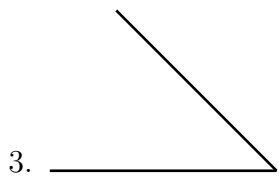
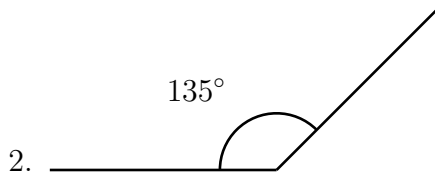
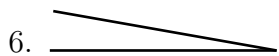


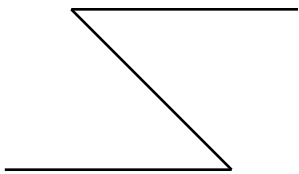
Use the robots to draw these paths



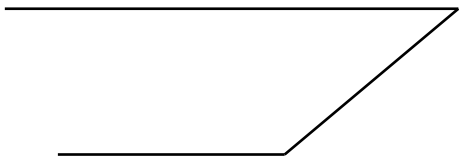
4. Create the paths from task 1-3 again, but use a different program than you did last time. (Hint: you can use the reflex angle)



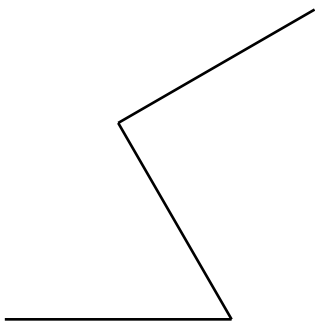
7.



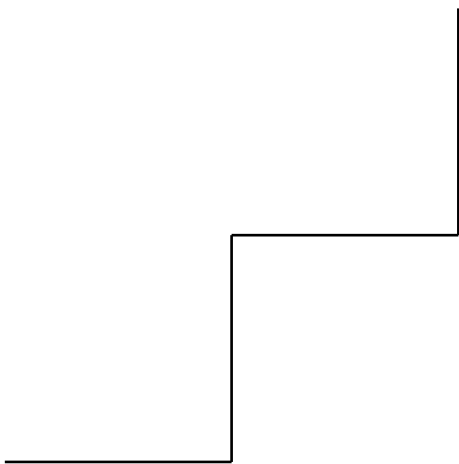
8.



9.



10.



11.

