firing map in cartesian coordinates; The rat is located in the center of the firing map; the activity of the firing map represents the activity of one cell in response to the appearance of the wall relative to the rat at a given egocentric direction and distance. The yellow area in the firing map indicates that this cell was mostly active when the borders of the arena were 10 cm to the left of the rat. The black ring represents the dashed line from panel D. The radius was chosen according to the distance from the rat to the bin with the maximal firing rate. (F) Polar plot of firing rates in different egocentric angles for the preferred distance (black ring, panel E). The cell in this example was tuned to a boundary on the left of the rat.

Figure 2: Examples of cells classified as 'pure' EBCs and conjunctive EBC x HD cells.

(A) 'pure' EBCs examples in POR, V2 and dPrS. i – the trajectory of the rat in the arena is represented by the black line; the red dots represent spike locations. The size of the arena is registered below. ii – allocentric firing map of the rat in the arena. The yellow color is for the maximal firing rates; the blue is for the lowest. Maximal firing is noted below map. Range of color map is given in parenthesis. iii-allocentric rate maps for trajectories of the rat for north (N), south (S), east (E) and west (W) heading direction. Color scale- as in panel ii. iv – HD polar rate map of the cell. Rayleigh score is for HD. v – egocentric rate map. The maximal distance is half the size of the arena in panel ii, in logarithmic scale. The preferred distance given in cm. Color scale- as in panel ii. vi – egocentric tuning curve of the cell. Rayleigh score is for egocentric tuning. (B) Examples of conjunctive EBC x HD cells recorded in POR, dPrS, PaS and MEC. The organization of this panel is similar to that of panel A.

See also Figure S1, Figure S3, Table S2 and Table S3.

Figure 3: Population statistics for egocentric cells using the GLM model.

(A) Distribution of the selected models for the 969 cells identified by the GLM model approach. (B) Directional tuning of EBCs according to their preferred egocentric directions. (C) EBC tuning to the rats' distances from the wall. (D) Cell class

distribution in different anatomical regions (from left to right: V2, POR, dPrS, PaS and MEC). Cell classes forming less than 1% of the population are not shown. (E) HD Rayleigh score (x-axis) and the p-value of original HD cell (y-axis) for cells classified as EBC x HD by the GLM. Each dot is a cell; the gray area represents the commonly used classification for HD cells. See also Figures S2-S4.

Figure 4: Generation of border cells: Model sketch and real data. (A) Theoretical model sketch for the generation of border cells. 16 schematic EBC x HD cells are arranged in a matrix. Rows represent the egocentric tuning of the cells, and columns represent the allocentric tuning of their HD component. As an example, we depicted the formation of an allocentric eastern border cell with no HD component, generated from the conjunction of four cells with different EBC and HD properties (red frame). (B) Recorded cells were used as building blocks for the model; For each conjunctive EBC x HD cell recorded in the square arena, we calculated the angle γ resulting from the conjunction of its allocentric HD angle and egocentric EBC angle. We then divided the resulting angles into four quadrants and summed all allocentric rate maps corresponding to each range of angles. (C) Same procedure as in panel B, for the circular arena case. See also Figure S4.

STAR★Methods

LEAD CONTACT AND MATERIALS AVAILABILITY:

This study did not generate new unique reagents.

Further information and requests for resources and reagents should be directed to and will be fulfilled by the Lead Contact.

EXPERIMENTAL MODEL AND SUBJECT DETAILS

Subjects and surgery

Four adult male Long-Evans rats (healthy, drug-naive, 400–600 g, 4-8 months old, not involved in previous procedures) were implanted with a microdrive under isoflurane anesthesia (~2%) and buprenorphine analgesia. The microdrives (Rogat and Omnetics) contained four tetrodes (17-mm, 90% platinum 10% iridium); the electrode tips were platinum-plated to reduce electrode impedances to ~200 k Ω at 1 kHz.

The microdrive was mounted on a moveable assembly for recording neuronal activity and local field potentials in the visual area V2, postrhinal cortex ('POR'), dorsal presubiculum ('dPrS') and parasubiculum ('PaS') (0.5-0.8 mm anterior of transverse sinus; 4.2-4.6mm ML; 0.8-2.0 mm DV).

A ground screw was inserted into the frontal bone plate and attached by a wire to the microdrive during recording sessions. Rats were monitored for 1-2 weeks of recovery prior to recording and maintained above 85% of their free-feeding weight.

Rats were in a 12/12hr light/dark regime, dark period 10:00-22:00. Rats were held in 46.2 x 40.3 x 40.4 cm cages with sawdust bedding. All experimental procedures were approved by the Animal Care and Use Committee of the Technion – Israel Institute of Technology.

METHOD DETAILS

Apparatus

The experimental arena consisted of a black open-top plastic square box, 120 x 120 x 60 cm, and 90 x 90 x 60 cm. Some of the recording sessions were performed in a circular arena as well, with a diameter of 90 cm and height of 60 cm, and in the square arena, in full darkness, via an infrared camera (Neuralynx). A cue card was attached to one of the walls for orientation.

Training procedures

Rats were handled and then trained to forage in the arena; the foraging was motivated by randomly scattering chocolate sprinkles in the recording enclosures. The training was repeated until full coverage of the arena was observed.

Data collection:

All data from the Derdikman lab were collected using the Digital Lynx SX data acquisition system (Neuralynx) at 32 KHz and Cheetah 5.6 software (Neuralynx). All signals were pre-processed with a bandpass filter of 600-6000 Hz. Single units were manually isolated into cell clusters using SpikeSort3D software (Neuralynx). The rats' position was tracked using two LEDs (red and green) mounted on a head-stage, connected to the implanted microdrive, or by using two infra-red LEDs, for tracking in the dark.

Rats were connected to the recording equipment and released in the center of the arena. The tetrodes were lowered in steps of 50 μm until single neurons could be isolated at appropriate depths. When single units were detected, the rat performed an open field session in the square arena. Then, cells were analyzed with Matlab and if relevant cells were detected, the rat was connected again to the recording equipment. If the cells from the first experiment were stable; the rat performed an additional open field task in a circular arena and in the square arena in full darkness. After each completed set of experiments, the tetrodes were moved further until new well-separated cells were encountered.

Histology

Rats were perfused with PBS (Sigma-Aldrich). Brains were removed and stored in 4% paraformaldehyde for 2-3 days at 4°C, then transferred to sucrose solutions of 30% over a period of 3-5 days. Following fixation, brains were sliced into 30 mm thick slices in a cryostat at -20°C. To identify tetrode traces, selected slices were treated with increasing gradients of ethanol solution to remove any fat in tissue, and then with decreasing gradients to rehydrate slice tissue. Finally, slices were stained with Cresyl violet to distinguish cell bodies.

QUANTIFICATION AND STATISTICAL ANALYSIS

All statistical analyses were conducted using MATLAB 2017b and MATLAB 2018a software.

In addition to the new data, we analyzed previously published data by Boccarda et al., (2010) [18] from dPrS, PaS and MEC. The data were recorded during open field tasks in square and circular arenas (for additional information on the methods, see Boccarda et al. (2010)[18]).

Spatial analysis

Allocentric rate map: The spatial rate map of each cell was computed by partitioning the arena into bins of 3 cm × 3 cm. Next, the spike-count per bin was computed and divided by the total time spent by the animal at the bin. The resulting rate map was then smoothed using a Gaussian kernel with standard deviation of $\sigma = 3$ bins.

Head direction: The rat's head direction was calculated for each video frame by computing the direction of the line perpendicular to the vector connecting the centers of the two light-emitting diodes on the rat's head (the color difference between the two diodes, green and red, enabled distinguishing forward from backward head-direction). The head-direction tuning of a neuron was computed by binning the data in 6° bins; the firing-rate in each bin was computed by dividing the number of spikes in that bin by the time the animal spent in the bin. The peak firing rate was defined as the highest rate in the head-direction tuning curve. The directionality of this tuning was quantified by computing the mean vector length of the circular distribution [28] (Rayleigh score). Only cells with a Rayleigh score ≥ 0.3 were classified as HD cells

Border cells: were analysed as described in Solstad et al., (2008)[8]. Briefly, border cells were characterized by identifying neighboring bins with firing rates that were higher than 0.3 times the maximum firing rate and covering a total area of a single wall. Border score range was between -1 (no border preference) and 1 (high border preference). We classified a cell as a border cell if its border score was ≥ 0.5 and the original border score was higher than 990/1000 of the shuffled ones ($p\text{-value} \leq 0.01$). The shuffling procedure was applied to determine the significance of each neuron's score. For each cell, the entire sequence of spikes was shifted in time by a random (uniformly-distributed) interval between 0.04 seconds and the duration of the session minus 0.04 seconds; If the range of shuffled spikes was within 30 seconds of the original times, a new time shift was drawn. The end of the session was wrapped to the beginning. This preserved the spike number and the temporal structure of the neuron's firing pattern but dissociated the time of spiking from the animal's original trajectory. This procedure was repeated 1000 times for each neuron; an original score higher than 990 of the shuffled ones classified the cell as a border cell ($p\text{-value} < 0.01$).

Egocentric analysis: To compute the egocentric rate map for each cell, we first calculated the walls' egocentric location relative to the rat, throughout the session. We computed, at each moment in the session, the distance from the rat's position as estimated from the LEDs on its head to the environment walls in every direction. From these directions to the walls, we subtracted the animal's head direction at each moment (Figure 1A).

Subsequently, the full range of egocentric directions was partitioned into 6° slices and egocentric distances were partitioned in logarithmic scale, up to half the size of the arena. The firing rate of the cell in each bin was computed by dividing the number of spikes in that bin by the time the animal spent in the bin (Figure 1, B and C). The resulting egocentric rate map was then smoothed using a Gaussian kernel with a standard deviation of $\sigma = 5$ bins. The bin with the highest firing rate was identified. The distance of the maximal bin was defined as the preferred distance to the wall, and the angle with the highest firing rate represented the preferred egocentric angle to the wall (Figure 1D-F).

EBCs were classified as significant egocentric cells if their Rayleigh score was higher than 95% (95/100) of the shuffled distribution (“p-value \leq 0.05”). If the range of shuffling was within 30 seconds of the original times, a new time shift was drawn.

Stability within a session: To quantify the stability of EBCs within a session, each session was divided into two equal-length time segments. An egocentric rate map (polar coordinates) was calculated for the first and the second segment. Stability scores were calculated by computing the correlation of the calculated egocentric rate maps between the segments. The second segment was shuffled 100 times as described above. Cells with stability scores higher than 95% of the shuffled ones were defined as stable.

Details on the GLM model

To determine the parameters encoded by the neurons’ activity, we fit a general linear model (GLM) to each neuronal activity sequence, modified from the LN model and code described in [19]. Briefly, the model aims to accurately describe the neuronal smoothed spike train r as an exponential function of the state of the animal, determined by the animals’ position (P), head direction (H), speed (S) and egocentric location of the walls (Ego):

$$r = e^{\sum_i x_i^T w_i / dt}$$

Where r is a vector of instantaneous firing rates in T time bins of $dt = 40$ ms. The state vector x is composed of one to four variables $x_i \in \{0,1\}$, weighted by the corresponding factors w_i . To prevent overfitting, we performed a cross validation procedure, where w_i was estimated on a subset of the data, and testing for maximum log likelihood was performed on separate test data set. This procedure was repeated 10 times. We tested separately for each of the following 15 models: four single factor ones (P , H , S , Ego), six double factors ($P \times H$, $P \times S$, $P \times Ego$, $H \times S$, $H \times Ego$, $S \times Ego$), four triple models ($P \times H \times S$, $P \times H \times Ego$, $P \times S \times Ego$, $H \times S \times Ego$), and a full model ($P \times H \times S \times Ego$). While the P , H , and S models were described in [19], our added egocentric component (Ego) is described in the following section.

Finally, we performed a one-sided signed rank test to the log likelihood values of each model, choosing the model with the smallest number of parameters, which accounted for the data significantly better than others ($p < 0.05$)[19]. For chosen model parameters, see Table S1.

Egocentric variable models and state vectors: To quantify the dependence of the cell's spiking activity on the egocentric location of the environment walls, we introduced the wall egocentric-location variable to the LN model (Ego). At each moment in time, each point in the environment walls had a specific distance and egocentric direction. This posed the problem of multiple animal-states at each time point, when considering the variable of the egocentric walls. To overcome this problem, we optimized the parameters of each egocentric direction as a distinct variable of the model. To compute the egocentric location of the walls, we first computed, at each moment in time, the distance and direction of each point on the walls from the animal's center of mass. From this direction, we subtracted the animal's head direction at each moment.

Then, the full range of egocentric directions was divided into 8 bins (45°). In addition, the full range of distances between the walls and the animal was distributed across a logarithmic scale and divided into 8 bins. Each bin of egocentric directions was considered a different variable of the model that varies in time by the wall's distance to the animal in that egocentric direction. That is, at each moment in time, the animal-state vector, for each egocentric direction, was denoted by a vector with a value of 0 on all elements, except for one element, which was set to 1, corresponding to the bin of the current wall's distance to the animal in this specific egocentric direction.

Only models containing all the egocentric directions, or none of them, were optimized and selected. i.e. a model with only some of the egocentric directions, and not others, was not selected. For examples of cells that were classified as pure egocentric or as conjunctive EBC x HD, see Figure S3.

Simulations

Simulation of shifted spike train for POR data: To check the reliability of the GLM method in classifying cells with an egocentric component, we generated a population of cells (POR cells) with random spike trains and ran the GLM on the simulated data. To produce the simulated population, each cell's spikes were cyclically shifted in time, and the new shifted population was used. Figure S4 A, B shows the results of the GLM classification on the simulated population).

Simulation of BC from EBC x HD cells: To examine the feasibility of our suggestion that BCs may be indeed generated as a combination of inputs from EBC x HD cells, as was suggested in Figure 4A. We used 120 cells that were classified as EBC x HD cells by the GLM. For each cell, we calculated a summed angle (γ) that represents the combined value of HD angle (1° - 360°) and EBC angle (1° - 360°). $\gamma = \text{mod}((HD^\circ + EBC^\circ), 360)$. Then we summed up all allocentric rate maps (divided by their maximum firing rate) of EBC x HD cells within four given ranges for the summed angles: (1) from 315 to 360 and from 1° to 45° ; (2) from 45° to 135° ; (3) from 135° to 225° ; (4) from 225° to 315° (Figure 4, B and C).

Simulation of EBC x HD cells from ‘pure’ EBC and HD cells: To simulate EBC x HD cells, we used our population of classified ‘pure’ EBCs. For each EBC, we randomly selected 8 HD cells from our data set for the simulation of a new population of EBC x HD cells, as follows:

We used each HD cell in order to generate a probability of selecting spikes from a pure EBC and repeated this procedure 100 times. The simulated spike train was generated by selecting those bins which contained spikes occurring in more than 30% of the repetitions. We calculated the allocentric and egocentric properties of the simulated cells and used the GLM analysis to classify the population to cell types (Figure S4 C and D).

DATA AND CODE AVAILABILITY

Data and custom Matlab codes used to generate all analyses are available from the Lead contact upon request.

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