



Master's thesis

Trondheim, 2015

Erik Falmår Wilthil

Master's thesis

NTNU
Norwegian University of
Science and Technology,
Faculty of Information Technology,
Mathematics and Electrical Engineering
Department of Engineering Cybernetics

Erik Falmår Wilthil

Singularity-Free Navigation System for an Autonomous Unmanned Aerial Vehicle

Trondheim, June 2015