

The *PlotMicroheart* program Micro Heart Result Visualization

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1 Warning: Preliminary Report

This report describes work still in progress. It is not completely updated on all details and parameters. Hence, use it with great care.

2 Operation of the Program

2.1 Preferred method: From Graphical User Interface

The program is run by starting Matlab in the directory containing the 'PlotMicroheart' m-files. This directory contains a Matlab *startup*-file which will set up the correct path-structure and call the GUI file, *PlotMicroheartGUI.m*. This is intended to be the main way to run the program.

The input values to the program are explained Table 1. Each of these input fields correspond to a data field in variable *measdata*.

2.2 Alternative: From Batch File, *PlotMicroheartBatch*

Alternatively, the program can also be run from a batch file, *PlotMicroheartBatch*. The file *PlotMicroheartBatch* gives an example on how this can be done. The program sets the fields in *measdata* to the selected parameters, and calls *PlotMicroheart(measdata)* to calculate and plot the results.

A listing of the example file is printed in Figure 3. The example shows how a loop can be made to select different parameters and plot the results in different figures. First, the *measdata* variable is initialized with common parameters. Then, the different parameters *acceleration*, *velocity*, and *position* are calculated for the same parameters, and the results plotted in figures '1', '2', and '3'. The example illustrates variation of the physical quantity (acceleration, velocity, position) to be plotted. Any parameter can of course be varied by this procedure, typical examples are different time intervals for one recording, and different sensors for the same interval.

2.3 Main program: *PlotMicroheart*

Either *PlotMicroheartGUI.m* or *PlotMicroheartBatch.m* will, when called, put the parameters to be used into a *struct*-variable *measdata*. The contents of *measdata* is given in Table 3. The program will then call the main function *PlotMicroheart(measdata)*, using the parameter fields in *measdata* to load the selected raw data file, calculate the traces, and plot the results in the selected figure window.

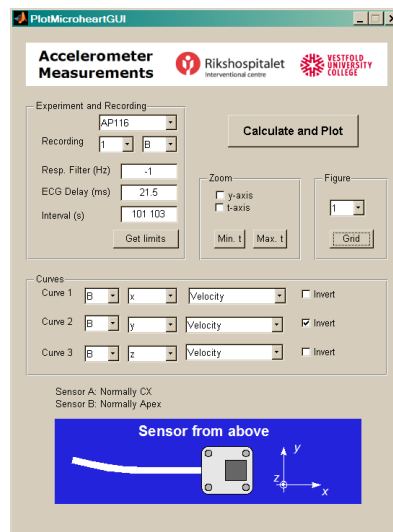


Figure 1. Graphical user interface to enter parameters and run the program *PlotMicroheart*.

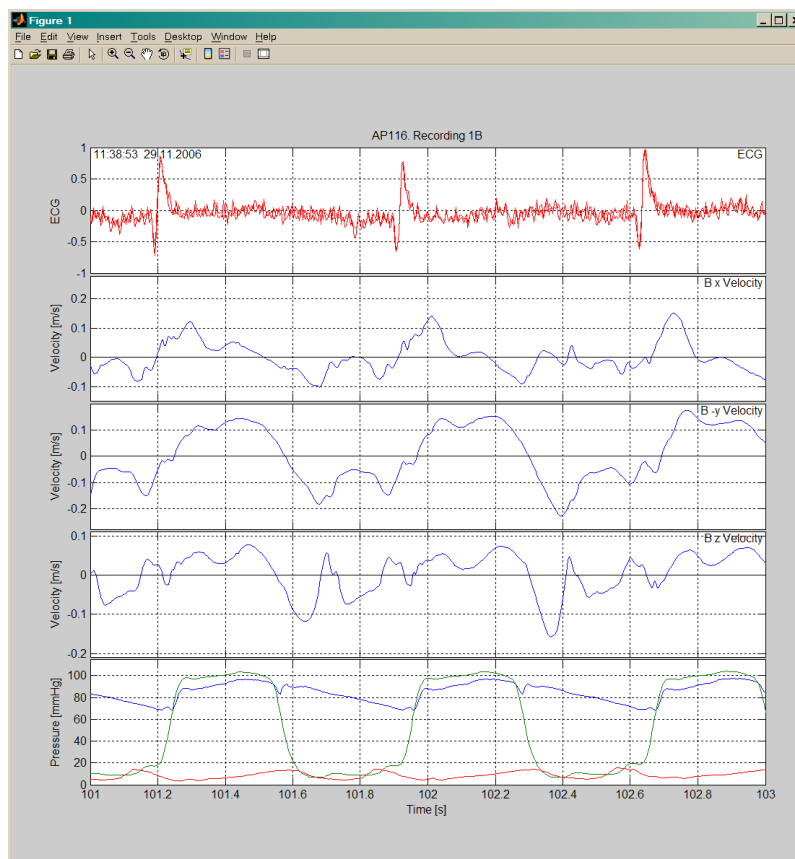
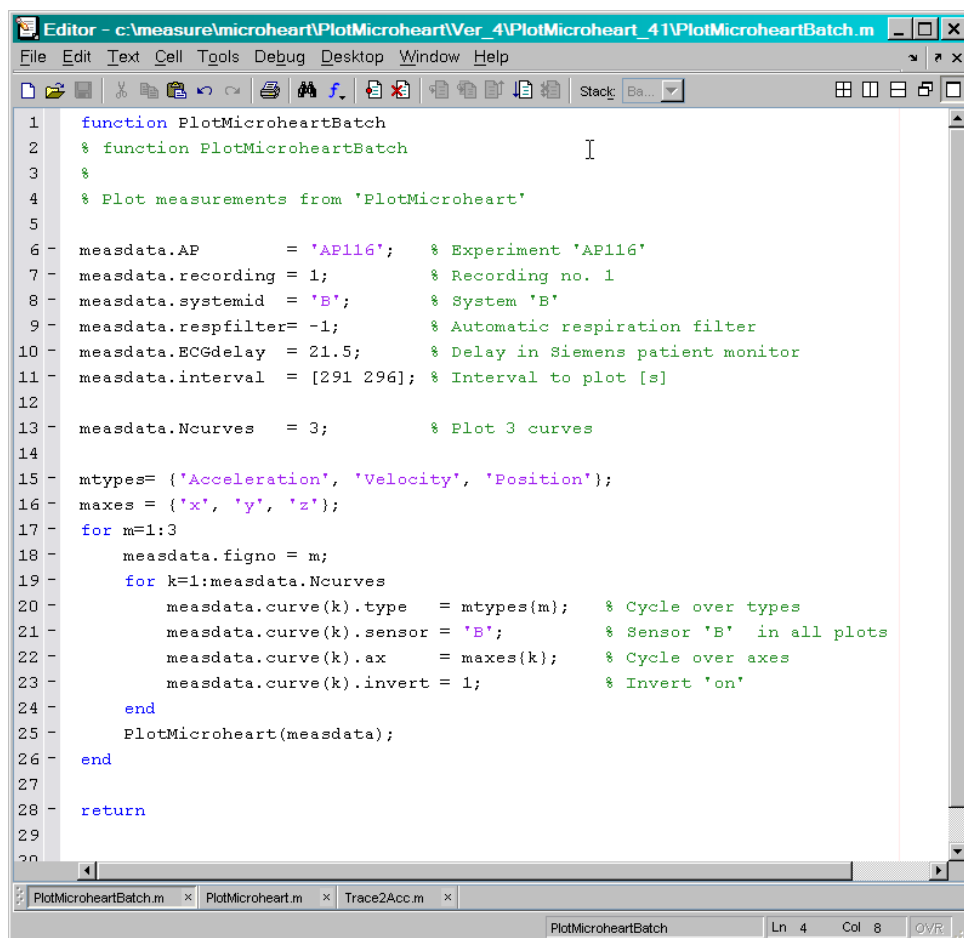


Figure 2. Example of result from *PlotMicroheart*, displaying the ECG signal (top), three velocity curves (middle), and the pressures (bottom).

Table 1. Operation of the program *PlotMicroheart*.

| GUI Field | <i>measdata</i> field | Description |
|--------------------------|--------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Experiment and Recording | | |
| Experiment | AP | A valid experiment code, e.g. 'AP116', 'AH006'. |
| Recording | recording | A valid recording number for the selected experiment, e.g. '1B', '2', '5B' |
| Resp. filter [Hz] | respfilter | Older measurements do not include the letter. Cutoff-frequency of the respiration high-pass filter. Negative input gives a default value depending on experiment: Pig, 'AP': $f_c = 1.0$ Hz Human, 'AH': $f_c = 0.6$ Hz |
| ECG delay [ms] | ECGdelay | Delay in the ECG monitoring unit. |
| Interval [s] | interval | Interval to plot, start and end values |
| Curves | | |
| Sensor | curve(k).sensor | Sensor 'A' or 'B', or no result, '0'. |
| Axis | curve(k).ax | 'x', 'y', or 'z' axis, or 'Length'. Ref. sensor image in Figure 1. |
| Quantity | curve(k).type | What to plot: 'Acceleration', 'Velocity' or 'Position'. |
| Invert | curve(k).invert | Invert y-axis scale. |
| Calculate and Plot | | Load data, calculate results, and plot graphs. |
| Zoom | | |
| y-axis | | Toggles y-axis zoom. |
| t-axis | | Toggles x-axis, or time-axis. |
| Min. t | | Set time-scale on all plots equal to the shortest interval. |
| Max. t | | Set time-scale on all plots equal to the longest interval. |
| Figure | | Number of figure where the result is plotted. |
| Grid | | Toggle grid lines in all plots. |



```

1 function PlotMicroheartBatch
2 % function PlotMicroheartBatch
3 %
4 % Plot measurements from 'PlotMicroheart'
5
6 measdata.AP = 'AP116'; % Experiment 'AP116'
7 measdata.recording = 1; % Recording no. 1
8 measdata.systemid = 'B'; % System 'B'
9 measdata.respfilter = -1; % Automatic respiration filter
10 measdata.ECGdelay = 21.5; % Delay in Siemens patient monitor
11 measdata.interval = [291 296]; % Interval to plot [s]
12
13 measdata.Ncurves = 3; % Plot 3 curves
14
15 mtypes= ('Acceleration', 'Velocity', 'Position');
16 maxes = {'x', 'y', 'z'};
17 for m=1:3
18     measdata.figno = m;
19     for k=1:measdata.Ncurves
20         measdata.curve(k).type = mtypes(m); % Cycle over types
21         measdata.curve(k).sensor = 'B'; % Sensor 'B' in all plots
22         measdata.curve(k).ax = maxes(k); % Cycle over axes
23         measdata.curve(k).invert = 1; % Invert 'on'
24     end
25     PlotMicroheart(measdata);
26 end
27
28 return
29
30

```

Figure 3. Example batch file *PlotMicroheartBatch* varying parameters to *PlotMicroheart* and plotting the results in different figures.

3 Organization of Functions

The structure of the program is illustrated in Table 2 and in Figure 4.

Table 2. Organization of functions used in *PlotMicroheart*.

| Function | Description |
|----------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------|
| Shell | |
| <code>varargout= PlotMicroheartGUI (varargin)</code> | Graphical user interface. Generated by Matlab's <i>Guide</i> , with variable initialization and callback functions added. |
| <code>PlotMicroheartBatch</code> | Batch operation. |
| Main function | |
| <code>[sample,wfmr,scaled]=PlotMicroheart (measdata)</code> | Load, calculate and plot results. |
| Sub functions | |
| <code>[sample,wfmr,par]=InterpretTRC (sourcefile)</code> | Load and interpret raw data data files. |
| <code>scaled= Trace2Acc (sample,wfmr,ch)</code> | Scale results, from Volts to acceleration. |
| <code>PlotMHTraces (curve,ECG,sample,measdata,pressure)</code> | Plot calculated results. |
| Utility functions | |
| <code>trace= BuildTrace (t0,dt,y)</code> | Build waveform trace from components. |
| <code>h=PlotWaveform (trace,method,varargin)</code> | Plot waveform trace. |
| <code>y=MHIntegrate (x,fs,fc,N)</code> | Integration with high pass filter. |
| <code>cal=ReadCalibration (sensor)</code> | Read sensor calibration data |

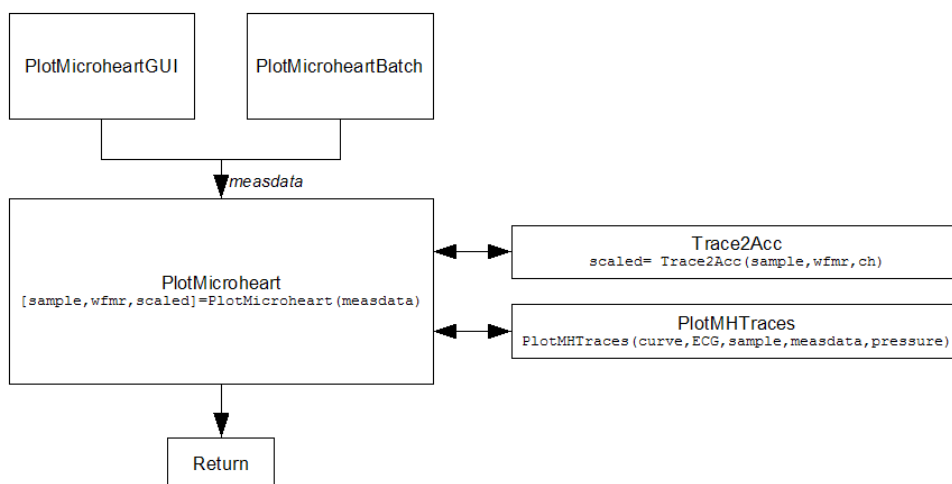


Figure 4. Illustration of the organization of main functions in *PlotMicroheart*.

4 Organization of Data

Data are stored in the *struct* variables listed in Table 3.

Table 3. *Struct*-variables used in *PlotMicroheart*.

| | Name | Description |
|----------------------------------|----------|----------------------------------------------------------------------------------------------------------------------------------------------------------|
| Loaded from raw data file | sample | Data identifying the measurement. Stored when data is recorded. |
| | wfm | Acquired waveform data, results of the measurement. |
| | par | Free, for extra parameters read from 'file-name.dat'. |
| Entered by operator, or from GUI | measdata | Data specifying which parameters to calculate. |
| Calculated | wfmr | Reduced version of wfm, containing. 1) Fields from wfm with only selected channels and intervals. 2) New fields needed for identification of data. |
| | scaled | Calculated and scaled results. |

5 Contents of the *struct*-Variables.

Table 4. Fields of the *struct*-variable *measdata*.

| Field | Size | Type | Description |
|------------------------|-----------------------|---------|---------------------------------------------------------------------------------------------------------------------------------------------------|
| AP | | string | A valid experiment code, e.g. 'AP116', 'AH006'. |
| recording | 1 | double | Recording number. |
| systemid | 1 | char | System id letter: 'A', 'B', ... |
| figno | 1 | double | Number of figure where the result is plotted. |
| respfilter | 1 | double | f_c of respiration high-pass filter [Hz]. Negative value gives a default f_c : Pig, 'AP': $f_c = 1.0$ Hz Human, 'AH': $f_c = 0.6$ Hz |
| ECGdelay | 1 | double | Delay in the ECG monitoring unit [ms]. |
| interval | 2×1 | double | Interval to plot, start and end values |
| Ncurves | 1 | double | No. of curves to plot. |
| curve | $1 \times N_{curves}$ | struct | Description of the curves to be plotted |
| Fields of <i>curve</i> | | | |
| curve(k).sensor | 1 | char | Sensor 'A' or 'B', or no result, '0'. |
| curve(k).ax | 1 | char | 'x', 'y', or 'z' axis, or 'Length'. |
| curve(k).type | | string | What to plot: 'Acceleration', 'Velocity' or 'Position'. |
| curve(k).invert | 1 | boolean | Invert y-axis scale. |

Table 5. Fields of the *struct*-variable *sample*.

| Field | Size | Type | Description |
|------------|------|--------|------------------------------------------|
| version | 64 | char | Acquisition program version number |
| sensor | 2 | cell | Sensor identifiers |
| operator | 64 | char | Operator initials |
| journalno | 64 | char | Reference to measurement, free text |
| id | 64 | char | Reference to test subject, free text |
| comment | 64 | char | Any comment, free text |
| code | 64 | char | Measurement code |
| no | 1 | double | Measurement number |
| date | 64 | char | Measurement date: <i>dd.mm.yyyy</i> |
| time | 64 | char | Measurement time: <i>hh.mm.ss</i> |
| filename | 64 | char | Name of original raw data file |
| path | 64 | char | Path where original raw data was stored |
| sensortype | 1 | double | Sensor type no. 0: 'MHP0xx', 1: 'MHP1xx' |

Table 6. Fields of the *struct*-variable *wfm*.

| Field | Size | Type | Description |
|-----------------|---------------|--------|------------------------------------------------------------------------------------------------------------|
| description | | char | Short description of contents |
| ver | M | double | Version number |
| N | 1 | double | Total no. of channels, including merged channels. |
| inputconfig | M | double | Configuration of ADC, from NI-DAQ |
| Lscalingcoeff | 2 | double | Length of scalingcoeff |
| scalingcoeff | Lscalingcoeff | double | Conversion of ADC data to volts, from NI-DAQmx. Offset and multiplier for each channel, |
| Lchannel | 1 | double | Length of channel |
| channel | Lchannel | double | ADC channel names, from NI-DAQmx. |
| samplemode | M | double | Code for 'Sample mode', from NI-DAQmx. |
| samplerate | 1 | double | Sample rate [S/s]. |
| Lverstring | 2 | double | Length of verstring. |
| verstring | Lverstring | char | Recording program(s) version number. |
| scaleoffset | N | double | ADC scaling coefficients, from 'scalingcoeff'. Included for compatibility between NI-DAQ 7 and NI-DAQmx |
| scalemultiplier | N | double | ADC scaling coefficients, from 'scalingcoeff'. Included for compatibility between NI-DAQ 7 and NI-DAQmx |
| trace | $N \times Nt$ | double | Measured traces. 12 bit data stored as 'uint16'. |
| tracename | N | cell | Trace names, codes giving channel contents. |
| axname | N | cell | Axis names, roughly identical to 'tracename'. |
| cmax | | cell | Correlation coefficients, when merging data from different systems. |

M is the number of measurement systems used to obtain the data.

$M = 1$: All data sampled on one system.

$M = 2$: Data merged from two systems. Typically, acceleration data is from the first system and pressure data from the second.

Table 7. Organization of channels in *wfm.trace*.

| Row no. | Symbol | Alt. symbol | Description |
|---------|----------|-------------|---------------------------------------------|
| 1 | V_{DD} | VDD | Supply voltage |
| 2 | ECG | ECG | ECG recorded with acceleration data |
| 3 | a_{Ax} | Ax | Acceleration, sensor A, axis x |
| 4 | a_{Ay} | Ay | Acceleration, sensor A, axis y |
| 5 | a_{Az} | Az | Acceleration, sensor A, axis z |
| 6 | a_{Bx} | Bx | Acceleration, sensor A, axis x |
| 7 | a_{By} | By | Acceleration, sensor A, axis y |
| 8 | a_{Bz} | Bz | Acceleration, sensor A, axis z |
| 9 | ECG_p | ECGp | ECG recorded with pressure data |
| 10 | p_1 | p1 | Pressure channel 1, normally aorta |
| 11 | p_2 | p2 | Pressure channel 2, normally left ventricle |
| 12 | p_3 | p3 | Pressure channel 1, normally left atrium |

Table 8. Fields of the *struct*-field *selection* in variable *wfmr*. This variable *wfmr* contains the same fields as *wfm*, but *trace* has been shortened to include only necessary sample points, and a new field *selection* contains time and sample infor for the selected part included in *trace*.

| Field | Size | Type | Description |
|-------|------|--------|-------------------------------------------------------------------------------|
| t0 | 1 | double | [s] Start time of <i>trace</i> , relative to the <i>trace</i> in <i>wfm</i> . |
| dt | 1 | double | [s] Sample interval. |
| n0 | 1 | double | Start index of <i>trace</i> , relative to the <i>trace</i> in <i>wfm</i> . |
| N | 1 | double | Number of points in <i>trace</i> . |

Table 9. Fields of the *struct*-variable *scaled*.

| Field | Size | Type | Description |
|-------------|----------------|----------|-----------------------------------------------------------|
| bias | <i>Na</i> | double | Bias values, B_k , for calibration of acceleration. |
| sensitivity | <i>Na</i> | double | Sensitivity values, S_k , for calibrating acceleration. |
| Na | 1 | double | Number of acceleration channels. |
| excluded | <i>dynamic</i> | double | List of excluded sample points. |
| Vdd | 1 | waveform | Supply voltage [V]. |
| ECG | 1 | waveform | ECG signal [V]. |
| a | 1 | waveform | Scaled acceleration vectors [g]. |
| p | 1 | waveform | Scaled pressure vectors [mmHg]. |

Table 10. Definition of the *waveform* variable.

| Field | Size | Type | Description |
|----------------|--------------|---------------|------------------------|
| Required t0 | 1 | double | Start time. |
| dt | 1 | double | Sample interval. |
| y | $N \times M$ | double | Data vectors. |
| Optional delay | 1 | double | Possible system delay. |
| name | | <i>string</i> | Name of trace |