



Vegard Wie Henriksen, Audun Gerhardsen Røine

NTNU
Norwegian University of
Science and Technology
Faculty of Information Technology,
Mathematics and Electrical Engineering
Department of Engineering Cybernetics

Master's thesis

Trondheim, 2016

Master's thesis

Vegard Wie Henriksen
Audun Gerhardsen Røine

Three-Axis Motion Compensated Crane Head Control

Trondheim, June 2016

