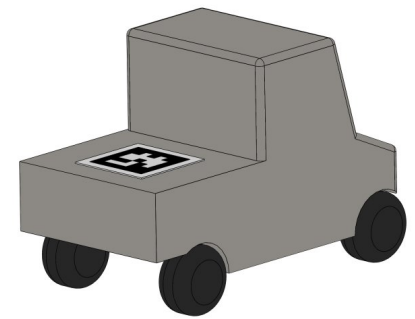


Vegard Line

Autonomous Landing of a Multirotor UAV on a Platform in Motion

June 2018



NTNU
Norwegian University of
Science and Technology
Faculty of Information Technology
and Electrical Engineering
Department of Engineering Cybernetics