

Numerical investigation of heat transfer in a CO₂ two-phase ejector

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Abstract

In this paper, the influence of heat transfer in the walls of an R744 two-phase ejector on ejector performance was investigated. A numerical investigation was performed using a computational fluid dynamic (CFD) model of the R744 two-phase flow coupled with the heat transfer inside the ejector. An ejector equipped with thermocouple channels was designed and manufactured to investigate temperature distribution in the inner walls under boundary conditions typical for a refrigeration and air-conditioning application in a supermarket. The ejector was installed on the test rig to perform a test series that evaluated the outer walls of the ejector with and without insulation. The experimental results were used to validate the proposed CFD model, and a numerical investigation was performed to analyse the influence of heat transfer on ejector performance. The motive nozzle and suction nozzle mass flow rates accuracies were within $\pm 7\%$ and $\pm 15\%$, respectively. In addition, the proposed CFD model predicted the wall temperatures with ± 5 K accuracy for most of the validated points. The heat transfer coefficient of the R744 two-phase flow inside the ejector is presented. The non-adiabatic inner walls degraded ejector performance. The maximum reduction of the mass entrainment ratio reached approximately 13%.

Keywords: carbon dioxide, heat transfer, CFD model, two-phase ejector, heat transfer coefficient, experimental investigation

Nomenclature

c specific heat, J/(kg·K)

E total enthalpy, J/kg

GCI grid convergence index, -

h total specific enthalpy, J/kg

HTC heat transfer coefficient, W/(m²·K)

k thermal conductivity, W/(m·K)

\dot{m} mass flow rate, kg/s

p pressure, Pa

T temperature, K

\mathbf{u} velocity vector, m/s

q heat flux, W/m²

\dot{W} expansion work rate, W

x vapour quality, -

Greek Symbols

α void fraction

χ mass entrainment ratio

Δ absolute difference

δ relative difference, %

η ejector efficiency, %

μ dynamic viscosity, Pa·s

ϕ non dimensional pressure difference, -

ρ density, kg/m³

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34	τ stress tensor, N/m ²	42	<i>HT</i> heat transfer
35	θ relaxation time, s	43	<i>MN</i> motive nozzle
36	<i>Subscripts</i>	44	<i>NAD</i> non-adiabatic wall
37	<i>AD</i> adiabatic wall	45	<i>OUT</i> ejector outlet
38	<i>CFD</i> computational fluid dynamics	46	<i>SN</i> suction nozzle
39	<i>EJ</i> ejector	47	<i>SWT</i> standard wall function
40	<i>EXP</i> experimental data	48	<i>VAR</i> variable
41	<i>EWT</i> enhanced wall function		

49 1. Introduction

50 Recently legislated regulations of the European Union and the declarations agreed on at the COP21 conference
51 in Paris require replacing a common synthetic refrigerant, i.e., hydro-fluorocarbons (HFCs), with environmentally
52 friendly and natural modern synthetic refrigerants [1]. Because of its non-flammability, non-toxicity and satisfac-
53 tory thermal properties, carbon dioxide (denoted as R744) is one of the most frequently adopted refrigerants in
54 modern commercial refrigeration systems [2]. Modern CO₂-based refrigeration systems have been widely intro-
55 duced in Scandinavia [3] and in northern and central USA [4]. The modification of the R744 refrigeration system
56 configuration facilitates using such systems in hot climates at a competitive energy performance level compared
57 to HFC-based systems [5]. One approach to improving the system coefficient of performance (COP) is the intro-
58 duction of a two-phase ejector as the primary expansion device [6].

59 The main aim of the ejector is to entrain the low-pressure suction stream by the supersonic expanded high-
60 pressure motive stream and thus to transfer the kinetic energy of the mixed flow into the pressure energy. There-
61 fore, the outlet pressure of the mixed stream is higher than the suction pressure. The integration of a two-phase
62 ejector into the R744 refrigeration system improves system energy performance up to 18% compared to the refer-
63 ence standard R744 direct expansion system [7]. The CO₂ ejector-based system has been investigated for different
64 applications: heat pump [8], air-conditioning [9] and refrigeration, particularly for supermarkets [10]. These the-
65 oretical and experimental investigations indicate a high potential for improving the energy performance of a R744
66 refrigeration system equipped with a two-phase ejector. However, because of the complexity of the physical phe-
67 nomena that occur inside the two-phase ejector, the ejector design must be based on a complex mathematical
68 model to work at high efficiency [11].

69 The CFD model of the R744 ejector based on a homogeneous equilibrium model (HEM) was presented by
70 Lucas et al. [12] and Smolka et al. [13]. Both proposed CFD models assumed adiabatic inner walls. In Lucas et al.
71 [12], the numerical model was implemented using OpenFOAM open-source software, and the investigation was
72 performed with and without the suction flow. The proposed model predicted the motive nozzle mass flow rate and
73 the pressure recovery within an error margin of 10% without the suction flow, and the discrepancy of the pressure
74 recovery increased up to 20% when the suction flow was considered. Moreover, the aforementioned two-phase
75 flow approach was successfully implemented for a numerical investigation of the steam ejector by Giacomelli et
76 al. [14]. The authors compared Wet Steam model available in the commercial software Ansys Fluent together with
77 HEM model. According to the results in [14] the HEM approach overestimates the variations of the main quantities
78 during shocks and expansion process, but is more stable and easy to adapt to various fluids.

79 Smolka et al. [13] developed a CFD enthalpy-based energy formulation model of the two-phase ejector with
80 adiabatic walls. The authors implemented an enthalpy-based form and real fluid properties from the REFPROP
81 libraries [15] to simulate the supersonic two-phase flow of carbon dioxide. The application range of HEM for
82 the transcritical CO₂ two-phase ejector at typical supermarket conditions was presented by Palacz et al. [16].
83 The authors stated that motive nozzle and suction nozzle mass flow rate (MFR) accuracies within $\pm 10\%$ were
84 obtained for motive nozzle conditions near and above the critical point. The validated HEM CFD model was
85 used to optimise a two-phase ejector [17]. HEM's high accuracy with respect to transcritical conditions enabled

86 a numerical investigation of the R744 multi-ejector block by Bodys et al. [18]. A multi-ejector module equipped
87 with four fixed-geometry ejectors was designed and manufactured in cooperation with SINTEF-SUT-DANFOSS
88 based on the CFD model developed by Smolka et al. [13]. In addition, a multi-ejector model was manufactured,
89 and performance mapping of each ejector was performed under refrigeration system operating conditions by
90 Banasiak et al. [19].

91 Numerical investigations performed using the HEM CFD model of the two-phase ejector facilitate simulating
92 real two-phase flow behaviour under transcritical conditions with high accuracy. However, the analysis of the R744
93 two-phase ejector in the subcritical region requires a more advanced numerical model. Palacz et al. [20] compared
94 the homogeneous relaxation model (HRM) with HEM to determine the accuracy improvement for operating condi-
95 tions below the critical point. The authors implemented an additional vapour mass balance equation based on
96 the numerical approach presented by Bilicki and Kestin et al. [21]. In addition, the relaxation time was defined ac-
97 cording to the definition proposed by Angielczyk et al. [22] for the CO₂ transcritical flow. The authors stated that
98 the motive nozzle and the suction nozzle mass flow rate accuracies of HRM were higher than those of HEM for the
99 subcritical region, and the discrepancy of HRM increased in the transcritical region. Haida et al. [23] presented
100 a modified HRM of the two-phase flow inside the ejector. The authors modified the constant relaxation time co-
101 efficients to improve model accuracy. The results for the R744 modified HRM two-phase flow inside the ejector
102 confirmed that the application range of the modified HRM under operating conditions typical for supermarket
103 application was extended compared to the HEM for a motive nozzle pressure up to 60 bar.

104 Yazdani et al. [24] used a nonhomogeneous mixture model to describe the R744 supercritical fluid flow inside
105 the ejector. The aforementioned model implemented additional set of equations describing the phase change
106 caused by boiling and cavitation. The $k - \omega$ SST turbulence model was applied. The numerical results in the
107 form of pressure profiles agreed well with the measured data. Furthermore, the difference between the simulated
108 and measured mass entrainment ratios (MER) was below 10%. Liao et al. [25] investigate the two-phase flow in
109 water-steam converging diverging nozzle by use of the two-fluid model incorporating drag and non-drag forces.
110 In addition, the pressure jump across the interface was omitted and only inter-phase heat transfer induced the
111 phase change. the authors stated that the satisfactory prediction of the mass flow rate and cross-section averaged
112 parameters was obtained when compared to the experimental data. Le et al. [26] proposed a two-phase mixture
113 CFD model to simulate flashing flow of the vaporised water in a converging-diverging nozzle. The thermal non-
114 equilibrium effect was implemented by use of the boiling delay model. The numerical results were compared to
115 the experimental data given from literature followed by the detailed sensitivity analysis. The authors stated that
116 the aforementioned model obtained acceptable accuracy of the global and local flow dynamics quantities.

117 The accuracy of the CFD two-phase ejector model is related to the defined turbulence approach. Croquer et al.
118 [27] performed investigation of the $k - \epsilon$ -based and $k - \omega$ -based turbulence models for a R134a ejector. The authors
119 stated that the $k - \epsilon$ with high-Reynolds number formulation and $k - \omega$ SST model in its high- or low-Reynolds
120 number formulation obtained χ deviation of 4%. The similar comparison of turbulence models was also done by
121 Mazzelli et al. [28] for 2D and 3D CFD air ejector model with rectangular cross-section. The investigation was
122 done for $k - \epsilon$, $k - \epsilon$ Realizable, $k - \omega$ SST and Reynolds Stress Model. Besagni et al. [29] compared aforementioned
123 turbulence models with additional $k - \epsilon$ RNG and Spalart-Allmaras turbulence approaches for an air ejector. The
124 detailed investigation for the foregoing turbulence models with different near-wall modelling options for a steam
125 ejector was presented by Besagni et al. [30]. Based on the results presented in [28, 29, 30] the $k - \omega$ SST showed
126 the best agreement in terms of local and global supersonic compressible flow inside the aforementioned ejectors.
127 Varga et al. [31] compared $k - \epsilon$ -based, $k - \omega$ -based and Transition SST turbulence models applied to the steam
128 CFD model. The authors stated that Transition SST model obtained best accuracy of COP and the critical back
129 pressure with the average discrepancy of 4% and 1.4%, respectively.

130 In addition to the numerical investigation of the homogeneous fluid flow assumptions and turbulence models,
131 the influence of friction loss on supersonic ejector performance has been analysed. Brezgin et al. [32] investigated
132 the roughness effect on a supersonic ejector using a CFD model for organic working fluid R245fa. The authors
133 stated that for given boundary conditions and ejector geometry, the performance rapidly decreased when a crit-
134 ical roughness height was exceeded. Mazzelli et al. [33] presented numerical simulations of the R245fa ejector
135 for an industrial chiller application based on an internal dynamics analysis. The authors concluded that surface
136 roughness strongly influenced the mass flow rate prediction of the CFD model compared to experimental data,
137 particularly for off-designed operating conditions. A similar conclusion was reported by Zhang et al. [34], who nu-

138 merically investigated the effect of friction on R134a supersonic ejector performance and found that an increase in
139 surface roughness rapidly decreased the mass entrainment ratio. In addition, the higher roughness of the ejector
140 wall surfaces changed the temperature and the Mach number of the flow inside the ejector.

141 Milazzo et al. [35] presented the influence of a different constant wall temperature and roughness on R245fa
142 ejector performance. The authors performed numerical simulations near the critical point of the two-dimensional
143 axisymmetric CFD ejector model. The change in the constant wall temperature resulted in a different mass en-
144 trainment ratio. Additionally, the heat transfer coefficient (HTC) along the axis at the ejector wall was presented
145 in [35]. The authors stated that the heat loss towards the ambient should be considered for a precise sizing of the
146 condenser and that the ejector's inner surfaces cannot be considered adiabatic.

147 In addition to friction loss and inner wall temperature investigations of the ejector, non-adiabatic wall analysis
148 has been performed for different expansion devices, e.g., a capillary tube. Numerical simulations of the R134a flow
149 through non-adiabatic capillary tubes were performed in [36]. The authors proposed a theoretical mathematical
150 model to consider the heat exchange between walls and a single or a two-phase flow of the working fluid. The
151 model was validated and used to design a non-adiabatic capillary tube. Agrawal et al. [37] investigated the effect
152 of a gas cooler and evaporator temperatures on R744 non-adiabatic capillary tube performance. The analysis also
153 considered capillary tube diameter and heat exchanger length. The authors stated that a shorter inlet adiabatic
154 capillary length and a longer non-adiabatic capillary length increased the heat transfer rate.

155 The main aim of this paper is to investigate the influence of heat transfer within a CO₂ two-phase ejector on
156 ejector performance. To the best knowledge of the authors, there is no such analysis in the literature. Therefore,
157 numerical simulations were performed of forced convection, heat conduction in the ejector body and the free
158 convection of the surroundings. The CO₂ two-phase flows within the ejector were simulated based on the modi-
159 fied HRM proposed by Haida et al. [23]. The R744 two-phase ejector was designed and manufactured in Gliwice,
160 Poland to experimentally investigate the inner wall temperatures. To validate the developed CFD model, an ex-
161 perimental test series was performed on the CO₂ ejector test rig at the NTNU/SINTEF Energy Research laboratory
162 in Trondheim, Norway. The sensitivity analysis of the wall conductivity, roughness, HTC of the free stream air and
163 turbulence model on the inner wall temperature distribution was done. In addition, the heat transfer coefficient
164 of the motive nozzle, suction nozzle and mixed streams under different operating conditions is presented.

165 2. R744 two-phase ejector for inner walls temperature measurement

166 Figure 1 presents the R744 two-phase ejector designed and manufactured by Institute of Thermal Technology
167 in Gliwice, Poland, to facilitate measuring the wall temperature close to the inner surface of the ejector. The
168 ejector was assembled from three parts: the motive nozzle, the suction nozzle together with the mixer and the
169 diffuser and finally the outlet port. The suction nozzle was designed as a tangential inlet to connect the nozzle
170 with the test rig. Therefore, the suction stream swirled in the suction chamber. Moreover, the aforementioned
171 part was defined to maintain a cross-section area in the converging part of the suction nozzle. Stainless steel
172 was used to manufacture the motive nozzle and brass for the remaining parts. Eight screws were used to bolt
173 the ejector. Swagelok connectors were used to connect the inlet and outlet ports with the test rig pipelines. In
174 addition, thirteen small holes were drilled throughout the ejector to facilitate inserting thermocouples for inner
175 wall temperature measurements.

176 The placement of the temperature probes is shown in Figure 2. The position of the sensors was selection to
177 avoid the influence of the nearest thermocouple on a single measurement. Therefore, two characteristic sections
178 were selected (Figure 2(a)). The thermocouples were placed to measure the wall temperature in the motive inlet,
179 in the suction inlet, between the converging-diverging nozzle and the converging suction nozzle, in the pre-mixer,
180 in the mixer and in the diffuser. The distance between the inner wall surface and the probes was 2 mm. The total
181 number of thermocouple channels was thirteen. The main geometric parameters of the two-phase ejector are
182 presented in Table 1. The ejector was designed based on the dimensions presented by Banasiak et al. [38] for
183 the smallest ejector called *Case 1*.

184 The designed and manufactured R744 ejector allows for the experimental investigation of the inner wall tem-
185 perature profile at different operating and ambient conditions. Hence, the ejector was firstly tested by performing
186 the pressure test using a nitrogen at 140 bar to avoid any leakage inside the ejector before it was connected to the

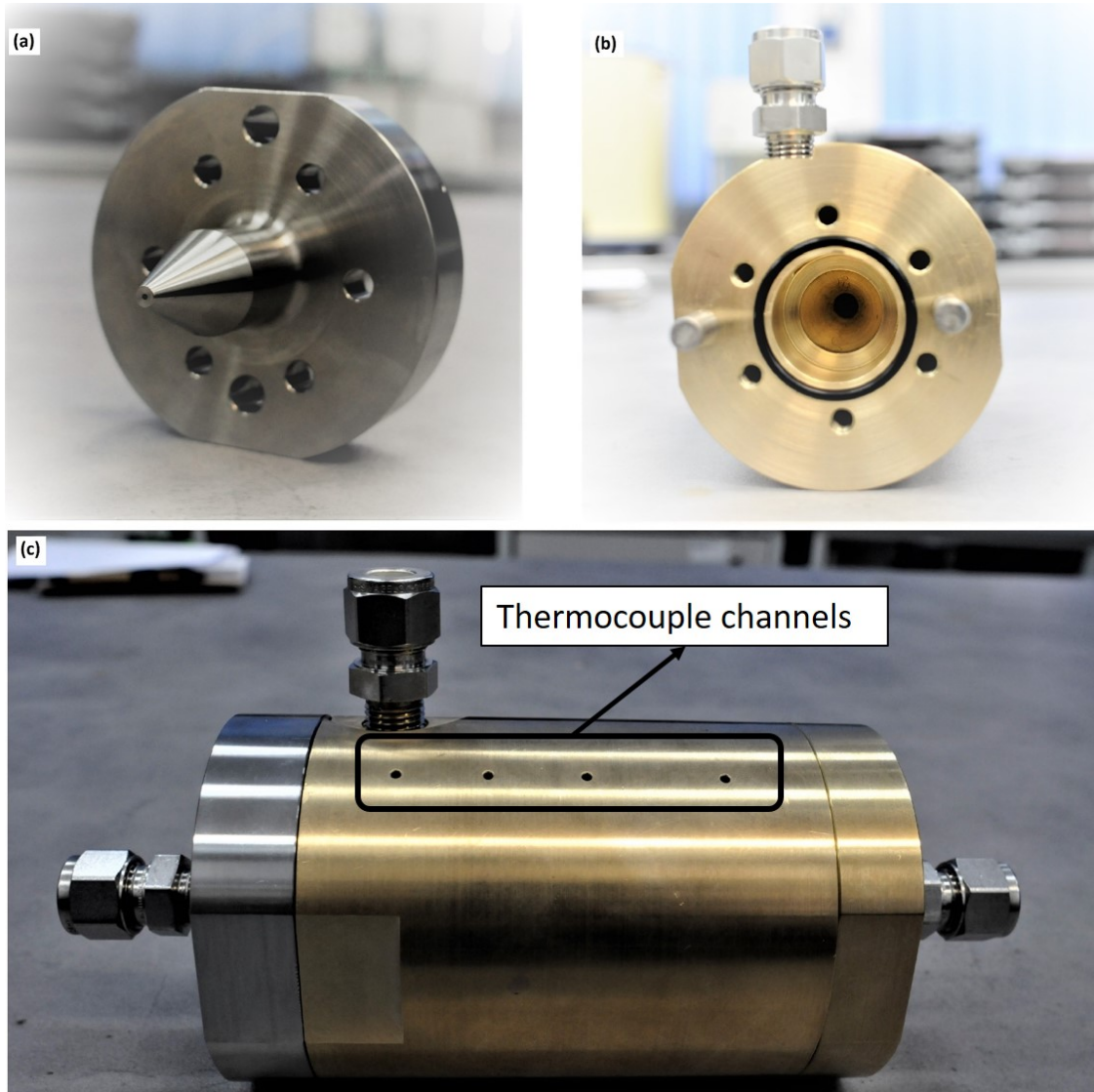


Figure 1: The R744 two-phase ejector for inner walls temperature measurement: (a) the motive nozzle; (b) the suction nozzle together with the mixing chamber and the diffuser; (c) the assembly with the thermocouples channels.

187 system. Then, the ejector was implemented to the test rig at the SINTEF/NTNU laboratory in Trondheim, Norway
 188 for a test campaign.

189 3. R744 two-phase ejector test series

190 The test rig was a R744 vapour compression unit, which facilitates the implementation of different expansion
 191 devices, e.g., an ejector, an expansion valve or a capillary tube [8, 13, 39, 40]. The simplified lay-out of the test rig
 192 with the measurement equipment was shown in Figure 3. The R744 loop of the system contains a semi-hermetic
 193 reciprocating compressor, two brazed plate heat exchangers working as a gas cooler (gc) and an evaporator (ev),
 194 an internal heat exchanger (IHX), a separator and the ejector for inner walls temperature measurement. The
 195 compressor was connected to the inverter, whereby the discharge pressure was set to accommodate different
 196 compressor frequencies. The discharge pressure varied in the range from 70 bar to 110 bar to analyse the ejector

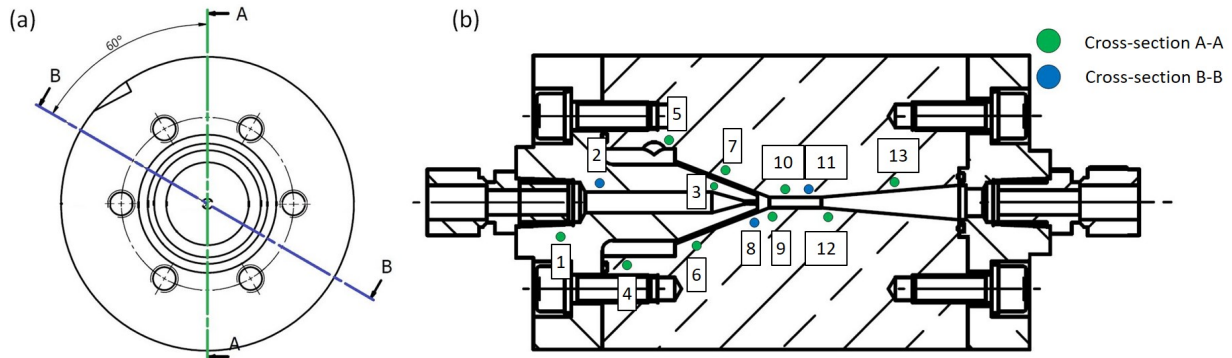


Figure 2: The thermocouples localisation in the R744 two-phase ejector: (a) selected cross-sections for thermocouple channels; (b) probes localisation along ejector axis.

Table 1: The main geometry parameters of the R744 two-phase ejector.

Parameter name	Unit	Dimension
Motive nozzle inlet diameter	10^{-3} m	6.00
Motive nozzle throat diameter	10^{-3} m	0.75
Motive nozzle outlet diameter	10^{-3} m	1.05
Motive nozzle converging angle	$^{\circ}$	30.00
Motive nozzle diverging angle	$^{\circ}$	2.00
Suction chamber diameter	10^{-3} m	31.00
Suction chamber length	10^{-3} m	21.10
Suction converging angle	$^{\circ}$	42.00
Pre-mixer length	10^{-3} m	3.50
Mixer length	10^{-3} m	15.00
Diffuser outlet diameter	10^{-3} m	8.00
Diffuser angle	$^{\circ}$	5.00
Outer wall diameter	10^{-3} m	75.00
Outer wall length	10^{-3} m	155.00
Outer brass wall length	10^{-3} m	130.00

197 performance for transcritical and close to critical point operating conditions. The evaporator pressure was controlled by the metering expansion valve. The evaporation temperature was set to -10°C and 0°C typical for cooling application and air-conditioning application in the supermarket [41]. The two-phase ejector was connected to the test rig using Swagelok connectors. Therefore, the expanded motive stream and entrained suction stream entered the separator tank at a higher pressure than the evaporation pressure.

202 The auxiliary glycol loops (gl) were used to provide cooling and heating in the gas cooler and in the evaporator. Each glycol loop is equipped with the glycol pump, an electric heat exchanger (EHX) and a glycol tank. The concentration of the glycol was set to approximately 50% to ensure the required operating conditions of the ejector. In addition, the test rig was equipped with the oil recovery loop to ensure the limitation of the oil concentration in the working fluid and ensure the safety oil level in the compressor.

207 The test facility was fully equipped with pressure, temperature and the mass flow-rate sensors, for which the

208 accuracies were adopted from the product data sheets. The temperature was measured in the nozzles and outlet
 209 collectors by PT100 class A resistance thermometers with an accuracy of $\pm(0.15 + 0.002 T)$, where T is the tem-
 210 perature in °C. The wall measurements were performed using T-type calibrated thermocouples with a reading
 211 accuracy of $\pm 0.75\%$. A piezoelectric transmitter was used to measure the pressure, with a reading accuracy of
 212 $\pm 0.3\%$. MFR measurement was performed using Coriolis RHM04 and RHM06 transducers, and the reading ac-
 213 curacy was $\pm 0.2\%$. The output signals from the sensors installed in the test rig were processed and transmitted
 214 using a National Instruments control unit to the LabView system. The data were exported as a CSV standard to the
 215 uncertainty analysis.

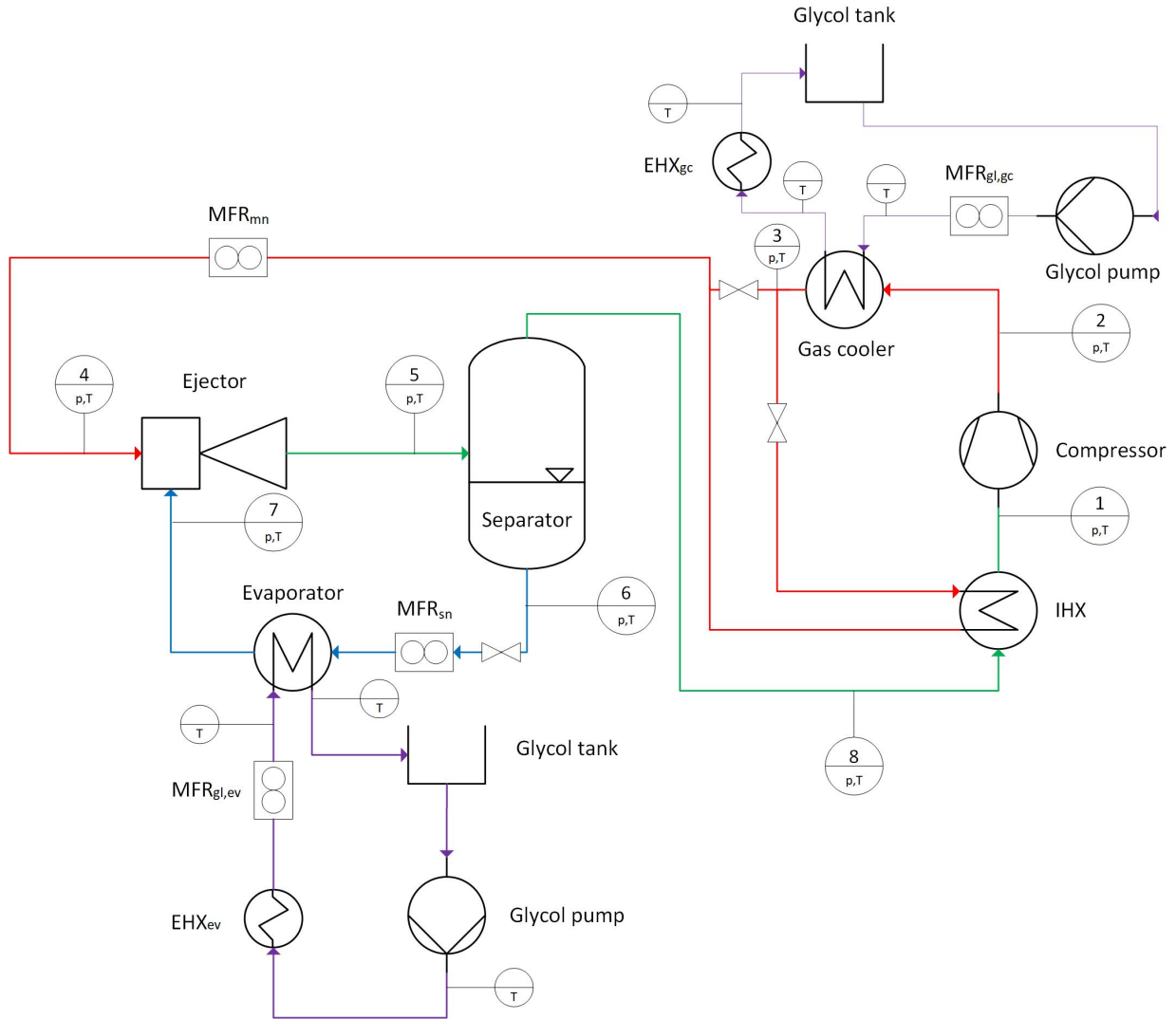


Figure 3: The simplified P&ID diagram of the R744 vapour compression test rig equipped with the ejector for inner walls temperature measurement: EHX - electric heat exchanger, IHX - internal heat exchanger.

The test series was performed to determine the transcritical and near-critical point operating conditions of the motive nozzle for a set of temperature differences between the motive nozzle and the suction nozzle. The experimental results were used for a mesh sensitivity analysis and to validate the R744 two-phase ejector CFD model.

$$\Delta T = T_{MN} - T_{SN} \quad (1)$$

216 where Δ is the absolute difference and T is the temperature in °C of the motive nozzle (MN) and the suction nozzle
 217 (SN). Moreover, the test campaign of the R744 two-phase ejector was done for two variants:

- 218 • Fully insulated outer walls
- 219 • The outer walls without an insulation

220 The foregoing variants allows the influence of the non-adiabatic outer walls on the R744 two-phase flow and
 221 the ejector performance. The experimental results were used for a mesh sensitivity analysis and a validation pro-
 222 cedure of the R744 two-phase ejector CFD model.

223 4. Numerical approach

224 The proposed numerical model of the CO₂ two-phase ejector simulated two-phase supersonic flow behaviour
 225 together with the heat transfer process that occurs between the high-temperature motive fluid and low-temperature
 226 suction fluid and inside ejector walls. In addition, the different ambient conditions and the conductivity of the
 227 outer ejector walls were considered in the proposed model. The CFD model approach together with the computa-
 228 tional procedure was described in Section 4.1. The influence of the heat transfer on the ejector performance can
 229 be shown by use of HTC. Hence, the calculation of HTC for each ejector component was presented in Section 4.2.

230 4.1. CFD model

The homogeneous relaxation flow assumption simplifies the numerical model to the equations that govern
 the mass, momentum, energy and vapour mass balance of the relaxation mixture. In addition, steady-state com-
 putations were performed for each operating condition. Therefore, all of the time derivatives in the governing
 equations were omitted. The mass balance is described as follows:

$$\nabla \cdot (\bar{\rho} \bar{\mathbf{u}}) = 0 \quad (2)$$

where the symbols $(\bar{\cdot})$ and $(\tilde{\cdot})$ denote the Reynolds- and Favre-averaged quantities, respectively. In addition, ρ
 is the fluid density in kg/m³ and \mathbf{u} is the fluid velocity vector in m/s. The momentum balance is defined by the
 following equation:

$$\nabla \cdot (\bar{\rho} \bar{\mathbf{u}} \bar{\mathbf{u}}) = -\nabla \bar{p} + \nabla \cdot \bar{\boldsymbol{\tau}} \quad (3)$$

where p is the pressure of the mixture fluid in Pa and $\boldsymbol{\tau}$ is the stress tensor in N/m². The vapour mass balance
 equation is described in the following form [21]:

$$\nabla \cdot (\bar{\rho} \bar{x}) = -\bar{\rho} \left(\frac{\bar{x} - \bar{x}_{eq}}{\bar{\theta}} \right) \quad (4)$$

where x is the instantaneous vapour quality of the two-phase flow, x_{eq} is the vapour quality at the equilibrium
 state and θ is the relaxation time in s. According to Haida et al. [23] the relaxation time for CO₂ two-phase flow is
 defined by the following equation:

$$\bar{\theta} = \theta_0 \cdot \bar{\alpha}^a \cdot \bar{\phi}^b \begin{cases} \theta_0 = 1.0e-07 & a = 0.0 & b = 0.0 & p_{mn} = 73.77 \text{ bar} \\ \theta_0 = 9.0e-06 & a = -0.67 & b = -1.73 & 59 \text{ bar} \leq p_{mn} \leq 73.77 \text{ bar} \\ \theta_0 = 1.5e-06 & a = -0.67 & b = -2.00 & p_{mn} \leq 59 \text{ bar} \end{cases} \quad (5)$$

where θ_0 , a and b are the constant relaxation time coefficient defined for different motive nozzle pressure ranges
 p_{mn} , α is the void fraction and ϕ is the non-dimensional pressure difference defined as follows:

$$\bar{\alpha} = \frac{\bar{x} \cdot \bar{\rho}}{\bar{\rho}_v} \quad (6)$$

$$\bar{\phi} = \left| \frac{\bar{p}_{sat} - \bar{p}}{p_{crit} - \bar{p}_{sat}} \right| \quad (7)$$

where ρ_v is the density of the saturated vapour, p_{sat} is the saturation pressure based on the motive nozzle inlet conditions and p_{crit} is the critical pressure of CO₂. According to Smolka et al. [13], the temperature-based form of the energy equation can be replaced by the enthalpy-based form. Hence, the energy balance of the R744 two-phase flow can be defined as follows:

$$\nabla \cdot (\rho \tilde{\mathbf{u}} \tilde{E}) = \nabla \cdot \left[\left(\frac{k_f}{\frac{\partial h}{\partial T}} \right)_p \nabla \tilde{h} - \left(\frac{k_f}{\frac{\partial h}{\partial T}} \right)_p \left(\frac{\partial h}{\partial p} \right)_T \nabla \tilde{p} + \tilde{\boldsymbol{\tau}} \cdot \tilde{\mathbf{u}} \right] + \tilde{q}_v \quad (8)$$

where T is the mixture temperature in K, k_f is the fluid thermal conductivity in W/(m·K), q_v is the heat source in W/m³ and E is the total specific enthalpy in J/kg defined as a sum of the specific mixture enthalpy and the kinetic energy:

$$\tilde{E} = \tilde{h} + \frac{\tilde{u}^2}{2} \quad (9)$$

where h is the mixture specific enthalpy in J/kg. The enthalpy-based form of the energy equation let to define fluid properties as a function of the pressure and specific enthalpy:

$$\{\rho, \mu, k_f, c_p\} = f(p, h) \quad (10)$$

where μ is the dynamic viscosity in Pa·s and c_p is the specific heat in J/(kg·K). The pressure-based boundary conditions were used for the motive nozzle and suction nozzle inlets and the outlet of the two-phase ejector. The heat transfer in the ejector walls was simulated using heat conduction equation in the following form:

$$\nabla (k_w \cdot \nabla T) = 0 \quad (11)$$

231 where k_w is the ejector wall thermal conductivity in W/(m·K). The foregoing heat conduction equation was im-
 232 plemented using the user-defined scalar (UDS) in Ansys Fluent software. The conjugate heat transfer method was
 233 used to couple heat transfer with the two-phase flow based on fourth kind boundary conditions. The near-wall
 234 fluid temperature was defined as a boundary condition of the ejector inner walls for the conductivity process. In
 235 two-phase flow, the local heat rate obtained due to the conductivity process between the ejector walls was im-
 236 plemented in the enthalpy-based equation as a heat source at each fluid cell. Therefore, the model defined the
 237 continuity of temperature and heat flux at the interface between the fluid and the solid sub-domains. Additionally,
 238 the fourth kind boundary condition facilitated defining the inner ejector walls as non-adiabatic or adiabatic walls.
 239 The outer ejector walls were defined as insulated walls with heat flux equal to zero or using the convection-type
 240 boundary condition. The ambient temperature was measured during the test series, and the heat transfer coef-
 241 ficient of air was assumed to be 5 W/(m²·K). As a result of the different heat transfer boundary conditions on the
 242 inner and outer ejector walls, four heat transfer variants was defined as follows:

- 243 • HT-1 - adiabatic inner walls and adiabatic outer walls
- 244 • HT-2 - non-adiabatic inner walls and adiabatic outer walls
- 245 • HT-3 - adiabatic inner walls in the motive nozzle part, non-adiabatic inner walls in the suction nozzle, mixer
 246 and diffuser and non-adiabatic outer walls
- 247 • HT-4 - non-adiabatic inner and outer walls

248 Finally, the coupled mathematical model of the two-phase flow together with the non-adiabatic ejector walls
 249 was defined. An implementation of the heat transfer in the ejector walls increased the computational time of
 250 the CFD model. As an example, the total computational time for 3-D CFD model was of approximately 14 hours
 251 with and approximately 10 hours without the ejector walls heat transfer, respectively. The difference between the
 252 solving times was affected by the solid domain consideration in the proposed model. A numerical approach was
 253 implemented in the discretised domain of the R744 two-phase ejector to perform the numerical computations un-
 254 der specified operating conditions, heat-transfer wall conditions and ambient conditions. The set of the boundary

Table 2: The set of the boundary conditions types in the R744 two-phase ejector.

Boundary name	Flow boundary	Turbulence boundary	Solid boundary
MN Inlet	$P_{MN}, T_{MN}, h_{MN}, q_{MN}$	Hydraulic diameter, turbulence intensity	-
SN Inlet	$P_{SN}, T_{SN}, h_{SN}, q_{SN}$		
Outlet	P_{out}	-	
Steel inner wall	Conjugate heat transfer	Wall function	Conjugate heat transfer
Brass inner wall			
Steel outer wall	-	-	Heat flux
Brass outer wall			

255 conditions types was shown in Table 2. The boundary conditions were defined for flow, turbulence and solid walls
 256 boundaries types.

257 The partial differential equations of the mathematical model were solved based on the PRESTO scheme for the
 258 pressure discretisation and the second-order upwind scheme for the other variables considered in the CFD model.
 259 The coupled method was employed for the coupling of the pressure and velocity fields. The set of the numerical
 260 schemes was listed in Table 3

Table 3: The set of the numerical schemes of the CFD model.

Discretisation	Scheme
Pressure-velocity coupling	Coupled algorithm [42]
Gradient	Green-gauss cell based
Momentum	Second-order upwind
Pressure	PRESTO! [42]
Density	
Energy [13]	Second-order upwind
Vapour mass balance [23]	
Heat conduction	
Turbulence kinetic energy	
Specific dissipation rate	
Intermittency (Transition SST)	Second-order upwind
Momentum thickness Reynolds number (Transition SST)	
Reynold stresses (Reynold Stress Model)	

261 The turbulence model was chosen based on the CFD model verification presented and discussed in Section
 262 5.2. The wall roughness was set to 2 μm according to the ejector manufacturers. The real fluid properties of
 263 R744 were approximated based on the data obtained using the REFPROP libraries [15]. Moreover, the physical
 264 properties of the CO₂ two-phase flow were calculated as a function of the pressure and specific enthalpy due to
 265 the enthalpy-based energy formulation defined in Eq. (8):

$$\{\rho, c_p, k_f, \mu\} = f(p, h) \quad (12)$$

where c_p is the specific heat capacity in J/(kg·K) and μ is the dynamic viscosity in Pa·s. The foregoing function allows for the R744 flow calculation in single- and two-phase flow conditions for subcritical, transcritical, and close to the critical operating conditions [13, 16]. The thermal conductivity of the stainless steel and brass was set to 16 W/(m·K) and 109 W/(m·K), respectively.

The proposed CFD model was used to analyse heat transfer in the R744 two-phase ejector and the influence of the ejector design and the temperature difference between both nozzles on ejector performance. The ejector work is described using the mass entrainment ratio and ejector efficiency definitions. The mass entrainment ratio is the ratio between the suction nozzle MFR and the motive nozzle MFR:

$$\chi = \frac{\dot{m}_{SN}}{\dot{m}_{MN}} \quad (13)$$

where χ is the mass entrainment ratio and \dot{m} is the mass flow rate of the motive nozzle (MN) and the suction nozzle (SN). The ejector efficiency was defined by Elbel et al. [6] as a ratio of the amount of the recovered ejector expansion work rate to the maximum possible expansion work rate recovery potential:

$$\eta_{ej} = \frac{\dot{W}_{rec}}{\dot{W}_{rec,max}} = \chi \cdot \frac{h(p_{out}, s_{SN}) - h(p_{SN}, s_{SN})}{h(p_{out}, s_{MN}) - h(p_{MN}, s_{MN})} \quad (14)$$

where η_{ej} is the ejector efficiency, \dot{W} is the expansion work rate in W and s is the specific entropy in J/(kg·K). In this paper, the mass entrainment ratio and ejector efficiency were used to analyse the heat-transfer influence on the R744 two-phase flow performance under operating conditions typical for refrigeration and air-conditioning applications. Therefore, the CFD two-phase ejector model was validated with the experimental data to ensure the high accuracy of the numerical model. The accuracy of the proposed CFD model was calculated as the relative error between the experimental data and the model result:

$$\delta_{var} = \frac{var_{CFD}}{var_{EXP}} - 1 \quad (15)$$

where δ_{var} is the relative error of the selected two-phase flow parameter obtained by the CFD model or given by the experimental data.

4.2. Heat transfer coefficient calculations

The heat transfer behaviour between the CO₂ two-phase flow and the ejector walls can be determined by HTC. The evaluation of the heat transfer coefficient within the R744 ejector facilitated the proper selection of the wall material and the consideration of the heat transfer in ejector shape design. In the motive nozzle, HTC can be defined in the following form:

$$HTC = \left(\frac{\dot{q}}{|T_{wall} - T_{stream}|} \right) \quad (16)$$

where HTC is the heat transfer coefficient in W/(m²·K) and \dot{q} is the heat flux in W/m². The temperature T_{wall} is the local wall temperature and T_{stream} is the local fluid temperature. The heat flux was given for each inner wall, whereas the local wall temperature and the local fluid temperature were taken from the inner walls and close to the inner walls, respectively. The Newton's law of cooling presented in Eq. (16) was also used for the suction nozzle, the mixer and the diffuser part of the two-phase ejector.

Finally, the proposed CFD model was verified and validated based on the experimental data obtained for the manufactured R744 two-phase ejector. Therefore, the experimental results and the numerical investigation are presented in this paper to analyse the heat transfer in the CO₂ two-phase ejector.

5. Results and discussion

5.1. Experimental results

Table 4 presents the experimental data of the R744 two-phase ejector with insulated outer walls. The motive nozzle boundary conditions varied in a range from approximately 75 bar and 290 K to over 106 bar and 306 K.

302 Therefore, the investigated region included ejector operation under transcritical and near-critical operating con-
303 ditions. The suction nozzle pressure was between approximately 27 bar and 37 bar, and the temperature was
304 above the evaporation temperature for each boundary condition. Additionally, the pressure difference between
305 the ejector outlet and the suction nozzle was below 4 bar. The test series was performed with ΔT in a range from
306 8 K to approximately 28 K to investigate the influence of the nozzle temperatures on the wall temperature dis-
307 tribution. Finally, the two-phase ejector exhibited a mass entrainment ratio between approximately 0.4 and 0.56
308 as the result of the small difference between the ejector outlet and the suction nozzle. In addition, the highest
309 ejector efficiency was approximately 12% for #AD8 at a motive nozzle pressure above 90 bar and the highest ΔT of
310 approximately 28 K. Due to the fact that the presented investigation was strongly focused on the different ΔT and
311 motive nozzle conditions, the ejector efficiency was a secondary effect of the experimental tests.

Table 4: The set of the experimental data of the R744 two-phase ejector with adiabatic (AD) outer walls.

BC	P_{MN} bar	T_{MN} K	P_{SN} bar	T_{SN} K	P_{out} bar	ΔT K	χ -	η_{ej} %
#AD1	87.4	294.8	38.8	283.2	39.5	11.6	0.6	6.1
#AD2	90.4	294.2	37.0	280.4	39.5	13.8	0.6	9.6
#AD3	83.7	302.3	33.4	283.9	34.9	18.4	0.5	9.2
#AD4	106.3	306.9	36.6	280.5	39.0	26.4	0.6	11.8
#AD5	91.4	300.0	35.8	291.8	37.5	8.2	0.5	11.2
#AD6	78.9	296.8	33.6	284.4	35.0	12.3	0.4	9.7
#AD7	75.3	299.3	27.5	283.9	29.0	15.4	0.4	9.9
#AD8	97.1	304.9	27.3	276.9	29.7	27.9	0.5	12.1

312 Table 5 presents the experimental data of the R744 two-phase ejector without outer wall insulation. Similar
313 to the results presented in Table 4, the motive nozzle was in a range of approximately 71 bar to over 100 bar.
314 However, the suction nozzle pressure varied between 24 bar and 28 bar with the pressure difference between the
315 ejector outlet below 4 bar. To determine the influence of the two-phase ejector environment on its performance,
316 the ambient temperature was measured. In the investigation presented in Table 5, the ambient temperature varied
317 slightly between 297 K and 298 K, and ΔT ranged from 15 K to approximately 33 K. The mass entrainment ratio
318 of the R744 ejector with non-adiabatic outer walls was between approximately 0.37 and 0.46. Similar to the test
319 series performed with insulated outer walls, the best performance of the R744 two-phase ejector was reached
320 under boundary condition #NAD8 with the motive nozzle pressure above 100 bar and with the highest ΔT of
321 approximately 32 K.

322 The operating conditions given from the test campaign were presented in Figure 4. The motive nozzle condi-
323 tions shown in Figure 4(a) were located close to the critical point, e.g. #NAD1 and #NAD2, but most of the in the
324 transcritical conditions below 110 bar. In addition, the test points were obtained for the motive nozzle tempera-
325 ture in the range from 293.15 K to 313.15 K. The results given from the adiabatic test series were reached for the
326 suction nozzle in the range from 26 bar to 40 bar, as shown in Figure 4(b). The suction nozzle conditions of the
327 non-adiabatic test points varied in the range from 25 bar to 30 bar. Moreover, the suction nozzle temperature of
328 both test series was above 273.15 K and below 293.15 K.

329 Figure 5 presents the experimental results for the wall temperature distribution of the R744 two-phase ejector.
330 The placement of each thermocouple was numbered (Figure 2). The wall temperature distribution is presented
331 under two boundary conditions for the ejector with adiabatic outer walls (#AD1 and #AD5) and under two bound-
332 ary conditions with non-adiabatic outer walls (#NAD2 and #NAD7) defined in Table 4 and in Table 5. The selected
333 boundary conditions obtained different ΔT between 8 K and 26 K and different motive nozzle temperatures in a
334 range from approximately 295 K to 306 K. It can be observed that the motive nozzle reached a higher temperature
335 than the second part of the ejector assembly. In addition, the removal of the adiabatic outer wall influenced the

Table 5: The set of the experimental data of the R744 two-phase ejector with non-adiabatic (NAD) outer walls.

BC	P_{MN} bar	T_{MN} K	P_{SN} bar	T_{SN} K	P_{out} bar	T_{amb} K	ΔT K	χ -	η_{ej} %
#NAD1	71.8	300.9	24.8	285.6	26.5	297.1	15.4	0.4	8.9
#NAD2	71.4	301.0	24.5	274.7	25.9	296.7	26.3	0.4	9.0
#NAD3	83.0	303.0	27.6	284.5	29.6	297.4	18.6	0.4	11.5
#NAD4	80.5	302.5	26.4	277.5	28.4	297.5	24.9	0.4	11.0
#NAD5	94.8	301.5	26.5	284.6	28.3	297.5	16.9	0.5	10.5
#NAD6	92.5	301.7	25.6	273.6	27.4	297.9	28.1	0.5	9.9
#NAD7	101.0	306.3	25.6	284.6	28.4	297.2	22.2	0.4	12.9
#NAD8	100.6	306.8	25.4	274.4	28.3	298.2	32.4	0.4	13.4

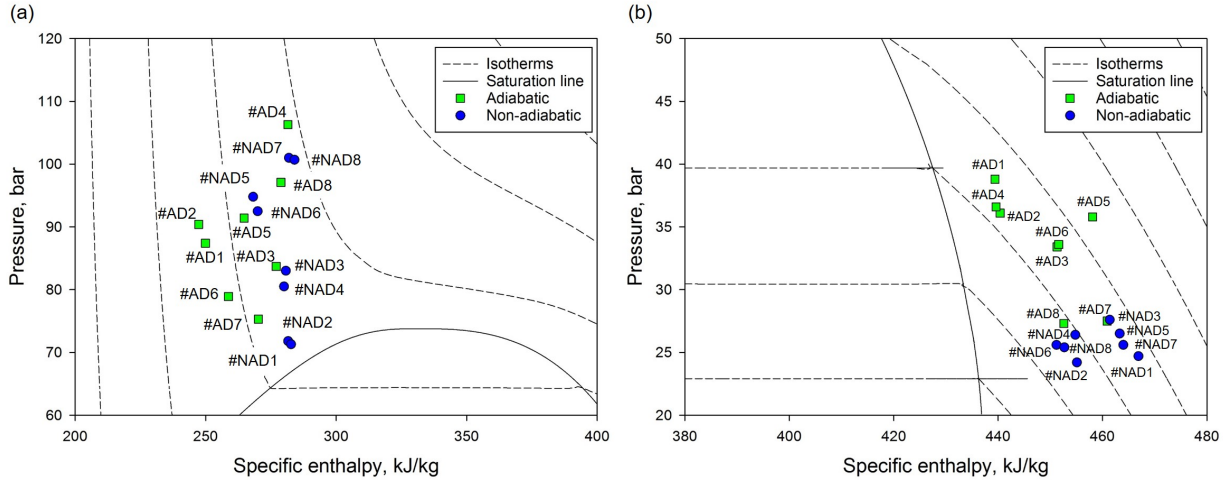


Figure 4: The pressure-specific enthalpy diagram with operating conditions defined in Table 4 and in Table 5: (a) motive nozzle; (b) suction nozzle.

336 temperature distribution close to the inlet of the motive nozzle. The second thermocouple exhibited a slightly
 337 lower temperature than the first probe under boundary conditions #NAD2 and #NAD7. The wall temperature of
 338 the suction nozzle and the mixer together with the diffuser decreased along the ejector axis. It can be observed
 339 that the thermocouples located at the end of the mixer and in the diffuser reached similar temperatures. There-
 340 fore, the influence of heat transfer on the two-phase flow behaviour appeared between the two nozzles and in the
 341 pre-mixing section with respect to the wall temperature distribution.

342 The experimental test series performed on the R744 two-phase ejector confirmed the influence of the ambient
 343 conditions on the wall temperature distribution under different operating conditions, particularly on the motive
 344 nozzle. Therefore, the investigation of the heat-transfer influence on ejector performance using the proposed CFD
 345 enabled us to determine the best solution for ejector efficiency.

346 5.2. Sensitivity analysis of the CFD model

347 As a result of the tangential suction inlet shape of the two-phase ejector, the numerical analysis was done based
 348 on the three-dimensional CFD model. The 3-D two-phase ejector geometry was discretised with a fully structured
 349 grid with a minimum orthogonal quality over 0.6. The numerical grid considered three domains with respect to

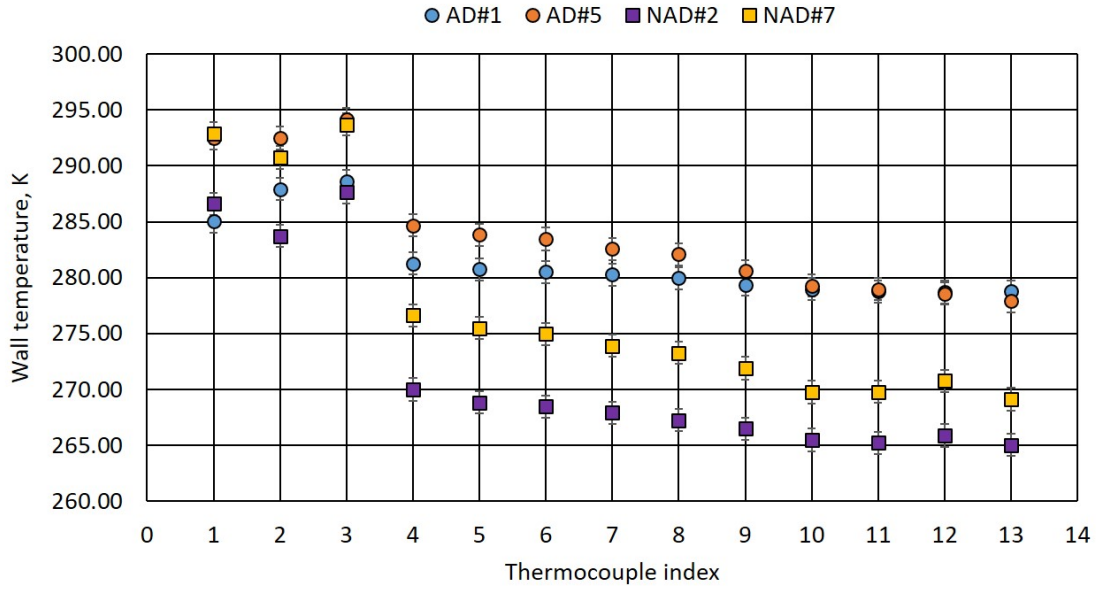


Figure 5: The wall temperature measurements of the R744 two-phase ejector at boundary conditions #AD1, #AD5, #NAD2 and #NAD7 defined in Table 4 and in Table 5.

the two-phase flow and two ejector walls with different materials. The numerical mesh was presented in Figure 6 for each domain and in the cross-section defined by a red dotted line in Figure 6(a) and Figure 6(b).

The results of the ejector mesh independence study are presented in Figure 7. The mesh sensitivity analysis was performed to avoid the influence of the ejector mesh on the global and local parameters, i.e., MFRs and temperature. Therefore, the motive nozzle and the suction nozzle MFRs are presented. In addition, the local temperatures of the motive nozzle are shown in Figure 7. Moreover, the local temperatures of the motive nozzle part were defined in Figure 2. All parameters obtained the similar values for the number of elements above approximately 2.5 millions elements. All parameters exhibited similar values for the number of elements above approximately 2.5 million. It can be observed that the suction nozzle MFR and temperature T_2 located close to the converging-diverging nozzle were the most sensitive parameters and strongly related to the number of mesh elements.

The mesh refinement was performed by increasing the element number at the selected geometrical parameters describing the R744 two-phase ejector as shown in Figure 7(b). The mesh refinement was done mostly in the converging-diverging part of the motive nozzle, converging part of the suction chamber, pre-mixer, mixer and the diffuser. The selected geometrical parameters presented in the cross-sectional view of the ejector defined the element number in the whole mesh with consideration of the boundary layer. In addition, the wall y^+ was calculated during the mesh sensitivity analysis to define the simulation of the near wall two-phase flow for each generated numerical grid. The results of the wall y^+ analysis were the following for the tested meshes:

- $y^+ \approx 45.0$ for 1.5 million elements
- $y^+ \approx 11.0$ for 2.0 million elements
- $y^+ \approx 3.2$ for 2.5 million elements
- $y^+ \approx 0.3$ for 3.0 million elements

The wall y^+ below 5.0 for the mesh above 2.0 millions elements confirmed high accuracy of the CFD results in the whole ejector, especially within the boundary layer. Finally, the numerical grid with 2.5 million elements was chosen for the validation procedure and further investigations.

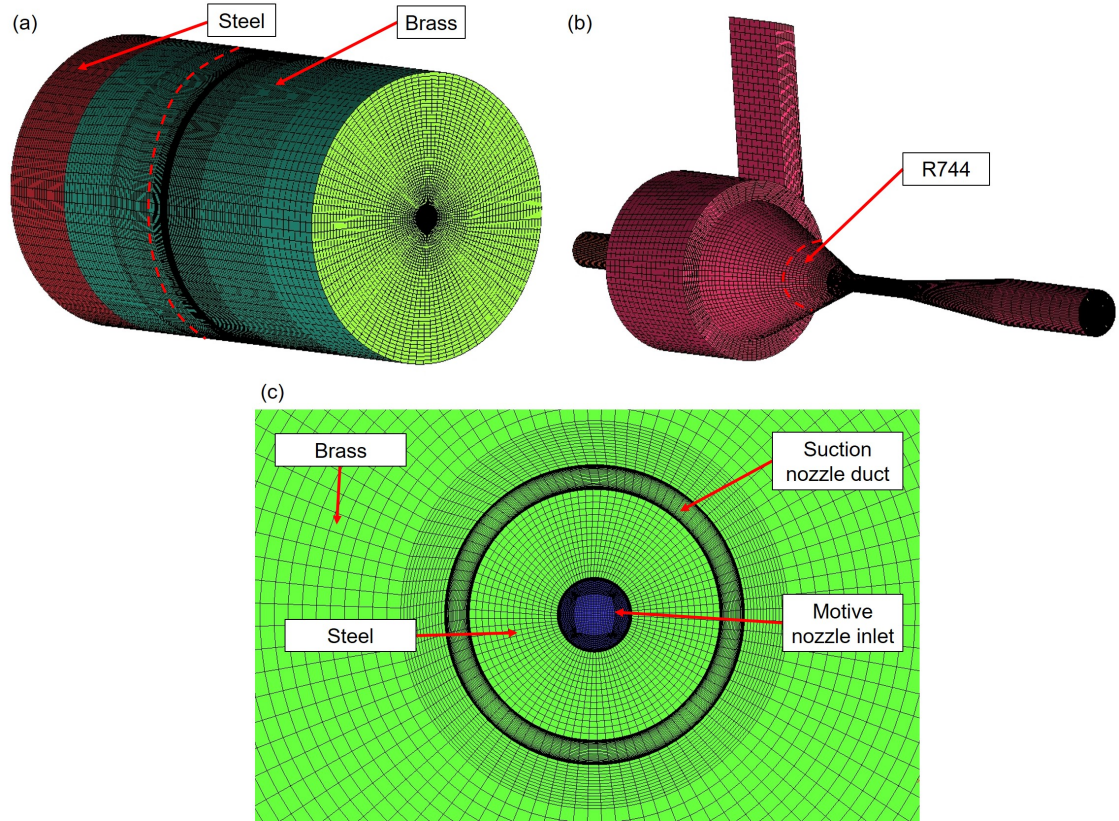


Figure 6: The numerical mesh grid of the R744 two-phase ejector: (a) outer solid walls; (b) interface between solid and fluid domains; (c) cross-sectional view through the motive nozzle throat.

375 Apart from the mesh sensitivity investigation, the grid convergence index (GCI) analysis was performed. The
 376 GCI analysis of χ was performed for the same boundary conditions #AD1 and numerical grids as for the aforemen-
 377 tioned mesh sensitivity analysis presented in Figure 7 based on an approach defined by Roache et al. [43]. The
 378 grid refinement ratio r of 1.28 was constant during mesh refinement. The order of convergence was calculated as
 379 follows:

$$p_{GCI} = \frac{1}{\ln(r)} \left| \ln \left(\left| \frac{\chi_c - \chi_m}{\chi_m - \chi_f} \right| \right) \right| \quad (17)$$

380 where p_{GCI} is the order of convergence and subscripts c, m, and f are defined for coarse, medium, and fine meshes,
 381 respectively. To provide a weighted correction to the fine grid solution, a second-order Richardson extrapolation
 382 method can be used [44]:

$$\chi_{ext} = \chi_f + \frac{\chi_f - \chi_m}{r^2 - 1} \quad (18)$$

383 Finally, GCI of the fine mesh can be solved in the following form:

$$GCI_f = \frac{1.25 \cdot \frac{|\chi_f - \chi_m|}{\chi_f}}{r^p - 1} \quad (19)$$

384 where GCI_f is the fine-grid convergence index. The results of the GCI analysis were set in Table 6. The GCI value
 385 of 0.48% confirmed negligible influence of the selected numerical grid on the CFD results.

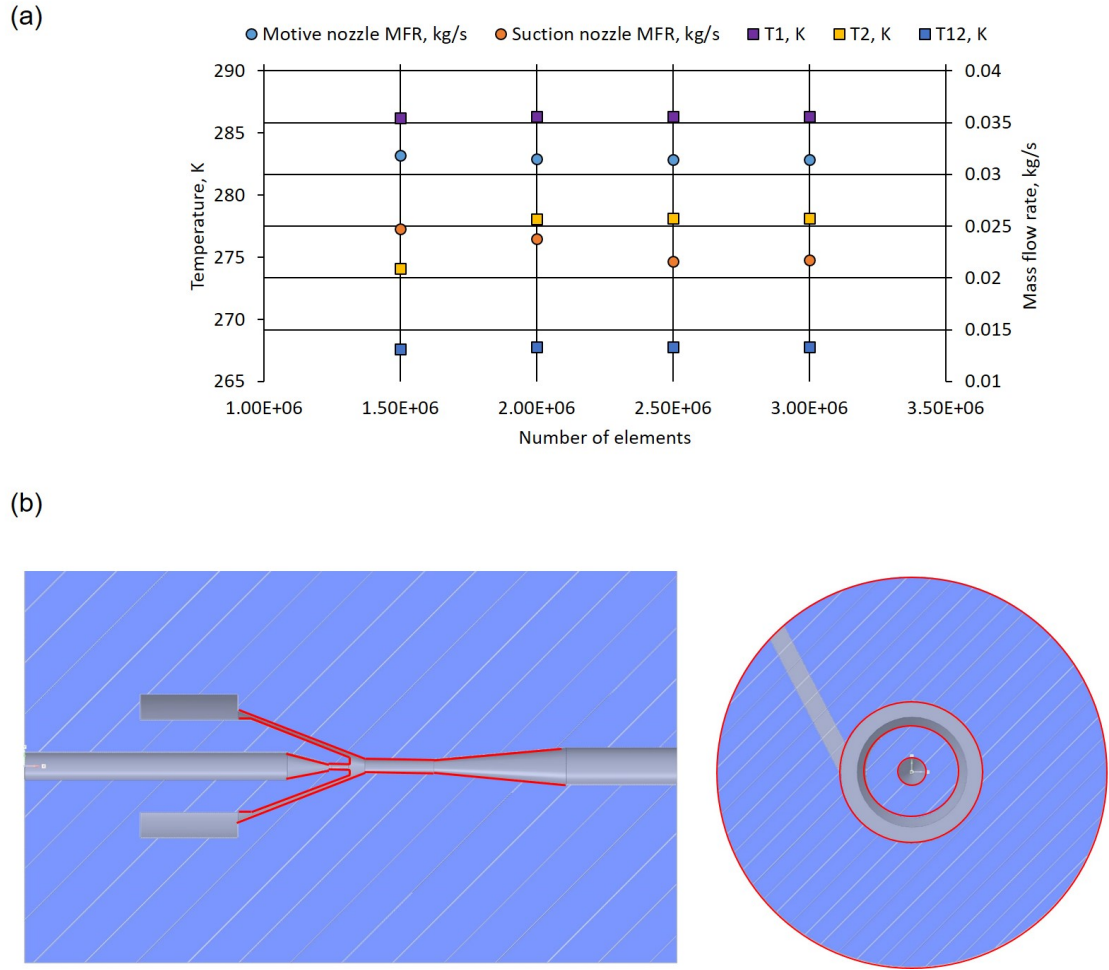


Figure 7: The mesh sensitivity analysis of the R744 two-phase ejector: (a) MN and SN MFRs and local wall temperatures at boundary conditions #AD1 defined in Table 4; (b) selected geometrical parameters for mesh refinement at the axial section and the cross-sections.

Table 6: Parameters of Grid convergence index analysis computed according to [43].

Parameter	Value
Constant grid refinement ratio (r)	1.28
Order of convergence (p_{GCI})	5.25
Extrapolated mass entrainment ratio (χ_{ext})	0.69
Fine-grid convergence index (GCI_f)	0.48%

386 The numerical investigation of the wall thermal conductivity and wall roughness influence on the wall temperature distribution was presented in Figure 8 for boundary condition #AD8 with high ΔT of approximately 28 K defined in Table 4. It can be seen that the change of the brass thermal conductivity negligible influenced the wall temperatures. An increase of k_w from 109 W/(m·K) to 153 W/(m·K) lowered wall temperature by 0.2 K at the measurement points as shown in Figure 8(a). The wall roughness sensitive analysis presented in Figure 8(b) indicated the walls temperature differences of the thermocouples 6÷13. The CFD model with wall roughness of 2 μ m

392 obtained lower values of the foregoing wall temperatures up to approximately 6 K when compared to the results
 393 with higher wall roughness. Therefore, the wall roughness influenced the heat transfer inside the R744 ejector,
 394 thereby it should be taken into the account during the design process. The influence of different HTC defined on
 395 the outer ejector walls showed almost identical HTC on the inner walls temperature distribution was presented
 396 in Figure 8(c). In similar to the wall thermal conductivity, HTC defined on the outer ejector walls had negligible
 397 effect on the temperature distribution close to the inner walls. A change of HTC from 10 W/(m²·K) to 2 W/(m²·K)
 398 reduced the inner walls temperature of thermocouples 11 ÷ 13 up to 0.2 K. The negligible effect of different turbu-
 399 lence intensity on the inner wall temperature distribution was presented in Figure 8(d) for the motive nozzle inlet
 400 and Figure 8(e) for the suction nozzle inlet. The reduction of the motive nozzle turbulence intensity from 25%
 401 to 1% slightly decreased the inner wall temperatures in the motive nozzle part, mixer and at the beginning of the
 402 diffuser. The reverse behaviour of the turbulence intensity appeared in the suction nozzle inlet. The inner wall
 403 temperatures increased at the end of mixer and in the diffuser during decreasing of the turbulence intensity.

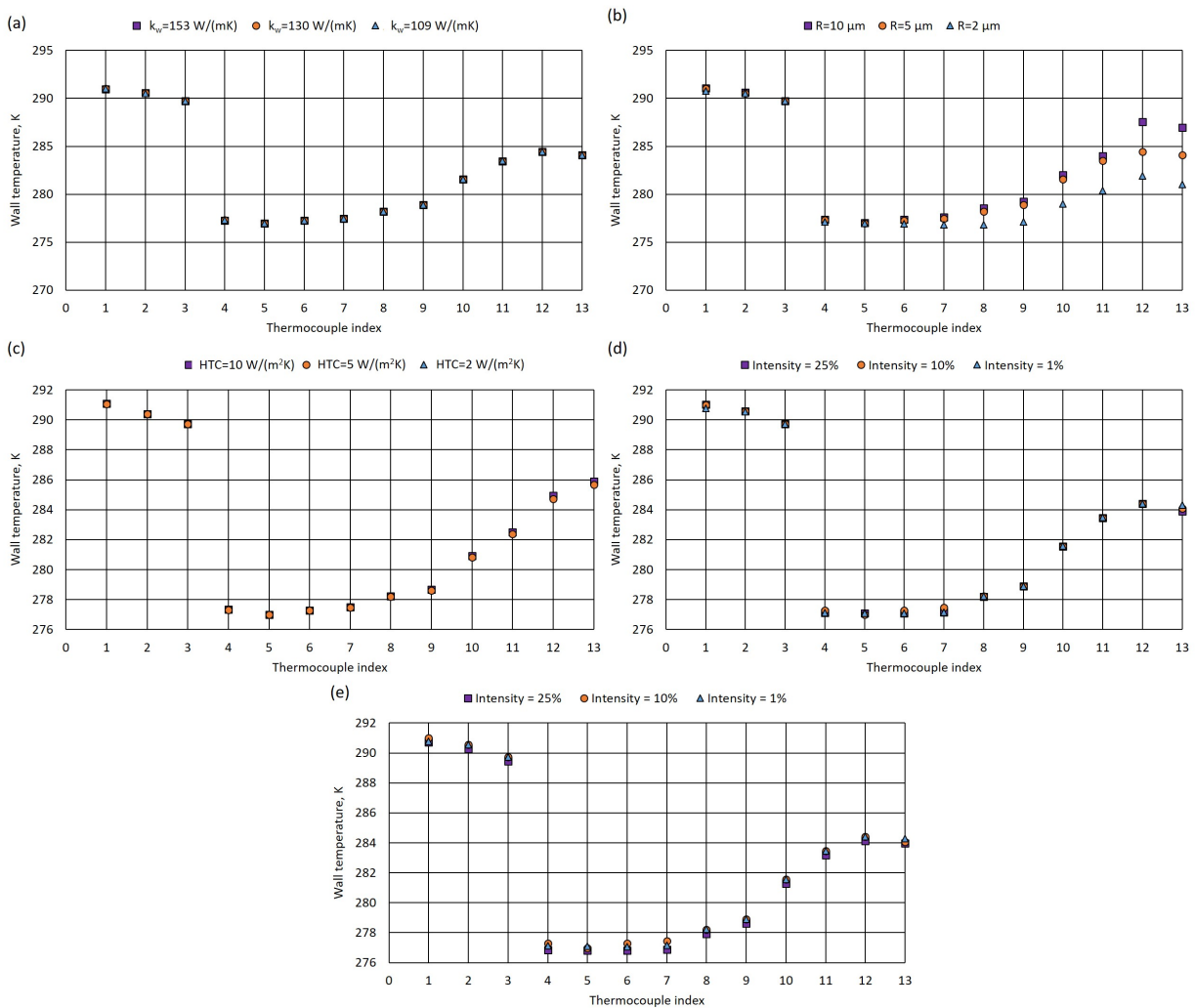


Figure 8: The sensitive analysis of the brass wall thermal conductivity and the wall roughness on the walls temperature distribution with boundary conditions #AD8 defined in Table 4: (a) the brass thermal conductivity; (b) wall roughness; (c) HTC defined on the outer ejector walls; (d) motive nozzle inlet turbulence intensity; (e) suction nozzle inlet turbulence intensity.

404 Figure 9 presents the influence of the turbulence model on the ejector walls temperature distribution and the
 405 ejector performance. The analysis was done for boundary condition #AD8 with high ΔT of 28 K defined in Table

406 4. The investigation was accomplished for four turbulence models: $k - \epsilon$ Realizable, $k - \omega$ SST, Transition SST
407 and Reynolds Stress model and then the results were compared to the experimental data. Moreover, $k - \epsilon$ Realiz-
408 able model and Reynolds Stress model required consideration of the near-wall treatment. In the aforementioned
409 investigation, two near wall formulations were analysed:

- 410 • Standard wall function (SWT) that is used for a broad range of wall-bounded flows and it becomes less
411 reliable, when the flow situations depart from the ideal conditions that are assumed in their derivation (30
412 $< y^+ < 300$) [30].
- 413 • Enhanced wall function (EWT) that is used for complex near wall fluid phenomena or low-Reynolds flows
414 ($y^+ < 1$) [30].

415 The $k - \omega$ SST, Transition SST and Reynolds Stress turbulence approaches took into account the near wall
416 formulation in their mathematical structure. However, the low-Reynolds implementation was enabled for $k - \omega$
417 SST and Transition SST models to fully resolve the near wall boundary layer. The foregoing turbulence models
418 were studied in the literature for the CFD numerical modelling of air and steam ejectors [28, 29, 30, 31].

419 As shown in Figure 9(a), the CFD model for each turbulence model obtained similar ejector walls temper-
420 atures for the thermocouples 1÷3. The temperature difference below 3 K was obtained for all investigated tur-
421 bulence models for the thermocouples 4÷6 located close to the suction chamber and at the beginning of the
422 pre-mixer. However, the mixing process of the motive and suction flows that appeared inside the pre-mixer and
423 mixer strongly influenced the prediction of the wall temperatures. Hence, the $k - \epsilon$ Realizable SWT and $k - \omega$ SST
424 approaches obtained high temperature difference for the thermocouples 8÷13 in the range from 10 K to 20 K. The
425 better agreement of the near wall CO₂ fluid flow modelling in EWT affected the inner wall temperature prediction.
426 Hence, the $k - \epsilon$ Realizable model with EWT reached a better prediction of the inner wall temperatures compared
427 to the same turbulence approach with SWT, especially at the end of the diffuser. The best accuracy of the temper-
428 ature captured in the mixer and diffuser walls was obtained for the Transition SST and Reynolds Stress turbulence
429 models with either SWT or EWT function. Furthermore, the CFD model with Transition SST reached wall tem-
430 perature differences of the thermocouples 12÷13 below 1 K. Besagni et al. [29] obtained similar overestimation of
431 the thermal field for the $k - \epsilon$ -based and $k - \omega$ -based turbulence models compared to the experimental data near
432 nozzle and in the centreline of an air ejector.

433 According to the χ comparison presented in Figure 9(b), the $k - \epsilon$ Realizable and Transition SST models ob-
434 tained similar χ value when compared to the experimental results. The CFD model with $k - \omega$ SST and Reynolds
435 Stress turbulence model reached lower χ of approximately 0.4. The slight difference of χ for each turbulence ap-
436 proach was obtained in the numerical study of Mazzelli et al. [28] and Besagni et al. [29]. Moreover, the results
437 presented by Varga et al. [31] confirmed the best agreement of the global flow parameters by using the Transition
438 SST approach. A use of the EWT in the $k - \epsilon$ Realizable and Reynolds Stress turbulence models increased χ com-
439 pared to the aforementioned models with SWT. The similar behaviour was indicated in [30]. The best prediction
440 of the wall temperature distribution and high accuracy of χ let to use the Transition SST turbulence model to the
441 validation procedure and further investigations.

442 5.3. CFD model validation

443 Table 7 presents the motive nozzle and the suction nozzle MFR discrepancies together with the wall tempera-
444 ture discrepancies of the proposed R744 two-phase ejector CFD model with insulated outer walls. The validation
445 procedure was performed for all boundary conditions presented in Table 4. It can be observed that the motive
446 nozzle MFR prediction of the CFD model was within $\pm 7\%$. The high accuracy of the motive nozzle MFR resulted
447 in the low wall temperature discrepancy of thermocouples 1÷3 located in the motive nozzle below ± 5 K. The suc-
448 tion nozzle MFR accuracy was within $\pm 10\%$ for all investigated points. The highest discrepancy of the suction
449 nozzle MFR of 10.6% was obtained for #AD1. The wall temperature predictions above 5 K of the thermocouples
450 6÷11 located at the end of pre-mixer and in the mixer were reached for #AD5. However, the accuracy of the ejector
451 wall temperatures was below 8 K for all boundary conditions of the thermocouples 4÷13. Therefore, the proposed
452 CFD model of the R744 two-phase ejector with insulated outer walls predicted the motive nozzle and the suction
453 nozzle MFRs together with the wall temperatures with acceptable accuracy.

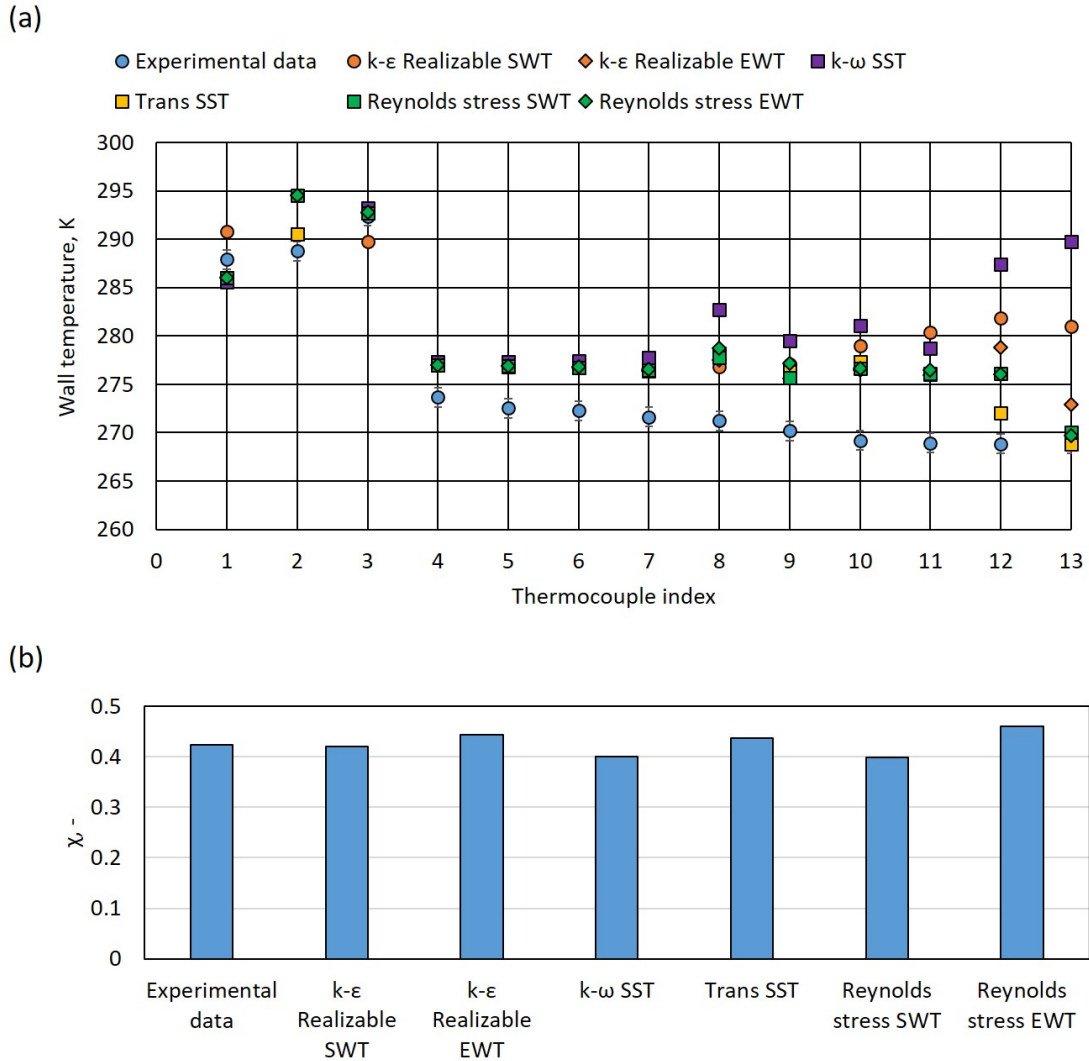


Figure 9: The turbulence model analysis of the R744 two-phase ejector with boundary conditions #AD8 defined in Table 4: (a) the wall temperature measurements; (b) χ value.

454 The validation procedure of the R744 two-phase ejector CFD model with non-adiabatic outer walls is pre-
 455 sented in Table 8. Both nozzle MFRs and the wall temperatures predictions of the proposed CFD model
 456 were compared to the experimental data presented in Table 5. Similar to the results set in Table 7, the motive nozzle
 457 MFR accuracy was high: within $\pm 5\%$. The suction nozzle MFR discrepancy was within $\pm 10\%$ for all boundary
 458 conditions except #NAD5. However, the suction nozzle MFR accuracy was below 12% for the foregoing bound-
 459 ary conditions, thereby the proposed CFD model predicted both streams at high accuracy at transcritical region
 460 and close to the critical point. The wall temperatures 1÷3 located in the motive nozzle part reached the absolute
 461 difference compared to the experimental data within ± 3.0 K. The accuracy within ± 7 K was obtained for wall tem-
 462 peratures 4÷13 under boundary conditions #NAD1, #NAD2, #NAD4, #NAD6, and #NAD8, thereby the proposed
 463 CFD model predicted the wall temperature of the suction nozzle and the mixer with high accuracy. The highest
 464 discrepancy of the wall temperatures 9÷12 was within ± 8 K at #NAD3, #NAD5 and #NAD7 as a result of the two-
 465 phase flow simulation within the mixer and the diffuser. However, the prediction of the wall temperatures 12 and
 466 13 below ± 5 K was reached for the remaining boundary conditions. Therefore, the proposed CFD model obtained

Table 7: The accuracy of the R744 two-phase ejector CFD model with AD outer walls.

BC	$\delta \dot{m}_{MN}$ %	$\delta \dot{m}_{SN}$ %	Δ_{T_1} K	Δ_{T_2} K	Δ_{T_3} K	Δ_{T_4} K	Δ_{T_5} K	Δ_{T_6} K	Δ_{T_7} K	Δ_{T_8} K	Δ_{T_9} K	$\Delta_{T_{10}}$ K	$\Delta_{T_{11}}$ K	$\Delta_{T_{12}}$ K	$\Delta_{T_{13}}$ K
#AD1	-5.4	10.6	1.8	2.0	0.4	1.9	2.4	2.6	3.8	3.3	4.4	3.9	2.0	-0.2	-0.2
#AD2	-5.1	0.2	3.5	2.2	0.3	-0.2	0.6	-0.4	-0.5	-0.3	0.2	0.7	0.7	-0.3	-0.5
#AD3	-1.9	7.9	0.5	-1.0	0.6	0.3	1.2	1.5	2.0	1.6	2.6	3.4	1.7	1.9	1.1
#AD4	-1.3	7.6	0.6	0.7	-1.9	3.5	4.3	4.4	7.9	5.5	7.6	5.8	3.4	1.4	-0.3
#AD5	-4.2	2.0	2.0	2.4	2.0	7.0	7.7	7.5	7.7	7.7	7.4	7.7	7.2	1.1	-0.3
#AD6	5.6	8.8	2.0	1.0	-0.8	1.2	1.9	2.0	2.3	2.7	3.4	3.5	4.5	4.0	3.7
#AD7	-7.2	6.5	4.3	2.6	0.3	2.9	3.3	3.4	3.6	3.6	4.5	5.4	5.7	4.9	0.6
#AD8	-0.7	5.6	-1.1	0.3	0.3	3.3	1.6	1.8	2.1	2.6	3.2	4.6	3.2	1.0	0.0

467 an accuracy range similar to that of the validation procedure presented in Table 7.

Table 8: The accuracy of the R744 two-phase ejector CFD model with NAD outer walls insulation.

BC	$\delta \dot{m}_{MN}$ %	$\delta \dot{m}_{SN}$ %	Δ_{T_1} K	Δ_{T_2} K	Δ_{T_3} K	Δ_{T_4} K	Δ_{T_5} K	Δ_{T_6} K	Δ_{T_7} K	Δ_{T_8} K	Δ_{T_9} K	$\Delta_{T_{10}}$ K	$\Delta_{T_{11}}$ K	$\Delta_{T_{12}}$ K	$\Delta_{T_{13}}$ K
#NAD1	-0.4	0.7	0.9	0.4	1.8	3.6	4.4	4.7	4.7	4.9	1.9	2.1	3.6	1.4	-0.6
#NAD2	-3.4	-5.8	-0.4	0.6	1.9	4.7	5.2	5.7	6.0	4.7	4.5	5.2	4.6	1.4	0.9
#NAD3	-2.7	-4.4	1.7	0.5	2.8	7.5	7.6	7.7	8.2	6.6	6.5	7.0	8.1	1.8	0.3
#NAD4	-2.9	-2.1	-0.7	0.7	1.3	4.3	5.0	5.4	5.7	3.6	3.8	5.5	4.2	0.3	-0.3
#NAD5	-0.7	11.0	1.5	0.8	2.9	5.8	6.3	6.3	6.6	6.1	6.3	7.4	7.9	4.1	0.5
#NAD6	-1.8	7.7	0.8	0.7	-1.4	2.9	3.8	4.2	4.4	0.8	1.7	4.5	6.1	0.8	-0.2
#NAD7	1.1	0.5	-0.7	-1.8	0.2	5.7	6.1	6.3	6.6	6.1	6.3	7.1	8.1	3.9	0.1
#NAD8	0.3	5.1	1.8	1.4	2.3	3.4	3.7	4.1	3.7	1.8	2.2	2.6	4.6	4.5	2.3

468 The validation procedure for both outer wall variants confirmed the high accuracy of the global and the local
469 parameters of the proposed CFD model. Therefore, the numerical investigation of the non-adiabatic inner and
470 outer walls enabled us to determine the influence of heat transfer within the ejector walls and of the two-phase
471 flow on ejector performance.

472 5.4. Influence of heat transfer on ejector performance

473 Figure 10 presents the temperature field of the R744 two-phase ejector for the section A-A defined in Figure
474 2(a). The results are shown under the boundary condition #AD1, defined in Table 4. The investigation was ac-
475 complished for four different ejector wall temperature variants. In Figure 10(a), the inner and outer walls were
476 adiabatic, whereby the temperature field only depended on the two-phase flow. The adiabatic outer walls and
477 the non-adiabatic inner walls are presented in Figure 10(b). It can be observed that heat transfer between the
478 motive flow and the inner wall of the motive nozzle influenced the temperature distribution, particularly in the
479 converging-diverging nozzle. The distance between the two streams increased the suction stream temperature
480 close to the inner wall. Therefore, the non-adiabatic inner wall and the material properties of the motive nozzle
481 influenced the motive stream and the suction stream parameters as well as the two-phase mixing flow inside the

482 pre-mixer. In Figure 10(c), the motive nozzle inner walls were adiabatic, and the inner walls of the suction nozzle,
 483 the mixer and the diffuser together with the outer walls were defined as non-adiabatic walls. It can be observed
 484 that the insulation of the motive nozzle prevented the influence of heat transfer on the motive stream and the suc-
 485 tion stream behaviour near the walls. Finally, the non-adiabatic inner and outer walls are shown in Figure 10(d).
 486 The temperature field was similar to the results presented for the adiabatic outer walls. Therefore, the ambient
 487 conditions did not influence the R744 two-phase ejector performance compared to the inner walls of the motive
 488 nozzle.

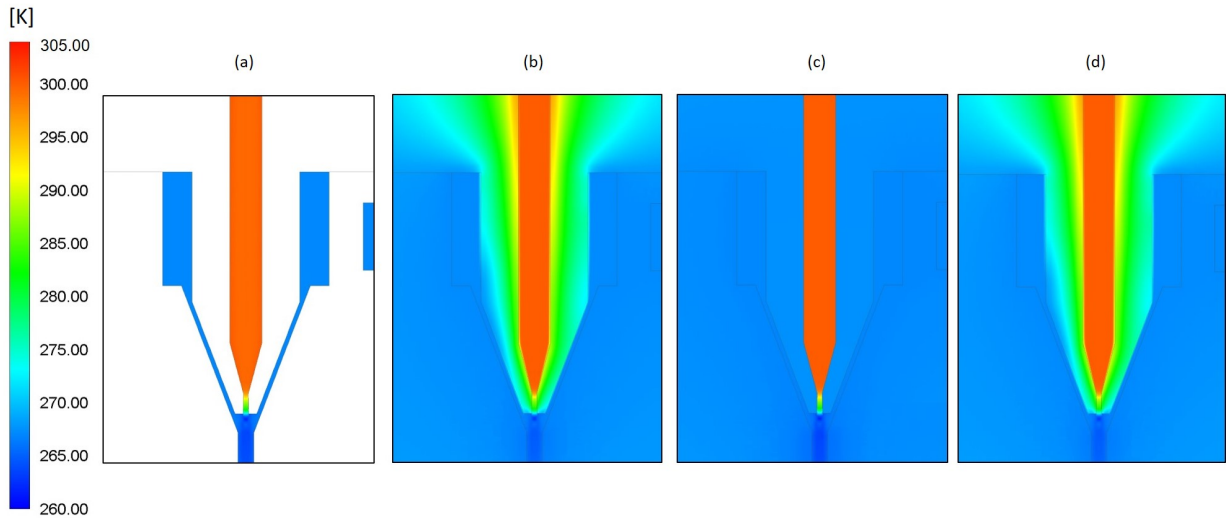


Figure 10: The temperature fields of the R744 two-phase ejector at boundary conditions #NAD2 defined in Table 5: (a) HT-1; (b) HT-2; (c) HT-3; (d) HT-4.

489 In addition to the temperature field presented in Figure 10, the investigation of the R744 two-phase suction
 490 flow behaviour enabled us to determine the influence of the tangential suction inlet on the flow swirl. Therefore,
 491 Figure 11 presents the streamlines of the R744 suction flow inside the two-phase ejector under boundary condition
 492 #NAD2 with high ΔT of approximately 26 K and the lowest suction pressure of 24.2 bar as defined in Table 5. The
 493 streamlines were coloured according to velocity magnitude to determine the region of the highest velocity. It
 494 can be observed that the suction flow formed a high swirl in the suction nozzle and in the mixer. As a result of
 495 the high rotational flow in the suction nozzle, the suction stream remained longer in the region near the motive
 496 nozzle inner wall. Therefore, the temperature increase of the swirled suction flow near the foregoing walls strongly
 497 influenced the mass flow rate and the performance of the two-phase ejector.

498 Figure 12 presents the influence of heat transfer on R744 two-phase ejector performance for four variants
 499 defined in Section 4.2. The investigation was performed for the two boundary conditions #AD1 and #AD4 defined
 500 in Table 4 and two boundary conditions #NAD6 and #NAD8 defined in Table 5. The foregoing boundary conditions
 501 were selected to analyse the heat transfer for different ΔT and different suction nozzle conditions. The motive
 502 nozzle MFR presented in Figure 12(a) confirmed the influence of heat transfer on the motive stream. The ejector
 503 with adiabatic inner walls in HT-1 exhibited lower MFR than the ejector with non-adiabatic inner walls in HT-2
 504 and HT-4 under selected boundary conditions. In addition, the difference in the motive nozzle MFR between HT-2
 505 and HT-4 was negligible. Considering the insulation of the motive nozzle inner walls in HT-3 was enough to enable
 506 us to determine a motive stream similar to that in HT-1.

507 The suction nozzle MFR analysis presented in Figure 12(b) enabled us to determine the influence of the suc-
 508 sion stream temperature increase near the motive nozzle wall on the suction nozzle MFR value. The two-phase
 509 ejector with all adiabatic walls in HT-1 and adiabatic inner walls only in the motive nozzle exhibited higher suction
 510 nozzle MFR compared to the non-adiabatic inner walls in HT-2 and HT-4 under each boundary condition. The
 511 decrease in the suction nozzle MFR of approximately 0.1 kg/s under each boundary condition strongly influenced
 512 ejector performance. However, the insulation of the motive nozzle inner walls prevented the degradation of ejec-

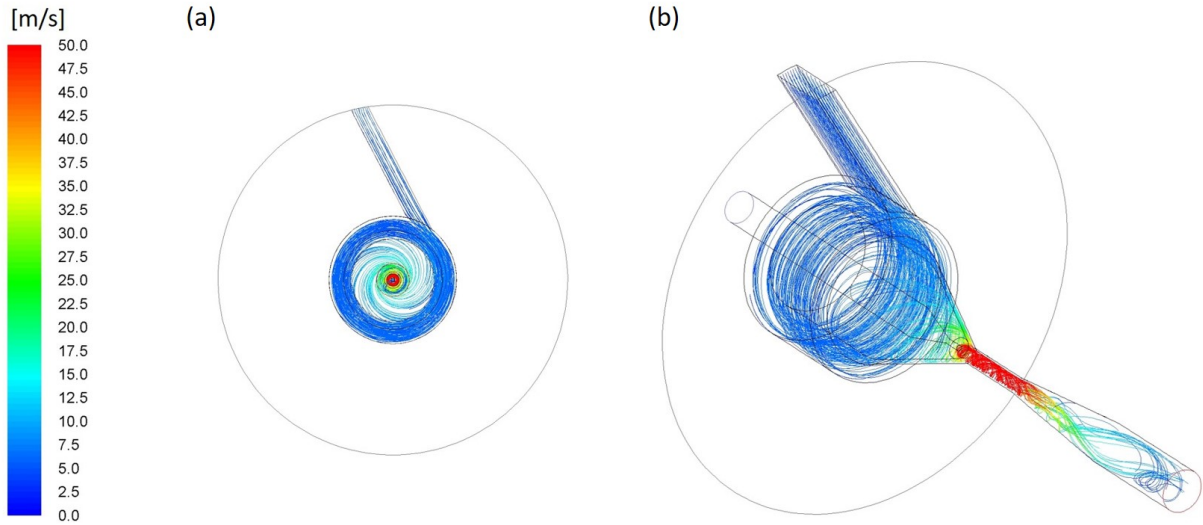


Figure 11: The suction flow streamlines coloured by the velocity magnitude of the R744 two-phase ejector at boundary conditions #NAD2 defined in Table 5: (a) cross-section view; (b) isometric view.

tor performance. Therefore, the effect of the swirling flow and the small thickness of the motive nozzle part close to the converging-diverging nozzle influenced the decrease in the suction nozzle MFR.

The increase in motive nozzle MFR and the decrease in suction nozzle MFR affected the decrease in χ , which was shown in Figure 12(c). The value of χ ranged from 0.42 to 0.6 under selected boundary conditions. However, the non-adiabatic inner walls in HT-2 and HT-4 decreased χ by approximately 0.1. In a manner similar to that described in the motive nozzle and suction nozzle MFR analysis, the two-phase ejector with adiabatic inner walls only in the motive nozzle achieved the best performance. Therefore, the highest relative degradation of χ for non-adiabatic walls (Figure 12(d)) was approximately 13% for HT-2 and HT-4 under #AD1. In addition, the ejector with non-adiabatic inner walls in HT-2 and HT-4 obtained a χ reduction over 10% under #AD4 and #NAD8. The lowest χ degradation of approximately 8% was reached under #NAD6 for HT-2 and HT-4. The two-phase ejector with adiabatic inner walls only in the motive nozzle defined in HT-3 obtained a small χ reduction below 1%. Therefore, an ejector should be constructed of low-conductivity material between the motive and suction nozzles. In addition, the replacement of the suction tangential inlet with an axial-type inlet improved ejector performance and reduced the influence of heat transfer between the nozzles.

5.5. Heat transfer coefficient of the R744 two-phase ejector

Figure 13 presents HTC of the CO₂ two-phase flow along the two-phase ejector for the motive nozzle, the mixer and diffuser. The HTC was investigated for boundary conditions #AD5 and #AD8 from Table 4 and #NAD1 and #NAD6 from Table 5. Similar to the results presented in Figure 12, the boundary conditions were selected for different ΔT from 8 K to 26 K. The highest HTC value of approximately 45 000 W/(m²K) was obtained in the diverging part of the motive nozzle under #AD8 and #NAD1. Additionally, the HTC rapidly increased in the converging-diverging nozzle as a result of the expansion process, supersonic flow beyond the motive nozzle throat and the small distance between the two streams. The small thickness of the motive nozzle at the end of the diverging part influenced the high value of the heat flux and the temperature difference between the motive stream and the wall temperature (Figure 10). In the pre-mixer and the mixer, the HTC decreased below 5 000 W/(m²K) as a result of the mixing process and the small impact of the brass wall temperature on heat transfer. Therefore, the R744 two-phase flow exhibited a similar HTC value in the mixer and in the diffuser. The high ΔT and the swirled suction flow affected the HTC increase in the diffuser (Figure 13) under #NAD6.

The HTC of the R744 suction flow inside the suction nozzle of the two-phase ejector is presented in Figure 14. The investigation was performed under boundary conditions #AD5, #AD8, #NAD1 and #NAD6 defined in

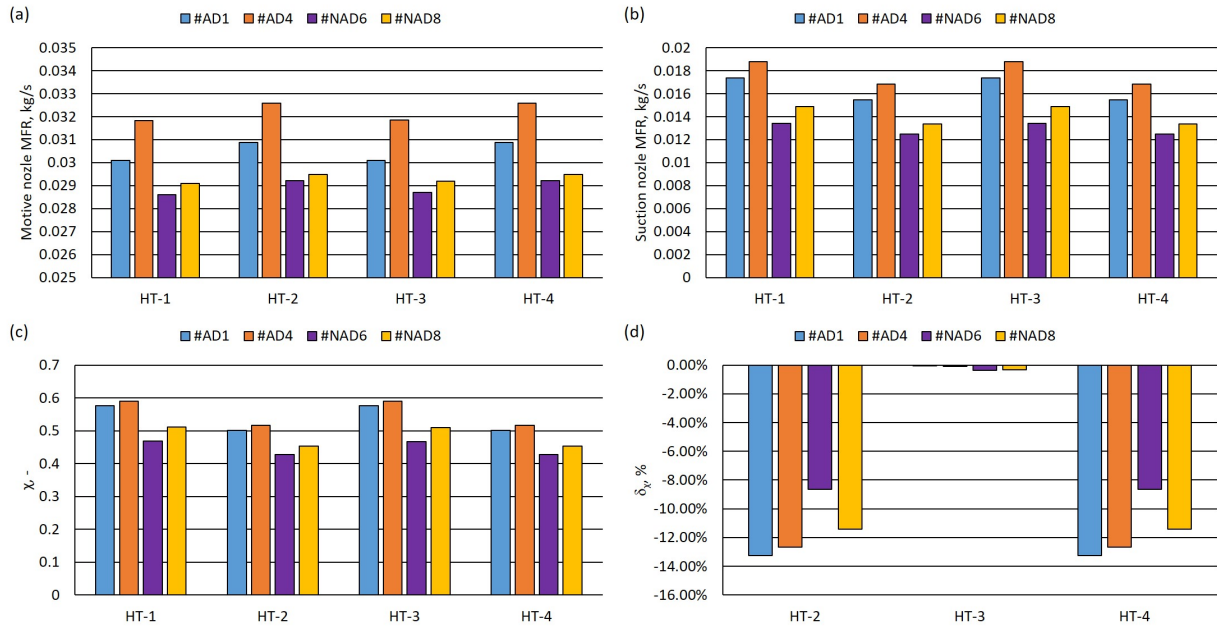


Figure 12: The heat transfer influence on the R744 two-phase ejector performance for four heat transfer variants at boundary conditions defined in Table 4 and Table 5: (a) motive nozzle MFR; (b) suction nozzle MFR; (c) mass entrainment ratio; (d) degradation of the mass entrainment ratio.

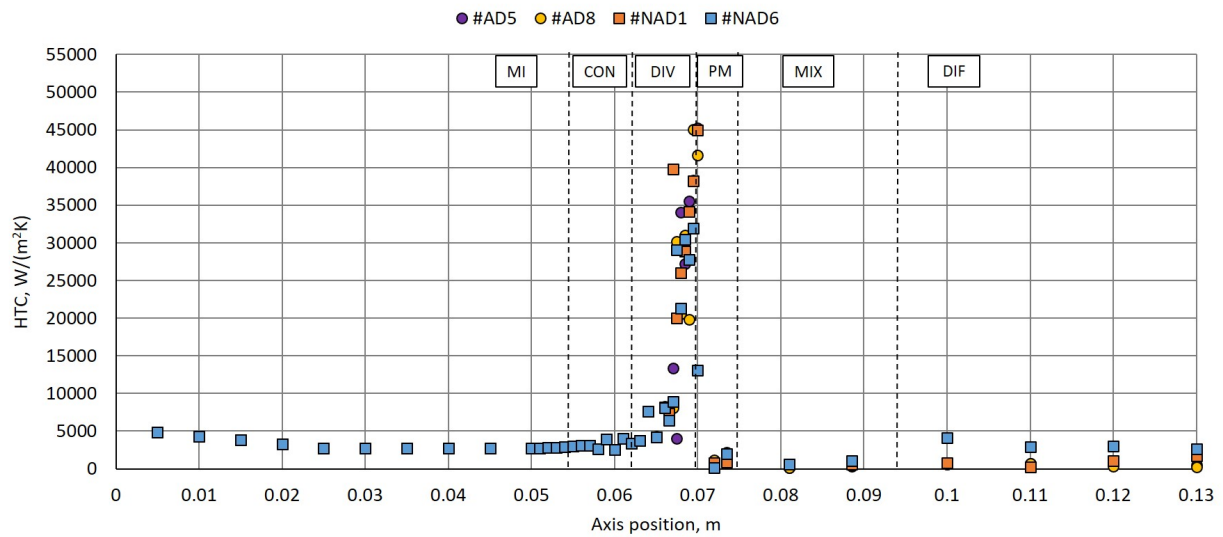


Figure 13: The HTC of the R744 two-phase flow along the two-phase ejector axis at boundary conditions defined in Table 4 and Table 5: MI - motive inlet; CON - motive nozzle converging part; DIV - motive nozzle diverging part; PM - pre-mixer; MIX - mixer; DIF - diffuser.

542 Table 4 and Table 5, respectively. In addition, the tangential inlet and the converging part of the suction nozzle
 543 were examined to evaluate the influence of the ejector design on the HTC calculations. The HTC value rapidly
 544 increased in the area of the tangential inlet and close to the pre-mixer. The highest HTC value of approximately
 545 20 000 W/(m²K) was registered at the end of the tangential inlet under boundary condition #AD5. In addition, the
 546 swirled flow in the converging part of the suction nozzle slightly increased in response to the flow direction from
 547 approximately 100 W/(m²K) to approximately 6 000 W/(m²K) for each investigated boundary condition. Finally,

548 the small distance between the motive stream and suction stream close to the pre-mixer influenced the high heat-
 549 flux values. Therefore, heat transfer strongly influenced the suction flow as a result of the suction inlet design and
 550 material selection.

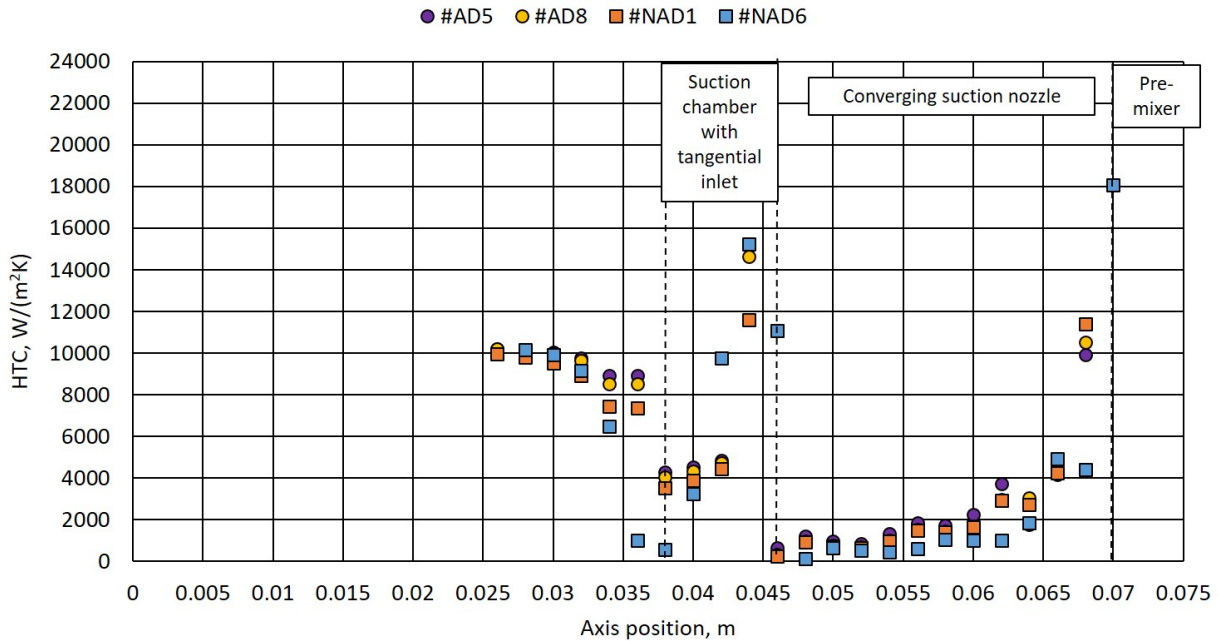


Figure 14: The HTC of the R744 two-phase flow inside the suction nozzle at boundary conditions defined in Table 4 and Table 5.

551

552 6. Conclusions

553 The proposed CFD model of the CO₂ two-phase ejector was developed by coupling the heat transfer within the
 554 ejector walls with the two-phase HRM model. A R744 two-phase ejector equipped with thermocouples channels
 555 was designed and manufactured to perform an experimental investigation. A test series was performed on the
 556 two-phase ejector to evaluate ejector performance under the transcritical operating regime and near the critical
 557 point. The experimental investigation was performed with and without insulation of the outer ejector walls. In
 558 addition, the temperature difference between the motive nozzle and the suction nozzle was determined. The
 559 efficiency of the two-phase ejector ranged from 6% to 14% as a result of a small pressure difference between the
 560 outlet and the suction nozzle. In addition, the wall temperature distributions indicated the negligible influence of
 561 non-adiabatic outer ejector walls on the temperature along the ejector.

562 To determine the accuracy of the CFD model, the developed numerical model was verified and validated. A
 563 mesh sensitivity analysis was performed to avoid the influence of the numerical mesh grid on ejector performance.
 564 The Transition SST turbulence model was implemented to the CFD model regarding to the good prediction of the
 565 wall temperature distribution as well as the mass entrainment ratio when compared to the $k-\epsilon$ Realizable and $k-\omega$
 566 SST models. The validation of the developed CFD model confirmed a good prediction of the mass flow rates. The
 567 motive nozzle MFR accuracy was within $\pm 7\%$ for ADs and NADs outer walls and the suction nozzle MFR accuracy
 568 was within $\pm 10\%$ for ADs and $\pm 14\%$ for NADs outer walls. Additionally, the wall temperature predictions of the
 569 two-phase R744 ejector CFD model were within ± 5 K for most of the validated points. Therefore, the developed
 570 CFD model facilitated investigating the influence of heat transfer on ejector performance and calculating the HTC
 571 of the CO₂ two-phase flow.

572 The temperature field of the R744 two-phase ejector confirmed the negligible influence of ambient conditions
573 on heat transfer within the ejector walls. However, non-adiabatic inner walls affected the fluid temperature dis-
574 tribution near the walls, particularly in the converging-diverging nozzle and the suction nozzle. In the suction
575 nozzle, the tangential inlet caused a swirling flow of the suction stream, increasing the heat transfer process close
576 to the inner walls. The non-adiabatic inner walls of the R744 two-phase ejector decreased the χ value from ap-
577 proximately 8% to 13%. The HTC along the motive nozzle and the suction nozzle confirmed the influence of heat
578 transfer on the R744 two-phase flow, particularly in the converging-diverging nozzle, in the area of the tangential
579 flow and close to the pre-mixer. Therefore, the use of low thermal conductivity materials may reduce the nega-
580 tive influence of heat transfer on ejector performance. However, to avoid device breakdown, the selection of the
581 material from which to manufacture the ejector should also consider the stress on the motive nozzle caused by
582 expansion.

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