

Optimization of sample size for two-point diameter verification in coordinate measurements

Petr Chelishchev¹, and Knut Sørby¹

Abstract. This paper investigates the possibility for reduction of sample size for inspection of two-point diameters with a coordinate measuring machine, by use of statistical methods. The statistical methods implement the parametric and non-parametric statistic. As confirmed by the simulation results it is possible to keep the 95% confidence level with a relatively small data sample. A low sample size would be especially important for an operative online dimension inspection with CNC machine and immediate correction of a suspected part.

Keywords: two-point diameter, sample size, test statistic, model simulation, measuring strategy, CMM.

1 Introduction

The main goal of Geometrical Product Specifications (GPS) inspection is to verify that the geometry and the dimensions of a part are inside of the tolerance limits specified by the drawing requirements, with some given confidence level. One of the important parameters of a measuring strategy in a coordinate measuring machine (CMM) is the number of the measuring points [1]. On one hand, a large sample size provides a better accuracy. On the other hand, a large sample size increases costs and time consumption in CMM inspection. The necessary sample size depends on many factors such as tolerance type (form, dimension etc.), magnitude of deviation from the desired value, and its ratio to the tolerance interval. Thus, the proper choice of an optimal number of measuring points is a nontrivial task.

Different approaches were suggested to discover the sample size problem. Parametric statistic principles based on the normal distribution of the measured variable has been suggested [2, 3]. A fuzzy logic approach to reduce the number of measuring points with CMM was proposed by Cappetti et al. [4]. Other approach-

¹ Petr Chelishchev (✉)

Department of Mechanical and Industrial Engineering, NTNU, NO-7491 Trondheim, Norway
e-mail: petr.chelishchev@ntnu.no

es with genetic algorithms [5], adaptive sample strategy with Kriging models [6] and combinations of analytical methods with uncertainty simulations [7] has been applied to solve the measuring strategy problem.

In a previous paper, the authors estimated the optimal sample size for detecting 95% of the radius variation range (roundness form deviation of cylinder cross-sections) with 95% confidence level [8].

In this paper, we have investigated reduction of number of measurements in two-point size verification of a circular feature. According to ISO 14405-1 [9], “the two point size is the distance between two opposite points on an extracted integral linear feature of size”. The two-point size of the cylinder is also called “two-point diameter”. The two-point size of a circular feature is illustrated in Fig.1.

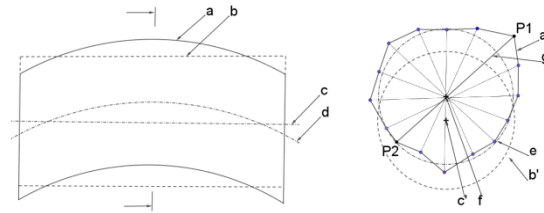


Fig. 1. Two-point diameter: a-actual cylinder; a'- section profile; b, b'-Gauss associated cylinder; c, c'- axis of Gauss associated cylinder; d-cylinder median line; e- Gauss associated circle (of section); f- Gauss associated circle center of e; g-actual local size (two-point diameter), the straight line between two opposite points P1 and P2, which goes through the center f

Research in the sample strategy field is generally focusing on the evaluation of geometrical form deviation (e.g. roundness, flatness) [5, 7, 8, 11]. In this paper: we consider the case when the diameter tolerance band is assumed to be larger than the variation of the two-point diameter in one single part. The parameters of interest in part inspection is the mean value and the variation of the two-point diameter.

2 Method and Material

We use the statistical hypotheses test approach to analyse the measurement data from CMM. The data sets need to be standardized and estimated before they are further applied for simulation. The more detail description is given bellow.

2.1 Experimental data

In this case study, we have inspected an internal cylinder of an aluminium workpiece with the internal diameter 60 mm and the length 130 mm. The measurements have been performed in a Leitz PMM-C-600 coordinate measuring machine with an analogue probe. The least square cylinder method has been used to establish the cylinder axis, which is the z-axis in the coordinate system. Three cross sections (A, B, C) were measured, the first on the top, the second in the middle and the third on the bottom respectively. There are 500 measuring points in each cross-section, and 250 diameter values D_i were calculated:

$$D_i = \sqrt{(x_i - x_{i+250})^2 + (y_i - y_{i+250})^2}, \quad i = 1 \dots 250 \quad (1)$$

For simplicity of presentation and further data processing, the array D_i has been transformed into $\xi_i = (\bar{D} - D_i) \cdot 1000$, where \bar{D} is the mean value of the diameter in each cross-section. We make an assumption that all the lines, which connect the two opposite points agree with two-point diameter definition terms shown in Fig.1.

In order to derive the distribution shape of probability density function (pdf) $f(\xi)$ of standardized variable ξ_i , the kernel density estimator (KDE) has been used [12]:

$$\hat{f}(\xi) = \frac{1}{bn} \sum_{i=1}^n K\left(\frac{\xi - \xi_i}{b}\right), \quad -\infty < \xi < \infty. \quad (2)$$

We have applied the Epanechnikov kernel K , the default MATLAB bandwidth b , and the sample size n with 250 variables ξ_i . The estimation results of pdf $f_A(\xi)$, $f_B(\xi)$, $f_C(\xi)$ for all three cross-sections are shown in Fig.2.

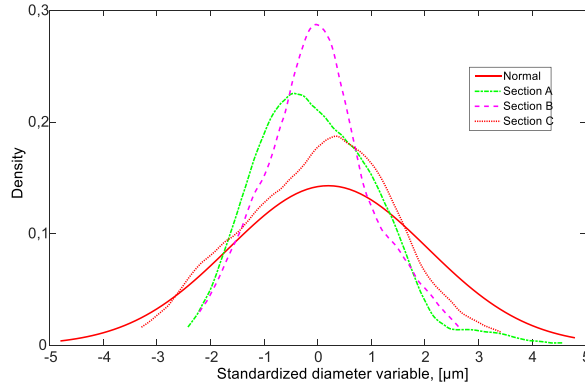


Fig. 2 The KDE $\hat{f}_A(\xi)$, $\hat{f}_B(\xi)$, $\hat{f}_C(\xi)$ based on 250 standardized diameter variables, and the adjusted normal distribution

At this point, for further purposes, we need to adjust the standard deviation σ_0 of the normal distribution in such way that the six-sigma interval could cover any of

The mean values of both normal distributions are located in such way that the distance between one of the means and one of the tolerance limits (1 – lower, 2 – upper) equals to $3 \cdot \sigma_0$ on each side as shown in Fig.3. The cases when the sample mean is below or above the mean of the Gauss curves (Fig. 3) correspond to the null hypotheses H_0^L or H_0^U . When one of the null hypotheses is accepted then the special procedure with large number of points will be suggested. Thereby, the method does not reject a part, but it recommends larger sample size when it is necessary.

As it was recently noticed, we need to test only one of the two hypotheses at the same time either for the lower tolerance (LTL) or for the upper tolerance limit (UTL). We consider the tolerance H7 for 60 mm diameter hole as an example, according to ISO 286-1 ($EI = 0$, $ES = +30 \mu\text{m}$) [14]. As long as the diameter variable D_i has been transformed, it has simplified a calculation of the tolerance limits: $LTL = EI$ and $UTL = ES$. Then the theoretical mean values are: $\mu_0^L = LTL + 3\sigma_0$ for the null hypothesis H_0^L and $\mu_0^U = UTL - 3\sigma_0$ for H_0^U (the lower and the upper tolerance limits respectively). Thereby the tested hypotheses H_0^L or H_0^U are formulated in this way: the sample mean of measurements is equal to the one of theoretical means of the normal distributions $N(\mu_0^L, \sqrt{\sigma_0^2/n})$, $N(\mu_0^U, \sqrt{\sigma_0^2/n})$ either $\mu_s = \mu_0^L$ (for H_0^L) or $\mu_s = \mu_0^U$ (for H_0^U), hence the alternative hypotheses H_1^L or H_1^U are $\mu_s > \mu_0^L$ or $\mu_s < \mu_0^U$ respectively. We use the sample mean $\bar{\xi} = \frac{1}{n} \sum_{i=1}^n \xi_i$ (to estimate μ_s) as the test statistic. The sample mean

is computed from the sample data generated by KDE, which has unknown non-normal distribution $K(\mu_s, \sigma_s)$. The alternative hypotheses H_1^L, H_1^U assume that the variation range of the sample data is inside of the critical range V_k . Then the critical range is defined with the lower bound $\bar{\xi}_k^L$ for the LTL and the upper bound $\bar{\xi}_k^U$ for UTL respectively by:

$$\bar{\xi}_k^L = u_{1-\alpha} \cdot \sqrt{\sigma_0^2/n} + \mu_0^L, \quad (3)$$

$$\bar{\xi}_k^U = u_\alpha \cdot \sqrt{\sigma_0^2/n} + \mu_0^U, \quad (4)$$

where u_α and $u_{1-\alpha}$ are the quantiles of levels α , $1-\alpha$ respectively for $N(0,1)$, and n is the number of observations. We have used the level of significance $\alpha = 0.05$ in the statistical simulation (i.e. $u_{0.05} = -1.645$ and $u_{0.95} = 1.645$).

3 Simulation Results

Table 3 Rejecting rates η_0^L of the sample mean location for the *Section B*

Mean difference, δ_j^L	Sample size, n						
	5	10	15	20	30	40	50
$\delta_1^L = \sigma_0$	0.82	0.99	1	1	1	1	1
$\delta_2^L = 0.5 \cdot \sigma_0$	0.21	0.46	0.66	0.82	0.95	0.99	1
$\delta_3^L = 0$	0.01	0.01	0.01	0.01	0.01	0.01	0.01

Table 4 Rejecting rates η_0^L of the sample mean location for the *Section C*

Mean difference, δ_j^L	Sample size, n								
	5	10	15	20	30	40	50	60	65
$\delta_1^L = \sigma_0$	0.75	0.95	0.99	1.00	1.00	1.00	1.00	1.00	1.00
$\delta_2^L = 0.5 \cdot \sigma_0$	0.29	0.47	0.63	0.75	0.88	0.95	0.98	0.99	1.00
$\delta_3^L = 0$	0.03	0.03	0.03	0.03	0.03	0.03	0.03	0.03	0.03

4 Discussion of results

There are four important categories of the measurements regarding to the simulation results of the data mean μ_S location. The first category G (good parts) corresponds to the intersection of two subsets $\{\mu_S \geq \mu_0^L + \sigma_0\} \cap \{\mu_S \leq \mu_0^U - \sigma_0\}$. The second category T (transitional parts) includes the subsets $\{\mu_0^L < \mu_S < \mu_0^L + \sigma_0\}$ and $\{\mu_0^U - \sigma_0 < \mu_S < \mu_0^U\}$, and the third category S (suspected parts) belongs to $\{\mu_S \leq \mu_0^L\}$ and $\{\mu_S \geq \mu_0^U\}$, which equivalents (according to the terms in section 2.2) with the fourth category F (fail parts) of subsets $\{\mu_S < LTL\}$ and $\{\mu_S > UTL\}$. Obviously, all the boundaries are fuzzy but they help to clarify the simulation results. For illustrational purposes, we presume a uniform distribution $U(0,30)$ of the manufacturing process over a long time period. The tolerance interval can be illustrated as follows in Fig.4. Thus, the content of each region (S, T, G respectively) can be easily evaluated:

$$\int_0^{3\sigma_0} \frac{1}{30} du = 0.16, \quad \int_{3\sigma_0}^{4\sigma_0} \frac{1}{30} du = 0.05, \quad \int_{\mu_0^L + \sigma_0}^{\mu_0^U - \sigma_0} \frac{1}{30} du = 0.57 \quad (5, 6, 7)$$

A correct decision about the data mean location μ_s for the S category can be defined at least with 95% probability (the accepting rate $1 - \eta_0^L$, $\delta_3^L = 0$) even with the five-observation sample size. Moreover, the solution is independent on the sample size.

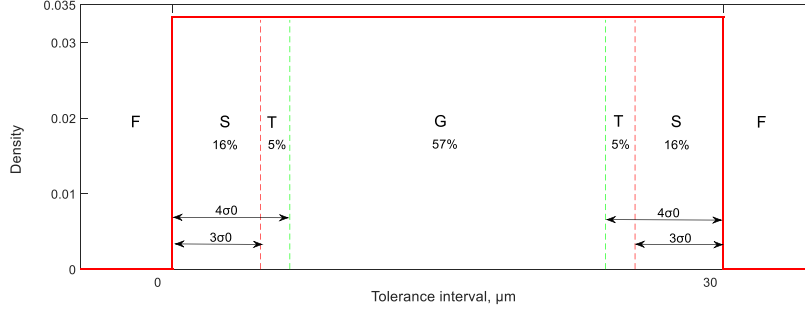


Fig. 4 The dimension tolerance interval based on the uniform distribution assumption

Similar for the G category, the correct conclusion about a low deviation of the mean value can be done at least with 95% probability (the rejecting rate η_0^L , $\delta_1^L = \sigma_0$) for the ten-observation sample size.

According to Table 2, 3, 4 ($\delta_2^L = 0.5 \cdot \sigma_0$), for the transitional category T , the large sample over 40 observations might be required to confirm the compliance of the size with the tolerance limits with 95% CL. Nevertheless, the T regions are only 10% regarding to (6) relative to whole the uniform distribution (Fig. 4). Even by using the 10 observations sample (corresponds to 20 measuring points for the two-point diameter), we are still able to make the right decision in about 45% of the cases. Namely, the total percentage will be below 10% of all possible issues.

5 Conclusion

In this paper, we have investigated the number of required points in measurement of two-point diameter, and performed a case study on a part with 60 mm diameter and H7 tolerance. The reliability of the method strongly depends on the proper choice of the six-sigma range. The method reduces to some degree the tolerance interval size (acceptance interval), but it is compensated by the significant minimization of the sample size, more than in 4 times relative to [8] (for approximately 89% cases estimated with (5) and (7) with the assumption of the uniform distribution of the process, Fig. 4). Such reduction of the sample strategy will be in high demand for online inspection with CNC machine, where the suspected part can be corrected immediately.

6 References

1. L.De Chiffre, Hansen H.N., Andreasen J.L., Savio E., Carmignato S., (2015) Geometrical Metrology and Machine Testing, DTU Mechanical Engineering
2. Hong-Tznong Yau, Chia-Hsiang Menq (1992) An automated dimensional inspection environment for manufactured parts using coordinate measuring machines. *Int. J. Prod. Res.*, 31(11): p. 1517-1536
3. Bernard C.J., Sheng-Dian Chiu (2002) Form tolerance-based measurement points determination with CMM. *Journal of Intelligent Manufacturing*, 13(2): p. 101-108
4. Cappetti N., Naddeo A., Villecco F. (2016) Fuzzy approach to measures correction on Coordinate Measuring Machines: The case of hole-diameter verification. *Measurement*, 93 (Elsevier Ltd.): p. 41-47
5. Changcai Cui, Shiwei Fu, Fugui Huang (2008) Research on the uncertainties from different form error evaluation methods by CMM sampling. *Int. J. Adv. Manuf. Technol.*, 43: p. 136-145
6. Barbato G., Barini E. M., Pedone P., Romano D., Vicario G. (2008) Sampling point sequential determination by kriging for tolerance verification with CMM, in *Proceedings of the 9th Biennial ASME Conference on Engineering Systems Design and Analysis, ESDA08*, ASME: Israel, p. 10
7. Ruffa S., Panciani G.D., F. Ricci, and Vicario G. (2013) Assessing measurement uncertainty in CMM measurements: comparison of different approaches. *Int.J.Metrol. Qual. Eng.* 4: p. 163-168.
8. Chelishchev P., Popov A., Sørby K. (2018) Robust estimation of optimal sample size for CMM measurements with statistical tolerance limits, in *ICMSC 2018 The 2nd International Conference on Mechanical, System and Control Engineering, MATEC Web of Conferences*, p. 5
9. ISO14405-1 (2016) Geometrical product specifications (GPS) — Dimensional tolerancing, in Linear sizes.
10. Hertzold G. (2006) *Geometrical Dimensioning and Tolerancing for Design, Manufacturing and Inspection : A Handbook for Geometrical Product Specification using ISO and ASME standards*. 2nd ed. ed. Geometrical dimensioning and tolerancing for design, manufacturing, and inspection, Burlington: Elsevier Science.
11. Raghunandan, R. and Venkateswara P. Rao (2008) Selection of sampling points for accurate evaluation of flatness error using coordinate measuring machine. *Journal of Materials Processing Tech.*, 202(1): p. 240-245.
12. Alexandre B.T. (2009) *Introduction to Nonparametric Estimation*. Springer-Verlag, New York
13. Ronald E.W., Raymond H.M., Sharon L.M., Keying Ye (2007) *Probability & Statistics for engineers & scientists*. Eighth ed., Pearson.
14. ISO286-1 (2010) Geometrical product specifications (GPS) — ISO code system for tolerances on linear sizes, in Part 1: Basis of tolerances, deviations and fits